

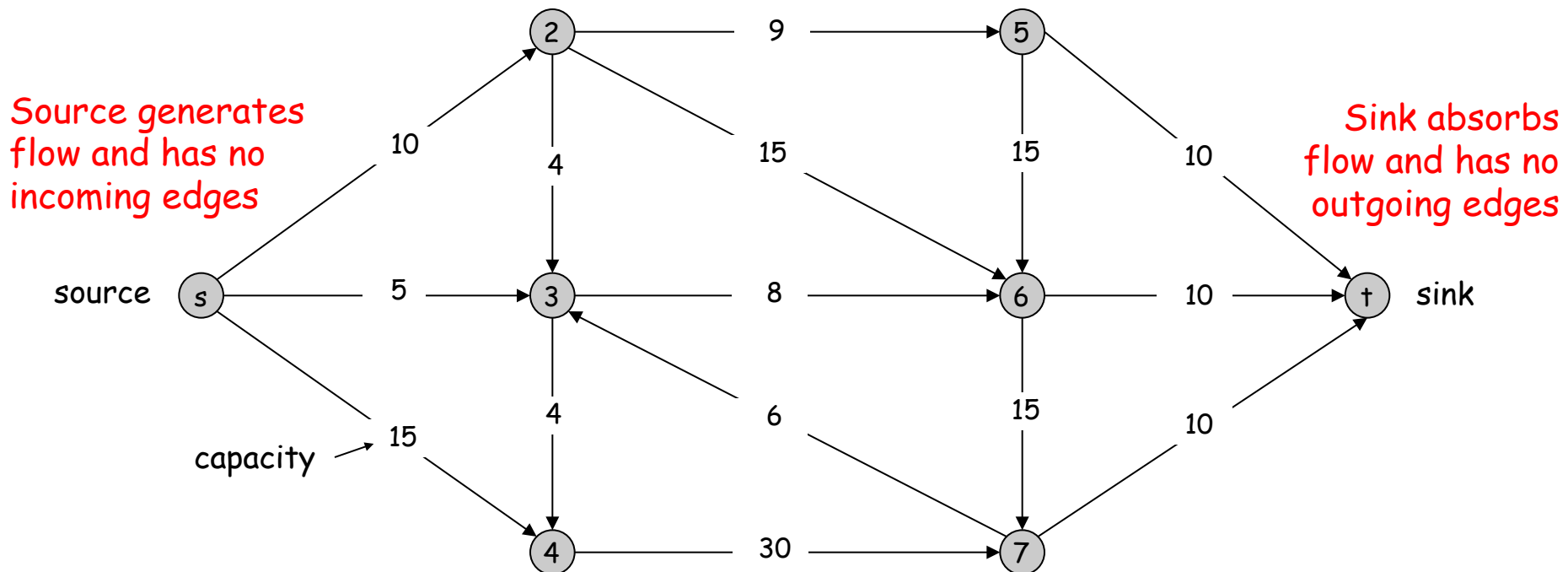
# Network Flow

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# Network Flow

## Flow network.

- Abstraction for material **flowing** through the edges.
  - E.g. traffic on highway, pipes carrying liquid, computer networks
- $G = (V, E)$  = directed graph.
- Two distinguished nodes:  $s$  = source,  $t$  = sink.
- $c(e)$  = capacity of edge  $e$ .  $c(e) \geq 0$ .

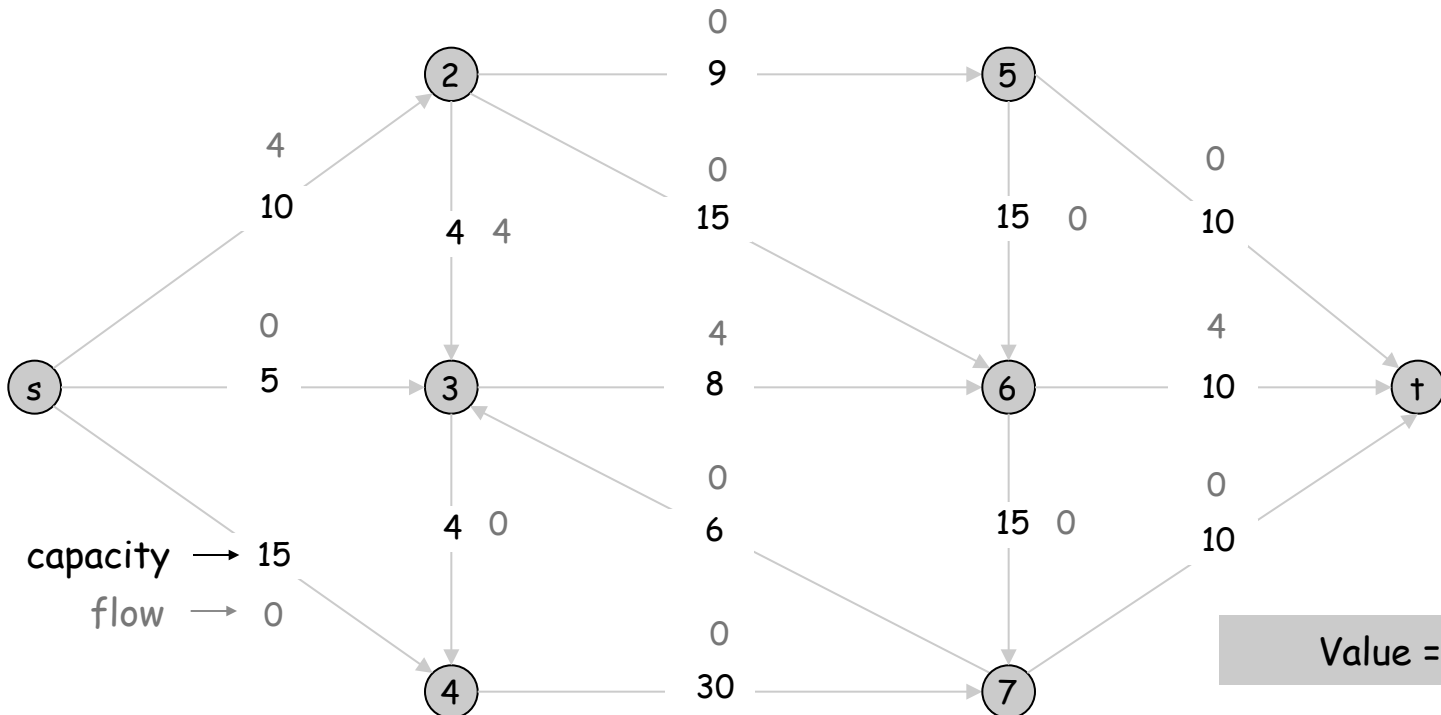


# Flows

Def. An **s-t flow** is a function that satisfies:

- For each  $e \in E$ :  $0 \leq f(e) \leq c(e)$  (capacity)
- For each  $v \in V - \{s, t\}$ :  $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$  (conservation)

Def. The **value** of a flow  $f$  is:  $v(f) = \sum_{e \text{ out of } s} f(e)$ .

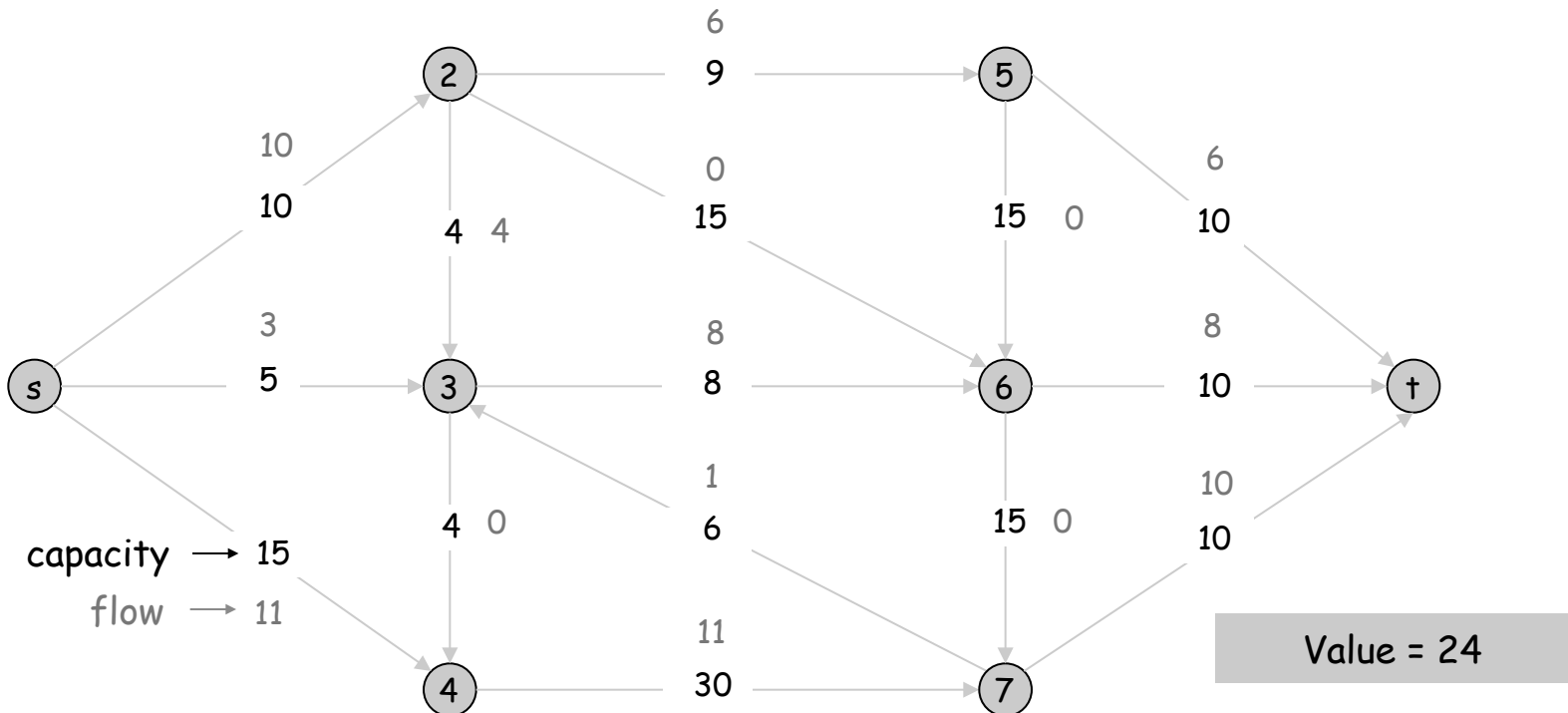


# Flows

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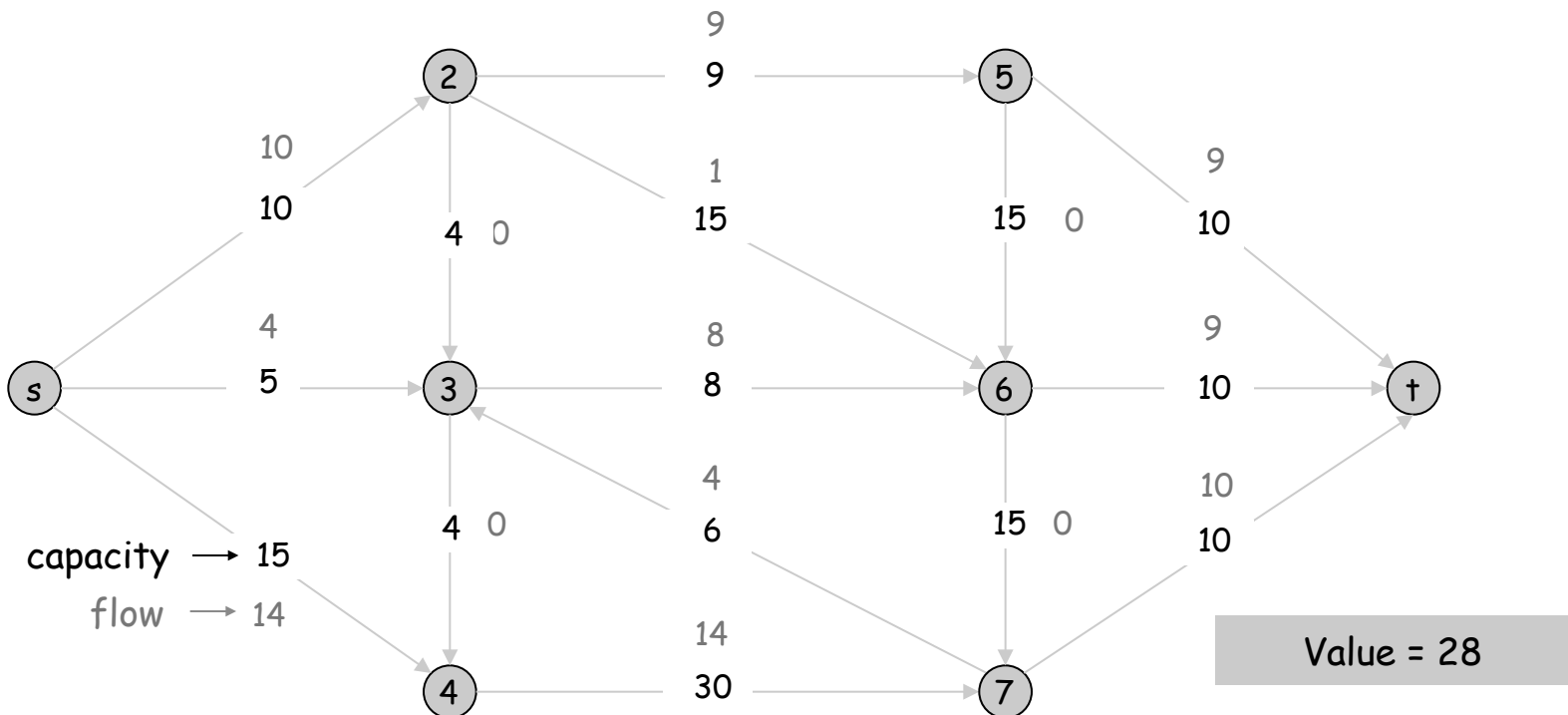
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# Maximum Flow Problem

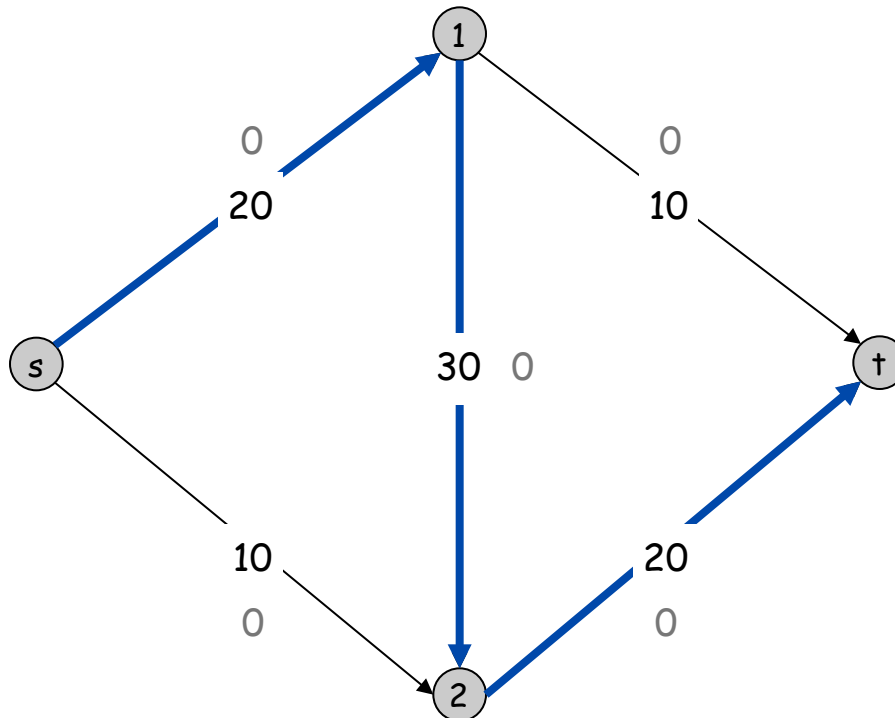
Max flow problem. Find s-t flow of maximum value.



# Towards a Max Flow Algorithm

## Greedy algorithm.

- Start with  $f(e) = 0$  for all edge  $e \in E$ .
- Find an s-t path  $P$  where each edge has  $f(e) < c(e)$ .
- Augment flow along path  $P$ .
- Repeat until you get stuck.

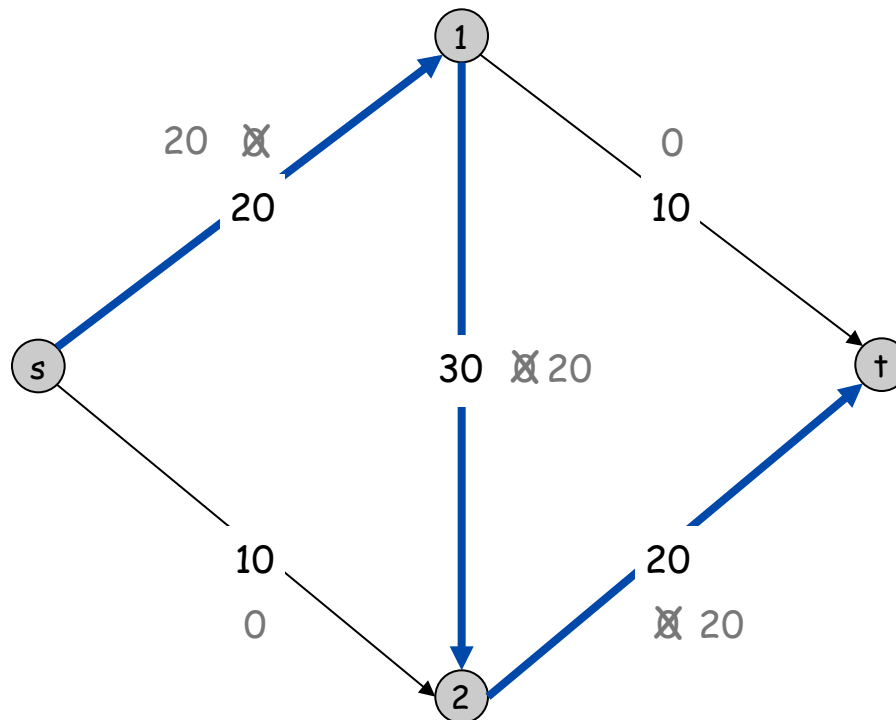


Flow value = 0

# Towards a Max Flow Algorithm

## Greedy algorithm.

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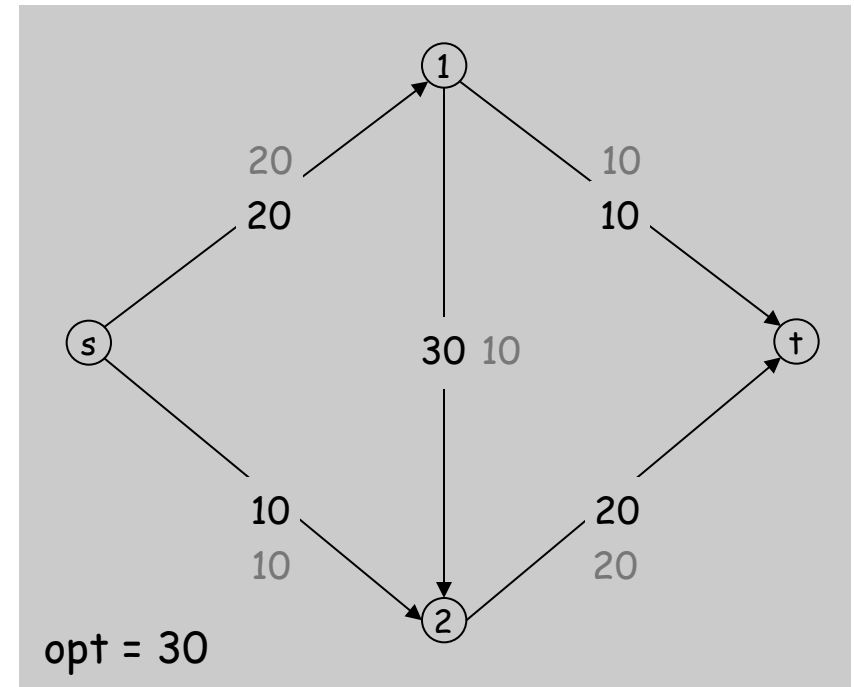
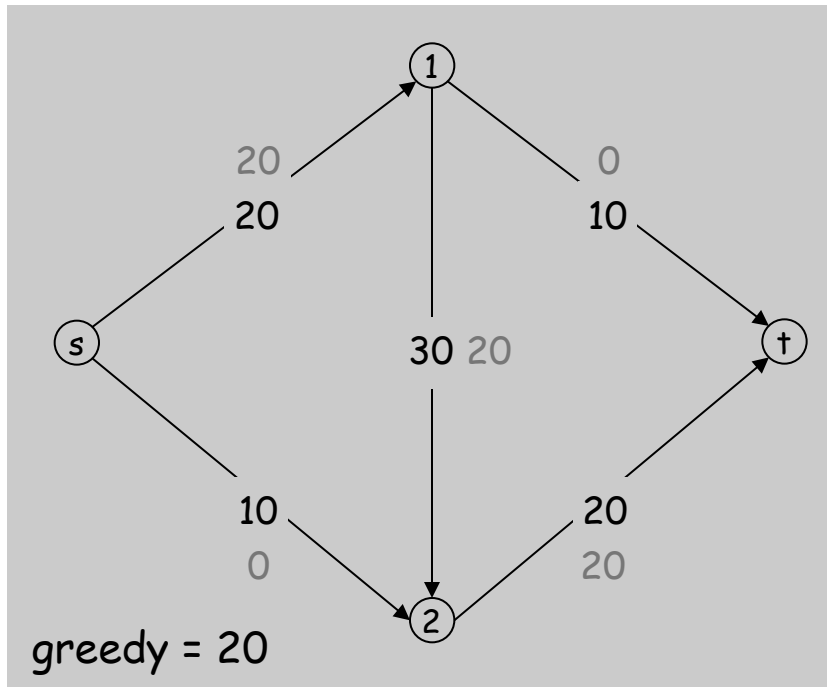


Flow value = 20

# Towards a Max Flow Algorithm

## Greedy algorithm.

- Start with  $f(e) = 0$  for all edge  $e \in E$ .
  - Find an s-t path  $P$  where each edge has  $f(e) < c(e)$ .
  - Augment flow along path  $P$ .
  - Repeat until you get **stuck**.
- ↖ locally optimality  $\nRightarrow$  global optimality

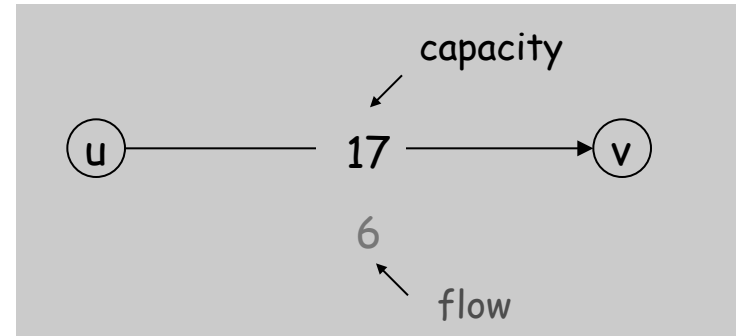




# Residual Graph

Original edge:  $e = (u, v) \in E$ .

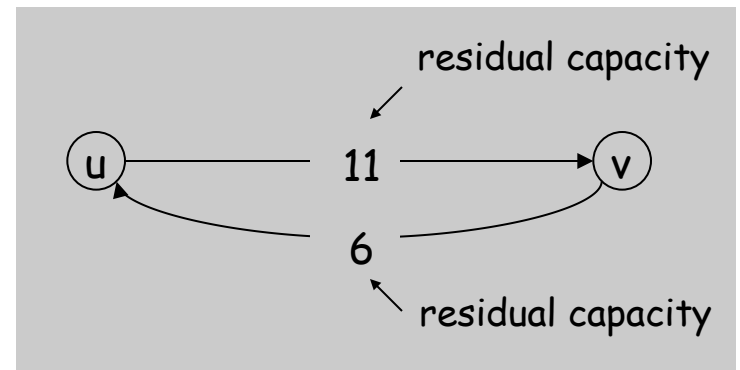
- Flow  $f(e)$ , capacity  $c(e)$ .



Residual edge.

- "Undo" flow sent.
- $e = (u, v)$  and  $e^R = (v, u)$ .
- Residual capacity:

$$c_f(e) = \begin{cases} c(e) - f(e) & \text{if } e \in E \\ f(e) & \text{if } e^R \in E \end{cases}$$



Residual graph:  $G_f = (V, E_f)$ .

- Residual edges with positive residual capacity.
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}$ .

# Ford-Fulkerson Algorithm

## Basic Algorithm:

- Identify an s-t path and augment the flow along that path
  - How to find a path? BFS or DFS
  - Bottleneck along path determines amount flow can be augmented
- Still need to include concepts of residual graph and forward/backward edges

```
Ford-Fulkerson ( G=(V,E) , c, s, t )  
1. Initialize flow f to 0  
2. While exists augmenting path p do  
3.     Augment flow f along p  
4. Return f
```

# Ford-Fulkerson Algorithm

## Complete Algorithm:

- Compute residual graph including both forward and backward edges

```
Ford-Fulkerson (  $G=(V,E)$  ,  $c$  ,  $s$  ,  $t$  )

1. For every edge  $e$  let  $f(e)=0$ 
2. Construct the residual graph  $G_f$ 
3. While exists  $s$ - $t$  path in  $G_f$  do
4.     Let  $p$  be an  $s$ - $t$  path in  $G_f$ 
5.     Let  $d=\min_{e \text{ in } p} c_f(e)$ 
6.     For every  $e$  on  $p$  do
7.         If  $e$  is a forward edge then
8.              $f(e)+=d$ 
9.         else
10.             $f(\text{reverse}(e))-=d$ 
11.    Update  $G_f$  (construct new  $G_f$ )
12.Return  $f$ 
```

# Analysis of Ford-Fulkerson

## Questions.

- Does it terminate?

**Assumption.** Flow capacities are all integer values.

**Invariant.** Every flow value  $f(e)$  and every residual capacities  $c_f(e)$  remains an integer throughout the algorithm. (Can be proven by induction over the iterations of the while loop)

**Theorem.** Let  $C = \sum_{e \text{ out of } s} c(e)$

Then the algorithm terminates in at most  $v(f^*) \leq C$  iterations.

**Pf.** Each augmentation increase value by at least 1.

# Analysis of Ford-Fulkerson

## Questions.

- What is the running time?

## How much work for each iteration?

- Finding an s-t path in the residual graph  $G_f$ 
  - $G_f$  has at most  $2m$  edges
  - Use BFS/DFS:  $O(m+n) = O(m)$  since assume  $G$  is connected
- Augment flow along the path
  - $O(n)$  to update each edge along the path
- Update the residual graph
  - $O(m)$  to update each edge
- Total running time for Ford-Fulkerson is:  $O(mC)$ 
  - NOTE - this is pseudo-polynomial (similar to Knapsack problem)
  - Running time grows exponentially with the length (number of bits) in the parameter  $C$

# Analysis of Ford-Fulkerson

Questions.

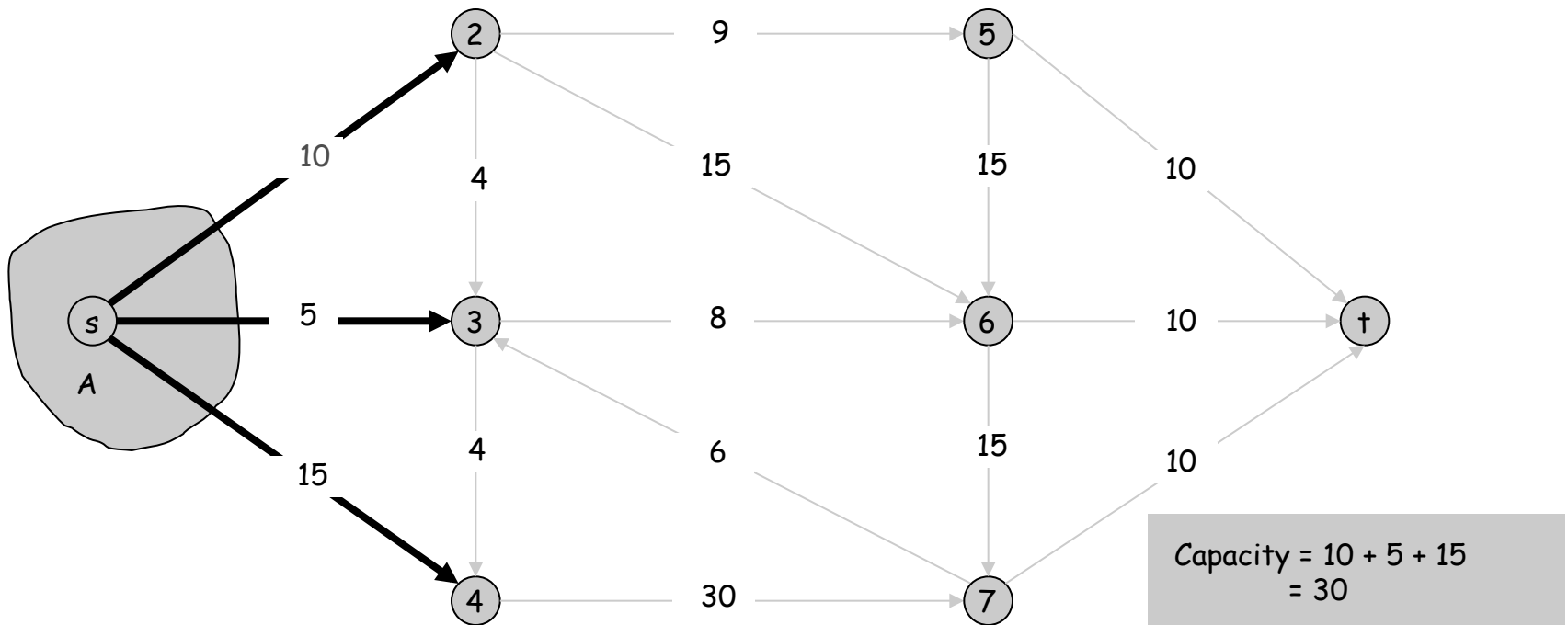
- Does it generate the maximum flow?

To see this we will introduce the concept of a graph cut

# Cuts

Def. An **s-t cut** is a partition  $(A, B)$  of  $V$  with  $s \in A$  and  $t \in B$ .

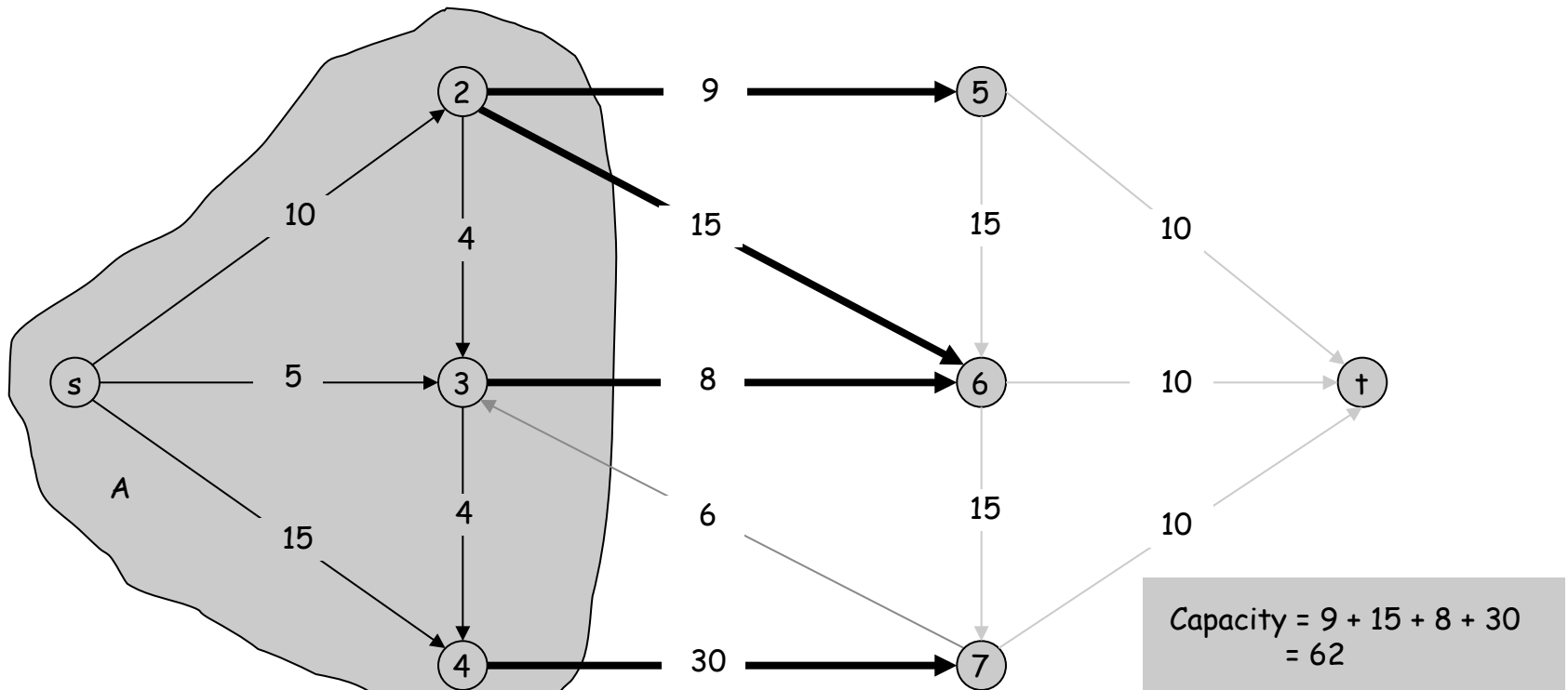
Def. The **capacity** of a cut  $(A, B)$  is:  $cap(A, B) = \sum_{e \text{ out of } A} c(e)$



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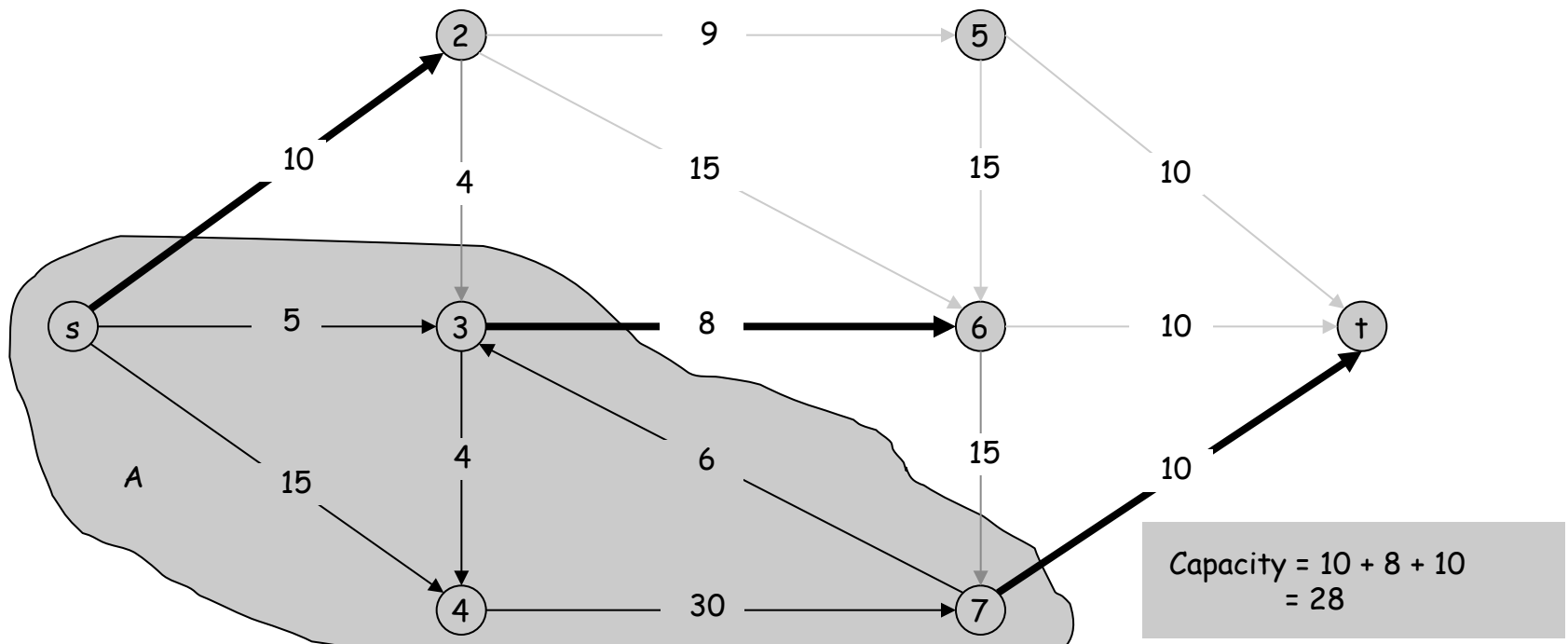
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# Minimum Cut Problem

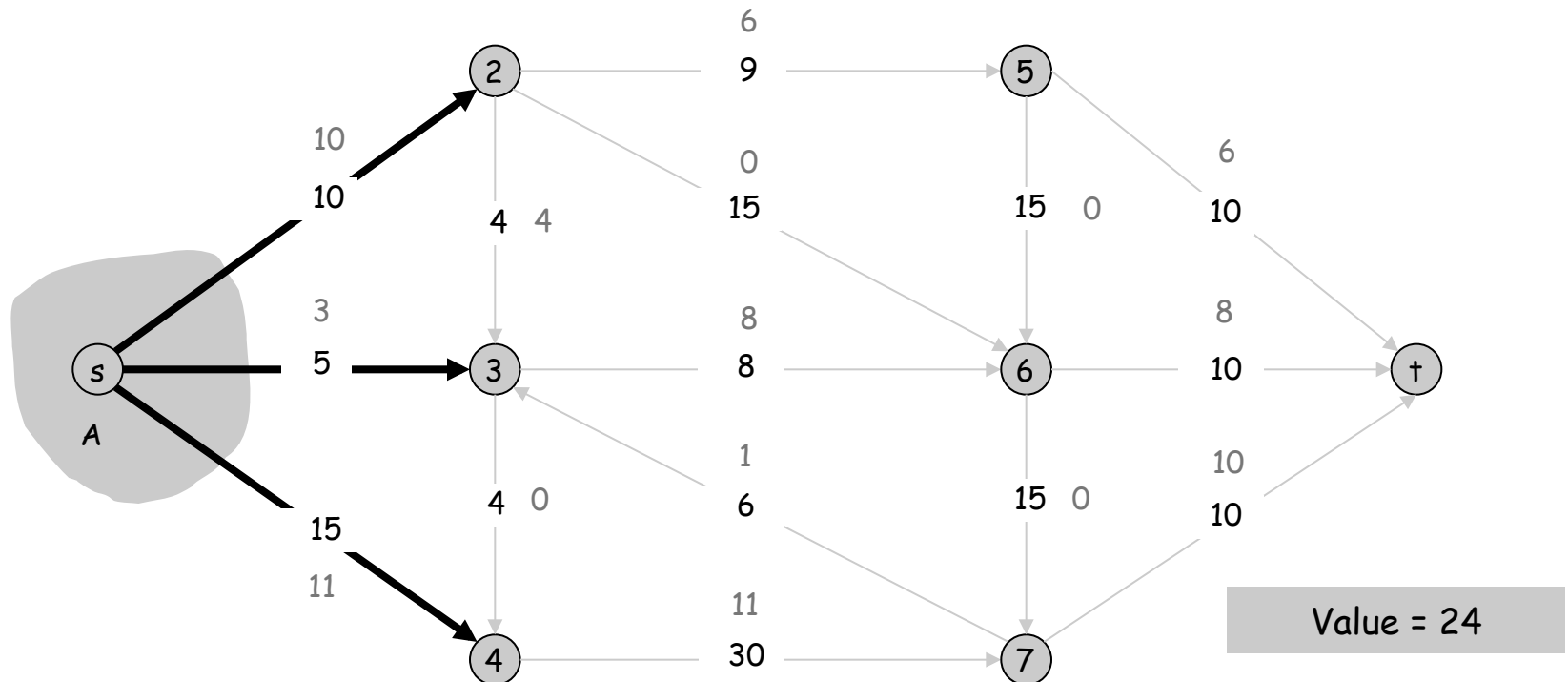
Min s-t cut problem. Find an s-t cut of minimum capacity.



# Flows and Cuts

**Flow value lemma.** Let  $f$  be any flow, and let  $(A, B)$  be any  $s$ - $t$  cut. Then, the net flow sent across the cut is equal to the amount leaving  $s$ .

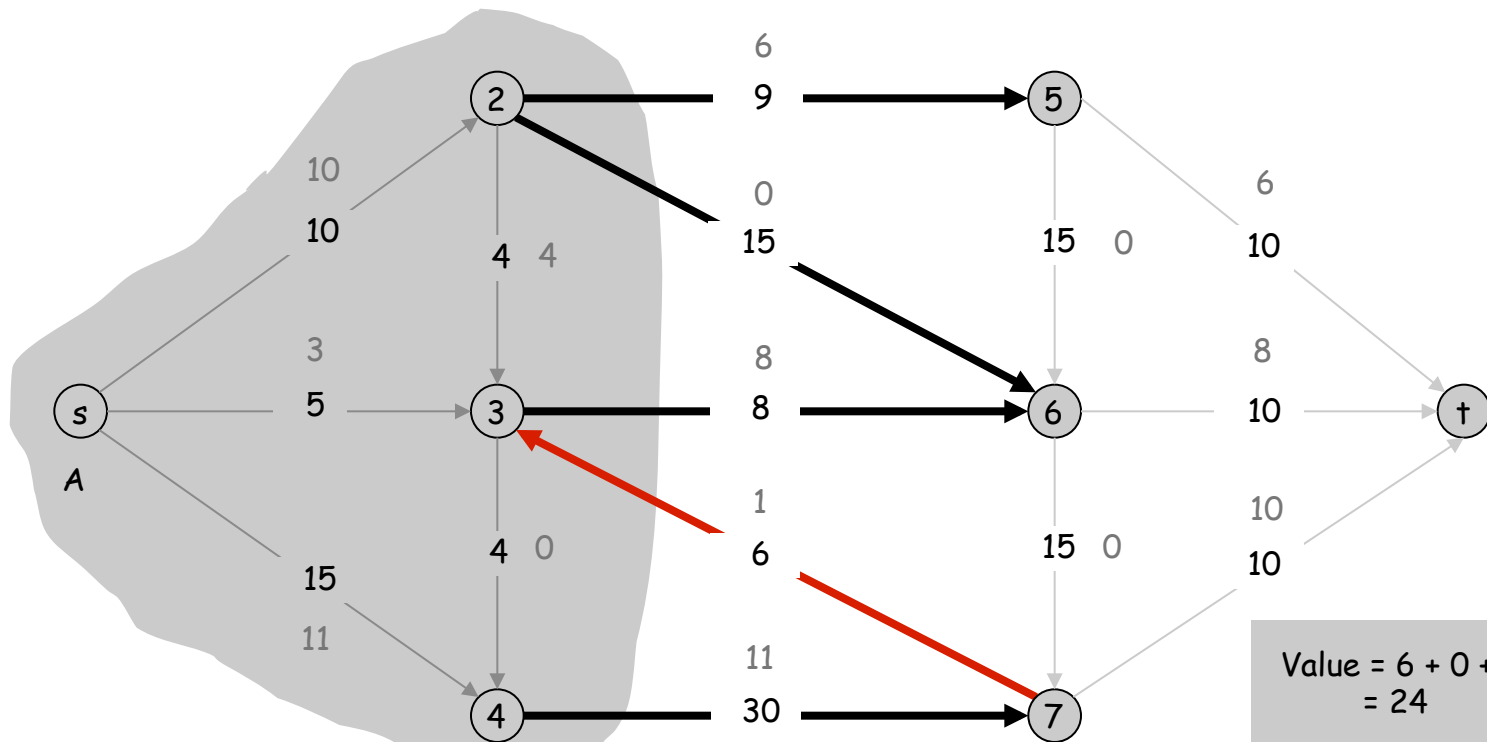
$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$$



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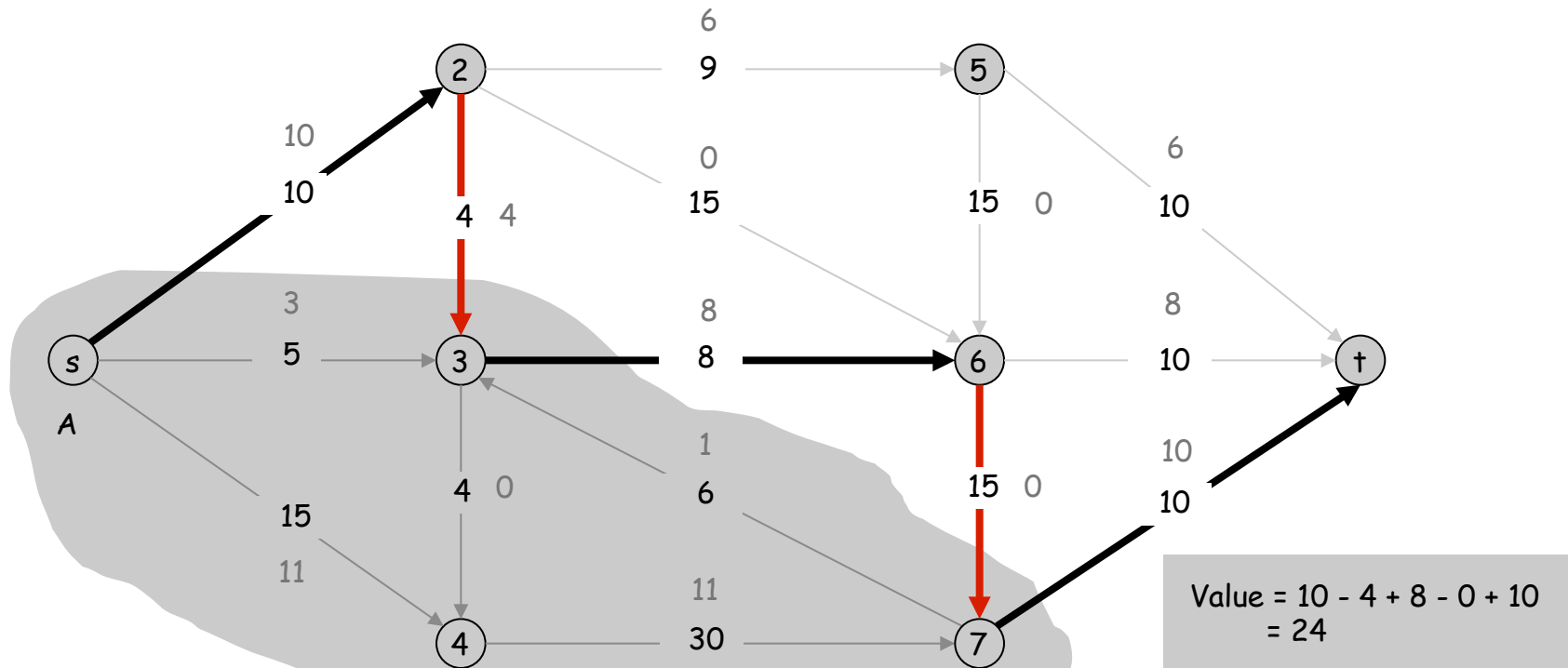
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# Flows and Cuts

**Flow value lemma.** Let  $f$  be any flow, and let  $(A, B)$  be any  $s$ - $t$  cut. Then

$$\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f).$$

**Pf.**

$$v(f) = \sum_{e \text{ out of } s} f(e)$$

by flow conservation, all terms  
except  $v = s$  are 0

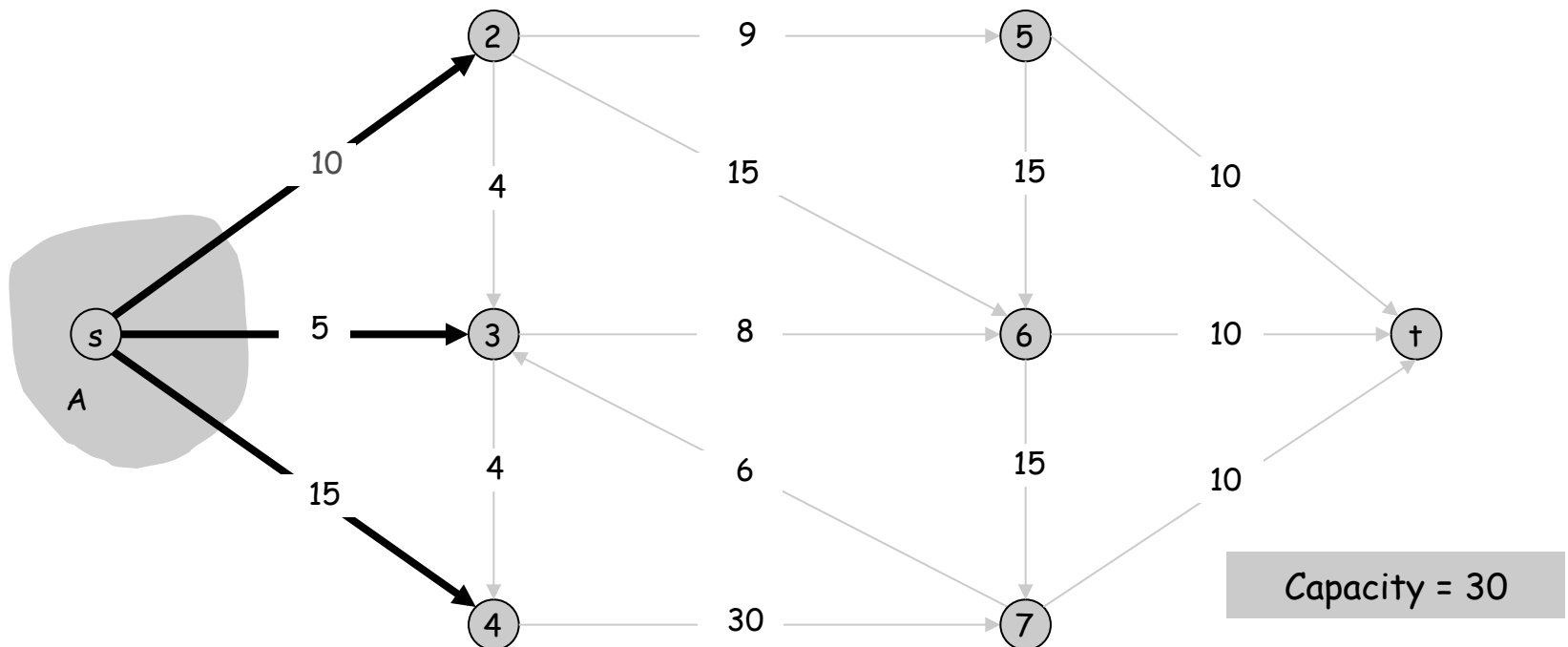
$$\longrightarrow = \sum_{v \in A} \left( \sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right)$$

$$= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e).$$

# Flows and Cuts

**Weak duality.** Let  $f$  be any flow, and let  $(A, B)$  be any  $s$ - $t$  cut. Then the value of the flow is at most the capacity of the cut.

Cut capacity = 30  $\Rightarrow$  Flow value  $\leq$  30

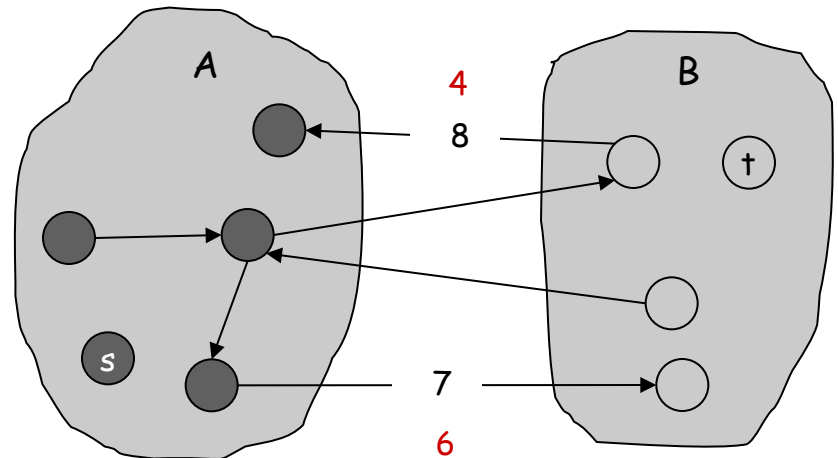


# Flows and Cuts

**Weak duality.** Let  $f$  be any flow. Then, for any  $s$ - $t$  cut  $(A, B)$  we have  $v(f) \leq \text{cap}(A, B)$ .

**Pf.**

$$\begin{aligned} v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\ &\leq \sum_{e \text{ out of } A} c(e) \\ &\leq \sum_{e \text{ out of } A} c(e) \\ &= \text{cap}(A, B) \quad \blacksquare \end{aligned}$$

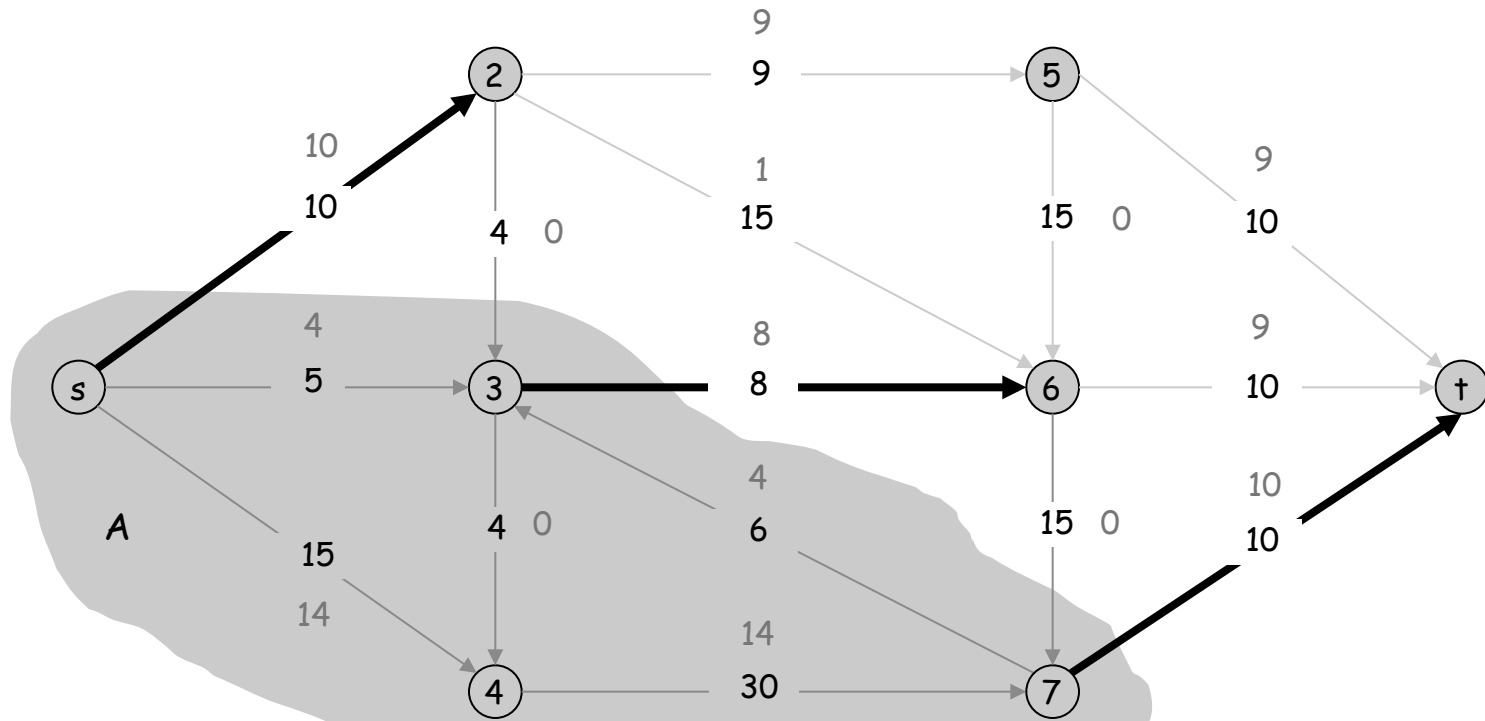


# Certificate of Optimality

**Corollary.** Let  $f$  be any flow, and let  $(A, B)$  be any cut. If  $v(f) = \text{cap}(A, B)$ , then  $f$  is a max flow and  $(A, B)$  is a min cut.

Value of flow = 28

Cut capacity = 28  $\Rightarrow$  Flow value  $\leq 28$





# Max-Flow Min-Cut Theorem

**Max-flow min-cut theorem.** [Ford-Fulkerson 1956] The value of the max flow is equal to the value of the min cut.

**The Ford-Fulkerson Algorithm generates a max flow**

To prove this we exhibit an s-t cut  $(A,B)$  with capacity equal to the flow generated by the algorithm

# Proof of Max-Flow Min-Cut Theorem

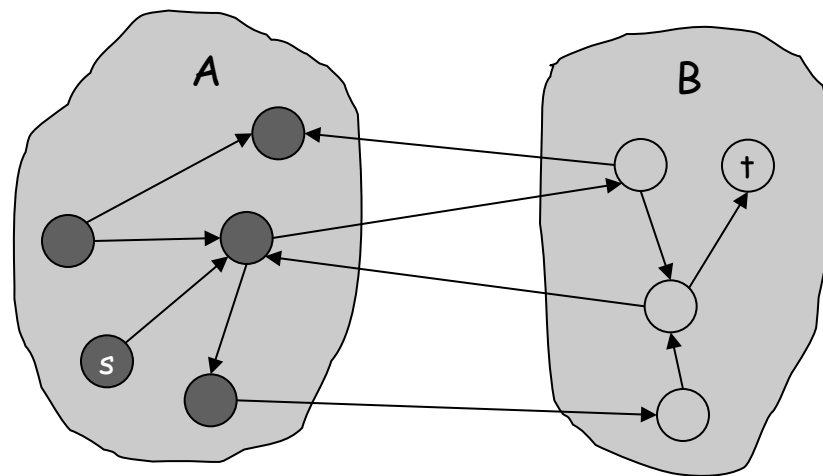
## Proof that Ford-Fulkerson generates a maximum flow

- Let  $f$  be a flow with no augmenting paths.
- Let  $A$  be set of vertices reachable from  $s$  in residual graph.
- By definition of  $A$ ,  $s \in A$ .
- By definition of  $f$ ,  $t \notin A$ .

$$\begin{aligned} v(f) &= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) \\ &= \sum_{e \text{ out of } A} c(e) \\ &= \text{cap}(A, B) \quad \blacksquare \end{aligned}$$

All outgoing edges from  $A$   
must be used at full capacity

All incoming edges to  $A$  must  
be unused



original network

# Choosing Good Augmenting Paths

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# Choosing Good Augmenting Paths

Use care when selecting augmenting paths.

- Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- If capacities are irrational, algorithm not guaranteed to terminate!

Goal: choose augmenting paths so that:

- Can find augmenting paths efficiently.
- Few iterations.

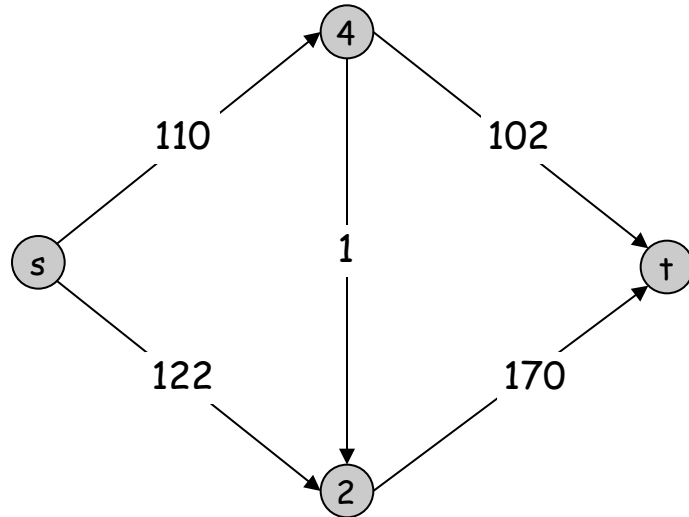
Choose augmenting paths with: [Edmonds-Karp 1972, Dinitz 1970]

- Max bottleneck capacity. (could be expensive to determine)
- Sufficiently large bottleneck capacity.
- Fewest number of edges.

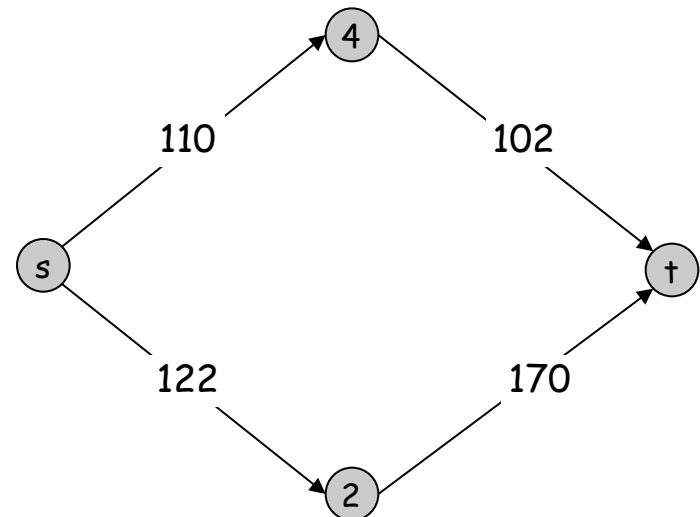
# Capacity Scaling

**Intuition.** Choosing path with highest bottleneck capacity increases flow by max possible amount.

- Don't worry about finding exact highest bottleneck path.
- Maintain scaling parameter  $\Delta$ .
- Let  $G_f(\Delta)$  be the subgraph of the residual graph consisting of only edges with capacity at least  $\Delta$ .



$G_f$

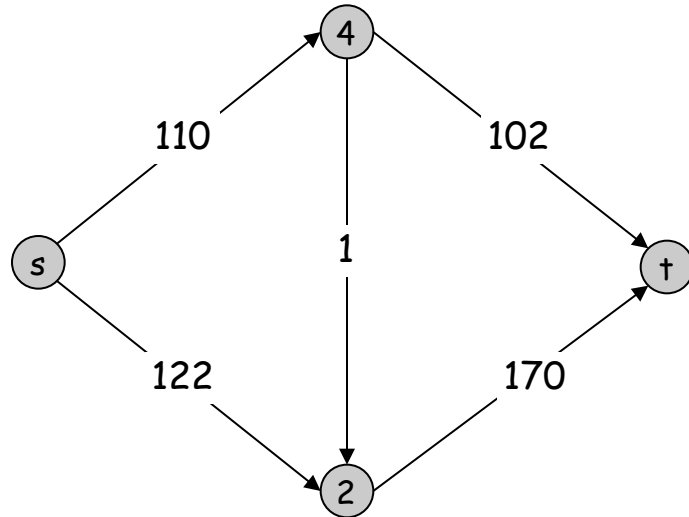


$G_f(100)$

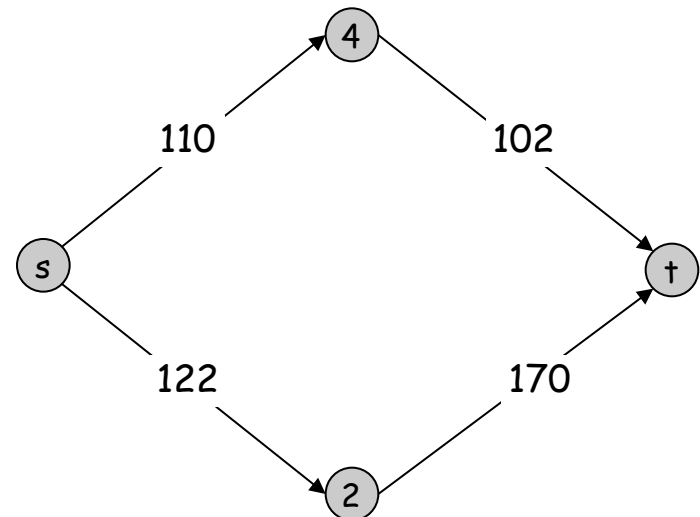
# Capacity Scaling

**Intuition.** Choosing path with highest bottleneck capacity increases flow by max possible amount.

- Start with  $\Delta$  = largest power of 2 that is smaller than  $C$ , the sum of the capacities of all edges out of  $s$ .
- Discover all  $s$ - $t$  paths in  $G_f(\Delta)$ .
- Divide  $\Delta$  by 2 and repeat, until finding all paths with  $\Delta = 1$ .



$G_f$



$G_f(100)$

# Capacity Scaling: Correctness and Running Time

## Correctness

- Assuming integer constraints for flow capacities
- When  $\Delta = 1 \Rightarrow G_f(\Delta) = G_f$ .
- Upon termination of  $\Delta = 1$  phase, there are no augmenting paths.

## Running Time

- The scaling max-flow algorithm finds a max flow in  $O(m \log C)$  augmentations. It can be implemented to run in  $O(m^2 \log C)$  time.
  - (reducing the dependency on flow capacity to  $\log C$ )

# Edmonds-Karp Algorithm

**General Idea:** For each iteration, the shortest augmentation path is chosen.

**Argument:** Each time an edge is a bottleneck edge on an augmentation path, it is temporarily removed from the residual graph. By the time it returns to the residual graph and is again a critical edge, it must be part of a shortest path that is at least length 2 longer than previously.

**Running Time:** Each edge can be a critical edge at most  $n/2$  times, since all shortest paths will be length  $n-1$  or less. Every augmentation must involve at least one critical edge. Thus the total number of augmentations is  $O(nm)$ , and the total running time of Edmonds-Karp is  $O(nm^2)$ .

Dependency on  $C$  has been completely removed.



# Maximum Flow and Minimum Cut

## Max flow and min cut.

- Two very rich algorithmic problems.
- Cornerstone problems in combinatorial optimization.
- Beautiful mathematical duality.

## Nontrivial applications / reductions. (See the Kleinberg / Tardos textbook)

- Data mining.
- Open-pit mining.
- Project selection.
- Airline scheduling.
- Bipartite matching.
- Baseball elimination.
- Image segmentation.
- Network connectivity.
- Network reliability.
- Distributed computing.
- Egalitarian stable matching.
- Security of statistical data.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Many many more . . .