

# Partial differential equations

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# Today's outline

## ① Introduction

## ② Instationary diffusion equation

- Discretization

- Solving the diffusion equation

- Non-linear source terms

## ③ Convection

- Discretization

- Central difference scheme

- Upwind scheme

## ④ Conclusions

- Other methods

- Summary

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Central difference scheme

Upwind scheme

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# Overview

## Main question

How to solve parabolic PDEs like:

$$\frac{\partial c}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} - u \frac{\partial c}{\partial x} + R$$

$$t = 0; 0 \leq x \leq \ell \Rightarrow c = c_0$$

with  $t > 0; x = 0 \Rightarrow -\mathcal{D} \frac{\partial c}{\partial x} + uc = u_{\text{in}} c_{\text{in}}$

$$t > 0; x = \ell \Rightarrow \frac{\partial c}{\partial x} = 0$$

accurately and efficiently?

# What is a PDE?

## Partial differential equation

An equation containing a function and their derivatives to multiple independent variables.

## Order of PDE

The highest derivative appearing in the PDE

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General second order ODE:

$$A \frac{\partial^2 f}{\partial x^2} + B \frac{\partial^2 f}{\partial x \partial y} + C \frac{\partial^2 f}{\partial y^2} + D \frac{\partial f}{\partial x} + E \frac{\partial f}{\partial y} + Ff = G$$

- Linear equation: Coefficients  $A, B, \dots, G$  do not depend on  $x$  and  $y$ .
- Non-linear equation: Coefficients  $A, B, \dots, G$  are a function of  $x$  and  $y$ .

# Classification of PDE's

$$A \frac{\partial^2 f}{\partial x^2} + B \frac{\partial^2 f}{\partial x \partial y} + C \frac{\partial^2 f}{\partial y^2} + D \frac{\partial f}{\partial x} + E \frac{\partial f}{\partial y} + Ff = G$$

The discriminant  $\Delta$  of a quadratic polynomial is computed as (note: only the higher order coefficients are important):

$$\Delta = B^2 - 4AC$$

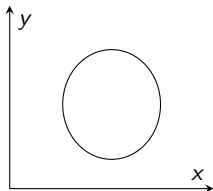
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- $\Delta < 0 \Rightarrow$  Elliptic equation  
(e.g. Laplace equation for stationary diffusion in 2D)
- $\Delta = 0 \Rightarrow$  Parabolic equation  
(e.g. instationary heat penetration in 1D)
- $\Delta > 0 \Rightarrow$  Hyperbolic equation  
(e.g. wave equation)





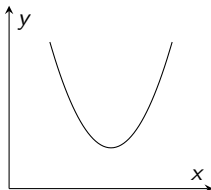
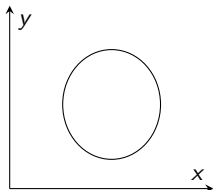
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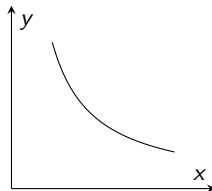
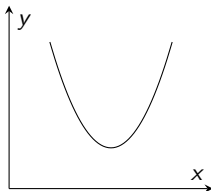
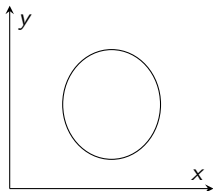
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# Importance of classification

Different PDE types require different solution techniques because of the difference in range of influence:

- *Characteristics*

Curves in  $xy$ -domain along with signal propagation takes place

- *Domain of dependence of point  $P$*

points in  $xy$ -domain which influence the value of  $f$  in point  $P$

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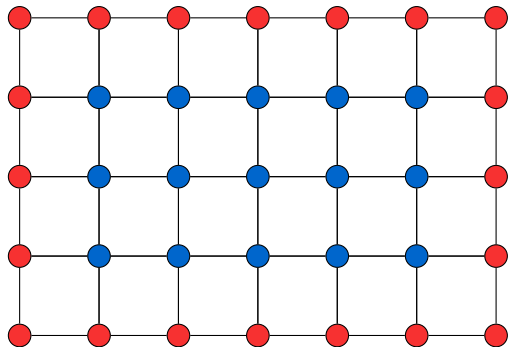
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## Example elliptic PDE (boundary value problems: BVP)



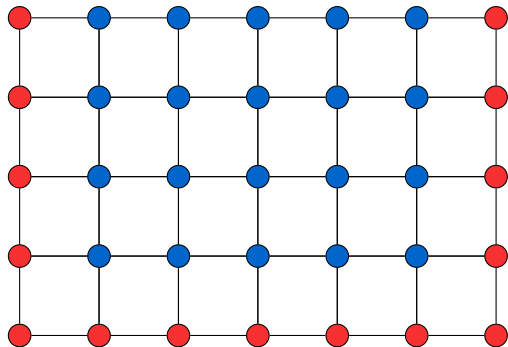
- Grid point at which dependent variable has to be computed
- Grid point at which boundary condition is specified

Typical example: Poisson equation

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = f(x, y)$$

Efficiency (memory requirements, CPU time) of the numerical method is of crucial importance.

## Example parabolic PDE (initial value problem: IVP)



- Grid point at which dependent variable has to be computed
- Grid point at which boundary condition is specified

Typical example: Poisson equation

$$\frac{\partial c}{\partial t} + u \frac{\partial c}{\partial x} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} + R$$

Stability (in numerical sense) of the numerical method is of crucial importance.



# Boundary conditions

- Dirichlet or fixed condition: prescribed value of  $f$  at boundary

$$f = f_0 \quad f_0 \text{ is a known function}$$

- Neumann condition: prescribed value of derivative of  $f$  at boundary

$$\frac{\partial f}{\partial n} = q \quad q \text{ is a known function}$$

- Mixed or Robin condition: relation between  $f$  and  $\frac{\partial f}{\partial n}$  at boundary

$$a \frac{\partial f}{\partial n} + bf = c \quad a, b \text{ and } c \text{ are known functions}$$

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# Numerical solution method

Finite differences (method of lines, MOL):

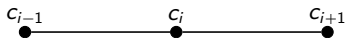
- 1 Discretize spatial domain in discrete grid points
- 2 Find suitable approximation for the spatial derivatives
- 3 Substitute approximations in PDE, which gives a system of ODE's, one for every grid points
- 4 Advance in time with a suitable ODE solver

Alternative methods: collocation, Galerkin or Finite Element methods

# Instationary diffusion equation (Fick's second law)

$$\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2}, \quad \text{with} \quad \begin{aligned} t = 0; 0 \leq x \leq \ell &\Rightarrow c = c_0 \\ t > 0; x = 0 &\Rightarrow c = c_L \\ t > 0; x = \ell &\Rightarrow c = c_R \end{aligned}$$


Second derivative  $\frac{\partial^2 c}{\partial x^2}$



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$$c_{i+1} = c_i + \left. \frac{\partial c}{\partial x} \right|_i \Delta x + \frac{1}{2} \left. \frac{\partial^2 c}{\partial x^2} \right|_i \Delta x^2 + \frac{1}{6} \left. \frac{\partial^3 c}{\partial x^3} \right|_i \Delta x^3 + \dots$$

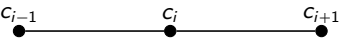
$$c_{i-1} = c_i - \left. \frac{\partial c}{\partial x} \right|_i \Delta x + \frac{1}{2} \left. \frac{\partial^2 c}{\partial x^2} \right|_i \Delta x^2 - \frac{1}{6} \left. \frac{\partial^3 c}{\partial x^3} \right|_i \Delta x^3 + \dots$$


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$$c_{i+1} + c_{i-1} = 2c_i + \left. \frac{\partial^2 c}{\partial x^2} \right|_i \Delta x^2 + \mathcal{O}(\Delta x^4)$$

$$\Rightarrow \left. \frac{\partial^2 c}{\partial x^2} \right|_i = \frac{c_{i+1} - 2c_i + c_{i-1}}{\Delta x^2} + \mathcal{O}(\Delta x^2)$$

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Second derivative  $\frac{\partial^2 c}{\partial x^2}$



A horizontal line with three black dots. Above the first dot is the label  $c_{i-1}$ , above the middle dot is  $c_i$ , and above the third dot is  $c_{i+1}$ .

$$c_{i+1} = c_i + \left. \frac{\partial c}{\partial x} \right|_i \Delta x + \frac{1}{2} \left. \frac{\partial^2 c}{\partial x^2} \right|_i \Delta x^2 + \frac{1}{6} \left. \frac{\partial^3 c}{\partial x^3} \right|_i \Delta x^3 + \dots$$

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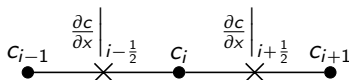
Due to symmetric discretization: second order (central discretization).



# Instationary diffusion equation (Fick's second law)

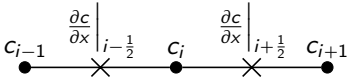
An alternative discretization:

$$\left. \frac{\partial^2 c}{\partial x^2} \right|_i = \frac{\left. \frac{\partial c}{\partial x} \right|_{i+\frac{1}{2}} - \left. \frac{\partial c}{\partial x} \right|_{i-\frac{1}{2}}}{\Delta x} + \mathcal{O}(\Delta x^2)$$



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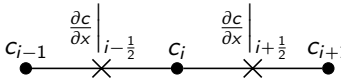
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$$= \frac{\frac{c_{i+1} - c_i}{\Delta x} - \frac{c_i - c_{i-1}}{\Delta x}}{\Delta x} = \frac{c_{i+1} - 2c_i + c_{i-1}}{\Delta x^2}$$

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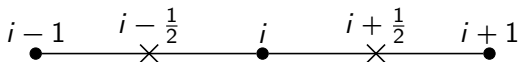
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This is convenient for the derivation of  $\frac{\partial}{\partial x} \left( \mathcal{D} \frac{\partial c}{\partial x} \right)$ :

$$\begin{aligned} \frac{\partial}{\partial x} \left( \mathcal{D} \frac{\partial c}{\partial x} \right) &= \frac{\mathcal{D}_{i+\frac{1}{2}} \frac{\partial c}{\partial x} \Big|_{i+\frac{1}{2}} - \mathcal{D}_{i-\frac{1}{2}} \frac{\partial c}{\partial x} \Big|_{i-\frac{1}{2}}}{\Delta x} = \frac{\mathcal{D}_{i+\frac{1}{2}} \frac{c_{i+1} - c_i}{\Delta x} - \mathcal{D}_{i-\frac{1}{2}} \frac{c_i - c_{i-1}}{\Delta x}}{\Delta x} \\ &= \frac{\mathcal{D}_{i+\frac{1}{2}} c_{i+1} - \left( \mathcal{D}_{i+\frac{1}{2}} + \mathcal{D}_{i-\frac{1}{2}} \right) c_i + \mathcal{D}_{i-\frac{1}{2}} c_{i-1}}{\Delta x} \end{aligned}$$

# Instationary diffusion equation (Fick's second law)

$$\frac{\partial^2 f}{\partial x^2}$$



# Instationary diffusion equation (Fick's second law)

$$\frac{\partial^2 f}{\partial x^2} \quad \begin{array}{ccccccc} & i-1 & & i-\frac{1}{2} & & i & & i+\frac{1}{2} & & i+1 \\ & \bullet & & \times & & \bullet & & \times & & \bullet \end{array}$$

$$f_{i+\frac{1}{2}} = f_i + \frac{1}{2}\Delta x \left. \frac{\partial f}{\partial x} \right|_i \Delta x + \frac{1}{2} \left( \frac{1}{2}\Delta x \right)^2 \left. \frac{\partial^2 f}{\partial x^2} \right|_i + \mathcal{O}(\Delta x^3)$$

$$f_{i-\frac{1}{2}} = f_i - \frac{1}{2}\Delta x \left. \frac{\partial f}{\partial x} \right|_i \Delta x + \frac{1}{2} \left( \frac{1}{2}\Delta x \right)^2 \left. \frac{\partial^2 f}{\partial x^2} \right|_i + \mathcal{O}(\Delta x^3)$$

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$$f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}} = \Delta x \frac{\partial f}{\partial x} + \mathcal{O}(\Delta x^3)$$

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$$\Rightarrow \left. \frac{\partial f}{\partial x} \right|_i = \frac{f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}}}{\Delta x} + \mathcal{O}(\Delta x^2)$$

Symmetric discretization yields second order!

# Instationary diffusion equation: spatial discretization

Substitution of spatial derivatives yields:

$$\frac{dc_i}{dt} = \mathcal{D} \frac{c_{i-1} - 2c_i + c_{i+1}}{\Delta x^2} \quad \text{for } i = 0, \dots, N$$

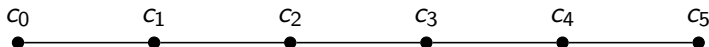
For example, using 6 (ridiculously low number!) grid points:

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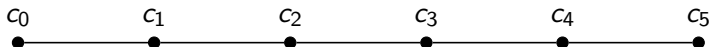


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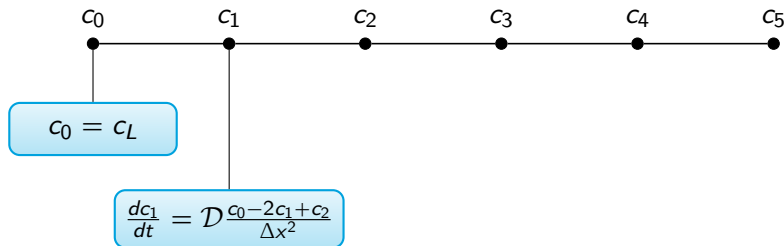
$c_0 = c_L$

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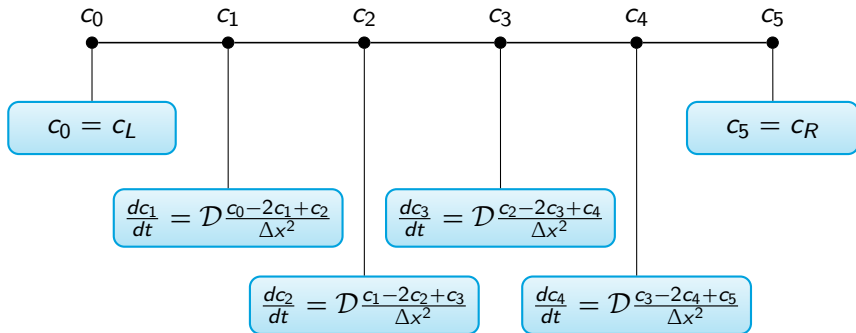


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For example, using 6 (ridiculously low number!) grid points:



# Instantaneous diffusion equation: boundary conditions

Two options:

- 1 Keep boundary conditions as additional equations:

$$c_0 = c_L, \frac{dc_1}{dt} = \mathcal{D} \frac{c_0 - 2c_1 + c_2}{\Delta x^2}, \frac{dc_2}{dt} = \mathcal{D} \frac{c_1 - 2c_2 + c_3}{\Delta x^2},$$
$$\frac{dc_3}{dt} = \mathcal{D} \frac{c_2 - 2c_3 + c_4}{\Delta x^2}, \frac{dc_4}{dt} = \mathcal{D} \frac{c_3 - 2c_4 + c_5}{\Delta x^2}, c_5 = c_R$$

- 2 Substitute boundary conditions to reduce number of equations:

$$\frac{dc_1}{dt} = \mathcal{D} \frac{c_L - 2c_1 + c_2}{\Delta x^2}, \frac{dc_2}{dt} = \mathcal{D} \frac{c_1 - 2c_2 + c_3}{\Delta x^2},$$
$$\frac{dc_3}{dt} = \mathcal{D} \frac{c_2 - 2c_3 + c_4}{\Delta x^2}, \frac{dc_4}{dt} = \mathcal{D} \frac{c_3 - 2c_4 + c_R}{\Delta x^2}$$

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Two options:

- 1 Keep boundary conditions as additional equations:

$$c_0 = c_L, \frac{dc_1}{dt} = \mathcal{D} \frac{c_0 - 2c_1 + c_2}{\Delta x^2}, \frac{dc_2}{dt} = \mathcal{D} \frac{c_1 - 2c_2 + c_3}{\Delta x^2},$$
$$\frac{dc_3}{dt} = \mathcal{D} \frac{c_2 - 2c_3 + c_4}{\Delta x^2}, \frac{dc_4}{dt} = \mathcal{D} \frac{c_3 - 2c_4 + c_5}{\Delta x^2}, c_5 = c_R$$

- 2 Substitute boundary conditions to reduce number of equations:

$$\frac{dc_1}{dt} = \mathcal{D} \frac{c_L - 2c_1 + c_2}{\Delta x^2}, \frac{dc_2}{dt} = \mathcal{D} \frac{c_1 - 2c_2 + c_3}{\Delta x^2},$$
$$\frac{dc_3}{dt} = \mathcal{D} \frac{c_2 - 2c_3 + c_4}{\Delta x^2}, \frac{dc_4}{dt} = \mathcal{D} \frac{c_3 - 2c_4 + c_R}{\Delta x^2}$$

# Instationary diffusion equation: temporal discretization

$$\frac{dc_i}{dt} = \mathcal{D} \frac{c_{i-1} - 2c_i + c_{i+1}}{\Delta x^2}$$

Time discretization: forward Euler (explicit)

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = \mathcal{D} \frac{c_{i-1}^n - 2c_i^n + c_{i+1}^n}{\Delta x^2}$$
$$\Rightarrow c_i^{n+1} = Fo c_{i-1}^n + (1 - 2Fo) c_i^n + Fo c_{i+1}^n \quad \text{with } Fo = \frac{\mathcal{D} \Delta t}{\Delta x^2}$$

Straightforward updating (explicit equation), simple to implement in a program but stability constraint  $Fo = \frac{\mathcal{D} \Delta t}{\Delta x^2} < \frac{1}{2}!$

Small  $\Delta x \Rightarrow$  small  $\Delta t \Rightarrow$  patience required ☹

# Instationary diffusion equation: temporal discretization

$$\frac{dc_i}{dt} = \mathcal{D} \frac{c_{i-1} - 2c_i + c_{i+1}}{\Delta x^2}$$

Time discretization: backward Euler (implicit)

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = \mathcal{D} \frac{c_{i-1}^{n+1} - 2c_i^{n+1} + c_{i+1}^{n+1}}{\Delta x^2}$$

$$\Rightarrow -Fo c_{i-1}^{n+1} + (1 + 2Fo) c_i^{n+1} - Fo c_{i+1}^{n+1} = c_i^n \quad \text{with } Fo = \frac{\mathcal{D} \Delta t}{\Delta x^2}$$

Requires the solution of a system of linear equations, but no stability constraints!

Note: extension to higher order schemes (with time step adaptation) straightforward.  
Often second or third order optimal, because for each Euler-like step in the additional order an often large system needs to be solved (not treated in this course).

# Solving the instationary diffusion equation: example

Solve the diffusion problem using explicit discretization:

$$\frac{\partial c_i}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} \quad \text{with} \quad \begin{aligned} 0 \leq x \leq \delta, \quad \delta &= 5 \cdot 10^{-3} \text{ m} \\ \delta/\Delta x &= 100 \text{ grid cells} \\ \mathcal{D} &= 1 \cdot 10^{-8} \text{ m}^2 \text{ s}^{-1} \\ t_{\text{end}} &= 5000 \text{ s} \\ c_L &= 1 \text{ mol m}^{-3} \quad c_R = 0 \text{ mol m}^{-3} \end{aligned}$$



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$$c_i^{n+1} = Fo c_{i-1}^n + (1 - 2Fo) c_i^n + Fo c_{i+1}^n \quad \text{with } Fo = \frac{\mathcal{D} \Delta t}{\Delta x^2}$$

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$$c_i^{n+1} = Fo c_{i-1}^n + (1 - 2Fo) c_i^n + Fo c_{i+1}^n \quad \text{with } Fo = \frac{\mathcal{D} \Delta t}{\Delta x^2}$$

- 1 Initialise variables
- 2 Compute time step so that  $Fo \leq \frac{1}{2} \Rightarrow \Delta t = 0.125\text{s}$
- 3 Compute 40000 time steps times 100 grid nodes!
- 4 Store solution

# Solving the instationary diffusion equation: example

Initialise the variables and matrices:

```

Nx = 100;                % Nc grid points
Nt = 4000;               % Nt time steps
D = 1e-8;                % m/s
c_L = 1.0; c_R = 0;     % mol/m3
t_end = 5000.0;          % s
x_end = 5e-3;            % m

% Time step and grid size
dt = t_end/Nt;
dx = x_end/Nx;

% Fourier number
Fo=D*dt/dx/dx

% Initial matrices for solutions (Nx times Nt)
c = zeros(Nt+1,Nx+1);   % All concentrations are zero
c(:,1) = c_L;           % Concentration at left side
c(:,Nx+1) = c_R;        % Concentration at right side

% Grid node and time step positions
x = linspace(0,x_end,Nx+1);

```

# Solving the instationary diffusion equation: example

Compute the solution (nested time-and-grid loop):

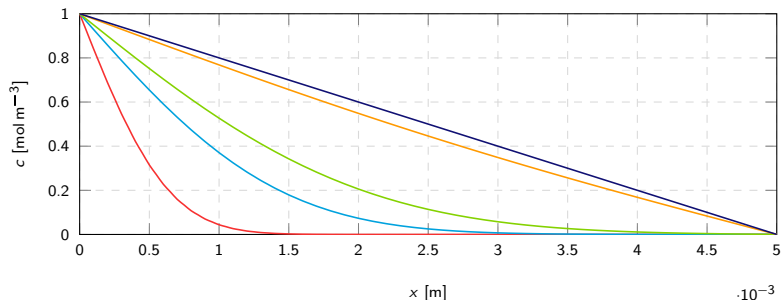
```
for n = 1:Nt % time loop
    for i = 2:Nx % Nested loop for grid nodes
        c(n+1,i) = Fo*c(n,i-1) + (1-2*Fo)*c(n,i) + Fo*
            c(n,i+1);
    end
end
```

# Solving the instationary diffusion equation: example

Compute the solution (nested time-and-grid loop):

```
for n = 1:Nt % time loop
    for i = 2:Nx % Nested loop for grid nodes
        c(n+1,i) = Fo*c(n,i-1) + (1-2*Fo)*c(n,i) + Fo*
            c(n,i+1);
    end
end
```

Plotting the solution at  $t = \{12.5, 62.5, 125, 625, 5000\}$  s.



# Solving the diffusion equation implicitly

Linear system  $A\mathbf{x} = \mathbf{b}$  from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ -Fo & (1 + 2Fo) & -Fo & 0 & \dots & 0 \\ 0 & -Fo & (1 + 2Fo) & -Fo & \dots & 0 \\ 0 & 0 & -Fo & (1 + 2Fo) & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ c_3^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ c_3^n \\ \vdots \\ c_m^n \end{pmatrix}$$

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$$\begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ -Fo & (1 + 2Fo) & -Fo & 0 & \dots & 0 \\ 0 & -Fo & (1 + 2Fo) & -Fo & \dots & 0 \\ 0 & 0 & -Fo & (1 + 2Fo) & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ c_3^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ c_3^n \\ \vdots \\ c_m^n \end{pmatrix}$$

$$1 \times c_0^{n+1} = c_0^n \text{ (boundary condition)}$$

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$$\begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ -Fo & (1+2Fo) & -Fo & 0 & \dots & 0 \\ 0 & -Fo & (1+2Fo) & -Fo & \dots & 0 \\ 0 & 0 & -Fo & (1+2Fo) & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ c_3^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ c_3^n \\ \vdots \\ c_m^n \end{pmatrix}$$

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$$Foc_0^{n+1} + (1 + 2Fo)c_1^{n+1} - Foc_2^{n+1} = c_1^n$$



# Solving the diffusion equation implicitly

Linear system  $A\mathbf{x} = \mathbf{b}$  from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ -Fo & (1 + 2Fo) & -Fo & 0 & \dots & 0 \\ 0 & -Fo & (1 + 2Fo) & -Fo & \dots & 0 \\ 0 & 0 & -Fo & (1 + 2Fo) & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ c_3^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ c_3^n \\ \vdots \\ c_m^n \end{pmatrix}$$

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# Solving the diffusion equation implicitly

Linear system  $A\mathbf{x} = \mathbf{b}$  from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ -Fo & (1 + 2Fo) & -Fo & 0 & \dots & 0 \\ 0 & -Fo & (1 + 2Fo) & -Fo & \dots & 0 \\ 0 & 0 & -Fo & (1 + 2Fo) & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ c_3^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ c_3^n \\ \vdots \\ c_m^n \end{pmatrix}$$

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$$Foc_2^{n+1} + (1 + 2Fo)c_3^{n+1} - Foc_4^{n+1} = c_3^n$$

# Solving the diffusion equation implicitly

Linear system  $A\mathbf{x} = \mathbf{b}$  from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ -Fo & (1 + 2Fo) & -Fo & 0 & \dots & 0 \\ 0 & -Fo & (1 + 2Fo) & -Fo & \dots & 0 \\ 0 & 0 & -Fo & (1 + 2Fo) & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ c_3^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ c_3^n \\ \vdots \\ c_m^n \end{pmatrix}$$

$$1 \times c_0^{n+1} = c_0^n \text{ (boundary condition)}$$

$$Foc_0^{n+1} + (1 + 2Fo)c_1^{n+1} - Foc_2^{n+1} = c_1^n$$

$$Foc_1^{n+1} + (1 + 2Fo)c_2^{n+1} - Foc_3^{n+1} = c_2^n$$

$$Foc_2^{n+1} + (1 + 2Fo)c_3^{n+1} - Foc_4^{n+1} = c_3^n$$

$$1 \times c_m^{n+1} = c_m^n \text{ (boundary condition)}$$

# Solving the diffusion equation implicitly in Matlab

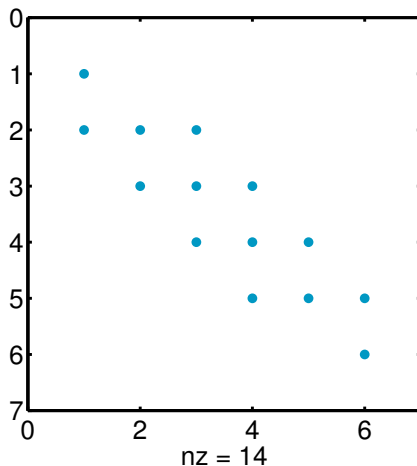
To solve the linear system, we need to define matrix  $A$ . It is clear that storing many zeros is not efficient in terms of memory. We use a *sparse matrix* format:

```
% Bands in matrix (internal cells)
A = sparse(Nx+1,Nx+1);
for i=2:Nx
    A(i,i-1) = -Fo;
    A(i,i) = (1+2*Fo);
    A(i,i+1) = -Fo;
end

% Set boundary cells, independent on neighbors:
A(1,1) = 1;           % Left
A(Nx+1,Nx+1) = 1;     % Right
```

# Solving the diffusion equation implicitly in Matlab

The command `spy(A)` shows a figure with the non-zero positions.



# Solving the diffusion equation implicitly in Matlab

The concentration matrix is initialised and the boundary conditions are set as follows:

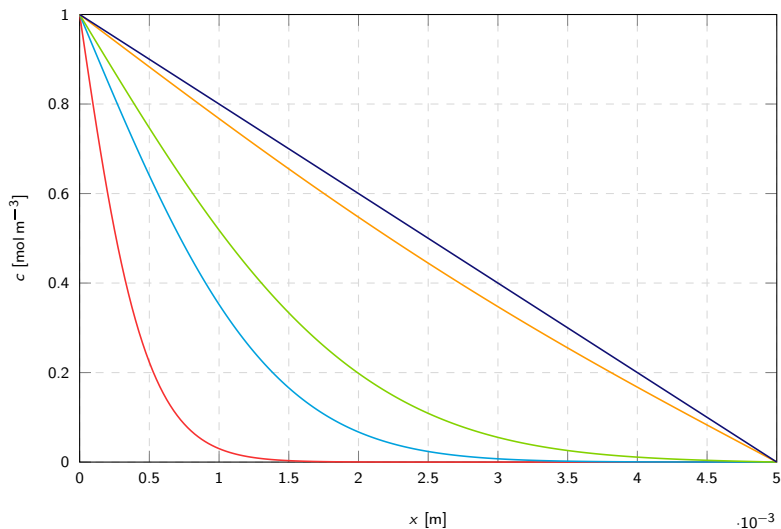
```
% Initial matrices for solutions (Nx times Nt)
c = zeros(Nt+1,Nx+1); % All concentrations are zero
c(:,1)      = c_L;      % Concentration at left side
c(:,Nx+1)   = c_R;      % Concentration at right side
```

The right hand side vector (**b**) can now be set during the time-loop:

```
for n = 1:Nt-1 % time loop
    b = c(n,:)'; % Set right hand side
    solX = A\b; % Solve linear system
    c(n+1,:) = solX; % Store solution each time step
end
```

# Solving the diffusion equation implicitly in Matlab

Plotting the solution at  $t = \{12.5, 62.5, 125, 625, 5000\}$  s.



# About explicit vs. implicit solutions

- Explicit solution:
  - Easy to implement
  - Very small time steps required.
  - This problem took about 0.5 s.
- Implicit solution:
  - Harder to implement, needs sparse matrix solver
  - No stability constraint
  - This problem took about 0.05 s
- The difference will become much larger for systems with e.g. more grid nodes!



## Extension with non-linear source terms

$$\frac{\partial c}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} + R(c) \quad \text{with} \quad \begin{aligned} t = 0; 0 \leq x \leq \ell &\Rightarrow c = c_0 \\ t > 0; x = 0 &\Rightarrow c = c_L \\ t > 0; x = \ell &\Rightarrow c = c_R \end{aligned}$$

## Extension with non-linear source terms

$$\frac{\partial c}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} + R(c) \quad \text{with} \quad \begin{array}{l} t = 0; 0 \leq x \leq \ell \Rightarrow c = c_0 \\ t > 0; x = 0 \Rightarrow c = c_L \\ t > 0; x = \ell \Rightarrow c = c_R \end{array}$$

- Forward Euler (explicit): simply add to right-hand side

$$\begin{aligned} \frac{c_i^{n+1} - c_i^n}{\Delta t} &= \mathcal{D} \frac{c_{i-1}^n - 2c_i^n + c_{i+1}^n}{\Delta x^2} + R(c_i^n) \\ \Rightarrow c_i^{n+1} &= Foc_{i-1}^n + (1 - 2Fo)c_i^n + Foc_{i+1}^n + R_i^n \end{aligned}$$

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- Backward Euler (implicit): linearization required

$$\begin{aligned} R(c_i^{n+1}) &= R(c_i^n) + \left. \frac{dR}{dc} \right|_i^n (c_i^{n+1} - c_i^n) \\ \frac{c_i^{n+1} - c_i^n}{\Delta t} &= \mathcal{D} \frac{c_{i-1}^{n+1} - 2c_i^{n+1} + c_{i+1}^{n+1}}{\Delta x^2} + R(c_i^{n+1}) \\ \Rightarrow -Foc_{i-1}^{n+1} + (1 + 2Fo - \left. \frac{dR}{dc} \right|_i^n) c_i^{n+1} - Foc_{i+1}^{n+1} &= c_i^n + R_i^n - \left. \frac{dR}{dc} \right|_i^n c_i^n \end{aligned}$$

# Extension with convection terms

$$\frac{\partial c}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} - u \frac{\partial c}{\partial x} + R$$

Discretization of first derivative  $\frac{dc}{dx}$ ,  
looks simple but is numerical headache!

Central discretization:  $\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{\Delta x}$

⇒ simple and easy, too bad it doesn't work: yields unstable solutions if convection dominated.

## Central difference scheme of 1st derivative

Unsteady convection:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Central difference for first derivative:

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

# Central difference scheme of 1st derivative

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$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

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Forward Euler discretization of temporal and spatial domain:

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = -u \frac{c_{i+1} - c_{i-1}}{2\Delta x} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_{i+1}^n - c_{i-1}^n}{2\Delta x} \Delta t$$

# Central difference scheme of 1st derivative

Unsteady convection:

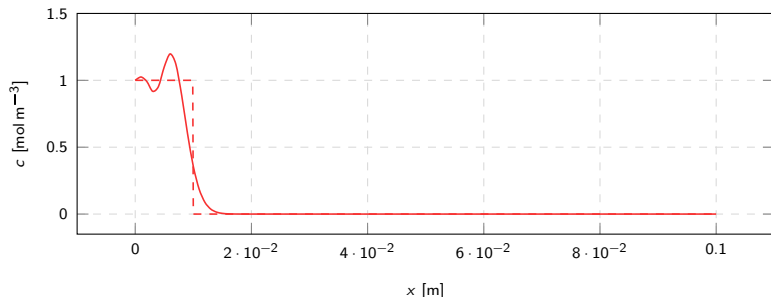
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# Central difference scheme of 1st derivative

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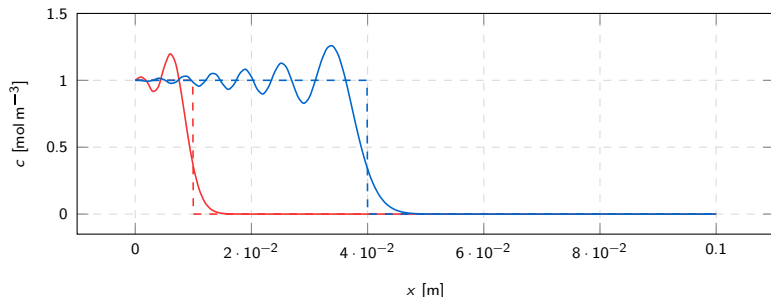
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# Central difference scheme of 1st derivative

Unsteady convection:

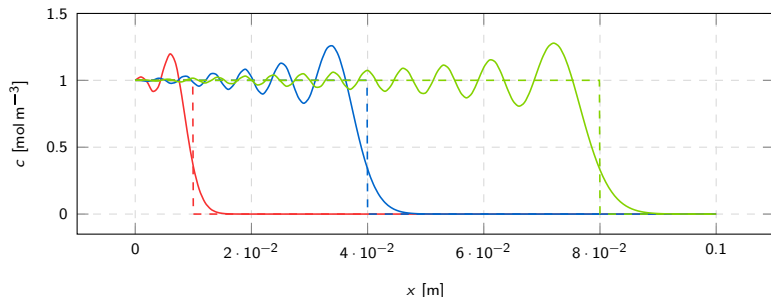
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Central difference for first derivative:

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

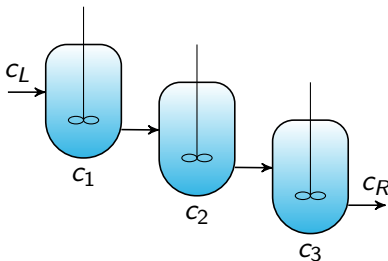
Forward Euler discretization of temporal and spatial domain:

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## Extension with convection terms

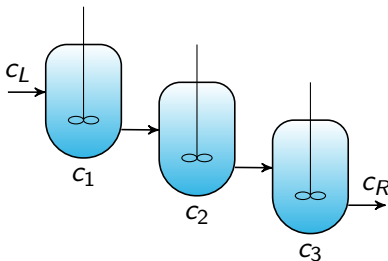
Solution: upwind discretization, like CSTR's in series:



First order upwind: 
$$-u \frac{dc}{dx} \Big|_i = \begin{cases} -u \frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \geq 0 \\ -u \frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

## Extension with convection terms

Solution: upwind discretization, like CSTR's in series:



$$\text{First order upwind: } -u \frac{dc}{dx} \Big|_i = \begin{cases} -u \frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \geq 0 \\ -u \frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

Stable if  $Co = \frac{u\Delta t}{\Delta x} < 1$  (with  $Co$  the Courant number). However, only 1<sup>st</sup> order accurate (large smearing of concentration fronts). Higher order upwind requires TVD schemes (trick of the trade)...

# First order upwind scheme of 1st derivative

Unsteady convection:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Upwind scheme for first derivative:

$$-u \frac{dc}{dx} \Big|_i = \begin{cases} -u \frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \geq 0 \\ -u \frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

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$$-u \frac{dc}{dx} \Big|_i = \begin{cases} -u \frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \geq 0 \\ -u \frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

Forward Euler discretization of temporal and spatial domain:

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = -u \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$
$$\Rightarrow c_i^{n+1} = \begin{cases} c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \geq 0 \\ c_i^n - u \frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

# Upwind scheme: example

Unsteady convection through a pipe:

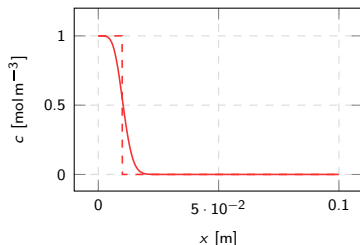
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{ m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

# Upwind scheme: example

Unsteady convection through a pipe:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{ m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells

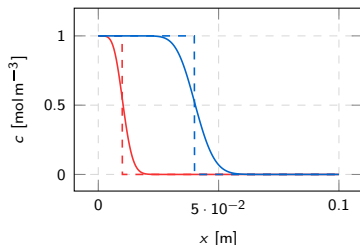


# Upwind scheme: example

Unsteady convection through a pipe:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{ m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells



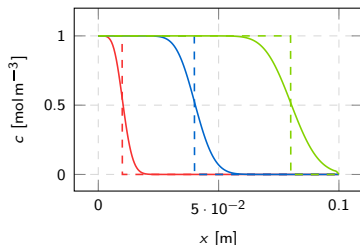


# Upwind scheme: example

Unsteady convection through a pipe:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{ m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells

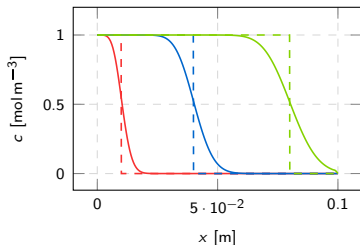


# Upwind scheme: example

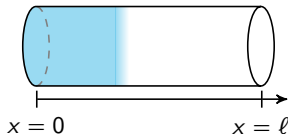
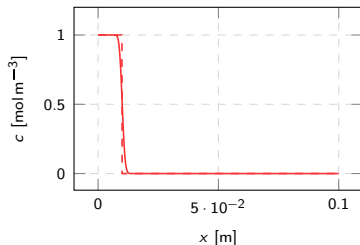
Unsteady convection through a pipe:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{ m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells



Using 1000 grid cells

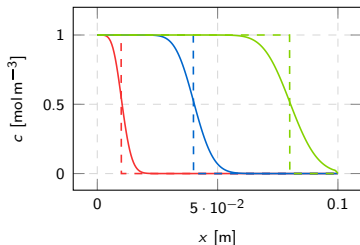


# Upwind scheme: example

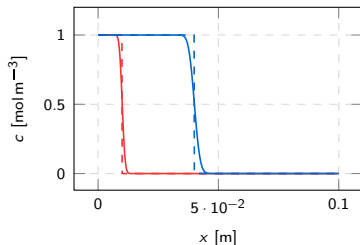
Unsteady convection through a pipe:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{ m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells



Using 1000 grid cells

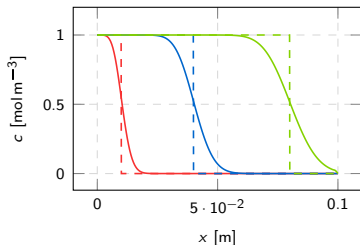


# Upwind scheme: example

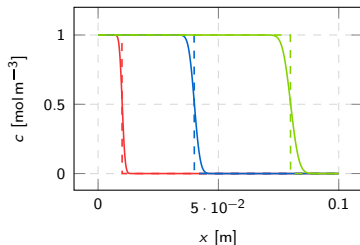
Unsteady convection through a pipe:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{ m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells



Using 1000 grid cells



# Central difference and upwind in Matlab

The results from the previous slides were computed using this script:

```
Nx = 1000;           % Nc grid points
Nt = 10000;          % Nt time steps
u = 0.001;           % m/s
c_in = 1.0;          % mol/m3
t_end = 100.0;        % s
x_end = 0.1;         % m

% Time step and grid size
dt = t_end/Nt; dx = x_end/Nx;

% Courant number
Co=u*dt/dx

% Initial matrices for solutions (Nx times Nt)
c1 = zeros(Nt+1,Nx+1); % All concentrations are zero
c1(:,1) = c_in;        % Concentration at inlet (all time steps)
)
an = c1; c2 = c1;      % Analytical and upwind solution

% Grid node and time step positions
x = linspace(0,x_end,Nx+1);
t = linspace(0,t_end,Nt+1);
```

# Central difference and upwind in Matlab

(continued)

```
for n = 1:Nt % time loop
    for i = 2:Nx % Nested loop for grid nodes
        % Central difference
        c1(n+1,i) = c1(n,i) - u*((c1(n,i+1) - c1(n,i)
            -1))/(2*dx))*dt;
        % Upwind
        c2(n+1,i) = c2(n,i) - u*((c2(n,i) - c2(n,i-1))
            /(dx))*dt;
        % Analytical
        an(n+1,i) = (x(i) < u*t(n+1))*c_in;
    end
end
```

## Extension to systems of PDE's

- Explicit methods: straightforward extension
- Implicit methods: yields block-tridiagonal matrix (note ordering of equations: all variables per grid cell)

## Extension to 2D or 3D systems

Spatial discretization in 2 directions — different methods available:

- Explicit
- Fully implicit
  - 1D gives tri-diagonal matrix
  - 2D gives penta-diagonal matrix
  - 3D gives hepta-diagonal matrix

Use of dedicated matrix solvers (e.g. ICCG, multigrid, ...)

- Alternating direction implicit (ADI)
  - Per direction implicit, but still overall unconditionally stable



# Further extensions for parabolic PDEs

- Higher order temporal discretization (multi-step) with time step adaptation
- Non-uniform grids with automatic grid adaptation
- Higher-order discretization methods, especially higher order TVD (flux delimited) schemes for convective fluxes (e.g. WENO schemes)
- Higher-order finite volume schemes (Riemann solvers)

# Summary

- Several classes of PDEs were introduced
  - Elliptic, Parabolic, Hyperbolic PDEs
- Diffusion equation: discretization of temporal and spatial domain was discussed
  - Solutions of the diffusion equation using explicit and implicit methods
  - How to add non-linear source terms
- Convection: upwind vs. central difference schemes