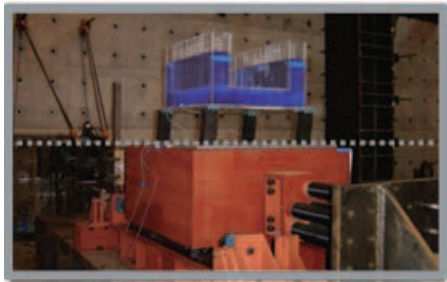


Control device → Experimental part



Structure model → Numerical part

Experimental part \_ TLMD

