



Regularizing Neural Networks via Adversarial Model Perturbation

Yaowei Zheng,¹ Richong Zhang,¹ Yongyi Mao²

¹BDBC and SKLSDE, Beihang University, Beijing, China ²School of EECS, University of Ottawa, Ottawa, Canada



Test Error (%)

 24.31 ± 0.303

 24.48 ± 0.351

 22.07 ± 0.256

 24.50 ± 0.234

 21.78 ± 0.210

 25.23 ± 0.229

 24.28 ± 0.138

Test Error (%)

 27.84 ± 0.297

 27.72 ± 0.337

 27.49 ± 0.179

 27.93 ± 0.271

 26.81 ± 0.254

 29.12 ± 0.145

 27.81 ± 0.327

 25.60 ± 0.168

(c) CIFAR-100

Test NLL

 1.056 ± 0.013

 1.110 ± 0.021

 2.099 ± 0.005

 0.950 ± 0.011

 0.910 ± 0.007

 1.110 ± 0.012

 1.059 ± 0.011

 0.774 ± 0.016

Test NLL

 1.827 ± 0.209

 1.221 ± 0.037

 1.136 ± 0.013

 1.535 ± 0.389

 1.873 ± 0.035

 1.049 ± 0.049

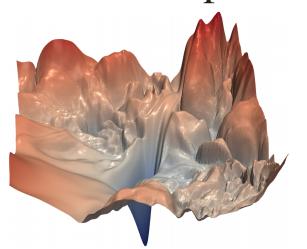
 1.605 ± 0.062

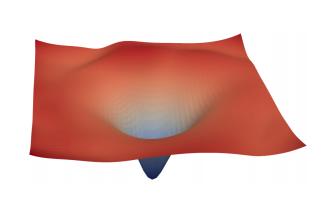
Summary

Background: Effective regularization schemes are highly desired in deep learning for alleviating overfitting and improving generalization.

Motivation: Previous work suggested that flat minima can improve generalization both in theoretical and empirical perspectives [1-4].

Contribution: We propose Adversarial Model Perturbation (AMP) as a powerful regularization scheme principled by the objective of finding flat minima, which achieves better classification performance and calibration results.





(Better minima are flatter, visualized by Li et al., 2018.)

Training Algorithm

Optimization Objective:

$$\min_{oldsymbol{ heta}} \max_{\Delta: \|\Delta\| \leq \epsilon} \mathcal{L}_{\mathrm{ERM}}(oldsymbol{ heta} + \Delta)$$

Pseudo-code:

while θ not converged do Initialize perturbation Δ with $\mathbf{0}$; for $n \leftarrow 1$ to N do Update Δ to maximize $\mathcal{L}_{ERM}(\boldsymbol{\theta} + \Delta)$ via gradient ascent with learning rate ζ ; if $\|\Delta\|_2 > \epsilon$ then Normalize Δ to restrict its norm $\|\Delta\|_2$ to ϵ ; Update θ to minimize $\mathcal{L}_{ERM}(\theta + \Delta)$ via gradient descent with learning rate η ;

PyTorch Implementation:

```
from amp import AMP
opt = AMP(params, lr=0.1, epsilon=0.5)
for inputs, targets in dataset:
 def closure():
    opt.zero_grad()
    outputs = model(inputs)
    loss = loss_fn(outputs, targets)
    loss.backward()
    return outputs, loss
  outputs, loss = opt.step(closure)
```

Official Code:

https://github.com/hiyouga/AMP-Regularizer

Method

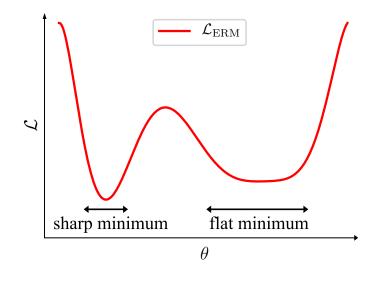
AMP: Adversarial Model Perturbation

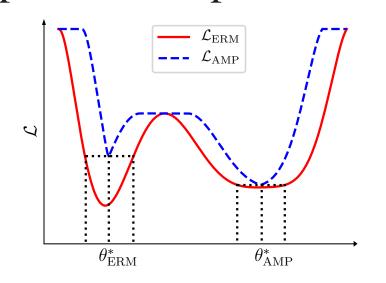
We derive an AMP loss from the empirical risk (ERM loss). Minimizing such an AMP loss can penalize the sharp minima by adversarially perturbing the model parameters.

$$\mathcal{L}_{ ext{ERM}}(oldsymbol{ heta}) := rac{1}{|D|} \sum_{(oldsymbol{x}, oldsymbol{y}) \in \mathcal{D}} \ell(oldsymbol{x}, oldsymbol{y}; oldsymbol{ heta})$$

$$\mathcal{L}_{\mathrm{AMP}}(oldsymbol{ heta}) := \max_{\Delta: \|\Delta\| \leq \epsilon} \mathcal{L}_{\mathrm{ERM}}(oldsymbol{ heta} + \Delta)$$

It can be seen as an analogue of a "max-pooling" operation on the empirical risk on each point in the parameter space.





Theoretical Justification

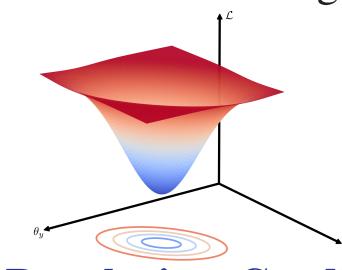
AMP Finds Flatter Minima:

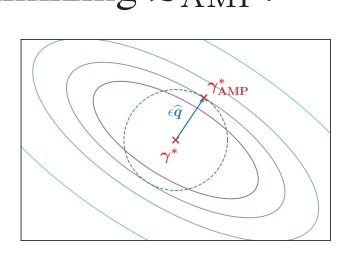
We assume that the loss surface of each local minimum in $\mathcal{L}_{\mathrm{ERM}}$ can be *locally* approximated as an inverted Gaussian surface γ with a mean vector μ and a covariance matrix κ . Under the locally Gaussian assumption, the empirical risk $\gamma(\theta; \mu, \kappa, A, C)$ is minimized when $\theta = \mu$ and the minimum value is $\gamma^*(\mu, \kappa, A, C) = C - A$. The minimum value of the AMP loss is the empirical risk at the location in the narrowest principal direction of the cross-section of the loss surface:

$$\gamma^*_{ ext{AMP}}(oldsymbol{\mu}, oldsymbol{\kappa}, A, C) = C - A \exp\left(-rac{\epsilon^2}{2\sigma^2}
ight)$$

where σ^2 is the smallest eigenvalue of κ .

It is clear that γ_{AMP}^* although related to the minimum value of empirical risk γ^* , it also takes into account the curvature of the surface around the local minimum. Thus we can find a flatter minimum through minimizing \mathcal{L}_{AMP} .





AMP Regularizes Gradient Norm:

Consider that N=1. The AMP training is equivalent to ERM training with an additional term:

$$\mathcal{J}_{\mathrm{ERM}}(\boldsymbol{\theta}) := \mathcal{J}_{\mathrm{ERM}}(\boldsymbol{\theta}) + \Omega(\boldsymbol{\theta})$$

where

$$\Omega(\boldsymbol{\theta}) := \begin{cases} \zeta \|\nabla_{\boldsymbol{\theta}} \mathcal{J}_{\text{ERM}}(\boldsymbol{\theta})\|_{2}^{2}, \|\zeta\nabla_{\boldsymbol{\theta}} \mathcal{J}_{\text{ERM}}(\boldsymbol{\theta})\|_{2} \leq \epsilon \\ \epsilon \|\nabla_{\boldsymbol{\theta}} \mathcal{J}_{\text{ERM}}(\boldsymbol{\theta})\|_{2}, \|\zeta\nabla_{\boldsymbol{\theta}} \mathcal{J}_{\text{ERM}}(\boldsymbol{\theta})\|_{2} > \epsilon \end{cases}$$

Experiments

Results on Image Classification Benchmarks:

PreActResNet18	Test Error (%)	Test NLL	PreActResNet18	Test Error (%)	Test NLL
ERM	2.95 ± 0.063	0.166 ± 0.004	ERM	5.02 ± 0.212	0.239 ± 0.009
Dropout	2.80 ± 0.065	0.156 ± 0.012	Dropout	4.86 ± 0.148	0.223 ± 0.009
Label Smoothing	2.78 ± 0.087	0.998 ± 0.002	Label Smoothing	4.85 ± 0.115	1.038 ± 0.003
Flooding	2.84 ± 0.047	0.130 ± 0.003	Flooding	4.97 ± 0.082	0.166 ± 0.003
MixUp	2.74 ± 0.044	0.146 ± 0.004	MixUp	4.09 ± 0.117	0.198 ± 0.004
Adv. Training	2.77 ± 0.080	0.151 ± 0.018	Adv. Training	4.99 ± 0.085	0.247 ± 0.006
RMP	2.93 ± 0.066	0.161 ± 0.010	RMP	4.97 ± 0.167	0.239 ± 0.008
AMP	2.30 ± 0.025	0.096 ± 0.002	AMP	3.97 ± 0.091	0.129 ± 0.003
VGG16	Test Error (%)	Test NLL	VGG16	Test Error (%)	Test NLL
ERM	3.14 ± 0.060	0.140 ± 0.027	ERM	6.32 ± 0.193	0.361 ± 0.012
Dropout	2.96 ± 0.049	0.12410.027	T		
I abal Cmaathina	∠. 90⊥0.0 1 9	0.134 ± 0.027	Dropout	6.22 ± 0.147	0.314 ± 0.009
Label Smoothing	3.07 ± 0.070	0.134 ± 0.027 1.004 ± 0.002	Dropout Label Smoothing	6.22 ± 0.147 6.29 ± 0.158	0.314 ± 0.009 1.076 ± 0.003
Flooding			*		
C	3.07 ± 0.070	1.004 ± 0.002	Label Smoothing	6.29 ± 0.158	1.076 ± 0.003
Flooding	3.07 ± 0.070 3.15 ± 0.085	1.004 ± 0.002 0.128 ± 0.003	Label Smoothing Flooding	6.29 ± 0.158 6.26 ± 0.145	$\frac{1.076 \pm 0.003}{0.234 \pm 0.005}$
Flooding MixUp	3.07 ± 0.070 3.15 ± 0.085 3.09 ± 0.057	1.004 ± 0.002 0.128 ± 0.003 0.160 ± 0.003	Label Smoothing Flooding MixUp	6.29 ± 0.158 6.26 ± 0.145 5.48 ± 0.112	$\begin{array}{c} 1.076 \pm 0.003 \\ \underline{0.234 \pm 0.005} \\ 0.251 \pm 0.003 \end{array}$

CIFAR-10	
CIFAK-1U	

Improvement over Various Data Augmentation Techniques:

Test Error (%)	Augment	WideResNet-28-10		PyramidNet-164-270	
Dataset	Technique	ERM	AMP	ERM	AMP
SVHN	Vanilla	2.57 ± 0.067	2.19 ± 0.036	2.47 ± 0.034	2.11 ± 0.041
	Cutout	2.27 ± 0.085	1.83 ± 0.018	2.19 ± 0.021	1.82 ± 0.023
	AutoAug	1.91 ± 0.059	1.61 ± 0.024	1.80 ± 0.044	1.35 ± 0.056
CIFAR-10	Vanilla	3.87 ± 0.167	3.00±0.059	3.60 ± 0.197	2.75±0.040
	Cutout	3.38 ± 0.081	2.67 ± 0.043	2.83 ± 0.102	2.27 ± 0.034
	AutoAug	2.78 ± 0.134	2.32 ± 0.097	2.49 ± 0.128	1.98 ± 0.062
CIFAR-100	Vanilla	19.17 ± 0.270	17.33±0.110	17.13 ± 0.210	15.09±0.092
	Cutout	18.12 ± 0.114	16.04 ± 0.071	16.45 ± 0.136	14.34 ± 0.153
	AutoAug	17.79 ± 0.185	14.95 ± 0.088	15.43 ± 0.269	13.36 ± 0.245

Calibration Results: (lower is better)

PreActResNet18

Label Smoothing

Adv. Training

Flooding

MixUp

VGG16

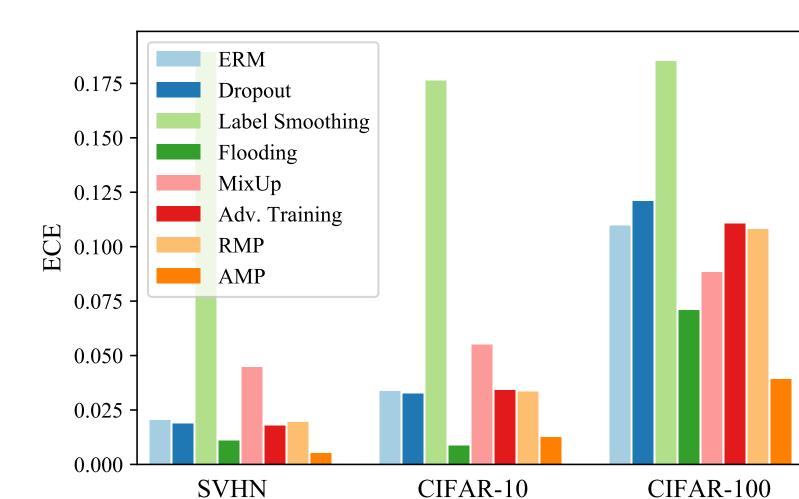
Dropout

Flooding

MixUp

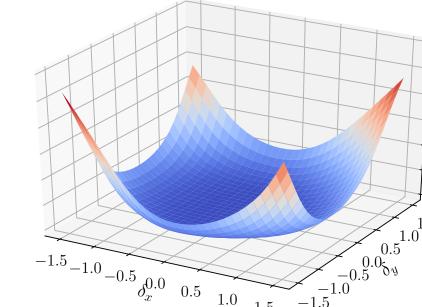
Label Smoothing

Adv. Training



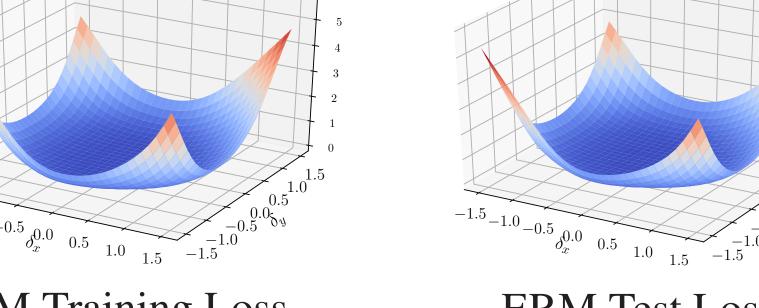
Flatness of the Selected Minima:

(a) SVHN

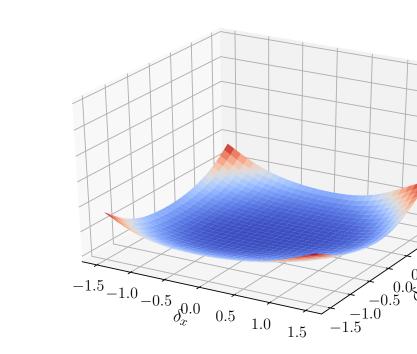




AMP Training Loss

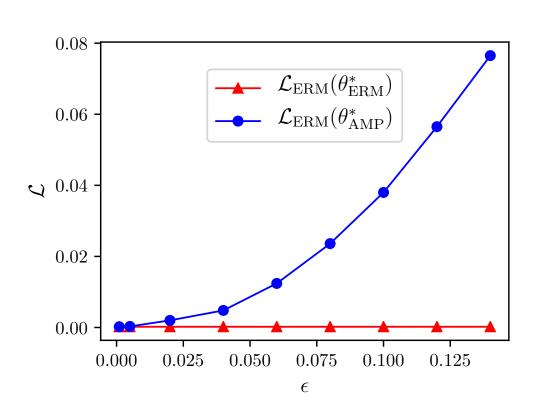


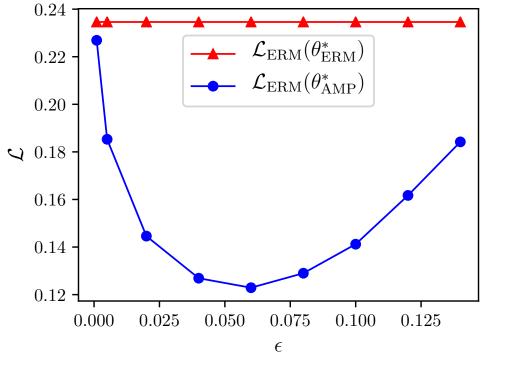
ERM Test Loss



AMP Test Loss

Loss Values with Varying Perturbation Size:





(a) CIFAR-10 Training Set

(b) CIFAR-10 Test Set

References:

- [1] Hochreiter et al. Flat minima. Neural Computation, 9(1):1-42, 1997.
- [2] Keskar *et al*. On large-batch training for deep learning: Generalization gap and sharp minima. In ICLR, 2017.
- [3] Li et al. Visualizing the loss landscape of neural nets. In NeurIPS, 2018.
- [4] Foret et al. Sharpness-aware minimization for efficiently improving generalization. In ICLR, 2021.

