

MusAssist: A Domain Specific Language for Music

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Chapter 1

Introduction

Domain specific languages, or DSLs, are programming languages tailored towards a specific application. Formally, a DSL is defined as “a computer programming language of limited expressiveness focused on a particular domain.” This definition encompasses four critical features: (1) the computer programming language (PL) itself, (2) a “language nature” (i.e. a sense of fluency from the way individual expressions can be combined), (3) limited expressiveness (since the purpose of a DSL is to be used in an particular domain, it should not have the complexity of a general purpose language, or GPL), and (4) domain focus (the motivation to create the DSL in the first place). Note that domain focus is simply a consequence of the limited expressiveness of the DSL (Fowler and Parsons [2011]).

DSLs can generally be placed into three categories: external DSLs, internal DSLs, and language workbenches. An *external DSL* is a PL that is separated from the primary PL of its application. It normally uses a custom syntax, but sometimes borrows the syntax of an existing PL (an example of this is XML). The code for an external DSL is conventionally parsed by code of the host application using text parsing methods. Besides XML, common external DSLs include regular expressions, SQL, and Awk (Fowler and Parsons [2011]).

An *internal DSL* is embedded in an already existing GPL, making use of its syntax and semantics. A program written in an internal DSL is already valid code in the host GPL, but only makes use of a small subset of the GPL’s powerful expressive features in order to handle a specific aspect of the domain. Thus, a “custom feel” is achieved using the GPL. Lisp is the hallmark GPL for creating internal DSLs, but Ruby is also common. Rails, one of Ruby’s best-known frameworks, is frequently considered to be a collection of internal DSLs (Fowler and Parsons [2011]).

Finally, a *language workbench* is a customized IDE for building and defining DSLs (Fowler and Parsons [2011]).

Music itself has a highly structured framework, and a musical score itself can be thought of as having many of the formal features of a PL. With the increased flexibility afforded to a DSL via its limited expressiveness, it can be much more effectively tailored to the application (i.e. music) than an GPL could be. Depending on the goals of the programmer, a DSL can be used to target a particular aspect of music, whether that be notation, algorithmic composition, signal processing, or live coding with music performance.

MusAssist is an external DSL devised for music notation. It attempts to organically model a composer’s flow of thought by allowing them not only to write a

Chapter 2

Background

DSLs for music have not been studied as extensively as other application domains, but are a fascinating area of inquiry that explores the expressive power of languages and pushes the boundaries of computational creativity. The era of music DSLs began in 2008 with Ge Wang’s invention of the ChuckK audio processing language. ChuckK is actually a GPL broadly tailored towards music, as it spans the application domains of “methods for sound synthesis, physical modeling of real-time world artifacts and spaces (e.g., musical instruments, environmental sounds), analysis and information retrieval of sound and music, to mapping and crafting of new controllers and interfaces (both software and physical) for music, algorithmic/generative processes for automated or semi-automatic composition and accompaniment, [and] real-time music performance.” With ChuckK, Wang developed a language that is “expressive and easy to write and read with respect to time and parallelism,” thus providing users with a “platform for precise audio synthesis/analysis and rapid experimentation in computer music.” (Wang [2008]).

A multitude of programming paradigms have been used for music DSLs, including declarative programming, functional programming, object-oriented programming, synchronous programming, and subcategories of synchronous programming called strong-timed programming and mostly-strongly-timed programming. The choice of programming paradigm for a music DSL depends on the specific musical subdomain the language targets. For instance, a DSL intended to handle musical signal processing or live coding (i.e. applications that have to do with the time dimension of music) would benefit from using one of the synchronous programming paradigms.

Notably, though, the choice to make a DSL external or internal is not related to the choice of programming paradigm. In general, according to Cuadrado, Izquierdo, and Molina, internal DSLs are preferred over external DSLs when there is no significant tradeoff in performance, the runtime infrastructure of the parent language is easily reused, and the target audience is comfortable using the parent language. Otherwise, an external DSL would most likely be a better choice. These same considerations apply when designing a DSL for music. (Cuadrado et al. [2012]).

This chapter serves as a review of the existing literature on the better-known DSLs for music. The chapter is organized as follows. Section 2.1 examines the programming paradigms commonly utilized in DSLs for music. Section 2.2 is a review of some common external DSLs for music, and Section 2.3 looks at examples of existing internal DSLs for music. Finally, Sections 2.4 and Section 2.5 consider applications of music DSLs in the fields of algorithmic composition and human-computer interaction (HCI), respectively.

2.1 Programming Paradigms Used in Music DSLs

2.1.1 Declarative Programming

In contrast to the more commonly encountered paradigm of imperative programming, declarative programming is a programming model that eliminates control flow in favor of simply stating, or declaring, what the desired action or result is. Declarative programming is commonly used by DSLs in database management, and relies on pre-existing language features to execute the desired action without relying on control flow structures such as conditional logic and loops. In other words, declarative programming emphasizes *what* the final result is, while imperative programming focuses on *how* to get there. As an analogy, if someone hails a taxi, they *declare* to the driver where they wish to go – they do not give him turn-by-turn (i.e. imperative) directions. (Bertram [2021])

Musical markup languages such as Michael Good’s MusicXML and LilyPond fall under this category.

2.1.2 Functional Programming

Functional programming is a programming paradigm centered around building functions for immutable values. It emphasizes *pure functions*, or functions that never alter variables but instead produce new ones as output. Pure functions can also be thought of as functions without *side effects*, or when the function neither relies on nor modifies anything outside of its parameters. The GPL Haskell is perhaps the most famous example of a functional PL (Joury [2020]).

Du Bois and Ribeiro describe HMusic, a DSL for music programming and live coding that is embedded in Haskell (thus giving HMusic the power of functional programming). HMusic provides abstractions for patterns and tracks, defined inductively. The inspiration behind HMusic was to let artists express themselves through software. The abstractions for patterns and tracks in HMusic greatly resemble grids from sequencers, drum machines, and digital audio workstations (Bois and Ribeiro [2019]).

2.1.3 Object-Oriented Programming

Rather than functions, object-oriented programming (or OOP) is centered around the objects that the developers want to create and use. The building blocks of OOP are classes (blueprints for objects), objects (instances of classes with custom-defined data), methods that describe an object’s behavior, and attributes that reflect the state of the object. OOP’s main principles are encapsulation (i.e. data-hiding – all important information is hidden within an object with only the most important data exposed), abstraction (objects only expose internal mechanisms that are useful and generalizable for other objects), inheritance (in which classes reuse code from other classes), and polymorphism (in which objects can share behaviors and assume many forms) (Gillis and Lewis [2021]).

Nishino et al describe LC, an external DSL with dynamic and strong typing for computer music. LC is an object-oriented PL and is *prototyped – based* (as opposed to class-based) (Nishino et al. [2013]). In a prototype-based language, “each object defines its own behavior and has a shape of its own.” This is in contrast to class-based languages like Java, where “each object is an instance of a specific class.” In particular, prototype-based languages allow for *slots* (i.e. fields/methods) to be added to an object dynamically, after it has been created. Prototype-based languages therefore open up large amounts of flexibility and tolerance in relation to the dynamic modification of the system

at runtime. LC adopts prototype-based programming at the levels of compositional algorithms and sound synthesis (specifically, the user can build and modify a unit-generator graph dynamically) (Nishino et al. [2014]).

2.1.4 Synchronous Programming

Synchronous programming is a programming paradigm in which operations take place sequentially, or linearly, as opposed to asynchronous programming, where operations occur in parallel. This means that in synchronous programming, long-running operations can be “blocking” – i.e. the program cannot proceed to the next operation until the current operation has completed and returned some outcome (DeepSource). Synchronous PLs are often aimed towards programming reactive systems (Petit and Serrano [2020]).

Petit and Serrano describe Skini, a programming methodology and execution environment they created for “interactive structured music,” where the composer would program their scores in the HipHop.js synchronous reactive language. The scores are then executed (i.e. played) live, and involve audience interaction. The purpose of Skini is to help composers create a balance between the precise determinism of written composition and the nondeterminism of social interaction. Skini uses synchronous DSLs rather than GPLs as the “temporal constructs” of synchronous PLs (parallelism, sequence, synchronization, and preemption) can directly represent musical scores, and their relative flexibility allows composers to easily try out different ideas (Petit and Serrano [2020]).

2.1.5 Strongly-Timed Programming

Strongly-timed programming is a type of synchronous programming first introduced by Ge Wang in 2008 in his development of the ChuckK audio programming language. He defines it as “well-defined separation of synchronous logical time from real-time” which helps the user to debug, specify, and reason about programs written in the language. Thus, one can create programs without having to consider external factors like “machine speed, portability and timing behavior across different systems.” The powerful deterministic concurrency offered by this model allows for extremely tightly woven control and audio computation, thus giving rise to a DSL that allows the programming to transition seamlessly from digital signal processing, at the sample level, to more “gestural levels of control.” (Wang [2008]).

Nishino et al. build upon Wang’s work in strongly-timed programming. They further refine the definition of strongly-timed programming to be a variation of synchronous programming integrating explicit control of logical synchronous time into an imperative PL in order to achieve precise timing behavior that is predicated on the “ideal synchronous hypothesis,” in which that “all computation and communications are assumed to take zero time (that is, all temporal scopes are executed instantaneously).” Nishino et al.’s DSL LCSynth, the parent language of their object-oriented DSL LC, uses strongly-timed programming address the issue of imprecise timing behavior in microsound synthesis (Nishino [2012]).

Nishino et al. go on to introduce yet another paradigm called *mostly-strongly-timed programming* that is an extension of strongly-time programming. In mostly-strongly-timed programming, in addition to the principles of strongly-timed-programming, there is also support for explicit context switching between synchronous (i.e. non-preemptive) behavior and asynchronous (i.e. preemptive) behavior whose execution can be suspended at any arbitrary time. Nishino et al.’s object-oriented DSL LC makes use of mostly-strongly-timed programming (Nishino [2012]).

2.2 Survey of External DSLs for Music

2.2.1 LilyPond

2.2.2 PyTabs

Simić et al. present PyTabs, a DSL they designed and created for simplified musical notation. PyTabs allows the user to describe a composition comprising many sequences that can be provided in tablature or chord notation. PyTabs also provides functionality for playing a piece written in it. The authors propose a solution via PyTabs to problems in simplified music notation (specifically, the visual problem of tablature notation, and the lack of standardization of how to specify note duration in tablature notation) by standardizing these issues into a formal language. They used Python to implement PyTabs, but PyTabs is not embedded in Python; it is an external DSL (Simić et al. [2015]).

In PyTabs, the logic for parsing tablature notation is extracted into a generic parser, and then per-instrument parsing is defined later in the concrete implementation. Chord construction consists of one of the 12 semitones, a number representing octave, and a decoration (i.e. major, minor) that indicates the quality of the chord. In the future, the authors plan to add support for more instruments, as well as the ability to generate standard musical notation from PyTabs, and vice versa (Simić et al. [2015]).

2.2.3 LCSynth

Recall from Section 2.4 the DSL LSynth, created by Nishino et al, that was inspired by Wang’s strongly-timed GPL ChuckK. In the background information to LSynth, Nishino discusses the unit-generator concept, a software module from 1960 that uses “conceptually similar functions to standard electronic equipment used for electronic sound synthesis.” He also talks about microsound synthesis techniques, which differs from the traditional unit-generator concept in that it does not originate in electronic sound synthesis where the signal is a function of time. Instead, microsound synthesis involves many short sound particles (microsounds) that overlap to create the total sound. The current issue with microsound synthesis is that most computer music PLs are not capable of handling the precise timing behavior required (for instance, most general purpose PLs cannot do this) (Nishino [2012]).

Nishino et al. came up with a novel abstraction of the sound synthesis framework, as well as a new programming concept for computer music. Nishino et al. also consider the difficulty of microsound synthesis to be an issue in the abstraction of the underlying sound synthesis software framework in the PL’s design, i.e. an incompatibility between the abstractions and the user’s understanding of the domain, which they call the “usability problem.” (Nishino [2012]).

LCSynth integrates *counterpart entities* to the user’s perception of microsound synthesis techniques. This helps remove the *structural misfits* between the representations implemented in the design of currently used music DSLs and the user’s individual understanding of microsound synthesis techniques. However, LCSynth is not a stand-alone PL and works solely in the sound-synthesis domain. This is where Nishino et al.’s DSL LC comes in. It fully integrates LCSynth into its design. (Nishino [2012]).

2.2.4 LC

Nishino et al describe LC, a strongly-timed prototype-based language of dynamic and strong typing that was originally intended to be a control language for LCSynth. LC supports lexical closure, lightweight concurrency (i.e. lexically scoped name binding in a PL with first-class functions), and live computer music. These features enhance dynamism in the language, such as through live coding and rapid prototyping, in order to assist the artistic endeavors of the user. Live coding is “a computational arts practice that involves the real-time creation of generative audio-visual software for interactive multimedia performance.” Interpreted scripting languages are preferable for live coding, but DSLs specific to music are often even better (Nishino et al. [2013]).

Nishino et al. discusses the static-typing vs dynamic-typing issue for such DSLs. Dynamic typing is preferred as it is “ideally suited for prototyping systems with changing or unknown requirements” and “indispensable for dealing with truly dynamic program behaviors.” Nishino et al. also chose to make LC strongly, rather than weakly, typed, in order to avoid random bugs arising from implicit type casting. Recall from Section 2.2 that LC is also an object-oriented PL and is *prototyped-based* (as opposed to class-based). LC is also *duck-typed* – i.e. it features a framework for “truer polymorphic designs based on what an object can support rather than that object’s inheritance hierarchy”). Furthermore, LC supports lightweight concurrency, which enables features such as quick creation/destruction of threads and less memory usage (Nishino et al. [2013]).

LC performs sound synthesis and program execution in logical synchronous time as strongly-typed programs in a single virtual machine. This allows for precise timing behavior. In addition, LC allows for a great amount of flexibility for runtime modification, which makes it suited for applications like live-coding performances on laptops (Nishino et al. [2013]).

Through LC, Nishino et al. also successfully address three current issues in music DSL design: (a) lack of support for dynamic modification of a computer music program, (b) lack of support for precise timing behavior and other time-related features, and (c) the difficulty in microsound synthesis programming. These issues will correspond to the three core features of LC: (1) prototype based programming, both for algorithmic composition and for sound synthesis, (2) the use of the “mostly-strongly-timed programming” concept, and (3) the integration of objects and functions that represent microsounds with the corresponding operations for microsound synthesis. The first two of these features were discussed in Sections 2.2 and 2.4. The third feature utilizes algorithmic scheduling of microsound objects for its microsound synthesis framework. Every sample within a microsound object can be accessed directly, and utility methods are provided in order to manipulate multiple samples simultaneously. Unlike previous work with microsound synthesis, LC’s microsound synthesis does not depend on the unit-generator concept, and it also provides a generalized programming paradigm for real-time interactive computer music DSLs (Nishino et al. [2014]).

2.2.5 mimium

Matsuura and Jo describe a novel full-stack DSL called *mimium* (an acronym for **minimal** – **musical** – **medium**) that combines temporal-discrete control and signal processing in a single PL. It can describe everything from low-level signal processing, all the way to discrete event processing in unified semantics. *mimium* is user-friendly; it has intuitive imperative syntax and supports stateful functions as Unit Generators just as one would normally define and apply functions. The LLVM compiler infrastructure is used so that the runtime performance equals that of lower-level languages. *mimium* adds the least possible number of features related to sound, and it also implements a

general purpose functional PL. Thus, compiler implementation is simplified, and language self-extensibility is increased (Matsuura and Jo [2021]).

Though *mimum* is an external DSL, its syntax is modeled after that of Rust due to the shorter reserved words (suitable for fields) that can perform fast prototyping like music. The basic syntax includes function definitions and calls as well as conditionals (if-else statements). *mimum* also uses the functional model. For instance, a single *if* statement can be used as an expression that can directly return a value (Matsuura and Jo [2021]).

The architecture of *mimum*'s compiler resembles that of a general purpose functional language. It is based on the *mincaml* compiler and is implemented in C++. Recall that the compiler uses the LLVM infrastructure. In *mimum*, the only compiled functions of the LLVM intermediate representation that depend on the runtime system are one for task registration, and one for getting the internal time. Essentially all other code is compiled on memory and subsequently executed. Thus, *mimum* can achieve similar execution speed to low-level languages like C (Matsuura and Jo [2021]).

Two essential features of *mimum* allow the description of continuous signal processing as well as discrete control processing in unified semantics. The first is the syntax for deterministic task scheduling at the sample level, as well as the implementation of the schedule. For instance, *mimum*'s @ operator can specify the time at which to execute a function. In *mimum*, @ is combined with the *temporal recursion design pattern* that describes repetitive event processing as a function that calls itself recursively with a time delay. @ is used to increase readability in the implementation of temporal recursion. The second feature is a description of the semantics that are utilized to define the Unit Generator for signal processing. This is achieved by hiding state variables and combining only feedback connections and limited built-in functions with states (Matsuura and Jo [2021]).

2.3 Survey of Internal DSLs for Music

2.3.1 MusicXML

MusicXML

2.3.2 HMusic

Recall the DSL HMusic, embedded in the functional PL Haskell, that was first introduced in Section 2.1. On a more technical level, HMusic is an algebra (i.e. a set and its associated functions) for creating music patterns. The set of all possible patterns is defined inductively as an ADT (algebraic data type) in Haskell. The user can write recursive Haskell functions to operate on patterns, as patterns themselves are a recursive datatype in HMusic. HMusic also defines the ADT Track, which associates an instrument to a pattern. Tracks can be the parallel composition of two existing tracks, and HMusic has support for multi-tracks consisting of tracks of varying size composed in sequence. Finally, HMusic defines a set of primitives for playing tracks and live coding. Users can play songs written in HMusic, loop tracks, and modify tracks while they are being played. Live coding is implemented through a simple UI based on the concepts of looping and function application (Bois and Ribeiro [2019]).

2.3.3 T-calculus

The T-calculus is a more mathematical approach to an external music DSL design presented by Janin in 2016. He describes a new algebraic model for music writing and programming based on separating the contents of music objects (i.e. what music they define) and the usage of music objects (i.e. how they could be combined). He approaches this from a mathematical perspective. Specifically, he models music objects with a “tilted music graph” that can be combined using the “tilted sum” operator, which is both sequential and parallel. The resulting algebraic structure is an *inverse monoid* (a monoid is a set with an associative binary operation and an identity element, and an inverse monoid is a monoid where each element in the set has a unique multiplicative inverse). To implement this, Janin developed a high level DSL called T-calculus embedded in Haskell. T-calculus is reactive, hierarchical, and modal. (Janin [2016]).

Janin discusses how every music program can itself be viewed as a music score detailing the music to be played. From the perspective of music representation formalisms, music PLs must also be abstract enough to account for the composer’s creativity. Janin feels that classical western music notation can itself be seen as a music PL, but with the limitation that it only encodes music but cannot create it. In order to handle all such necessary elements of music representation as well as software engineering requirements, a unified theory of musical objects with algebraic properties must be described. A *music algebra* defines (1) the basic music objects to be used and (2) the combinators that allow the creation of complex music objects via simple ones. Janin’s goal is to define a music algebra from which he will derive a PL and a representation formalism. He does so by using *timed graphs* (directed acyclic graphs with labeled edges) that can then be combined via *tilted composition*. The vertices of timed graphs represent synchronization points, and the edge labels represent the duration of to-be-determined music objects or rests. Tiled composition involves the combining of two musical objects via the *synchronization step* (gluing the input root of the first object to the input root of the second) and the *fusion step* (removing potential ambiguity from the synchronization step). The resulting music algebra is created by adding additional edge attributes to the tiled timed graphs, which preserves the inverse monoid structure. (Janin [2016]).

2.4 Applications in Algorithmic Composition

2.4.1 Skini

Recall the DSL Skini from Section 2.3. Skini is in fact a synchronous internal DSL embedded in the GPL JavaScript that has intriguing applications in algorithmic composition. Music created in the Skini production environment is based on three principles: audience interaction determines what gets played next, the music constitutes sequences of patterns made up of elementary musical elements, and the music (though interactive) must still follow a rigid structure defined by the composer beforehand, which prioritizes artistic consistency over varied interactive performances. Skini may seem like jazz, but unlike jazz, the improvisation comes from the audience, rather than the composer (Petit and Serrano [2020]).

A Skini composition is an example of “synthesis by concatenation” of patterns. (The music is then produced by playing patterns according to audience selections). The composer will organize the patterns into *repetitive groups* and *tanks* (groups without repetition). The program implementing the score will simulate a large state machine. States correspond to group activation (i.e. the ability for the audience to choose a group) and de-activation, and transitions will model the audience

interaction and passing time. For the program, the authors use HipHop.js, a synchronous reactive language that is a multi-tier extension of JavaScript, in order to simplify the programming of the complex temporal behaviors inherent to musical scores. HipHop.js executes steps known as *reactions* or *instants*. Steps execute statements in sequence or in parallel; statements communicate using *broadcast signals*, each of which has a unique *present/absent status* (Petit and Serrano [2020]).

Finally, the Skini execution environment of the HipHop.js program has two essential data structures: the “matrix of available groups of patterns” (which is controlled by the execution of the HipHop.js score, and identifies at every moment which groups and tanks are activated) and “pattern queues” (which are provided by the audience and subsequently used by the synthesizers). Skini has been used in real-life live performances, in both jazz and classical settings.(Petit and Serrano [2020]).

2.4.2 Advantages of using DSLs over Virtual Machines (VMs) for Music

It is reasonable to consider that perhaps other avenues of computation, such as Virtual Machines (VMs), would be more effective to work with music than a DSL. However, Sulyok et al. demonstrate otherwise. They look into the effect of embedding various levels of musical data in VM architectures, as well as “phenotype representations” of an algorithmic music composition system. The authors consider two distinct sets of instructions for a linear genetic programming framework: the first is Turing-complete register machine with no knowledge of the nature of its output, and the other is a DSL tailored to music composition, designed around awareness of its output. DSL instructions include transfer, branching, and conditional instructions (Sulyok et al. [2019]).

The “phenotype” is the output of the VM. It comprises a sequence of notes, where a note is defined by duration and pitch. (Linear genetic programming is a kind of genetic programming in which the programs in the population get represented as a linear sequence of instructions from a PL). The fitness metric for the genetic programming framework was derived by the extraction of musical elements from a corpus of Hungarian folk songs. These same elements were extracted from the phenotype and assessed for maximum similarity to the corpus (Sulyok et al. [2019]).

In total, the authors considered six configurations, by using two VM architectures (the is a general-purpose von Neumann machine, or the GP machine, and the other is the DSL machine), and three different pitch schemes. The authors found that the DSL machine outperformed the GP machine even from early generations. Therefore, the instruction set tailored towards music increases the chance that even a truly random genetic string would lead to a desirable output (Sulyok et al. [2019]).

2.5 Applications in HCI

2.5.1 Computational Counterpoint Marks

Martinez presents a novel approach for extending the traditional staff domain (i.e. the domain of Western classical music notation, also known as Common Western Music Notation (CWMN)) to the PL domain. The syntax of his external DSL is intended to model the interaction between people and computers in a live electronics music performance. Therefore, both humans and computers will be able to understand the notation. This allows for a unified music representation for live performance that is human-readable and does not depend on technology (Martinez [2021]).

Martinez extends CWMN to the interactive domain through the creation of abstract-verbal statements called *Computational Counterpoint Marks* on the score phonetic-dimension. Computational Counterpoint Marks are human-readable annotations acting as expression-marks added to a score. They accurately describe the logic of an interaction between the performer and the computer. This enhances the accompanied graphic signs, leading to a unified and human-readable representation of an interactive piece’s performance logic. Furthermore, novel score annotations can also be understood by a computer via the digital score. This means that the musical score itself actually becomes the source code of a piece’s performance logic, which allows the computer to perform live during a concert. Finally, Martinez considers the time domain. Specifically, he proposes symbolic rather than absolute time representation that is based on traditional score notation. Martinez’s model maps symbolic time to absolute time through an estimate based on updates during performance about the current symbolic time (Martinez [2021]).

2.5.2 Research through Design

The development of Nishino et al.’s original external DSL LCSynth was approached through the HCI method ‘Research through Design’ (RtD), in which designers and researchers develop “a product that transforms the world from its current state to a preferred state” and “the artifacts produced in this type of research become design exemplars, providing an appropriate conduit for research findings to easily transfer to the HCI research and practice communities.” RtD places an emphasis on the contribution of knowledge to academia rather than the design of a commercial product (Nishino [2012]).

Nishino et al. use RtD to develop a new DSL focusing on the problem of microsound synthesis. He came up with a novel abstraction of the sound synthesis framework, as well as a new programming concept for computer music. Recall from Section 4.3 that Nishino et al. consider the potential incompatibility between the abstractions and the user’s understanding of the domain that they call the “usability problem.” They address this from a formal perspective in their paper “LCSynth: A Strongly-Timed Synthesis Language that Integrates Objects and Manipulations for Microsounds,” which the reader may peruse for further reading in this area. (Nishino [2012]).

2.6 Summary

DSLs are a fascinating and effective way to bridge the conceptual gap between computing and music. Since Wang introduced Chuck in 2008, external and internal DSLs utilizing programming paradigms including functional programming, object-oriented programming, synchronous programming, strongly-time programming, and mostly-strongly-timed programming have made advances in handling issues in microsound synthesis and signal processing, such as in the LCSynth, LC, and mimium languages. On a higher level, DSLs like PyTabs, Skini, and Computational Counterpoint Marks have addressed the areas of music notation representation and algorithmic composition, as well as intersect with the field of HCI. Finally, the novel concepts of live coding and laptop music are considered with the DSLs HMusic and even LC.

Chapter 3

MusAssist Features and Syntax

Chapter 4

The MusAssist Compiler

4.1 Lexing

4.2 Parsing

4.3 Intermediate Representations

4.4 Code Generation

Chapter 5

Sample Programs

Chapter 6

Future Work

Chapter 7

Conclusion

Clearly, DSLs are a powerful mechanism to push the boundaries of computational creativity in the field of music. Unfortunately, DSLs for music have not been studied extensively and remain an extremely comparatively small area of research, though scholars such as Wang continue to lead research in institutions such as Stanford's CCRMA (Center for Computer Research in Music and Acoustics). By continuing to examine the creative expressive power of DSLs in music, we can continue to increase our understanding of the creative capabilities and extent of customization possible for a programming language.

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