

Many of the slides in this lecture are either from or adapted from slides provided by the authors of the textbook "Computer Systems: A Programmer's Perspective," 2<sup>nd</sup> Edition and are provided from the website of Carnegie-Mellon University, course 15-213, taught by Randy Bryant and David O'Hallaron in Fall 2010. These slides are indicated "Supplied by CMU" in the notes section of the slides.

## **Simplistic View of Processor**

```
while (true) {
  instruction = mem[eip];
  execute(instruction);
}
```

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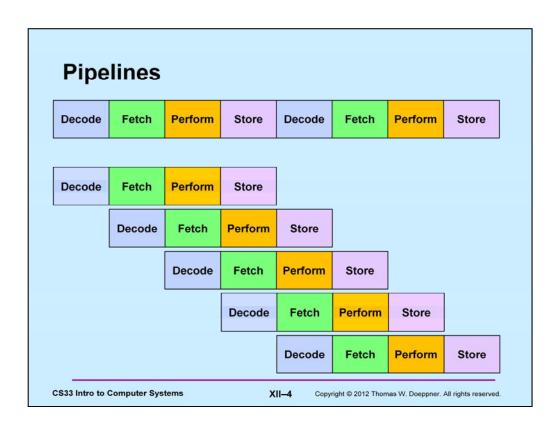
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#### Some Details ...

```
void execute(instruction_t instruction) {
  decode(instruction, &opcode, &operands);
  fetch(operands, &in_operands);
  perform(opcode, in_operands, &out_operands);
  store(out_operands);
}
```

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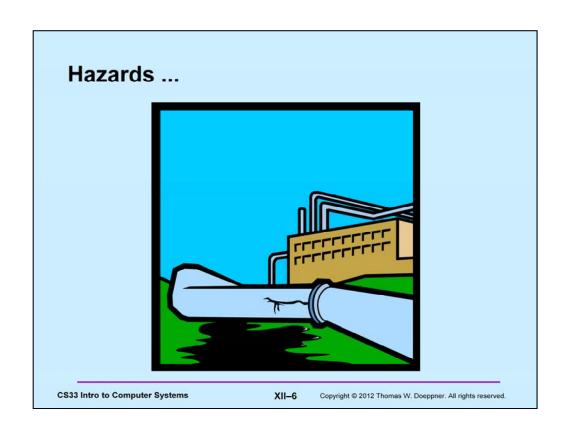


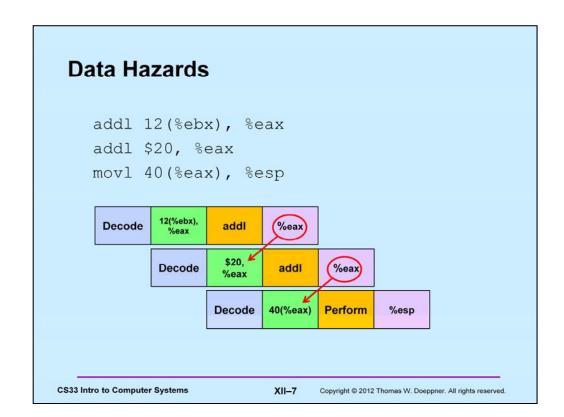
## **Analysis**

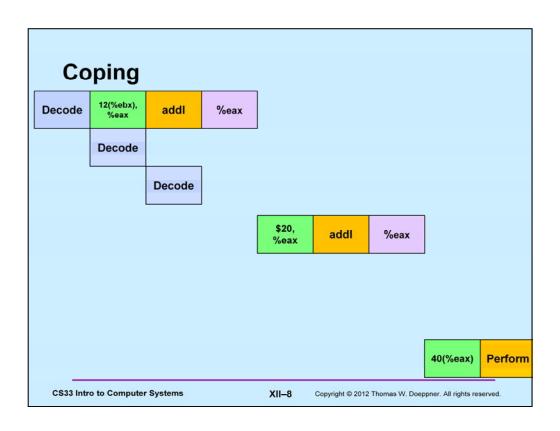
- Not pipelined
  - each instruction takes, say, 320 nanoseconds
    - » 320 ns latency
  - 3.125 billion instructions/second (GIPS)
- Pipelined
  - each instruction still takes 320 ns
    - » latency still 320 ns
  - an instruction completes every 80 ns
    - » 12.5 GIPS throughput

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## **Control Hazards**

```
mov1 $0, %ecx
.L2:
 movl %edx, %eax
 andl $1, %eax
 addl %eax, %ecx
 shrl %edx
 jne .L2 # what goes in the pipeline?
 movl %ecx, %eax
  . . .
```

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## Coping: Guess ...

- · Branch prediction
  - assume, for example, that conditional branches are always taken
  - but don't do anything to registers or memory until you know for sure

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## **Today**

- Overview
- · Generally useful optimizations
  - code motion/precomputation
  - strength reduction
  - sharing of common subexpressions
  - removing unnecessary procedure calls
- · Optimization blockers
  - procedure calls
  - memory aliasing
- Exploiting instruction-level parallelism
- · Dealing with conditionals

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#### **Performance Realities**

There's more to performance than asymptotic complexity

- Constant factors matter too!
  - easily see 10:1 performance range depending on how code is written
  - must optimize at multiple levels:
    - » algorithm, data representations, procedures, and loops
- Must understand system to optimize performance
  - how programs are compiled and executed
  - how to measure program performance and identify bottlenecks
  - how to improve performance without destroying code modularity and generality

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## **Optimizing Compilers**

- · Provide efficient mapping of program to machine
  - register allocation
  - code selection and ordering (scheduling)
  - dead code elimination
  - eliminating minor inefficiencies
- · Don't (usually) improve asymptotic efficiency
  - up to programmer to select best overall algorithm
  - big-O savings are (often) more important than constant factors
    - » but constant factors also matter
- · Have difficulty overcoming "optimization blockers"
  - potential memory aliasing
  - potential procedure side-effects

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## **Limitations of Optimizing Compilers**

- · Operate under fundamental constraint
  - must not cause any change in program behavior
  - often prevents it from making optimizations when would only affect behavior under pathological conditions
- Behavior that may be obvious to the programmer can be obfuscated by languages and coding styles
  - e.g., data ranges may be more limited than variable types suggest
- Most analysis is performed only within procedures
  - whole-program analysis is too expensive in most cases
- · Most analysis is based only on static information
  - compiler has difficulty anticipating run-time inputs
- · When in doubt, the compiler must be conservative

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## **Generally Useful Optimizations**

- Optimizations that you or the compiler should do regardless of processor / compiler
- Code Motion
  - reduce frequency with which computation performed
    - » if it will always produce same result
    - » especially moving code out of loop

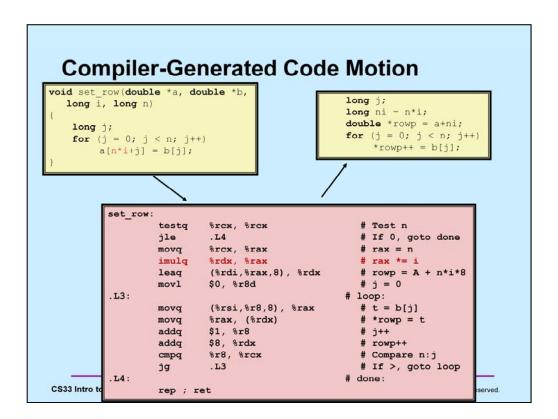
```
      void set_row(double *a, double *b, long i, long n)

      {
      long j; for (j = 0; j < n; j++) a[n*i+j] = b[j];</td>

      for (j = 0; j < n; j++) a[ni+j] = b[j];</td>

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```

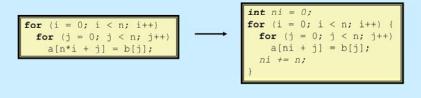


## **Reduction in Strength**

- · Replace costly operation with simpler one
- · Shift, add instead of multiply or divide

```
16*x --> x << 4
```

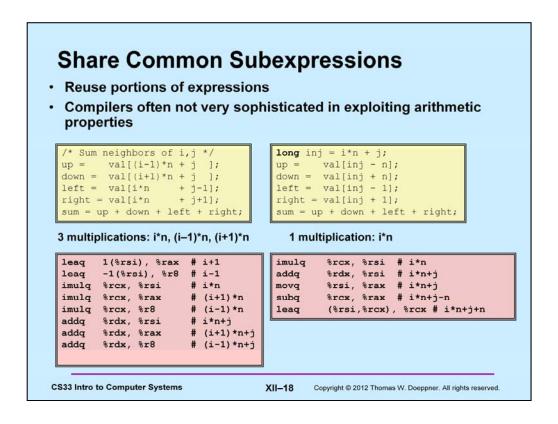
- utility is machine-dependent
- depends on cost of multiply or divide instruction
  - » on Intel Nehalem, integer multiply requires 3 CPU cycles
- · Recognize sequence of products



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## **Optimization Blocker #1: Procedure Calls**

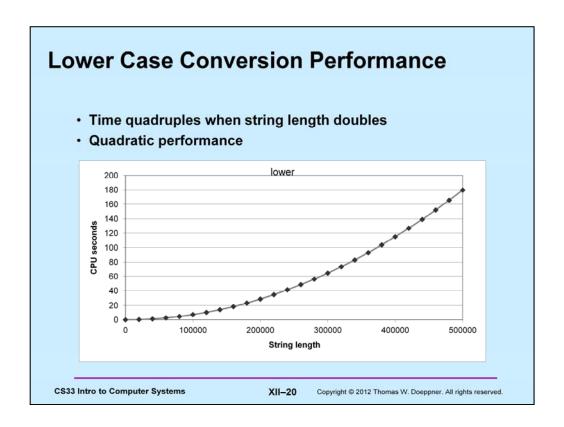
Procedure to convert string to lower case

```
void lower(char *s)
{
  int i;
  for (i = 0; i < strlen(s); i++)
    if (s[i] >= 'A' && s[i] <= 'Z')
       s[i] -= ('A' - 'a');
}</pre>
```

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XII\_19

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# **Convert Loop To Goto Form**

```
void lower(char *s)
   int i = 0;
   if (i >= strlen(s))
    goto done;
   if (s[i] >= 'A' && s[i] <= 'Z')</pre>
      s[i] -= ('A' - 'a');
   if (i < strlen(s))</pre>
    goto loop;
 done:
```

strlen executed every iteration

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## **Calling Strlen**

```
size_t strlen(const char *s)
{
    size_t length = 0;
    while (*s != '\0') {
        s++;
        length++;
    }
    return length;
}
```

- · strlen performance
  - only way to determine length of string is to scan its entire length, looking for null character
- · Overall performance, string of length N
  - N calls to strlen
  - overall O(N2) performance

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## **Improving Performance**

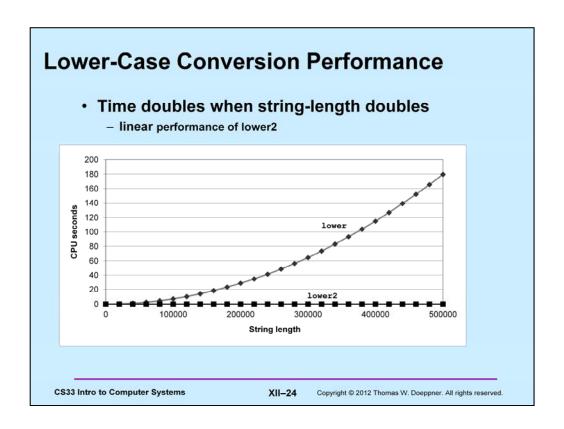
```
void lower2(char *s)
{
   int i;
   int len = strlen(s);
   for (i = 0; i < len; i++)
      if (s[i] >= 'A' && s[i] <= 'Z')
        s[i] -= ('A' - 'a');
}</pre>
```

- Move call to strlen outside of loop
  - since result does not change from one iteration to another
  - form of code motion

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```
Optimization Blocker: Procedure Calls
· Why couldn't compiler move strlen out of inner loop?
   - procedure may have side effects
       » alters global state each time called
   - function may not return same value for given arguments
       » depends on other parts of global state
       » procedure lower could interact with strlen

    Warning:

   - compiler treats procedure call as a black box
   - weak optimizations near them
                                     int lencnt = 0;
· Remedies:
                                     size_t strlen(const char *s)
   - use of inline functions
                                          size t length = 0;
       » gcc does this with -O2
                                          while (*s != '\0') {
   - do your own code motion
                                             s++; length++;
                                          lencnt += length;
                                          return length;
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```

```
Memory Matters
   /* Sum rows of n X n matrix a
      and store result in vector b */
   void sum rows1(double *a, double *b, long n) {
       long i, j;
for (i = 0; i < n; i++) {
           b[i] = 0;
           for (j = 0; j < n; j++)
                b[i] += a[i*n + j];
               # sum_rows1 inner loop
               .L3:
                        addsd
                                  (%rcx), %xmm0
                                                              # FP add
                                 $1, %rax
$8, %rcx
                        addq
                        addq
                        cmpq
                                 %rdx, %rax
                                  %xmm0, (%rsi, %r8,8)
                                                              # FP store
                        jne
  Code updates b[i] on every iteration
   Why couldn't compiler optimize this away?
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```

Note that a is passed as a 1-D array, but interpreted as a 2-D array. This isn't terribly good programming style (gcc, fortunately, refrains from commenting on one's style), but it is definitely the sort of program that gcc must be prepared to deal with.

#### **Memory Aliasing** /\* Sum rows of n X n matrix a and store result in vector b \*/ void sum rows1(double \*a, double \*b, long n) { long i, j; for (i = 0; i < n; i++) { b[i] = 0;for (j = 0; j < n; j++) b[i] += a[i\*n + j]; Value of B: double A[9] = init: [4, 8, 16] { 0, 1, 2, 4, 8, 16}, 32, 64, 128}; i = 0: [3, 8, 16] i = 1: [3, 22, 16]double B[3] = A+3;i = 2: [3, 22, 224] sum\_rows1(A, B, 3); · Code updates b[i] on every iteration · Must consider possibility that these updates will affect program behavior **CS33 Intro to Computer Systems** XII-27 Copyright © 2012 Thomas W. Doeppner. All rights reserved.

#### **Removing Aliasing** /\* Sum rows of n X n matrix a and store result in vector b \*/ void sum\_rows2(double \*a, double \*b, long n) { long i, j; for (i = 0; i < n; i++) {</pre> double val = 0; for (j = 0; j < n; j++) val += a[i\*n + j];</pre> b[i] = val; # sum\_rows2 inner loop .L6: addq \$1, %rax addsd (%rcx), %xmm0 # FP Add addq \$8, %rcx cmpq %rdx, %rax .L6 jne · No need to store intermediate results **CS33 Intro to Computer Systems** XII-28 Copyright © 2012 Thomas W. Doeppner. All rights reserved.

## **Optimization Blocker: Memory Aliasing**

- Aliasing
  - two different memory references specify single location
  - easy to have happen in C
    - » since allowed to do address arithmetic
    - » direct access to storage structures
  - get in habit of introducing local variables
    - » accumulating within loops
    - » your way of telling compiler not to check for aliasing

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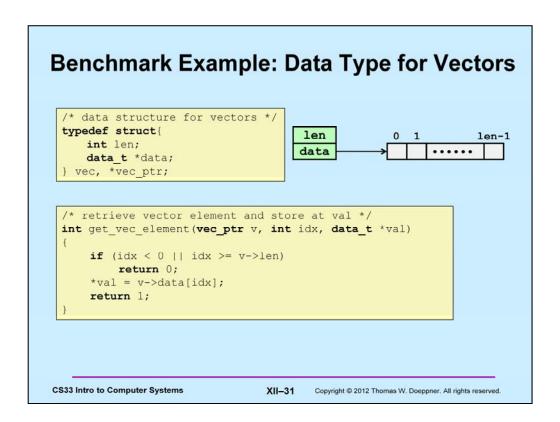
## **Exploiting Instruction-Level Parallelism**

- Need general understanding of modern processor design
  - hardware can execute multiple instructions in parallel
- Performance limited by data dependencies
- Simple transformations can have dramatic performance improvement
  - compilers often cannot make these transformations
  - lack of associativity and distributivity in floatingpoint arithmetic

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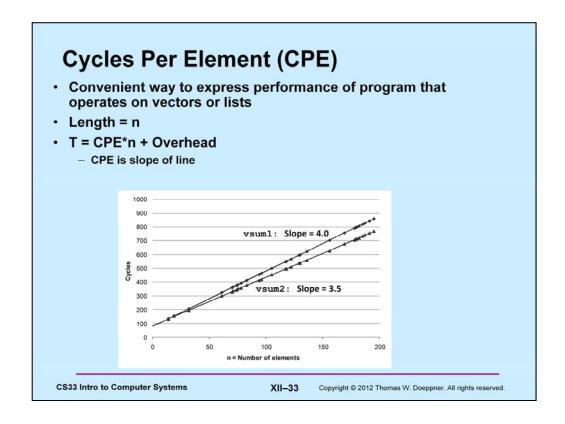
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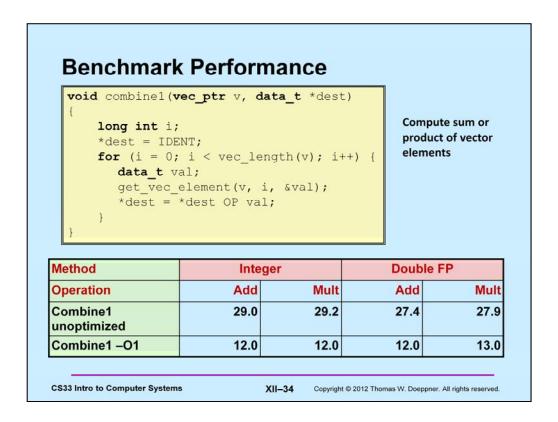


```
Benchmark Computation
   void combine1(vec_ptr v, data_t *dest)
                                                         Compute sum or
        long int i;
                                                         product of vector
        *dest = IDENT;
                                                         elements
        for (i = 0; i < vec_length(v); i++) {</pre>
           data_t val;
          get_vec_element(v, i, &val);
           *dest = *dest OP val;
   · Data Types

    Operations

       - use different declarations
                                           - use different definitions of
                                            OP and IDENT
         for data_t
           » int
                                              » + / 0
           » float
                                               » * / 1
           » double
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```





#### Move vec\_length void combine2(vec\_ptr v, data\_t \*dest){ long int i; long int length = vec\_length(v); \*dest = IDENT; for (i = 0; i < length; i++) {</pre> data\_t val; get\_vec\_element(v, i, &val); \*dest = \*dest OP val; Method **Double FP** Integer Operation Mult Mult Add Add 29.0 29.2 27.9 Combine1 27.4 unoptimized Combine1 -O1 12.0 12.0 12.0 13.0 8.03 8.09 Combine2 10.09 12.08 **CS33 Intro to Computer Systems** XII-35 Copyright © 2012 Thomas W. Doeppner. All rights reserved.

#### **Eliminate Procedure Calls**

```
void combine3(vec_ptr v, data_t *dest) {
    long int i;
    long int length = vec_length(v);
    data_t *data = get_vec_start(v);
    *dest = IDENT;
    for (i = 0; i < length; i++) {
        *dest = *dest OP data[i];
    }
}</pre>
```

Method	Integer		Double FP	
Operation	Add	Mult	Add	Mult
Combine2	8.03	8.09	10.09	12.08
Combine3	6.01	8.01	10.01	12.02

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