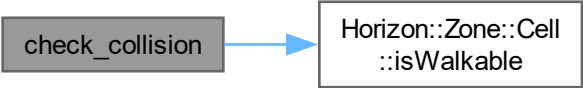


check_collision



```
graph LR; A[check_collision] --> B[Horizon::Zone::Cell::isWalkable]
```

The diagram consists of two rectangular boxes connected by a blue arrow. The left box is gray and contains the text 'check_collision'. The right box is white with a black border and contains the text 'Horizon::Zone::Cell::isWalkable'. A blue arrow points from the right side of the gray box to the left side of the white box.

Horizon::Zone::Cell
::isWalkable