Download

Download or clone the repository at:

https://github.com/i-n-g-o/attiny_examples

AVR Programming with the ATtiny45

Becky Stewart and Ingo Randolf

What is a microcontroller?

- Processor, memory, some other useful stuff.
- Arduino is a microcontroller platform in that it contains a microcontroller and a bunch of other things to make interacting with that microcontroller easier.

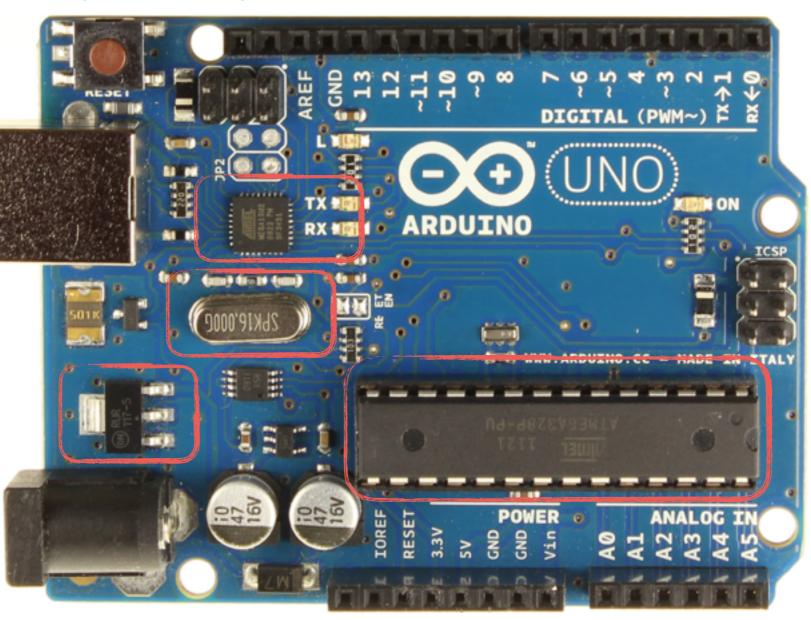
What is on the Arduino Uno board?

Microcontroller (ATmega328P) with bootloader

Voltage regulator

USB interface

External oscillator

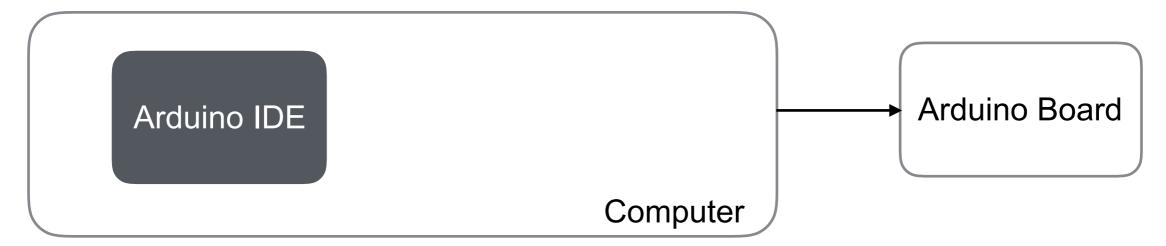


Why Not Just Use an Arduino?

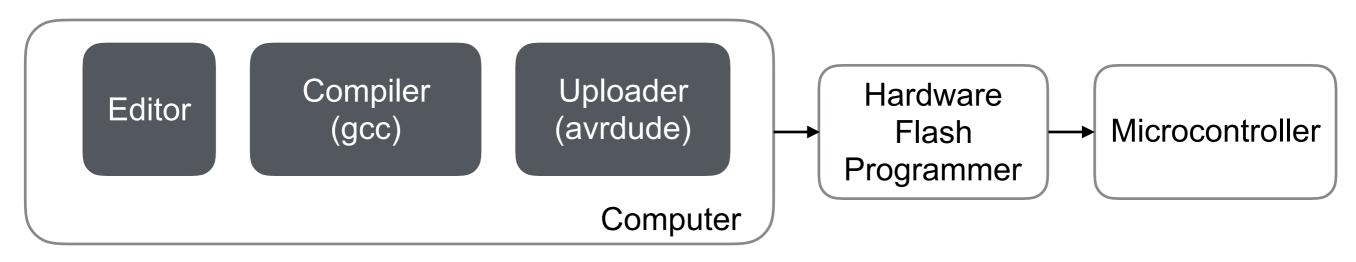
- Lots of extra stuff on there you might not need
- Cost
- It's physically big and awkward
- Want more flexibility on pins and wiring
- Arduino IDE not great
- Arduino library can be slow
- To understand what is actually going on

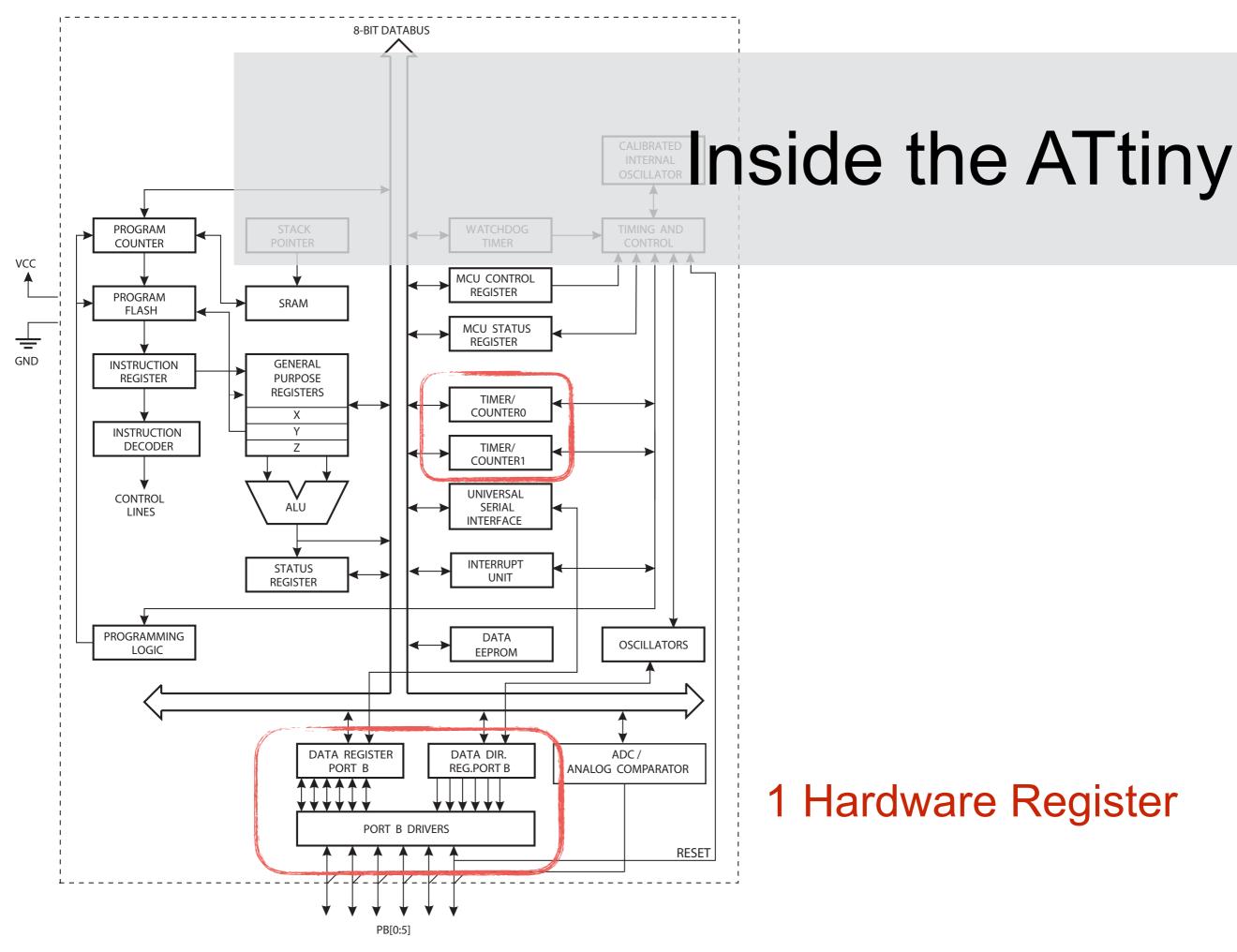
Toolchain

With Arduino

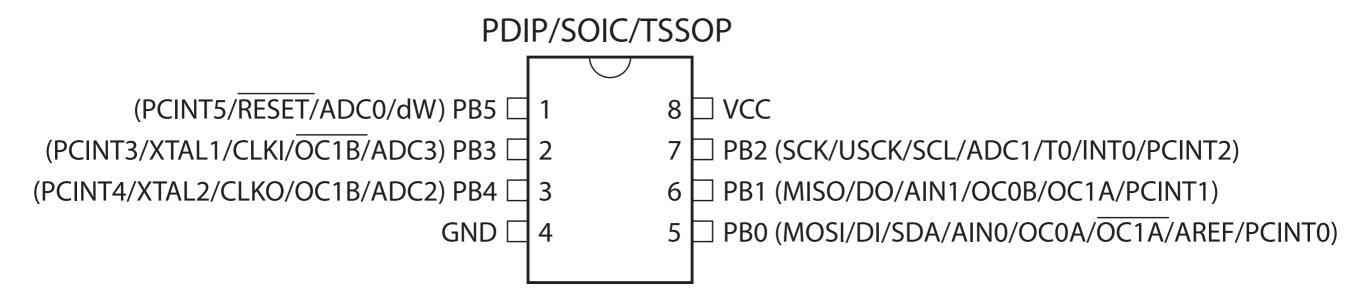


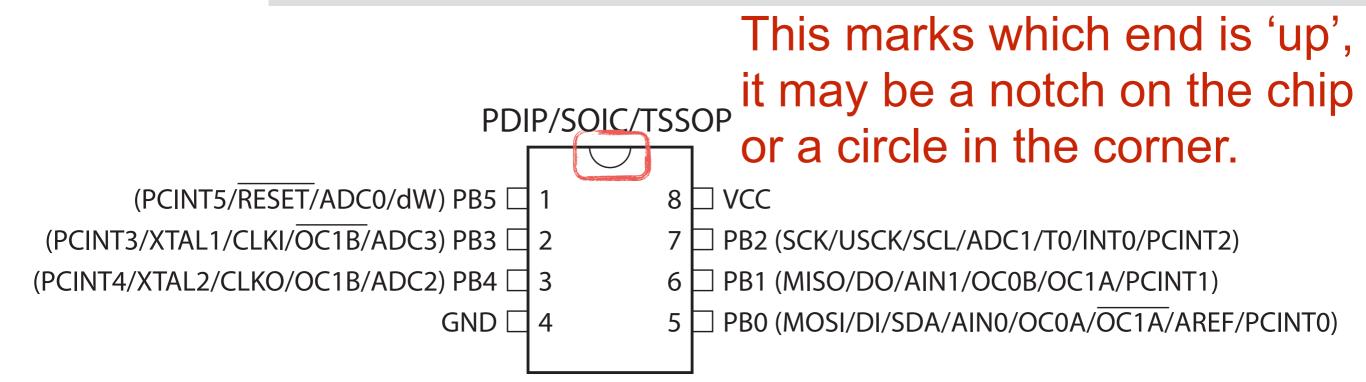
Without Arduino

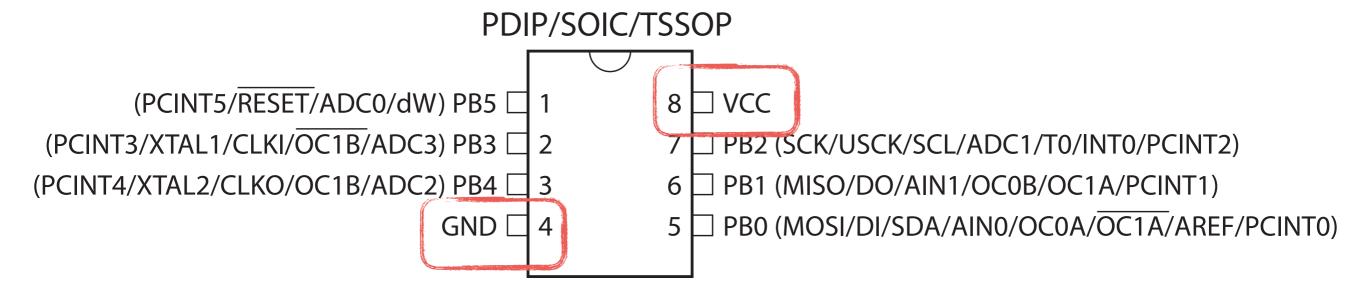


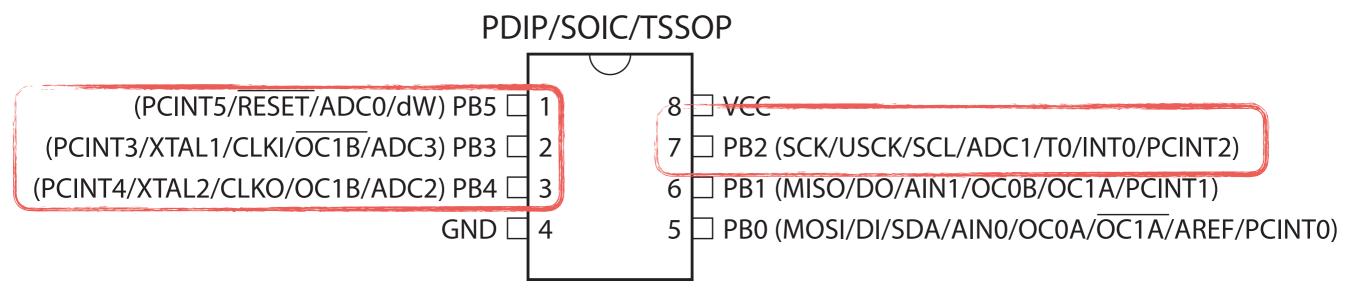


1 Hardware Register

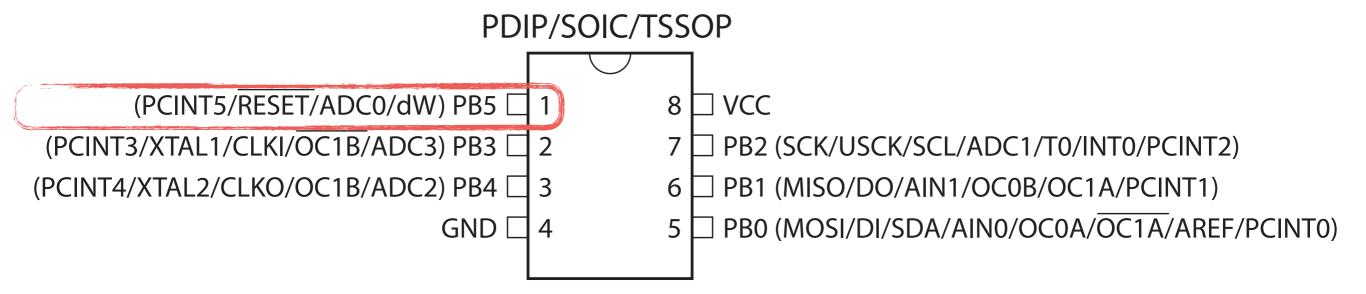








Analog Inputs



If RESET is held low for long enough, will reset the chip

Using avrdude

- Pro-tip: gently bend legs of ATtiny so fits cleanly into holder/breadboard
- In a terminal type:
 - > avrdude -p t45 -c usbtiny

Using avrdude

- Pro-tip: gently bend legs of ATtiny so fits cleanly into holder/breadboard
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 - > avrdude -p t45 -c usbtiny

 ATtiny45 Using a USBTiny programmer

Blinking

- Download code if you haven't already
- In a terminal window, use cd to go to the directory

```
/etextile-summercamp/00-blink_with_delay
```

- In the terminal type
 - > make
- Then type
 - > make install

```
/* Defines pins, ports, etc */
#include <avr/io.h>
                                         /* Functions to waste time */
#include <util/delay.h>
int main(void) {
 // ----- Inits ---- //
                             // Data Direction Register B: writing a one to the bit
 DDRB = 0b000001;
                             //enables output.
 // ----- Event loop ----- //
 while (1) {
                               /* Turn on first LED bit/pin in PORTB */
   PORTB = 0b0000001;
   delay ms(1000);
                                                           /* wait */
                              /* Turn off all B pins, including LED */
   PORTB = 0b00000000;
   _delay_ms(1000);
                                                           /* wait */
                                                  /* End event loop */
                                    /* This line is never reached */
 return 0;
```

```
#include <avr/io.h>
#include <util/delay.h>

/* Defines pins, ports, etc */
/* Functions to waste time */

same as Arduino
```

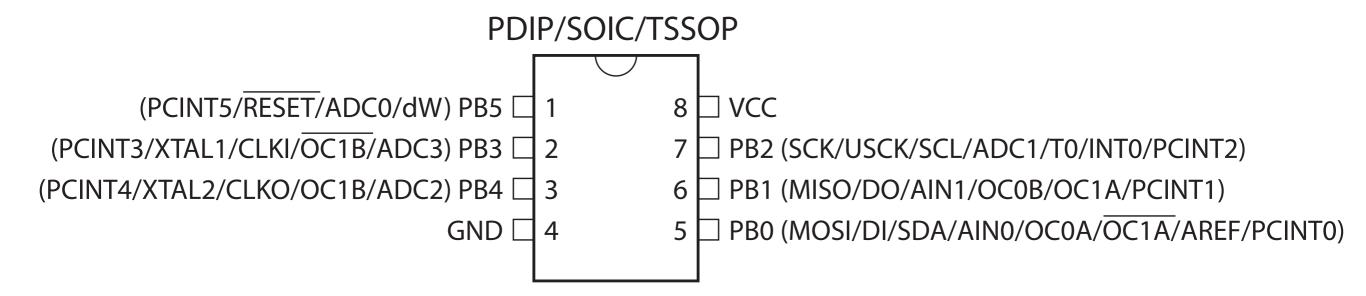
```
int main(void) {
 // ----- Inits ---- //
                            // Data Direction Register B: writing a one to the bit
 DDRB = 0b000001;
                            //enables output.
 // ----- Event loop ----- //
 while (1) {
                     /* Turn on first LED bit/pin in PORTB */
   PORTB = 0b0000001;
   delay ms(1000);
                                                          /* wait */
   PORTB = 0b00000000;
                     /* Turn off all B pins, including LED */
                                                          /* wait */
   _delay_ms(1000);
                                                /* End event loop */
                                    /* This line is never reached */
 return 0;
```

```
/* Defines pins, ports, etc */
#include <avr/io.h>
                                          /* Functions to waste time */
#include <util/delay.h>
                  same as Arduino
int main(void) {
                                    like setup() and pinMode()
  // ----- Inits ---- //
                              // Data Direction Register B: writing a one to the bit
 DDRB = 0b0000001;
                              //enables output.
  // ----- Event loop ----- //
 while (1) {
                               /* Turn on first LED bit/pin in PORTB */
   PORTB = 0b0000001;
   delay ms(1000);
                                                             /* wait */
   PORTB = 0b00000000;
                               /* Turn off all B pins, including LED */
   delay ms(1000);
                                                             /* wait */
                                                   /* End event loop */
                                     /* This line is never reached */
 return 0;
```

```
/* Defines pins, ports, etc */
#include <avr/io.h>
                                           /* Functions to waste time */
#include <util/delay.h>
                  same as Arduino
int main(void) {
                                    like setup() and pinMode()
  // ----- Inits ----- //
                              // Data Direction Register B: writing a one to the bit
 DDRB = 0b0000001;
                              //enables output.
  // ---- Event loop ---
                                like loop(), digitalWrite()
 while (1) {
                                and delay()
/* Turn on first LED bit/pin in PORTB */
   PORTB = 0b00000001;
   delay ms(1000);
                                                             /* wait */
                                /* Turn off all B pins, including LED */
   PORTB = 0b00000000;
   _delay_ms(1000);
                                                             /* wait */
                                                    /* End event loop */
                                      /* This line is never reached */
  return 0:
```

Hardware Registers

- Registers are (tiny) physical switches on the chip and you turn them on and off by setting them to 1 or 0
- The ATtiny45 has one set of registers name B
 - Bigger microcontrollers like the ATmega have more like C and D



Hardware Registers

- Data direction registers are like pinMode()
 - 1 sets that pin to output, 0 to input

 PORT is the register for setting outputs 0 for LOW and 1 for HIGH for each pin

PIN is the register for reading in inputs (not using this yet)

Binary and Hex Numbers

Decimal (Base 10) - 0 1 2 3 4 5 6 7 8 9

```
x = 49;
```

Binary (Base 2) - 0 1

```
x = 0b0101; // 5 in base 10
```

Hexadecimal (Base 16) - 0 1 2 3 4 5 6 7 8 9 A B C D E F

```
x = 0xFF; // 255 in base 10, 11111111 in base 2
```

Task

Change the delay time

Task

Change the LED pin

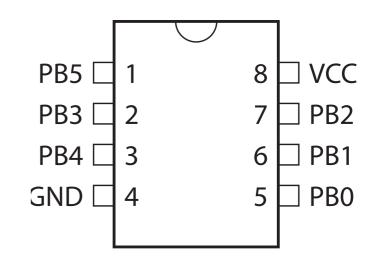
Build the LED circuit using a breadboard

Reading Input

In a terminal window, use cd to go to the directory

```
/etextile-summercamp/01-button_read
```

- On a breadboard connect a switch to PB1 and ground.
- In the terminal type
 - > make
- Then type
 - > make install



Reading Input

- The PINB holds the values of the input on each pin, whether HIGH or LOW
- Setting the PORTB HIGH for an input pin turns on the pull-up resistor

Bitmasks

OR

A	В	out
0	0	0
0	1	1
1	0	1
1	1	1

AND

A	В	out
0	0	0
0	1	0
1	0	0
1	1	1

XOR

Α	В	Out
0	0	0
0	1	1
1	0	1
1	1	0

Bitmasks

OR

A	В	out
0	0	0
0	1	1
1	0	1
1	1	1

AND

A	В	out
0	0	0
0	1	0
1	0	0
1	1	1

XOR

A	В	Out
0	0	0
0	1	1
1	0	1
1	1	0

$$1 << 2 = 00000100$$

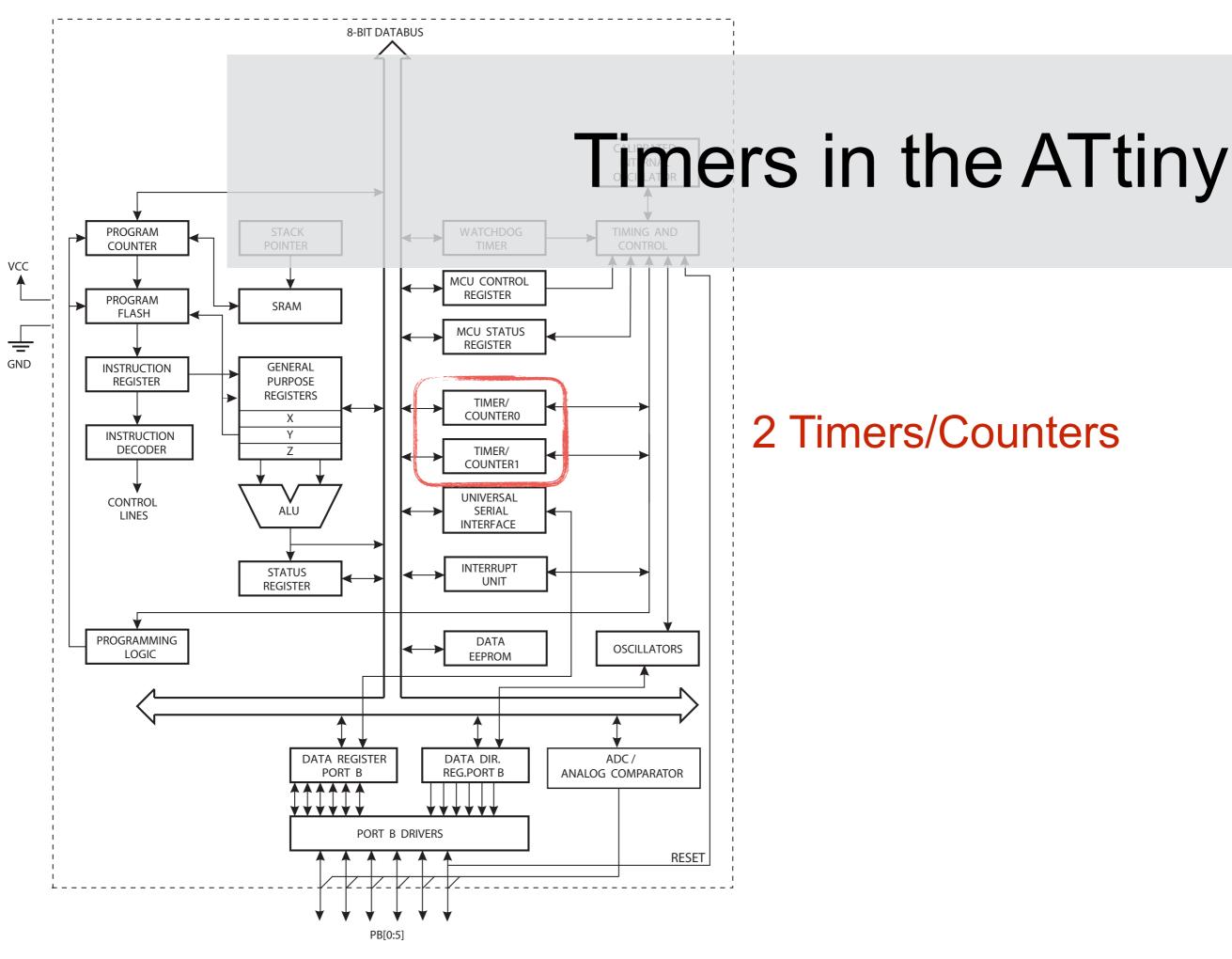
00000100 & 00010100 = 00000100 want to clear all bits and set the mask

00000100 | 00010100 = 00010100 want to leave all other bits alone and set the mask

0000100 ^ 00010100 = 00010000 want to leave all other bits alone and toggle the mask

Blinking (Reprise)

- We are forcing the microcontroller to sit and do nothing while it waits an amount of time.
- Instead, we can set an internal alarm clock so we can do other things and it will just tell us when time is up.
- Called the Timer Compare Unit.



2 Timers/Counters

Blinking (Reprise)

In a terminal window, use cd to go to the directory

```
/etextile-summercamp/02-blink_with_timer
```

- In the terminal type
 - > make
- Then type

```
>make install
```

Clear Timer on Compare (CTC)

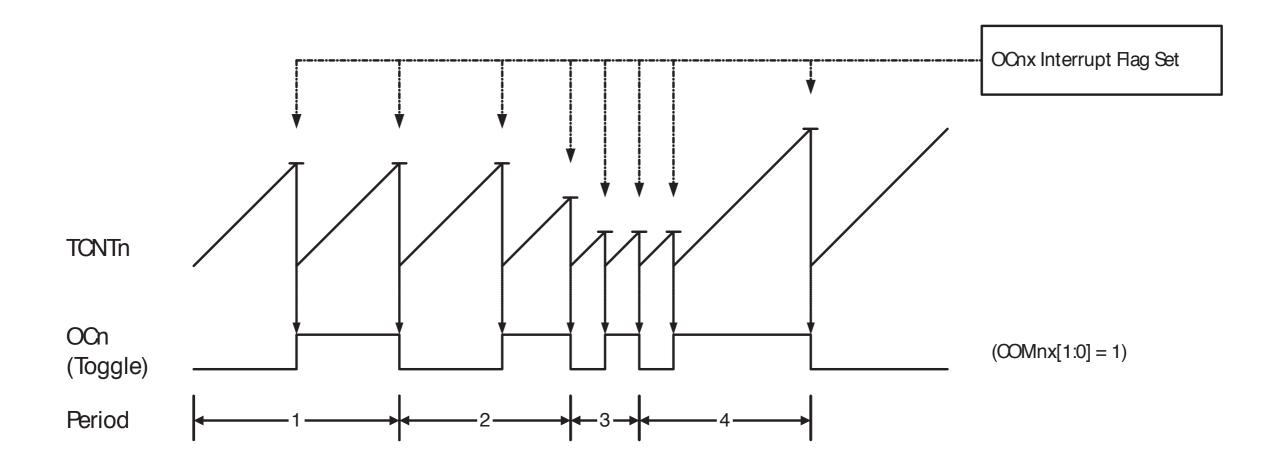
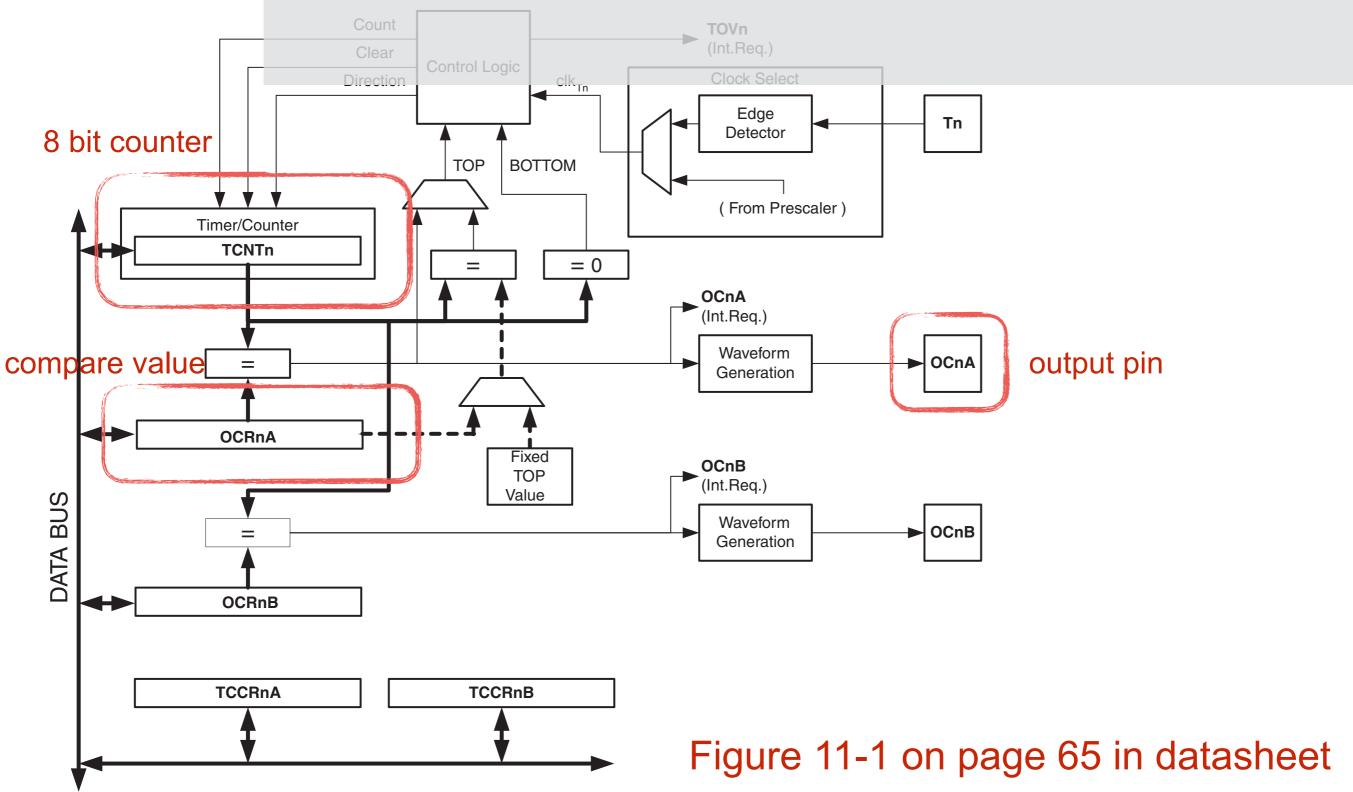


Figure 11-7 on page 72 in datasheet

8 bit Timer/Counter



ATMega

- ATMEGA168
- ATMEGA328P
- ATMEGA32U4

ATtiny

- ATTINY45-20PU
- ATTINY85V-20SU

ATMega

- ATMEGA168
- ATMEGA328P
- ATMEGAB2U4

ATtiny

Name of product family

- ATTINY45-20PU
- ATTINY85V-20SU

ATMega

- ATMEGA 168
- ATMEGA328P
- ATMEGA32U4

ATtiny

Size of Memory in KB

- ATTINY45-20PU
- ATTINY85V-20SU

ATMega

- ATMEGA168
- Atmel picoPower (low power consumption)
- ATMEGA328P
- ATMEGA32U4

USB controller

ATtiny

- ATTINY45-20PU
- Max clock speed
- ATTINY85V-20\$U

ATMega

- ATMEGA168
- ATMEGA328P
- ATMEGA32U4

ATtiny

Package

- ATTINY45-20PU
- ATTINY85V-20SU





Can run at 1.8V instead of 2.7V

Resources

- Make: AVR Programming by Elliot Williams
 - Example code: https://github.com/hexagon5un/AVR-Programming
- http://www.atmel.com/images/atmel-2586-avr-8-bit-microcontrollerattiny25-attiny45-attiny85_datasheet.pdf
- http://www.avrfreaks.net/
- http://www.ladyada.net/learn/avr/index.html