

All Sources Shortest Path: The Floyd-Warshall Algorithm

All Sources Shortest Path Problem

Shortest path network.

- Directed graph $G = (V, E, w)$.
- Weight w_e = weight of edge e .

Shortest path problem: for all pairs of vertices (u,v) , find shortest directed path from u to v .

Option #1: **if all edge weights are non-negative**, just run Dijkstra n times ($n = |V|$)

- Each iteration of Dijkstra takes $O(n^2)$ for array-based or $O(m \log n)$ for heap-based
- Total complexity is either $O(n^3)$ or $O(mn \log n)$
- This is a case where just repeatedly using a solution to a simpler problem works out fine.

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Option #2: **if some edge weights are negative**

- Use Bellman-Ford single source shortest path algorithm
 - However, it has complexity $O(nm)$ for a single source.
 - So all sources solution is $O(n^2m)$, which is $O(n^4)$ for dense graphs

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Option #3: **if some edge weights are negative**

- Floyd-Warshall algorithm
 - Dynamic programming solution to compute all sources shortest paths
 - Works with negative weights (or without) - we assume no negative cycles, however
 - Complexity $O(n^3)$



Floyd-Warshall Algorithm

Floyd-Warshall algorithm.

- Build a 3-dimensional dynamic programming array (hence the $O(n^3)$ complexity) that keeps track of the shortest path between any two vertices, using only some subset of the entire collection of vertices as intermediate steps along the path.
- $S[i][j][k] :=$ shortest path from vertex i to vertex j , using only vertices $1, 2, \dots, k$ as intermediate vertices along the path
- Solution: for each i, j : $S[i][j][n]$ gives the shortest path from i to j allowing all vertices at intermediate steps

Floyd-Warshall Algorithm

Floyd-Warshall algorithm.

- Number the vertices $1, 2, \dots, n$
- Consider subset $1, 2, \dots, k$
- For any $i, j \in V$, consider all paths from i to j whose intermediate vertices are restricted to $1, 2, \dots, k$
 - Let p be a shortest path among these.
 - p is a simple path (it has no cycles)
 -  All cycles are assumed non-negative weight,
 - There can't be a positive weight cycle in a shortest path (we could just remove it and have a better path)
 - Any zero-weight cycle can be removed without affecting the shortest path
 -  This means each vertex appears at most once along path p

Floyd-Warshall Algorithm

Floyd-Warshall algorithm.

- Recurrence relation: consider if vertex k is part of path p
 - If not, then all intermediate vertices are in $1, \dots, k-1$, so the best solution for shortest path from i to j using $1, 2, \dots, k$ will be the same as using $1, 2, \dots, k-1$
 - If yes, p can be split into two subpaths - p_1 , the path from i to k , and p_2 , the path from k to j
 - ✎ p_1 and p_2 are themselves shortest paths
 - Why? If not, we could form a better path from i to k than the path p by using the better subpaths
- Optimal subproblems:
 - ✎ p_1 is a shortest path from i to k using $1, 2, \dots, k-1$ (because no vertex is used twice in the simple path)
 - ✎ p_2 is a shortest path from k to j using $1, 2, \dots, k-1$

Floyd-Warshall Algorithm

Floyd-Warshall algorithm.

- Recurrence relation
- $S[i][j][k] = \min(S[i][j][k-1], S[i][k][k-1] + S[k][j][k-1])$ for $k > 0$
- $S[i][j][0] = w_{ij}$ if there is an edge e directed from i to j
0 if $i=j$
 ∞ otherwise
- We can build up from the bottom, considering more and more vertices along the intermediate path

Floyd-Warshall Algorithm

Floyd-Warshall algorithm.

- Complexity: $O(n^3)$, small constant factor makes practical use possible even for moderate size of n
- Initialization weights $w(i,j)$ are 0 if $i=j$ and ∞ if no edge exists

Floyd-Warshall ($G=(V,E,w)$)

```
1. For i=1 to |V| do
2.   For j=1 to |V| do
3.     S[i,j,0] = w(i,j)
4. For k=1 to |V| do
5.   For i=1 to |V| do
6.     For j=1 to |V| do
7.       S[i,j,k] = min {
8.         S[i,j,k-1],
9.         S[i,k,k-1]+S[k,j,k-1] }
10.Return S[:, :, n]  # return 2d array with n = |V|
```