Gi-Cheon Kang

website: gicheonkang.com email: chonkang@snu.ac.kr

EDUCATION Seoul National University

Seoul, Korea

Ph.D. in Artificial Intelligence

Sept. 2020 - Feb. 2025

Advisor: Prof. Byoung-Tak Zhang

Thesis: Embodied language agents for real-world robotic tasks: visually-grounded interaction & skill learning

Seoul National University

Seoul, Korea

M.S. in Cognitive Science

Mar. 2018 – Feb. 2020

Advisor: Prof. Byoung-Tak Zhang

Ajou University

Suwon, Korea

B.Eng. in Software and Computer Engineering

Mar. 2011 - Feb. 2018

INTERESTS

Machine Learning, Robot Learning, Natural Language Processing

My research lies at the intersection of robot learning and natural language processing, where I explore how language can be used to teach robots and improve human-robot interaction.

- Language-driven robotics: Developing (1) vision-language-action (VLA) models that learn visuomotor policies from natural language supervision [6], and (2) robots that perform realworld tasks through language interaction with humans [13, 14, 11]
- Visually-grounded dialog: Building vision-and-language models (VLMs) that can continuously communicate with humans about images [12, 10, 7] and videos [9]

EXPERIENCE AI Institute for SNU (AIIS)

Seoul, Korea

Postdoctoral Researcher

March. 2025 - Aug. 2025 (expected)

Hosts: Jun Ki Lee and Byoung-Tak Zhang Studying foundation models for robotics.

SNU-NAVER Hyperscale AI Center

Seoul, Korea

Student Researcher

Sept. 2021 - May 2022

Hosts: Jin-Hwa Kim, Sungdong Kim, and Donghyun Kwak

Studied a semi-supervised learning approach for visual dialog. Published at CVPR 2023.

Seoul National University (SNU)

Seoul, Korea

Research Assistant

Sept. 2020 - Feb. 2025

Advisor: Byoung-Tak Zhang

I have studied machine learning algorithms that connect natural language to perception and action. Developed interactive robots, grasping desired objects through dialog with users (ICRA 2024 Oral) and a lifelong learning framework for robots to adapt to real-world environments without human supervision (IROS 2023 Oral). Currently studying how non-experts can teach robotic skills only through natural language (CoRLW 2024).

SK T-Brain Seoul, Korea

Research Intern Jan. 2020 - March. 2020

Hosts: Jin-Hwa Kim and Hwaran Lee

Worked on discovering sparse structures in visual dialog. Published at Findings of EMNLP 2021.

HONORS	&
AWARDS	

Youlchon AI Star Fellowship	Aug. 2024
IPAI Ph.D. Fellowship	May 2024
Daeha Scholarship	May 2022
Ranked 3rd Place, Visual Dialog Challenge @ CVPR 2019	June 2019
Software-Centered University Hackathon, Prize from Microsoft Korea	Sept. 2017
Yeoju Honor Scholarship	May 2016

SELECTED PUBLICA-TIONS

- [15] Socratic Planner: Self-QA-Based Zero-Shot Planning for Embodied Instruction Following Suyeon Shin, Sujin Jeon*, Junghyun Kim*, Gi-Cheon Kang*, Byoung-Tak Zhang IEEE International Conference on Robotics and Automation (ICRA), 2025
- [14] **PGA: Personalizing Grasping Agents with Single Human-Robot Interaction**Junghyun Kim, <u>Gi-Cheon Kang</u>*, Jaein Kim*, Seoyoon Yang, Minjoon Jung, Byoung-Tak Zhang *IEEE/RSJ International Conference on Intelligent Robots and Systems*, (IROS), 2024
- [13] **PROGrasp: Pragmatic Human-Robot Communication for Object Grasping**Gi-Cheon Kang, Junghyun Kim, Jaein Kim, Byoung-Tak Zhang

 IEEE International Conference on Robotics and Automation (ICRA), 2024 (Oral)
- [12] **The Dialog Must Go On: Improving Visual Dialog via Generative Self-Training**Gi-Cheon Kang, Sungdong Kim*, Jin-Hwa Kim*, Donghyun Kwak*, Byoung-Tak Zhang

 IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2023
- [11] GVCCI: Lifelong Learning of Visual Grounding for Language-Guided Robotic Manipulation
 Junghyun Kim, Gi-Cheon Kang*, Jaein Kim*, Suyeon Shin, Byoung-Tak Zhang
 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2023 (Oral)
- [10] Reasoning Visual Dialog with Sparse Graph Learning and Knowledge Transfer Gi-Cheon Kang, Junseok Park, Hwaran Lee, Byoung-Tak Zhang*, Jin-Hwa Kim*

 Findings of Empirical Methods in Natural Language Processing (EMNLP Findings), 2021
- [9] Attend What You Need: Motion-Appearance Synergistic Networks for Video Question Answering Ahjeong Seo, Gi-Cheon Kang, Joonhan Park, Byoung-Tak Zhang Annual Meeting of the Association for Computational Linguistics (ACL), 2021
- [8] Label Propagation Adaptive Resonance Theory for Semi-Supervised Continuous Learning Taehyeong Kim, Injune Hwang, Gi-Cheon Kang, Won-Seok Choi, Hyunseo Kim, Byoung-Tak Zhang
 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), 2020
- [7] Dual Attention Networks for Visual Reference Resolution in Visual Dialog
 Gi-Cheon Kang, Jaeseo Lim, Byoung-Tak Zhang
 Conference on Empirical Methods in Natural Language Processing (EMNLP), 2019

WORKSHOP PAPERS

[6] CLIP-RT: Learning Language-Conditioned Robotic Policies from Natural Language Supervision

<u>Gi-Cheon Kang*</u>, Junghyun Kim*, Kyuhwan Shim, Junki Lee†, Byoung-Tak Zhang† <u>CoRL Workshop on Language and Robot Learning</u> (LangRob), 2024

- [5] Generative Self-training Improves Pre-training for Visual Dialog Gi-Cheon Kang, Sungdong Kim*, Jin-Hwa Kim*, Donghyun Kwak*, Byoung-Tak Zhang ICML Workshop on Pre-training: Perspectives, Pitfalls, and Paths Forward (ICMLW), 2022
- [4] Improving Robustness to Texture Bias via Shape-focused Augmentation Sangjun Lee, Inwoo Hwang, Gi-Cheon Kang, Byoung-Tak Zhang CVPR Workshop on Human-centered Intelligent Services: Safety and Trustworthy (CVPRW), 2022

[3] C^3 : Contrastive Learning for Cross-domain Correspondence in Few-shot Image Generation Hyukgi Lee, Gi-Cheon Kang, Chang-Hoon Jeong, Hanwool Sul, Byoung-Tak Zhang NeurIPS Workshop on Controllable Generative Modeling in Language and Vision (NeurIPSW), 2021

[2] Contextualized Bilinear Attention Networks

Gi-Cheon Kang, Seonil Son, Byoung-Tak Zhang ECCV Workshop on VizWiz Grand Challenge (ECCVW), 2018

PREPRINTS [1] Continual Vision-and-Language Navigation

Seongjun Jeong, Gi-Cheon Kang, Seongho Choi, Joochan Kim, Byoung-Tak Zhang $arXiv\ Preprint, 20\overline{24}$

INVITED TALKS	PROGrasp: Pragmatic Human-Robot Communication for Object Grasping IEEE International Conference on Robotics and Automation (ICRA)	May 2024
	The Evolution of Language Models: From Basic NLP to ChatGPT and Beyond Dept. of Energy Resources Engineering, Seoul National University	Nov. 2023
	The Dialog Must Go On: Improving Visual Dialog via Generative Self-Training IEEE RO-MAN Workshop on Learning by Asking for Intelligent Robots and Ager	nts Aug. 2023
	Reasoning Visual Dialog with Sparse Graph Learning and Knowledge Transfer KSC 2021 - Top-tier Conference Paper Presentation Session Annual Conference on Human and Cognitive Language Technology	Dec. 2021 Oct. 2021
	Dual Attention Networks for Visual Reference Resolution in Visual Dialog ICCV 2019 - Video Turing Test Workshop SK Telecom AI Center	Nov. 2019 Sept. 2019
SERVICES	Reviewing	
SERVICES	(ML) Neural Information Processing Systems (NeurIPS) (ML) International Conference on Machine Learning (ICML) (ML) International Conference on Learning Representations (ICLR) (AI) AAAI Conference on Artificial Intelligence (AAAI) (NLP) ACL Rolling Review (ARR) (NLP) Annual Meeting of the Association for Computational Linguistics (ACL) (NLP) Empirical Methods in Natural Language Processing (EMNLP) (Robotics) IEEE Robotics and Automation Letters (RA-L) (Robotics) IEEE/RSJ International Conference on Intelligent Robots and Systems (IRC	
	(Workshop) CoRL Workshop on Language and Robot Learning (LangRob)	2024

EXTRA	BI Lab Tennis Club	2023 – Present
CURRICULAR	BI Lab Conference Deadline Site Administrator	2018 - Present
ACTIVITIES	Military Service in Republic of Korea Army	2012 - 2014

(Workshop) ICML Workshop on Pre-training: Perspectives, Pitfalls, and Paths Forward

(Workshop) ICLR Workshop on Reliable and Responsible Foundation Models

2024

2022