Gi-Cheon Kang

website: gicheonkang.com email: chonkang@snu.ac.kr

EDUCATION Seoul National University

Seoul, Korea

Ph.D. in Artificial Intelligence

Sept. 2020 – Feb. 2025

Advisor: Prof. Byoung-Tak Zhang

Thesis: Embodied language agents for real-world robotic tasks: visually-grounded interaction & skill learning

Seoul National University

Seoul, Korea

M.S. in Cognitive Science

Mar. 2018 – Feb. 2020

Mar. 2011 - Feb. 2018

Advisor: Prof. Byoung-Tak Zhang

Ajou University

Suwon, Korea

B.Eng. in Software and Computer Engineering

INTERESTS Machine Learning, Robot Learning, Embodied & Multimodal AI

- **Robotics Foundation Models**: Building vision-language-action (VLA) models for generalist robot policies, with a focus on grounding web-scale knowledge to robotic control.
- **Embodied Reasoning**: Investigating vision-language models (VLMs) for task planning and reasoning about language instructions in physical environments.
- **Vision & Language**: Developing interactive VLMs that engage in continuous, grounded communication with humans about images and videos

EXPERIENCE AI Institute for SNU (AIIS)

Seoul, Korea

Postdoctoral Fellow

March. 2025 – Current

Hosts: Jun Ki Lee and Byoung-Tak Zhang

Working on vision-language-action (VLA) models for robot manipulation. Published at RSS 2025.

SNU-NAVER Hyperscale AI Center

Seoul, Korea

Student Researcher

Sept. 2021 – May 2022

Hosts: Jin-Hwa Kim, Sungdong Kim, and Donghyun Kwak

Studied a semi-supervised learning approach for visual dialog. Published at CVPR 2023.

Seoul National University (SNU)

Seoul, Korea

Research Assistant

Sept. 2020 - Feb. 2025

Advisor: Byoung-Tak Zhang

I have studied machine learning algorithms that connect natural language to perception and action. Developed interactive robots, grasping desired objects through dialog with users (ICRA 2024 Oral) and a lifelong learning framework for robots to adapt to real-world environments without human supervision (IROS 2023 Oral).

SK T-Brain Seoul, Korea

Research Intern Jan. 2020 - March. 2020

Hosts: Jin-Hwa Kim and Hwaran Lee

Worked on discovering sparse structures in visual dialog. Published at Findings of EMNLP 2021.

HONORS & AWARDS

RSS Pioneers <i>Top early-career researchers in robotics (area: robot learning & foundation models)</i>	2025
Youlchon AI Star Fellowship Awarded to 10 PhD students for excellence in core AI research	2024
IPAI Ph.D. Fellowship	2024
Daeha Scholarship	2022
3rd Place, Visual Dialog Challenge @ CVPR 2019	2019
Software-Centered University Hackathon, Prize from Microsoft Korea	2017
Yeoju Honor Scholarship	2016

SELECTED PUBLICATIONS

(* denotes equal contribution)

PEER-REVIEWED CONFERENCE PAPERS

- [1] CLIP-RT: Learning Language-Conditioned Robotic Policies from Natural Language Supervision Gi-Cheon Kang*, Junghyun Kim*, Kyuhwan Shim, Jun Ki Lee, Byoung-Tak Zhang Robotics: Science and Systems (RSS), 2025
- [2] Socratic Planner: Self-QA-Based Zero-Shot Planning for Embodied Instruction Following Suyeon Shin, Sujin Jeon*, Junghyun Kim*, Gi-Cheon Kang*, Byoung-Tak Zhang IEEE International Conference on Robotics and Automation (ICRA), 2025
- [3] **PGA:** Personalizing Grasping Agents with Single Human-Robot Interaction
 Junghyun Kim, Gi-Cheon Kang*, Jaein Kim*, Seoyoon Yang, Minjoon Jung, Byoung-Tak Zhang *IEEE/RSJ International Conference on Intelligent Robots and Systems*, (IROS), 2024
- [4] PROGrasp: Pragmatic Human-Robot Communication for Object Grasping Gi-Cheon Kang, Junghyun Kim, Jaein Kim, Byoung-Tak Zhang *IEEE International Conference on Robotics and Automation* (ICRA), 2024 (Oral)
- [5] **The Dialog Must Go On: Improving Visual Dialog via Generative Self-Training**Gi-Cheon Kang, Sungdong Kim*, Jin-Hwa Kim*, Donghyun Kwak*, Byoung-Tak Zhang

 IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2023
- [6] GVCCI: Lifelong Learning of Visual Grounding for Language-Guided Robotic Manipulation Junghyun Kim, Gi-Cheon Kang*, Jaein Kim*, Suyeon Shin, Byoung-Tak Zhang IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2023 (Oral)
- [7] Reasoning Visual Dialog with Sparse Graph Learning and Knowledge Transfer Gi-Cheon Kang, Junseok Park, Hwaran Lee, Byoung-Tak Zhang*, Jin-Hwa Kim* Findings of Empirical Methods in Natural Language Processing (EMNLP Findings), 2021
- [8] Attend What You Need: Motion-Appearance Synergistic Networks for Video Question Answering Ahjeong Seo, Gi-Cheon Kang, Joonhan Park, Byoung-Tak Zhang Annual Meeting of the Association for Computational Linguistics (ACL), 2021
- [9] Label Propagation Adaptive Resonance Theory for Semi-Supervised Continuous Learning Taehyeong Kim, Injune Hwang, Gi-Cheon Kang, Won-Seok Choi, Hyunseo Kim, Byoung-Tak Zhang IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), 2020
- [10] **Dual Attention Networks for Visual Reference Resolution in Visual Dialog**Gi-Cheon Kang, Jaeseo Lim, Byoung-Tak Zhang

 Conference on Empirical Methods in Natural Language Processing (EMNLP), 2019

 ICCV Workshop on Video Turing Test (VTT), 2019 (Spotlight)

WORKSHOP PAPERS

[11] Generative Self-training Improves Pre-training for Visual Dialog
Gi-Cheon Kang, Sungdong Kim*, Jin-Hwa Kim*, Donghyun Kwak*, Byoung-Tak Zhang
ICML Workshop on Pre-training: Perspectives, Pitfalls, and Paths Forward (ICMLW), 2022

[12] Improving Robustness to Texture Bias via Shape-focused Augmentation Sangjun Lee, Inwoo Hwang, Gi-Cheon Kang, Byoung-Tak Zhang CVPR Workshop on Human-centered Intelligent Services: Safety and Trustworthy (CVPRW), 2022

[13] C^3 : Contrastive Learning for Cross-domain Correspondence in Few-shot Image Generation Hyukgi Lee, Gi-Cheon Kang, Chang-Hoon Jeong, Hanwool Sul, Byoung-Tak Zhang NeurIPS Workshop on Controllable Generative Modeling in Language and Vision (NeurIPSW), 2021

[14] Contextualized Bilinear Attention Networks

Gi-Cheon Kang, Seonil Son, Byoung-Tak Zhang ECCV Workshop on VizWiz Grand Challenge (ECCVW), 2018

PREPRINTS

[15] Continual Vision-and-Language Navigation

Seongjun Jeong, Gi-Cheon Kang, Seongho Choi, Joochan Kim, Byoung-Tak Zhang arXiv Preprint, 2024

INVITED TALKS	CLIP-RT: Learning Language-Conditioned Robotic Policies from Natural Language Supervi Robotics: Science and Systems (RSS)	ision June 2025
	Foundation Models for Robotics: Learning and Interaction Robotics: Science and Systems (RSS) Pioneers Workshop	June 2025
	Vision-Language-Action Models for Robotic Manipulation Korea Robotics Society (KROS) Workshop on Mobile Manipulation	May 2025
	PROGrasp: Pragmatic Human-Robot Communication for Object Grasping IEEE International Conference on Robotics and Automation (ICRA)	May 2024
	The Evolution of Language Models: From Basic NLP to ChatGPT and Beyond Dept. of Energy Resources Engineering, Seoul National University	Nov. 2023
	The Dialog Must Go On: Improving Visual Dialog via Generative Self-Training IEEE RO-MAN Workshop on Learning by Asking for Intelligent Robots and Age	ents Aug. 2023
	Reasoning Visual Dialog with Sparse Graph Learning and Knowledge Transfer KSC 2021—Top-tier Conference Paper Presentation Session Annual Conference on Human and Cognitive Language Technology	Dec. 2021 Oct. 2021
	Dual Attention Networks for Visual Reference Resolution in Visual Dialog ICCV 2019 - Video Turing Test Workshop SK Telecom AI Center	Nov. 2019 Sept. 2019
SERVICES	Reviewing Conference on Neural Information Processing Systems (NeurIPS) International Conference on Machine Learning (ICML) International Conference on Learning Representations (ICLR) AAAI Conference on Artificial Intelligence (AAAI) ACL Rolling Review (ARR) Annual Meeting of the Association for Computational Linguistics (ACL) Empirical Methods in Natural Language Processing (EMNLP) IEEE Robotics and Automation Letters (RA-L) IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	2023 - 2025 2024 - 2025 2024 - 2025 2025 2024 - 2025 2023 - 2024 2022 - 2023 2024 2024

EXTRABI Lab Tennis Club2023 – PresentCURRICULARBI Lab Conference Deadline Site Administrator2018 – PresentACTIVITIESMilitary Service in Republic of Korea Army2012 – 2014