

Image Super-Resolution: On its technical detail and subtasks

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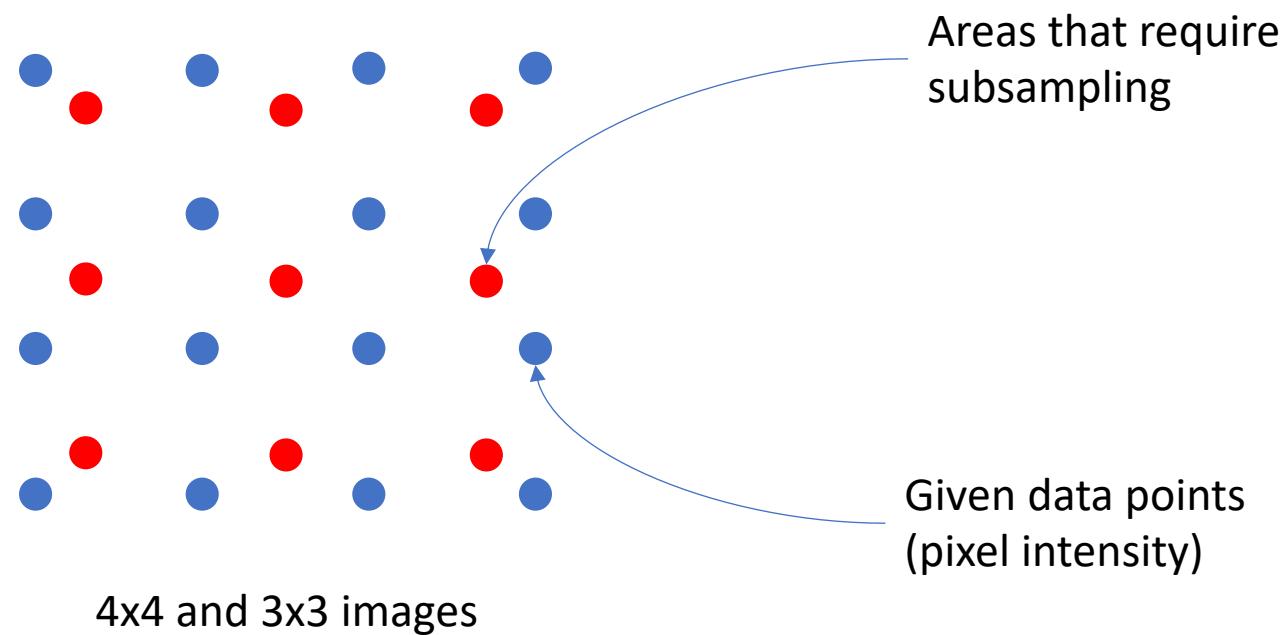
- What is SR?
- SR pipeline

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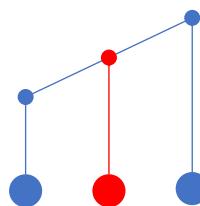
Preliminaries: Interpolation techniques for image resizing

- Changing image resolution (i.e. Number of pixels)

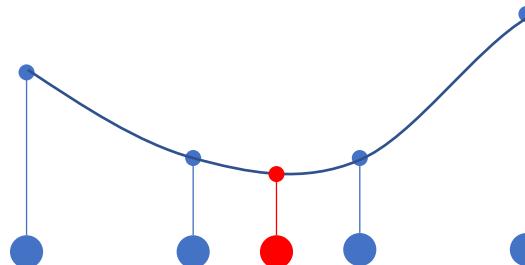


Preliminaries: Interpolation techniques for image resizing

1. Geometric interpolation methods (1d example)



Linear interpolation: $ax + b$
-> Need to solve a 2d linear system



Cubic interpolation: $ax^3 + bx^2 + cx + d$
-> Need to solve a **4d linear system**

Preliminaries: Interpolation techniques for image resizing

2. Convolution interpolation methods (reformulating interpolation problem)

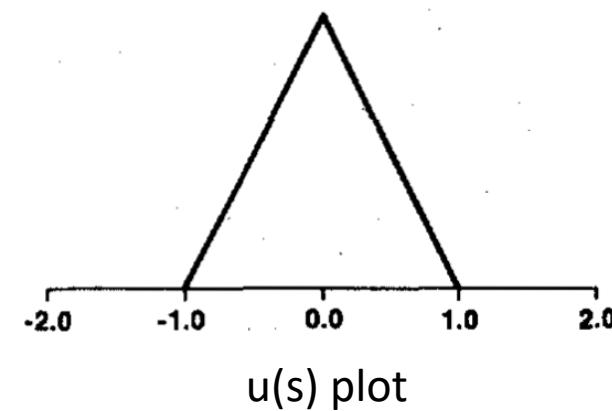
For equally spaced data, many interpolation functions can be written in the form

$$\underline{g(x) = \sum_k c_k u\left(\frac{x - x_k}{h}\right)}. \quad (1)$$

Among the interpolation functions that can be characterized in this manner are cubic splines and linear interpolation functions. (See Hou and Andrews [3].)

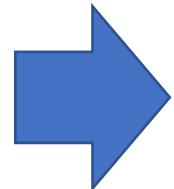
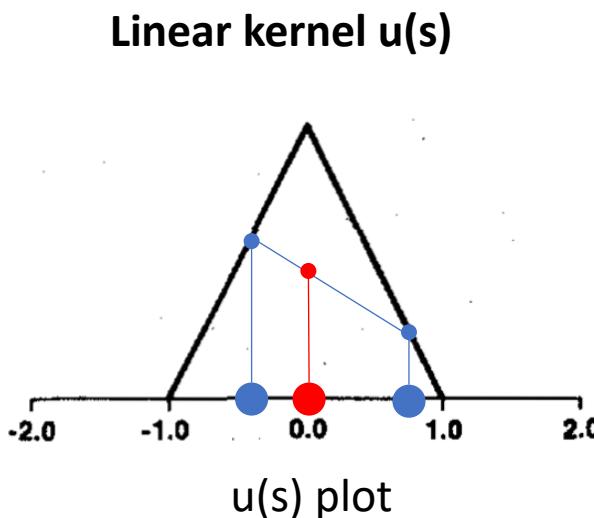
In (1), and for the remainder of this paper, h represents the sampling increment, the x_k 's are the interpolation nodes, u is the interpolation kernel, and g is the interpolation function. The c_k 's are parameters which depend upon the sampled data. They are selected so that the interpolation condition, $g(x_k) = f(x_k)$ for each x_k , is satisfied.

Linear interpolation



Preliminaries: Interpolation techniques for image resizing

2. Convolution interpolation methods (linear)



Same as linear interpolation!

- We can also reduce convolution interpolation method to cubic interpolation by using cubic kernel, but it still requires solving 4d linear systems.

$$g(x) = \sum_k c_k u\left(\frac{x - x_k}{h}\right)$$

Preliminaries: Interpolation techniques for image resizing

2. Convolution interpolation methods (efficient cubic)

For equally spaced data, many interpolation functions can be written in the form

$$\underline{g(x) = \sum_k c_k u\left(\frac{x - x_k}{h}\right)}. \quad (1)$$

Among the interpolation functions that can be characterized in this manner are cubic splines and linear interpolation functions. (See Hou and Andrews [3].)

In (1), and for the remainder of this paper, h represents the sampling increment, the x_k 's are the interpolation nodes, u is the interpolation kernel, and g is the interpolation function. The c_k 's are parameters which depend upon the sampled data. They are selected so that the interpolation condition, $g(x_k) = f(x_k)$ for each x_k , is satisfied.

Cubic convolution interpolation

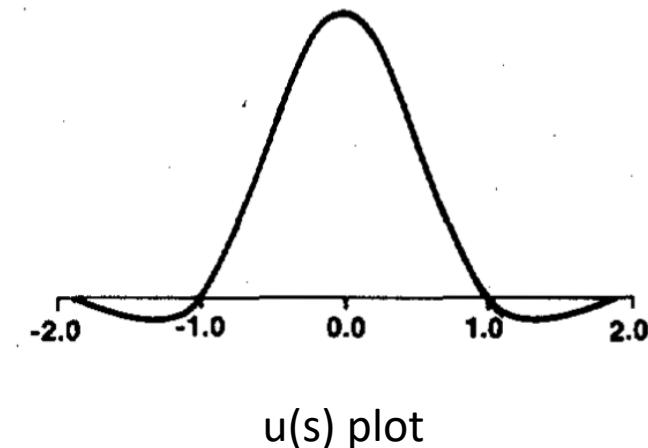
- 1. $u(0) = 1, u(n)=0$ for non-integer number n
(for computational efficiency)
- + 2. symmetric, 2 pieces of cubic polynomial
- 3. Differentiable in $x=n$, concave/convex property

Preliminaries: Interpolation techniques for image resizing

2. Convolution interpolation methods

Cubic convolution interpolation

$$u(s) = \begin{cases} (a+2)|s|^3 - (a+3)|s|^2 + 1 & 0 < |s| < 1 \\ a|s|^3 - 5a|s|^2 + 8a|s| - 4a & 1 < |s| < 2 \\ 0 & 2 < |s|. \end{cases}$$



Theoretical range of a is between -3 and 0 [2]
($a = -0.5, -0.75$ are used frequently)



Don't need to solve
4d linear systems

[1] Keys, Robert. "Cubic convolution interpolation for digital image processing." *IEEE transactions on acoustics, speech, and signal processing* 29.6 (1981): 1153-1160.

[2] Bernstein, Ralph. "Digital image processing of earth observation sensor data." *IBM Journal of research and development* 20.1 (1976): 40-57.

Preliminaries: Interpolation techniques for image resizing

3. Interpolation performance

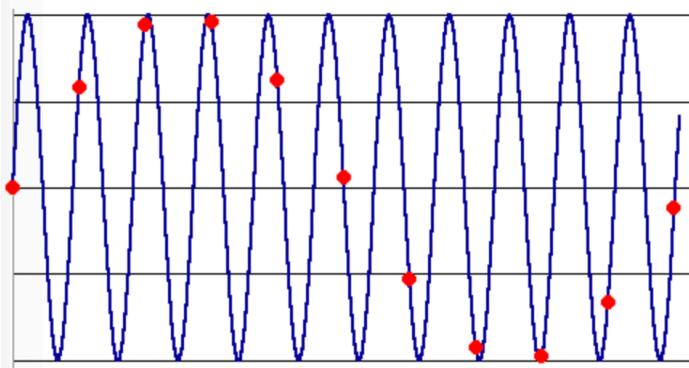
- i. Time complexity: **linear interp < cubic conv < cubic interp**
- ii. Image results: **linear interp < cubic conv < cubic interp**

4. Popular implementations (library)

- i. Malab imresize: cubic conv ($a = -0.5$)
- ii. Python PIL resize: cubic conv ($a = -0.75$)
- iii. OpenCV resize: cubic conv ($a = -0.75$)
- iv. `scipy.misc.imresize` => This is a wrapper of PIL
- v. `Scipy.interpolate.interp1d/2d` : cubic/bicubic interpolation
(don't use this for images)

Preliminaries: Aliasing

- When downsizing (downsampling) an image, some high-frequency components cannot be fit into the image grid.



Moiree Effect

Preliminaries: Aliasing

- We need to apply a low-pass filter (anti-aliasing filter) before downsizing an image!
- Matlab imresize simply broadens the cubic kernel to accomplish anti-aliasing



Without prefiltering



With prefiltering (**no aliasing, but blurring!**)

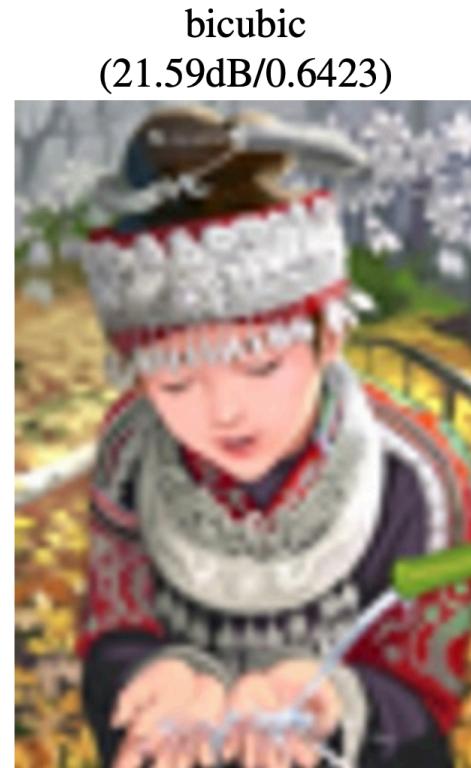
<https://stackoverflow.com/questions/26823140/imresize-trying-to-understand-the-bicubic-interpolation>

<https://kr.mathworks.com/matlabcentral/answers/232462-imresize-with-bicubic-downsampling>

https://eeweb.engineering.nyu.edu/~yao/EL5123/lecture8_sampling.pdf

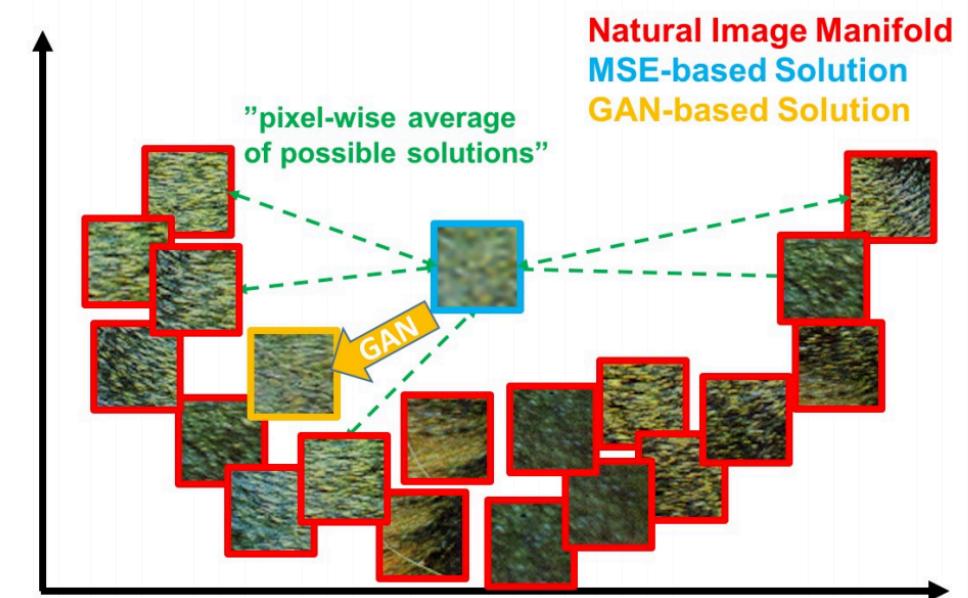
SR settings: What is SR?

- Increasing the resolution (number of pixels) of an image with **plausible high-frequency details**.

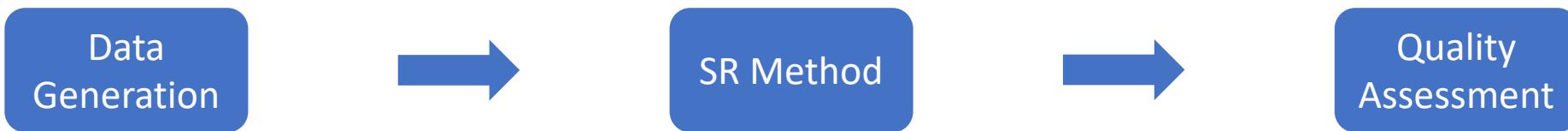


SR settings: What is SR?

- Increasing the resolution (number of pixels) of an image with plausible high-frequency details.
- SR is inherently an **ill-posed problem** because there are many plausible answer patches (high-resolution [HR]) to one low-resolution (LR) input.



SR settings: SR pipeline



SR settings: SR pipeline



- Make (HR, LR) pairs for training set.
- SR tasks typically assume a degradation setting from HR to LR.
- Simplest setting: Matlab imresize (bicubic conv) with scale s.
 - $\text{LR} = \text{imresize}(\text{HR}, s)$
- See **NTIRE challenges** for more information.

SR settings: SR pipeline



- An SR method that maps $\text{LR} \rightarrow \text{HR}$.
- Random crop, Flip, rotation used to augment training set.
- Same augmentation can be used to boost SR performance on test phase [1].

SR settings: SR pipeline



- Compare HR and SR result (estimated HR) to assess SR quality.
 - Usually removes (shave) the border of output image.
- PSNR, SSIM [1] is commonly used.
- Metrics based on human perception: LPIPS [2]
- No-reference metrics: NIQE, BRISQUE, PIQUE (usually used in generative model like SRFflow [3])

[1] Wang, Zhou, et al. "Image quality assessment: from error visibility to structural similarity." *IEEE transactions on image processing* 13.4 (2004): 600-612.

[2] Zhang, Richard, et al. "The unreasonable effectiveness of deep features as a perceptual metric." *Proceedings of the IEEE conference on computer vision and pattern recognition*. 2018.

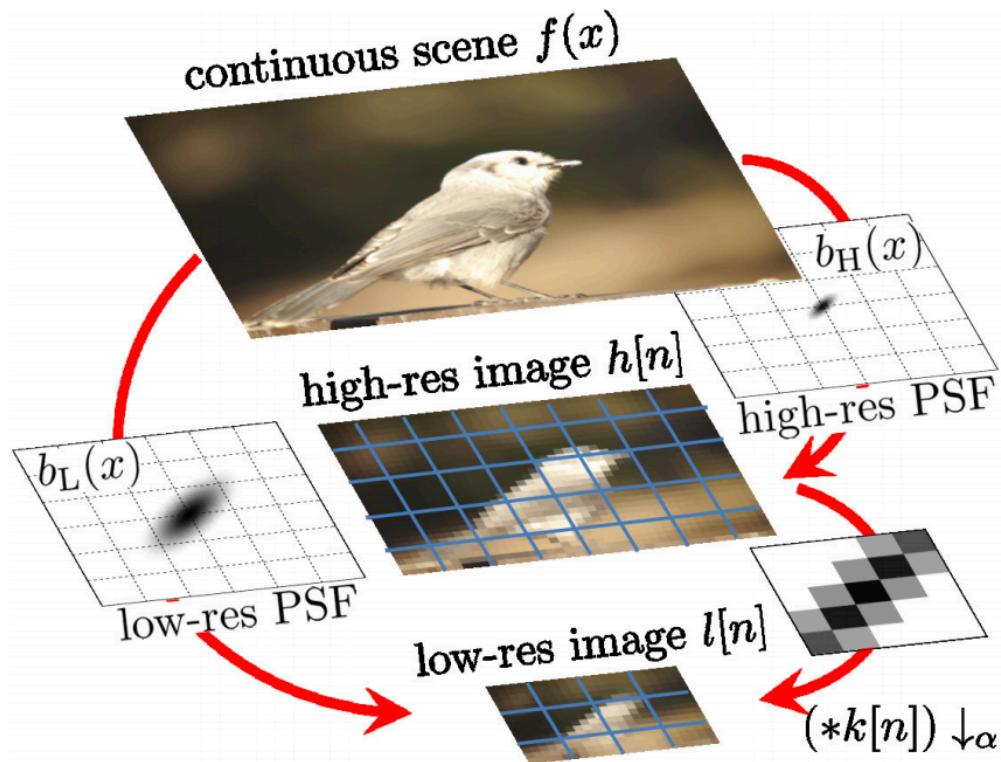
[3] Lugmayr, Andreas, et al. "Srfflow: Learning the super-resolution space with normalizing flow." *European Conference on Computer Vision*. Springer, Cham, 2020.

Subtasks: Different degradations

- Deep neural network-based SR methods are **very sensitive to degradation** (e.g. downsampling) method used in dataset.
 - Simple bicubic degradation setting doesn't make SR networks able to handle SR in general natural images.
- So various degradation settings have been proposed to resemble real-world settings.

Subtasks: Different degradations

- Blind SR: there is a **blur kernel** that we don't know.



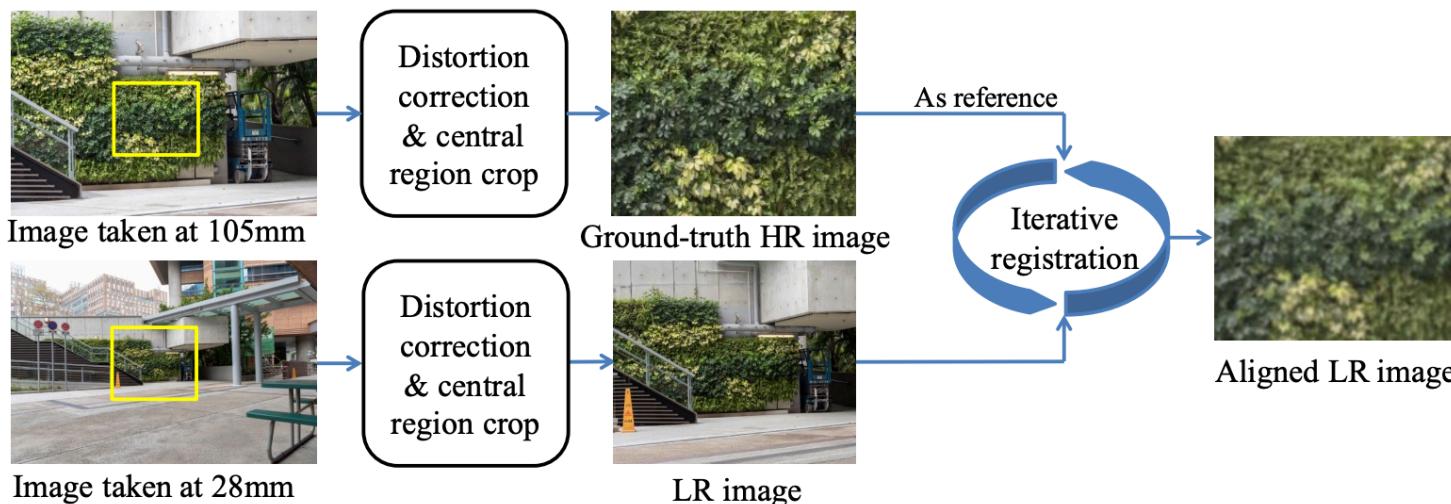
$$I^{LR} = \underline{(k \otimes I^{HR}) \downarrow_s + n}$$

Unknown kernel

Subtasks: Different degradations

- RealSR: Real camera setting => **Spatially varying kernel**

$$\mathbf{I}^L(i, j) = \mathbf{I}_{i,j}^H \odot \mathbf{k}_{i,j} + \mathbf{v}(i, j)$$



Subtasks: Other

1. SR on multiple scales:

- Conventional SR trains on one specific scale factor. In real-world scenarios, we may have to handle multiple (or arbitrary) scale with one parameter set (Meta-SR [1])

2. Content-aware SR:

- SR utilizing high-level (semantic) information (TextZoom [2], ProgFSR [3])

[1] Hu, Xuecai, et al. "Meta-SR: A magnification-arbitrary network for super-resolution." *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition*. 2019.

[2] Wang, Wenjia, et al. "Scene text image super-resolution in the wild." *European Conference on Computer Vision*. Springer, Cham, 2020.

[3] Deokyun Kim, et al. "Progressive Face Super-Resolution via Attention to Facial Landmark" *Proceedings of the 30th British Machine Vision Conference (BMVC)*, 2019.