

RASPBERRY PI WORKSHOP

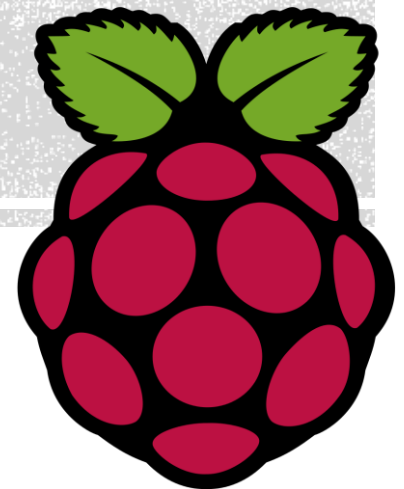
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SparkLab Innovation Center



DAY 1 – INTRODUCTION TO RPI AND BASIC APPLICATION

- What is Raspberry Pi?
- Parts of the Raspberry Pi System
- Set-up Configuration
- Interfacing Basics
- Linux File System
- Python Programming
- Control Structures
- GPIO and other basic applications

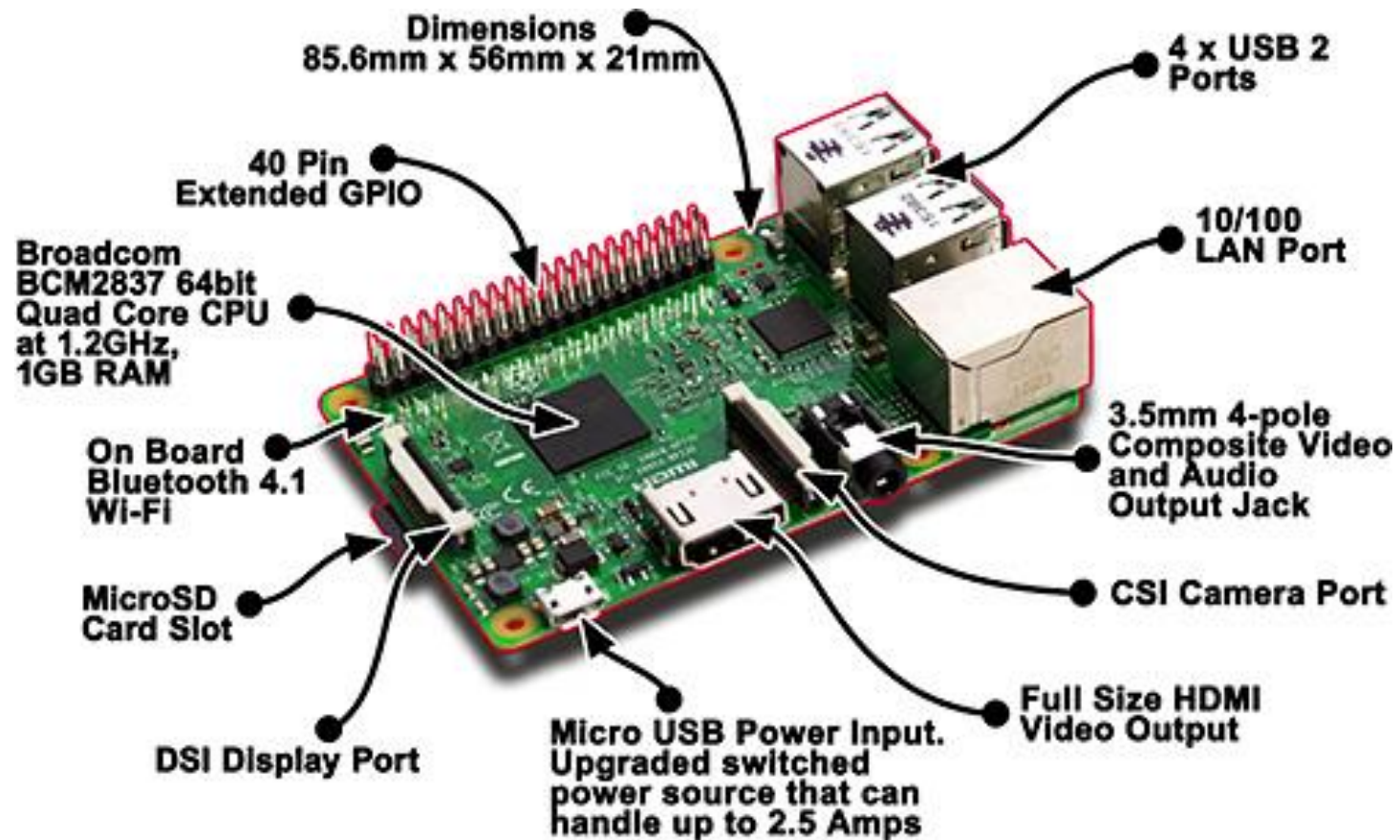


DAY 2 – INTERFACING WITH THE RASPBERRY PI, IOT AND OTHER ADVANCED APPLICATIONS

- Interfacing with Arduino (LM35)
- Internet of Things



WHAT IS RASPBERRY PI?



RAPBERRY PI 2 AND 3

Raspberry
Pi 3



Raspberry
Pi 2



RASPBERRY PI SPECIFICATIONS

Raspberry Pi 2 Model B		Raspberry Pi 3 Model B
Chip	Broadcom BCM2835 (SoC)	Broadcom BCM2837 (SoC)
CPU	32-bit Quad-core Cortex-A7, 900 MHz	64-bit Quad-core ARM Cortex-A53, 1.2 GHz
GPU	Broadcom VideoCore IV, 250 MHz	Broadcom VideoCore IV, 400 Mhz
Memory	1GB DDR2, 450 MHz	1GB DDR2, 900 MHz
USB 2.0	4 ports	4 ports
Connectivity	10/100 Ethernet jack	10/100 Ethernet jack 802.11n Wireless LAN Bluetooth 4.1 Bluetooth Low Energy (BLE)
Video Output	HDMI, Composite Video (3.5mm jack)	HDMI, Composite Video (3.5mm jack)
Audio Output	3.5mm jack, HDMI	3.5mm jack, HDMI
Onboard Storage	microSD Slot (32GB max)	microSD Slot (64 GB)
Dimension	8.6cm x 5.4cm x 1.5cm	8.6cm x 5.4cm x 1.5cm



RASPBERRY PI OPERATING SYSTEMS



NOOBS



RASPBIAN



UBUNTU MATE



SNAPPY UBUNTU CORE



WINDOWS 10 IOT CORE



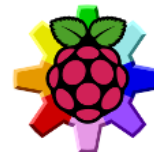
OSMC



LIBREELEC



PINET



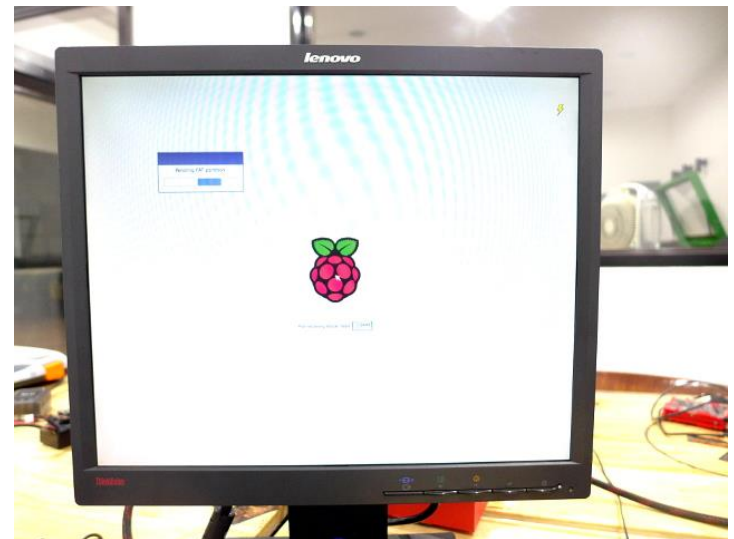
RISC OS



WEATHER STATION



DIRECT SETUP



Monitor

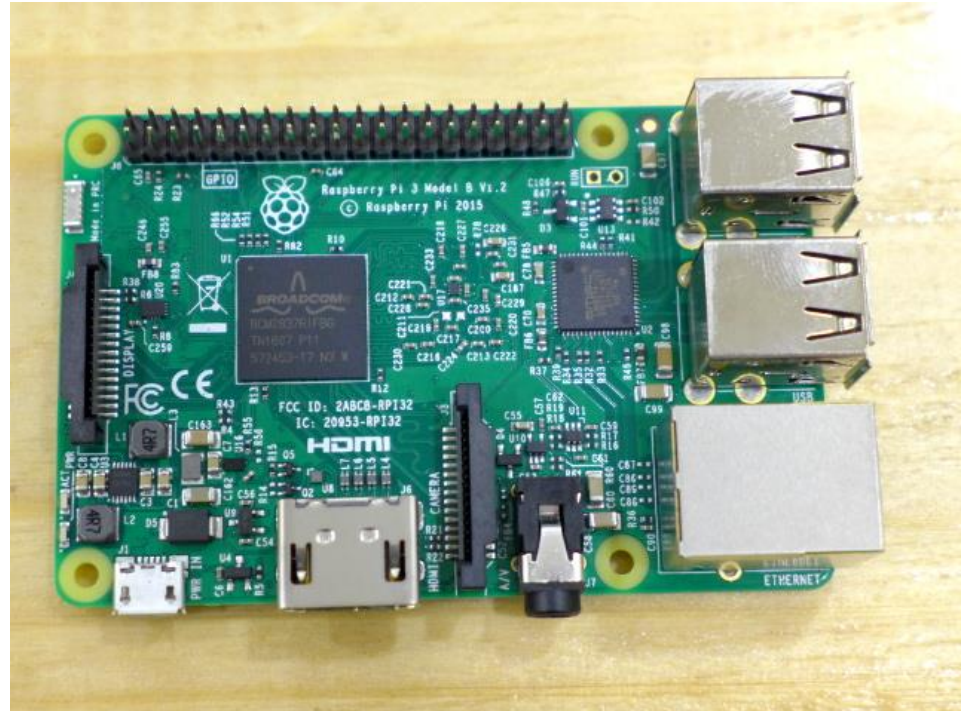


HEADLESS SETUP

Power Adaptor



SD Card



LAN Cable (Optional)



GETTING STARTED (RASPBIAN)

1. Download Raspbian and Extract Zip Files

<http://www.raspberrypi.org/downloads/>

Raspbian Jessie with Pixel (1.42 GB)

Raspbian Lite (292 MB)

2. Install win32DiskImager

<https://sourceforge.net/projects/win32diskimager/>

3. Run as Administrator win32DiskImager

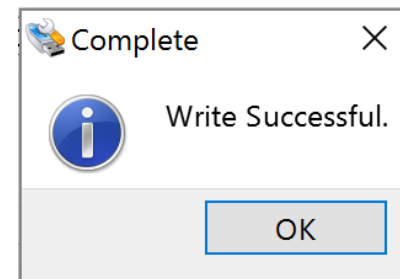
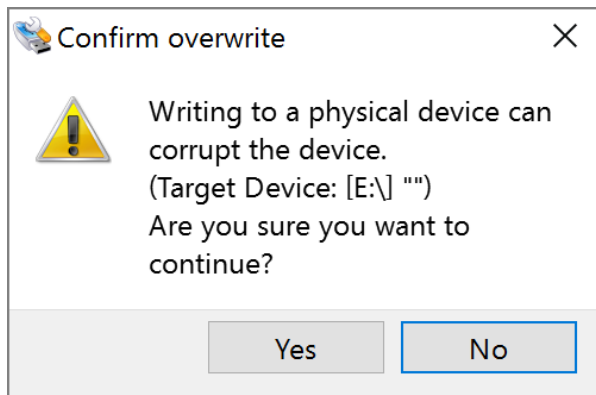
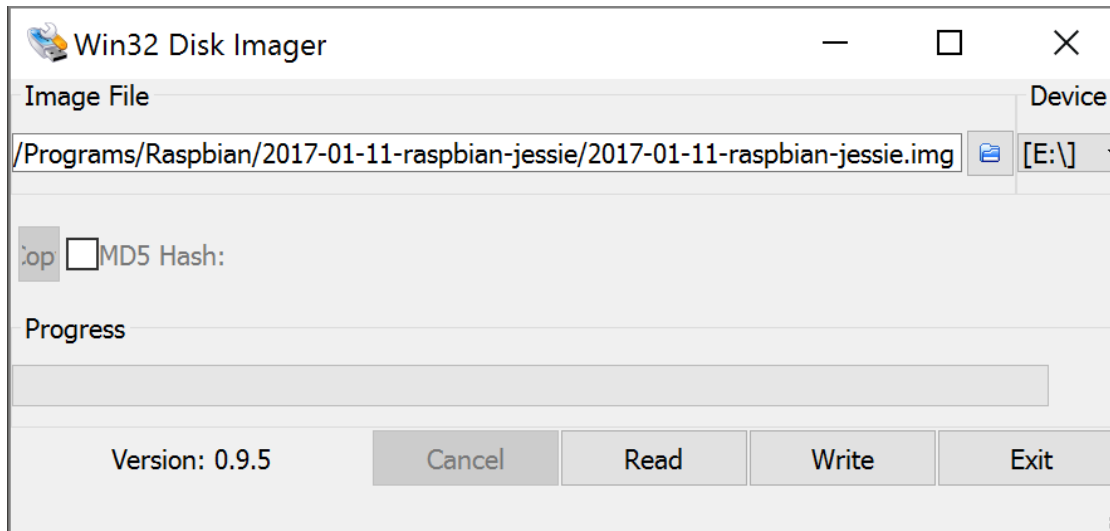
4. Select the drive of the SD Card

5. Select the image (img) on the Extracted Files

6. Click Write

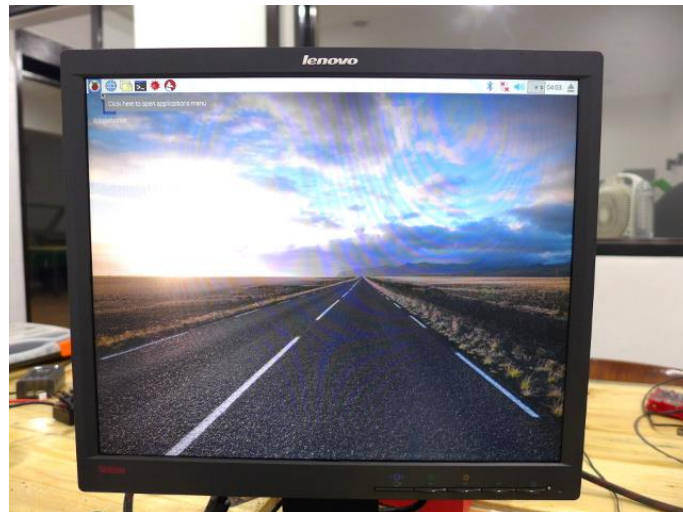


GETTING STARTED (RASPBIAN)



GETTING STARTED (RASPBIAN)

7. Wait...
8. Insert SD Card on Raspberry Pi (RPi)
9. Connect the RPi to the Monitor, Keyboard & Mouse.
10. Power the RPi by plugging the mini-USB to a power source (i.e. Charger, Power Bank, USB Port)
11. Wait...
12. Finished!!!



WHAT CAN THE RASPBERRY PI DO?

- Office (Documents, Spreadsheets, Presentation)
- Play videos and music
- Internet Browsing
- Programming (Python, Java, C, C++, etc.)
- Database server
- Physical Computing (GPIO)



GOAL

Control the Raspberry Pi 3 remotely.

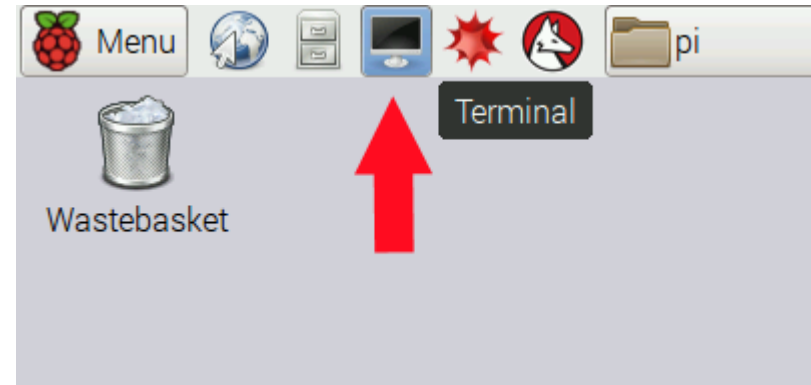
Remotely – using other computers.

Get used to the Terminal.



CHANGING THE KEYBOARD SETUP

- Open Terminal
- Command: `sudo raspi-config`
- Select '5 Internationalisation Options'
- Select 'Generic 105-key (Intl) PC'
- Select 'Other'
- Select 'English (US)'
- Select 'English (US)'
- Select 'The default keyboard layout'
- Select 'No compose key'
- Select 'No' – *Option for Ctrl+Alt+Backspace to do something*
- Select 'Finish'



CHANGING THE PASSWORD ON RPI

Default

User: pi
Password: raspberry

1. Open Terminal
2. Command: `passwd`



CONNECTING TO WIFI (HEADLESS WAY)

1. Open Terminal
2. Command: `sudo iwlist wlan0 scan`
Scans the area for Wireless Network (WiFi)
Remember desired ESSID
3. Command: `sudo nano /etc/wpa_supplicant/wpa_supplicant.conf`
4. Add to the end of the file

```
network={
    ssid="ESSIDName"
    psk="Password"
}
```
5. Command: `sudo ifdown wlan0 && sudo ifup wlan0`



SHUTDOWN & REBOOT

SHUTDOWN

`sudo halt`

REBOOT

`sudo reboot`



GETTING THE IP ADDRESS OF RPI

- Command: `ifconfig`

```
pi@raspberrypi:~ $ ifconfig
eth0      Link encap:Ethernet  HWaddr b8:27:eb:09:ca:66
          inet6 addr: fe80::8e5:9b21:5dbe:e28/64 Scope:Link
          UP BROADCAST MULTICAST  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:526 errors:0 dropped:0 overruns:0 frame:0
          TX packets:526 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1
          RX bytes:43152 (42.1 KiB)  TX bytes:43152 (42.1 KiB)

wlan0     Link encap:Ethernet  HWaddr b8:27:eb:5c:9f:33
          inet addr:192.168.254.30  Bcast:192.168.254.255  Mask:255.255.255.0
          inet6 addr: fe80::2c6b:8ce0:baf9:aa8b/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:22792 errors:0 dropped:3143 overruns:0 frame:0
          TX packets:13027 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:22963435 (21.8 MiB)  TX bytes:1828425 (1.7 MiB)

pi@raspberrypi:~ $
```



REMOTE CONNECTION (SSH)

- Git-Bash
 1. Extract Portable Git
 2. Open PortableGit folder
 3. Run **git-bash.exe**
- Enable SSH on Raspberry Pi Configuration
- SSH (Secure Shell)
 - Command: `ssh pi@[ip address of RPi]`

`ssh pi@192.168.43.12`



REMOTE CONNECTION (SFTP)

- SFTP (SSH File Transfer Protocol)
 - Extension of the SSH to handle file transfers
- Programs: FileZilla, WinSCP
- FileZilla
 1. Extract FileZilla Zip (Portable Application)
 2. Run **filezilla.exe**

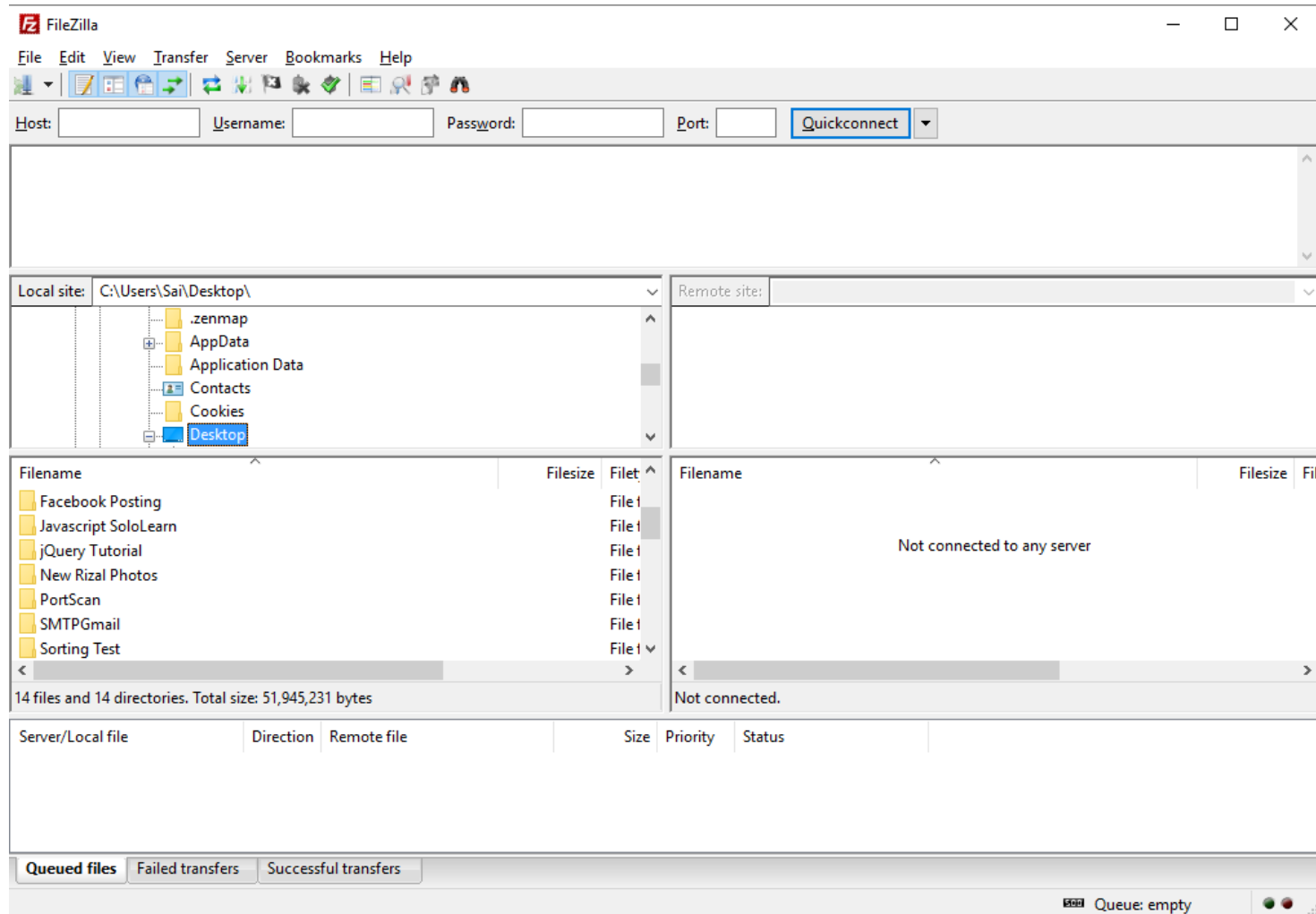


REMOTE CONNECTION (SFTP) - FILEZILLA

1. File → Site Manager
2. New Site
3. General Tab
 - Host: IP Address of Raspberry Pi
 - Protocol: SFTP – SSH File Transfer Protocol
 - Logon Type: Ask for password
 - User: pi
4. Connect
 - Will ask for the password of your RPi



REMOTE CONNECTION (SFTP) - FILEZILLA



REMOTE CONNECTION (SFTP) - EXERCISE

Copy the following files
to the Desktop folder
of your Raspberry Pi

- example1080.mp4
- example2k.mp4



PLAYING VIDEO VIA SSH

- SSH to your Raspberry Pi

- Command
 1. `cd`
 2. `cd Desktop`
 3. `omxplayer example1080.mp4`



LINUX COMMANDS

- `ls` – list directory items
- `cd` – change directory
 - `cd` - goes to Home Directory
 - `cd ..` - goes back to the parent directory
 - `cd /[Name of Directory]` - goes to the desired directory
 - `cd /` - goes to the root directory
- `ifconfig` – gets the IP Config
- `sudo` – SuperUser Do
- `wget` – downloads a file



LINUX COMMANDS

- touch – creates a file
- cp – copy files/directory
- rm – remove/delete files/directory
- mkdir – make directory
- rmdir – remove directory

- nano – opens the nano text-editor



NEVER RUN THIS COMMAND

`rm -rf /`

GET HELP

`[command] --help`
`man [command]`

Help for Command
Command Manual



LINUX COMMAND EXERCISE

1. Change directory to Desktop
2. Create a directory named 'Exercise1'
3. Change directory to 'Exercise1'
4. Create a file 'exercise1.txt'
5. Edit the contents of the file. Save and Exit.
6. Copy 'exercise1.txt' on the same folder with the name 'exercise2.txt'



UPDATING RASPBIAN (LINUX)

`sudo apt-get update`

`sudo apt-get upgrade`

`sudo apt-get dist-upgrade`



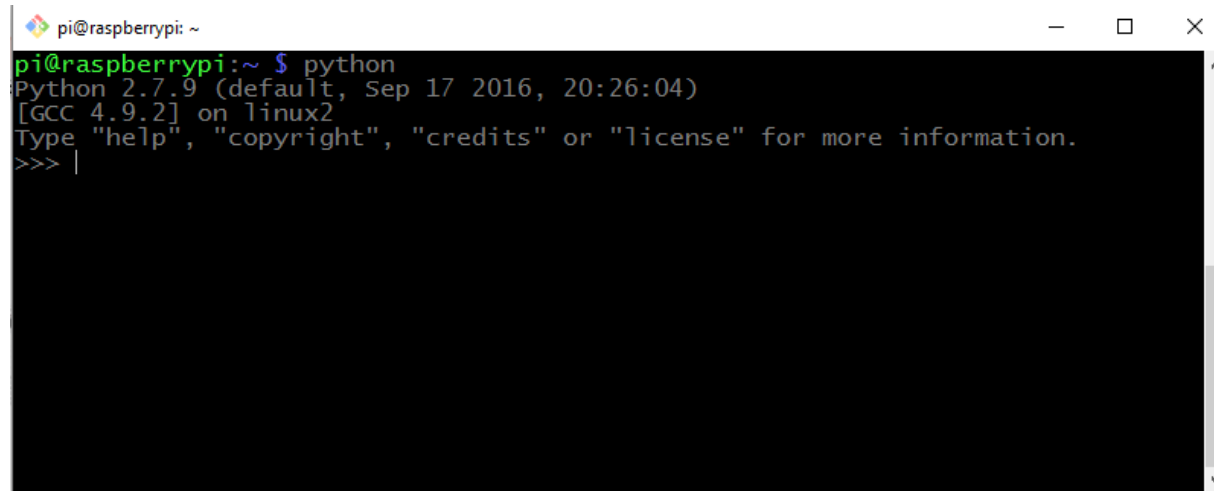
PYTHON (PROGRAMMING)

- High Level Programming Language
- Emphasis on Code Readability
- Fewer lines of code, faster development



PYTHON PROGRAMMING

- Command: `python`

A terminal window titled 'pi@raspberrypi: ~' with standard window controls. The terminal shows the command 'python' being executed, followed by the output: 'Python 2.7.9 (default, Sep 17 2016, 20:26:04) [GCC 4.9.2] on linux2'. It then displays the help text: 'Type "help", "copyright", "credits" or "license" for more information.' and the prompt '>>> |' on a new line.

```
pi@raspberrypi: ~  
pi@raspberrypi:~$ python  
Python 2.7.9 (default, Sep 17 2016, 20:26:04)  
[GCC 4.9.2] on linux2  
Type "help", "copyright", "credits" or "license" for more information.  
>>> |
```

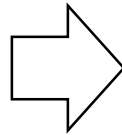
- `>>> print "Hello World!"`
- Exit command: `quit()`



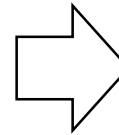
INTERPRET A SCRIPT



hello world.py



python



Hello World!

1. Create a new file “hello world.py”
2. Edit the file using nano, enter **print “Hello World!”**
3. Save and exit
4. Run the script by typing **python “hello world.py”**



PYTHON RESERVED WORDS

and	del	from	not	while
as	elif	global	or	with
assert	else	if	pass	yield
break	except	import	print	
class	exec	in	raise	
continue	finally	is	return	
def	for	lambda	try	



CODING STRUCTURE

- Indentation – focus on readability

```
w=5
for i in range w:
    print(w)
    print("Hello World!")
```

```
if w <= 5:
    print(w-1)
```



PYTHON VARIABLE TYPES

- Numbers (integer, float)
 - `iNumber = 3`
 - `fNumber = 3.0`
- Strings
 - `sName = "Mark John Luke Matthew"`
 - `len(sName)`
- List
 - `itemList = ["Kangkong", "Kalabasa", "Talong", "Sitaw", 1000]`
 - `itemList[0]`
 - `len(itemList)`
- Tuple
 - `itemTuple = ("Kangkong", "Kalabasa", "Talong", "Sitaw", 2000)`
 - `itemTuple[0]`
 - `len(itemTuple)`
- Dictionary
 - `itemDict = {'Kangkong':9, 'Kalabasa':6, 'Talong':7, 'Seven':4}`
 - `itemDict['Kangkong']`
 - `len(itemDict)`



LISTS

	Returns	Description
list[i] list[-i]	object on i	
list[1:2] list[3:]	objects on the specified range	
del list[i] del list[i:j]		removes the object in I
len(list)	number of objects in list	
list.append(obj)		adds the object on the end of the list
list.pop()	removed item	removes the last item
list.pop(i)	removed item	removes the item on i



DICTIONARY

	Description
<code>dic = {}</code>	Creates an empty Dictionary
<code>dic = {'item1': 2, 'item2': 'hello'}</code>	Creates a Dictionary with entries
<code>dic['keyword'] = obj</code>	Creates and entry to Dictionary Updates entry in Dictionary
<code>obj = dic['keyword']</code>	Assigns obj with the object with keyword in Dictionary



PYTHON CONTROL STATEMENTS (IF)

```
if expression1:  
    statement(s)  
elif expression2:  
    statement(s)  
elif expression3:  
    statement(s)  
else:  
    statement(s)
```



PYTHON CONTROL STATEMENTS (IF)

```
var1 = 100
var2 = 0
if var1 == 200:
    print("I'm at 1")
    print(var1)
elif var1 == 150:
    print("I'm at 2")
    print(var1)
elif var1 == 100 and var2 == 1:
    print("I'm at 3")
    print(var1)
else:
    print("I'm at 4")
    print(var1)
```



LOOPING (WHILE LOOP)

```
while expression:  
    statement(s)
```

```
i = 0
```

```
while i < 10:  
    i = i + 1  
    print(i)
```



LOOPING (FOR LOOP)

```
for i in range(10):  
    print('Number: ', i)
```

```
for i in range(5, 10):  
    print('Num: ', i)
```

```
for letter in 'Raspberry Pi':  
    print('Current Letter :', letter)
```

```
words = ['Mosaic', 'Ecological', 'Cosmonaut']  
for word in words:  
    print('Current word :', word)
```



FUNCTIONS (STRUCTURE)

```
def functionname( parameters ):
    statement(s)
    return [expression]
```



FUNCTIONS (EXAMPLE)

```
def add(a, b):  
    total = a+b  
    return total
```

```
def multiply(a, b):  
    product = a*b  
    return product
```

```
a = 2  
b = 3  
print(add(a,b))  
print(multiply(a,b))
```



FUNCTIONS (MULTIPLE RETURN)

```
def addmultiply(a, b):  
    total = a+b  
    product = a*b  
    return total, product
```

```
a = 2  
b = 3  
total, product = addmultiply(a, b)
```

```
print("total: ", total)  
print("product: ", product)
```



GPIO (GENERAL PURPOSE INPUT/OUTPUT)

Raspberry Pi GPIO Header

Pin#	NAME		NAME	Pin#
01	3.3v DC Power	■	DC Power 5v	02
03	GPIO02 (SDA1 , I ² C)	●	DC Power 5v	04
05	GPIO03 (SCL1 , I ² C)	●	Ground	06
07	GPIO04 (GPIO_GCLK)	●	(TXD0) GPIO14	08
09	Ground	●	(RXD0) GPIO15	10
11	GPIO17 (GPIO_GEN0)	●	(GPIO_GEN1) GPIO18	12
13	GPIO27 (GPIO_GEN2)	●	Ground	14
15	GPIO22 (GPIO_GEN3)	●	(GPIO_GEN4) GPIO23	16
17	3.3v DC Power	●	(GPIO_GEN5) GPIO24	18
19	GPIO10 (SPI_MOSI)	●	Ground	20
21	GPIO09 (SPI_MISO)	●	(GPIO_GEN6) GPIO25	22
23	GPIO11 (SPI_CLK)	●	(SPI_CE0_N) GPIO08	24
25	Ground	●	(SPI_CE1_N) GPIO07	26
27	ID_SD (I ² C ID EEPROM)	●	(I ² C ID EEPROM) ID_SC	28
29	GPIO05	●	Ground	30
31	GPIO06	●	GPIO12	32
33	GPIO13	●	Ground	34
35	GPIO19	●	GPIO16	36
37	GPIO26	●	GPIO20	38
39	Ground	●	GPIO21	40

Input

Output

Alternate Functions

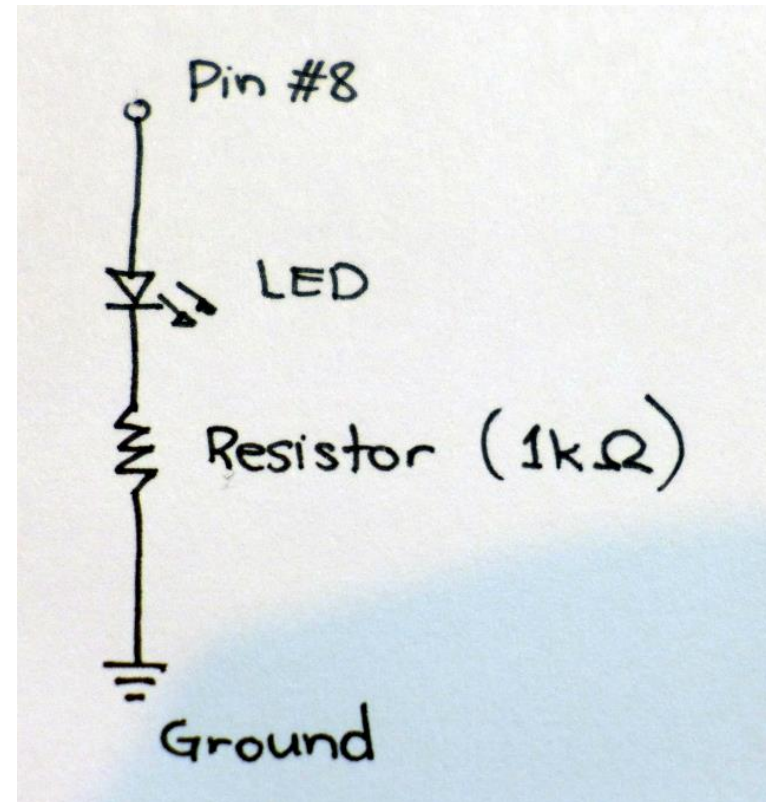
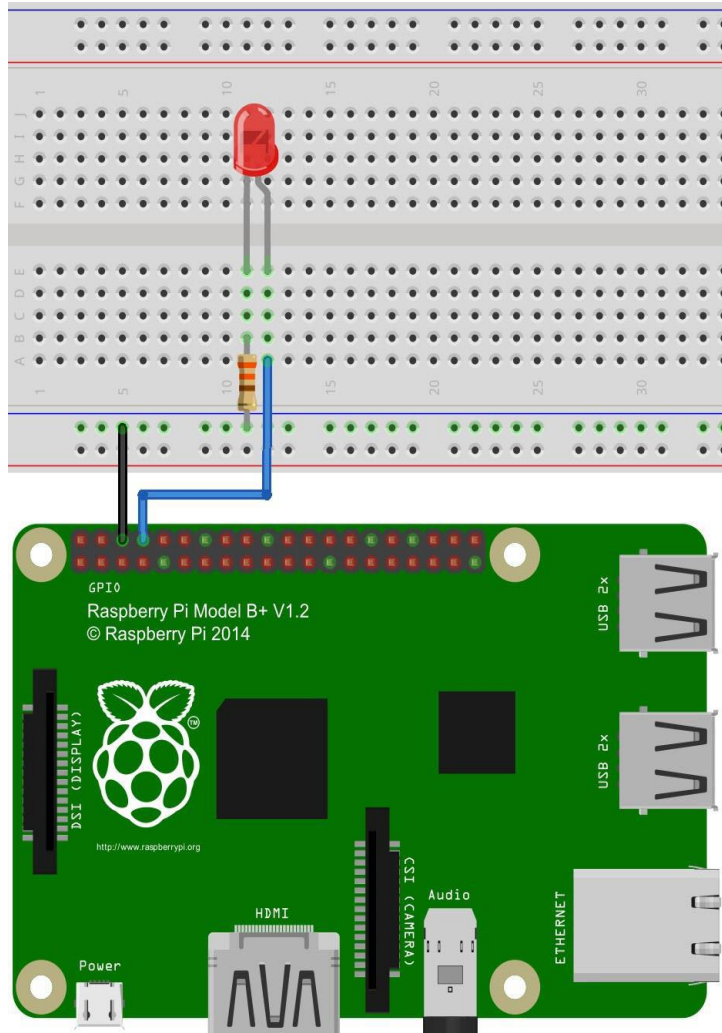


GPIO WARNING

- Do not short the GPIO pins to ground or 3.3V/5V.
- Logic high is 3.3V. Do not connect it with a 5V logic high system.
- Raspberry Pi does not have a protective circuit in its GPIO.



OUTPUT EXERCISE — LED BLINKER

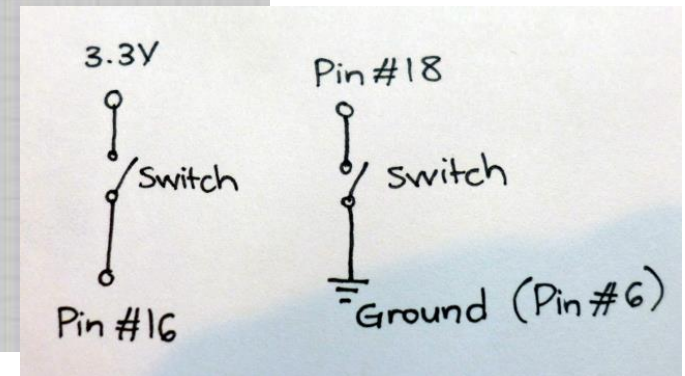
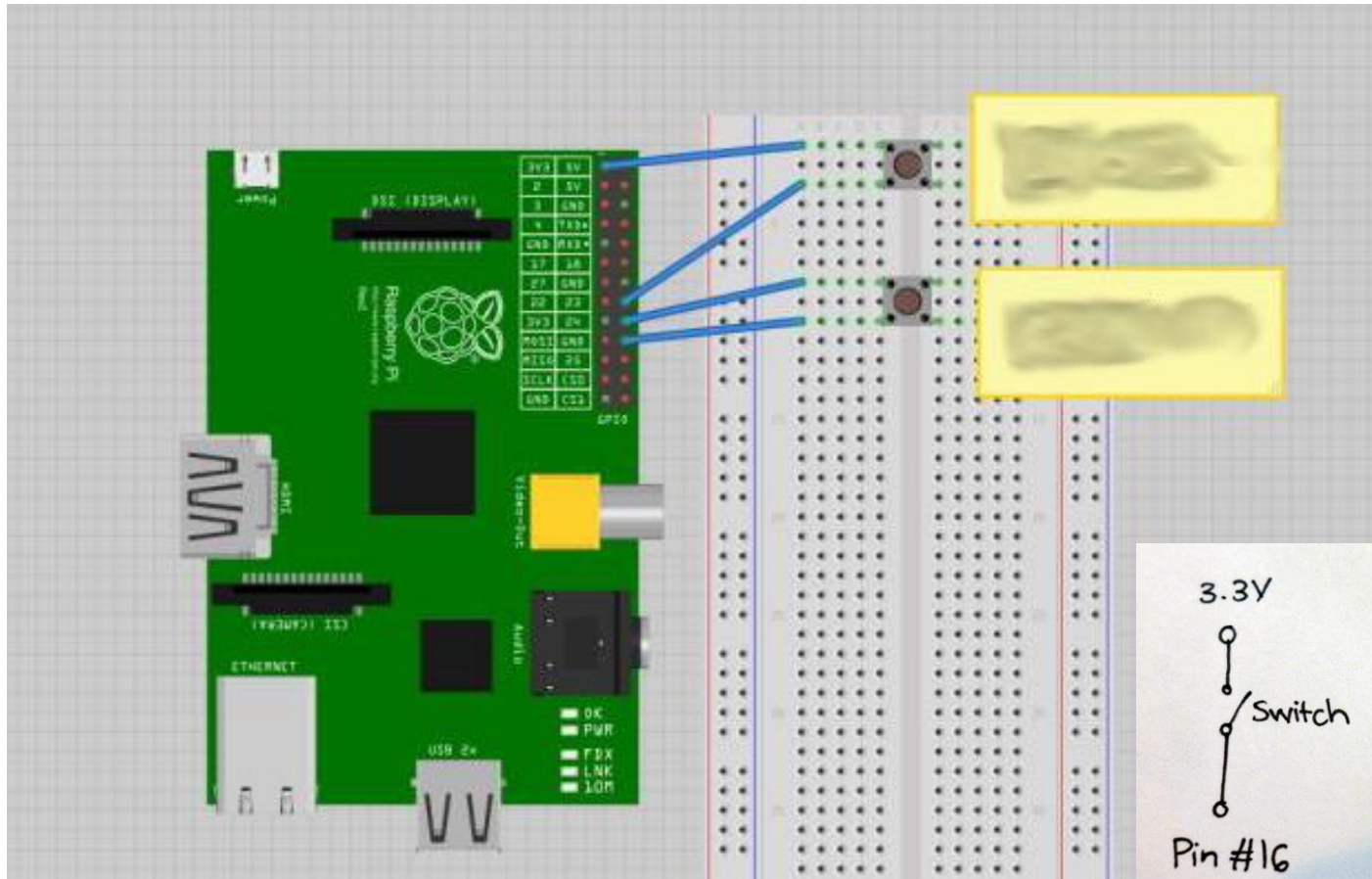


OUTPUT EXERCISE — LED BLINKER

```
1 import RPi.GPIO as GPIO
2 import time
3
4 GPIO.setmode(GPIO.BOARD)
5 GPIO.setup(8, GPIO.OUT)
6
7 try:
8     while True:
9         GPIO.output(8, True)
10        time.sleep(0.5)
11        GPIO.output(8, False)
12        time.sleep(0.5)
13
14 except KeyboardInterrupt:
15     GPIO.cleanup()
```



INPUT EXERCISE - BUTTONS



INPUT EXERCISE 1 - BUTTONS

```
1 import RPi.GPIO as GPIO
2
3 GPIO.setmode(GPIO.BCM)
4
5 GPIO.setup(23, GPIO.IN, pull_up_down = GPIO.PUD_DOWN)
6 GPIO.setup(24, GPIO.IN, pull_up_down = GPIO.PUD_UP)
7
8 try:
9
10     while True:
11         if(GPIO.input(23) == 1):
12             print("Button 1 pressed")
13
14         if(GPIO.input(24) == 0):
15             print("Button 2 pressed")
16
17 except KeyboardInterrupt:
18     GPIO.cleanup()
```



INPUT EXERCISE 2 - BUTTONS

```
1 import RPi.GPIO as GPIO
2
3 GPIO.setmode(GPIO.BCM)
4
5 GPIO.setup(23, GPIO.IN, pull_up_down = GPIO.PUD_DOWN)
6 GPIO.setup(24, GPIO.IN, pull_up_down = GPIO.PUD_UP)
7
8 try:
9
10     while True:
11         GPIO.wait_for_edge(23, GPIO.RISING)
12         print("Button 1 Pressed")
13
14         GPIO.wait_for_edge(23, GPIO.FALLING)
15         print("Button 1 Released")
16
17         GPIO.wait_for_edge(24, GPIO.FALLING)
18         print("Button 2 Pressed")
19
20         GPIO.wait_for_edge(24, GPIO.RISING)
21         print("Button 2 Released")
22
23 except KeyboardInterrupt:
24     GPIO.cleanup()
```



NEXT WEEK

- Interfacing via Serial UART
- Interfacing via Internet of Things (IoT)

