Exercise (2.6) in Polchinski

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PROBLEM STATEMENT

Given the transformation law for the metric:

$$\delta g_{ab} = -\partial_a v_b - \partial_b v_a \tag{1}$$

determine the most general $v^a(\sigma)$ that leaves flat ddimensional Euclidian metric δ_{ab} invariant up to a local rescaling.

SOLUTION II.

The case of d=2 is covered extensively in String Theory textbooks, so we will concentrate our efforts on d > 2 here.

Notation

Everywhere below a, b, and c are three different indices: $a \neq b, b \neq c, a \neq c$. Note that it means that most of the derivation does not apply to d=2. This the reason why d=2 is special.

m and n are possibly equal, but both non-negative integers: $m \geq 0, n \geq 0$.

В. Derivation

The local rescaling invariance imposes following constraints:

$$\partial_a v_a = \partial_b v_b, \tag{2}$$

$$\partial_b v_a = -\partial_a v_b. \tag{3}$$

For d > 2 we can derive an additional constraint:

$$\partial_c \left(\partial_b v_a \right) = -\partial_c \left(\partial_a v_b \right) = -\partial_a \left(\partial_c v_b \right) = \tag{4}$$

$$\partial_a \partial_b v_c = \partial_b \left(\partial_a v_c \right), \tag{5}$$

which is equivalent to:

$$\partial_b \left(\partial_c v_a - \partial_a v_c \right) = 2 \partial_b \partial_c v_a = 0. \tag{6}$$

This immediately implies that v_a can't have terms with three different coordinate variables:

$$v_a = \sum_{\substack{m \ge 0, n \ge 0 \\ mn}} c_{mn}^{(ab)} (\sigma_a)^m (\sigma_b)^n,$$
 (7)

$$c_{m0}^{(ab)} = c_{m0}^{(ac)}. (8)$$

In fact, the space of solutions is even smaller. The term

$$v_a = (\sigma_a)^{m+2} (\sigma_b)^{n+1} + \cdots \tag{9}$$

is incompatible with constraints:

$$\partial_c v_c = \partial_a v_a = (m+2)(\sigma_a)^{m+1}(\sigma_b)^{n+1}, \qquad (10)$$

but v_c can't have a term proportional $(\sigma_c)(\sigma_a)^{m+1}(\sigma_b)^{n+1}$ due to (6). Therefore to

$$c_{(m+2)(n+1)}^{(ab)} = 0. (11)$$

As we shall see only finitely few of them are non-zero, and even less are independent of each other.

The first constraint (2) can be translated from differential equation

$$\partial_a v_a = \sum m c_{mn}^{(ab)} (\sigma_a)^{m-1} (\sigma_b)^n, \tag{12}$$

$$\partial_b v_b = \sum n c_{nm}^{(ba)} (\sigma_b)^{n-1} (\sigma_a)^m, \partial_a v_a = \partial_b v_b$$
 (13)

to a relation between coefficients

$$(m+1)c_{(m+1)n}^{(ab)} = (n+1)c_{(n+1)m}^{(ba)}. (14)$$

Similarly (3) translates to

$$(n+1)c_{m(n+1)}^{(ab)} = -(m+1)c_{n(m+1)}^{(ba)}. (15)$$

Combining (14) and (15) together we see that

$$c_{(m+2)n}^{(ab)} = -\frac{(n+2)(n+1)}{(m+2)(m+1)}c_{m(n+2)}^{(ab)},\tag{16}$$

which together with (11) implies that

$$c_{m(n+3)}^{(ab)} \simeq c_{(m+2)(n+1)}^{(ab)} = 0,$$
 (17)

$$c_{(m+4)n}^{(ab)} \simeq c_{(m+2)(n+2)}^{(ab)} = 0.$$
 (18)

Therefore the only coefficients that can be non-zero are

$$c^{(a)} \equiv c_{00}^{(ab)}, \ c_1^{(a)} \equiv c_{10}^{(ab)}, \ c_{01}^{(ab)},$$

$$c_{11}^{(ab)}, \ c_{12}^{(ab)}, \ c_3^{(a)} \equiv c_{30}^{(ab)}.$$

$$(19)$$

$$c_{11}^{(ab)}, c_{12}^{(ab)}, c_{3}^{(a)} \equiv c_{30}^{(ab)}.$$
 (20)

We can also work out relations between them. Using (14) and (15):

$$c_1^{(a)} = c_{10}^{(ab)} = c_{10}^{(ba)} = c_1^{(b)}, (21)$$

$$c_{01}^{(ab)} = -c_{01}^{(ba)}, (22)$$

$$c_{01}^{(ab)} = c_{01}^{(ba)}, (22)$$

$$c_{11}^{(ab)} = -2c_{02}^{(ba)} = 2c_{20}^{(ba)} = 2c_{2}^{(b)}, (23)$$

$$c_3^{(a)} = c_{30}^{(ab)} = \frac{1}{3}c_{12}^{(ba)} = -\frac{1}{3}c_{12}^{(ab)} = -c_{30}^{(ba)} = -c_3^{(b)}, (24)$$

but the (24) has to be zero

$$c_3^{(a)} = -c_3^{(b)} = c_3^{(c)} = -c_3^{(a)} = 0. {(25)}$$

Before writing out the most general form of v^a , let us count the number of independent solutions

$$\#\left\{c^{(a)}\right\} = d,\tag{26}$$

$$\#\left\{c_1^{(a)} = c_1^{(b)}\right\} = 1,\tag{27}$$

$$\#\left\{c_{01}^{(ab)} = -c_{01}^{(ba)}\right\} = \frac{d(d-1)}{2},\tag{28}$$

$$\#\left\{c_2^{(a)}\right\} = d,$$
 (29)

and the total

$$d+1 + \frac{d(d-1)}{2} + d \tag{30}$$

$$=\frac{2d+2+d^2-d+2d}{2} \tag{31}$$

$$= \frac{2d + 2 + d^2 - d + 2d}{2}$$

$$= \frac{d^2 + 3d + 2}{2}$$
(31)

$$=\frac{(d+1)(d+2)}{2}. (33)$$

C. Result

The most general form of solution is:

$$v^{a} = c_{0} + c_{1}(\sigma_{a}) + c_{2}(\sigma_{a})^{2}$$

$$+ \sum_{b} \left[c_{3}(\sigma_{a})(\sigma_{b}) + -2c_{4}(\sigma_{b})^{2} \right]$$

$$+ \sum_{b} c_{5} \left[(\sigma_{a})^{3} - \frac{1}{3}(\sigma_{a})(\sigma_{b})^{2} \right].$$
 (34)