#### Partial differential equations

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### Today's outline

- Introduction
- 2 Instationary diffusion equation Discretization Solving the diffusion equation

Non-linear source terms

Convection

Discretization Central difference scheme Upwind scheme

- 4 Conclusions
  - Other methods Summary

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- Introduction
- Instationary diffusion equation Discretization Solving the diffusion equation Non-linear source terms
- Discretization
  Central difference scheme
  Upwind scheme
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#### Overview

#### Main question

How to solve parabolic PDEs like:

$$\frac{\partial c}{\partial t} = \mathcal{D}\frac{\partial^2 c}{\partial x^2} - u\frac{\partial c}{\partial x} + R$$

$$t = 0; 0 \le x \le \ell \implies c = c_0$$

with

$$t > 0; x = 0$$
  $\Rightarrow -\mathcal{D}\frac{\partial c}{\partial x} + uc = u_{\text{in}}c_{\text{in}}$ 

$$t > 0; x = \ell$$
  $\Rightarrow \frac{\partial c}{\partial x} = 0$ 

accurately and efficiently?

#### What is a PDE?

#### Partial differential equation

An equation containing a function and their derivatives to multiple independent variables.

#### Order of PDE

The highest derivative appearing in the PDE

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General second order PDE:

$$A\frac{\partial^2 f}{\partial x^2} + B\frac{\partial^2 f}{\partial x \partial y} + C\frac{\partial^2 f}{\partial y^2} + D\frac{\partial f}{\partial x} + E\frac{\partial f}{\partial y} + Ff = G$$

- Linear equation: Coefficients A, B, ..., G do not depend on x and v.
- Non-linear equation: Coefficients A, B, ..., G are a function of x and y.

$$A\frac{\partial^2 f}{\partial x^2} + B\frac{\partial^2 f}{\partial x \partial y} + C\frac{\partial^2 f}{\partial y^2} + D\frac{\partial f}{\partial x} + E\frac{\partial f}{\partial y} + Ff = G$$

The discriminant  $\Delta$  of a quadratic polynomial is computed as (note: only the higher order coefficients are important):

$$\Delta = B^2 - 4AC$$

Introduction

#### Classification of PDE's

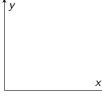
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Introduction 000000000

- $\Delta < 0 \Rightarrow$  Elliptic equation (e.g. Laplace equation for stationary diffusion in 2D)
- $\Delta = 0 \Rightarrow$  Parabolic equation (e.g. instationary heat penetration in 1D)
- $\Delta > 0 \Rightarrow$  Hyperbolic equation (e.g. wave equation)



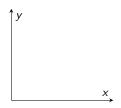
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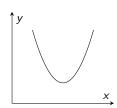
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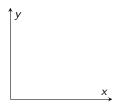
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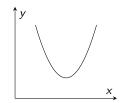
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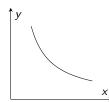
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#### Different PDE types require different solution techniques because of the difference in range of influence:

- Characteristics Curves in xy-domain along with signal propagation takes place
- Domain of dependence of point P points in xy-domain which influence the value of f in point P
- Range of influence of point P points in xy-domain which are influenced by the value of f in point P

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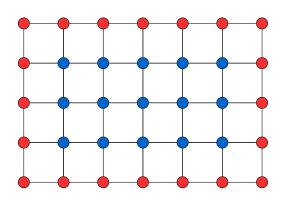
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### Example elliptic PDE (boundary value problems: BVP)



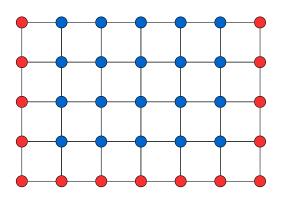
- Grid point at which dependent variable has to be computed
- Grid point at which boundary condition is specified

Typical example: Poisson equation

$$\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = f(x, y)$$

Efficiency (memory requirements, CPU time) of the numerical method is of crucial importance.

### Example parabolic PDE (initial value problem: IVP)



- Grid point at which dependent variable has to be computed
- Grid point at which boundary condition is specified

Typical example: Poisson equation

$$\frac{\partial c}{\partial t} + u \frac{\partial c}{\partial x} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} + R$$

Stability (in numerical sense) of the numerical method is of crucial importance.

#### Boundary conditions

Introduction

Dirichlet or fixed condition: prescribed value of f at boundary

$$f = f_0$$
  $f_0$  is a known function

 Neumann condition: prescribed value of derivative of f at boundary

$$\frac{\partial f}{\partial n} = q$$
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• Mixed or Robin condition: relation between f and  $\frac{\partial f}{\partial n}$  at boundary

$$a\frac{\partial f}{\partial n} + bf = c$$
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#### Numerical solution method

#### Finite differences (method of lines, MOL):

- 1 Discretize spatial domain in discrete grid points
- 2 Find suitable approximation for the spatial derivatives
- 3 Substitute approximations in PDE, which gives a system of ODE's, one for every grid points
- Advance in time with a suitable ODE solver

Alternative methods: collocation, Galerkin or Finite Element methods

$$\frac{\partial c}{\partial t} = \mathcal{D}\frac{\partial^2 c}{\partial x^2}, \quad \text{with} \quad \begin{array}{l} t = 0; 0 \leq x \leq \ell \Rightarrow c = c_0 \\ t > 0; x = 0 \Rightarrow c = c_L \\ t > 0; x = \ell \Rightarrow c = c_R \end{array}$$

Second derivative  $\frac{\partial^2 c}{\partial x^2}$   $\stackrel{c_{i-1}}{\bullet}$ 



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Second derivative 
$$\frac{\partial^2 c}{\partial x^2}$$

$$c_{i-1} = c_i + \frac{\partial c}{\partial x} \Big|_i \Delta x + \frac{1}{2} \frac{\partial^2 c}{\partial x^2} \Big|_i \Delta x^2 + \frac{1}{6} \frac{\partial^3 c}{\partial x^3} \Big|_i \Delta x^3 + \dots$$

$$c_{i-1} = c_i - \frac{\partial c}{\partial x} \Big|_i \Delta x + \frac{1}{2} \frac{\partial^2 c}{\partial x^2} \Big|_i \Delta x^2 - \frac{1}{6} \frac{\partial^3 c}{\partial x^3} \Big|_i \Delta x^3 + \dots$$

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Second derivative 
$$\frac{\partial^2 c}{\partial x^2}$$

$$c_{i-1} \quad c_i \quad c_{i+1}$$

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$$c_{i-1} = c_i - \frac{\partial c}{\partial x} \bigg|_i \Delta x + \frac{1}{2} \left. \frac{\partial^2 c}{\partial x^2} \right|_i \Delta x^2 - \frac{1}{6} \left. \frac{\partial^3 c}{\partial x^3} \right|_i \Delta x^3 + \dots$$

$$c_{i+1} + c_{i-1} = 2c_i + \frac{\partial^2 c}{\partial x^2} \bigg|_i \Delta x^2 + \mathcal{O}(\Delta x^4)$$

$$\Rightarrow \frac{\partial^2 c}{\partial x^2} \bigg|_i = \frac{c_{i+1} - 2c_i + c_{i-1}}{\Delta x^2} + \mathcal{O}(\Delta x^2)$$

$$\frac{\partial c}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2}, \quad \text{with} \quad \begin{array}{l} t = 0; 0 \leq x \leq \ell \Rightarrow c = c_0 \\ t > 0; x = 0 \Rightarrow c = c_L \\ t > 0; x = \ell \Rightarrow c = c_R \end{array}$$

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$$\begin{vmatrix} c_{i+1} + c_{i-1} = 2c_i + \frac{\partial^2 c}{\partial x^2} \Big|_i \Delta x^2 + \mathcal{O}(\Delta x^4) \end{vmatrix}$$
  
$$\Rightarrow \frac{\partial^2 c}{\partial x^2} = \frac{c_{i+1} - 2c_i + c_{i-1}}{\Delta x^2} + \mathcal{O}(\Delta x^2)$$

Due to symmetric discretization: second order (central discretization).

An alternative discretization:

$$\frac{\partial^{2} c}{\partial x^{2}}\bigg|_{i} = \frac{\frac{\partial c}{\partial x}\bigg|_{i+\frac{1}{2}} - \frac{\partial c}{\partial x}\bigg|_{i-\frac{1}{2}}}{\Delta x} + \mathcal{O}(\Delta x^{2}) \qquad \underbrace{c_{i-1} \quad \frac{\partial c}{\partial x}\bigg|_{i-\frac{1}{2}} \quad c_{i} \quad \frac{\partial c}{\partial x}\bigg|_{i+\frac{1}{2}} \quad c_{i+1}}_{\bullet}$$

$$C_{i-1} \xrightarrow{\frac{\partial c}{\partial x}\Big|_{i-\frac{1}{2}}} C_{i} \xrightarrow{\frac{\partial c}{\partial x}\Big|_{i+\frac{1}{2}}} C_{i+\frac{1}{2}}$$

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$$= \frac{c_{i+1} - c_{i}}{\Delta x} - \frac{c_{i} - c_{i-1}}{\Delta x}}{\Delta x} = \frac{c_{i+1} - 2c_{i} + c_{i-1}}{\Delta x^{2}}$$

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This is convenient for the derivation of  $\frac{\partial}{\partial x} \left( \mathcal{D} \frac{\partial c}{\partial x} \right)$ :

$$\begin{split} \frac{\partial}{\partial x} \left( \mathcal{D} \frac{\partial c}{\partial x} \right) &= \frac{\mathcal{D}_{i+\frac{1}{2}} \frac{\partial c}{\partial x} \Big|_{i+\frac{1}{2}} - \mathcal{D}_{i-\frac{1}{2}} \frac{\partial c}{\partial x} \Big|_{i-\frac{1}{2}}}{\Delta x} = \frac{\mathcal{D}_{i+\frac{1}{2}} \frac{c_{i+1} - c_i}{\Delta x} - \mathcal{D}_{i-\frac{1}{2}} \frac{c_i - c_{i-1}}{\Delta x}}{\Delta x} \\ &= \frac{\mathcal{D}_{i+\frac{1}{2}} c_{i+1} - \left( \mathcal{D}_{i+\frac{1}{2}} + \mathcal{D}_{i-\frac{1}{2}} \right) c_i + \mathcal{D}_{i-\frac{1}{2}} c_{i-1}}{(\Delta x)^2} \end{split}$$

$$\frac{\partial^2 f}{\partial x^2} \qquad i - 1 \qquad \stackrel{i - \frac{1}{2}}{\times} \qquad \stackrel{i}{\times} \qquad \stackrel{i + }{\times}$$

$$\frac{\partial^{2} f}{\partial x^{2}} \qquad i - 1 \qquad i - \frac{1}{2} \qquad i \qquad i + \frac{1}{2} \qquad i + 1$$

$$f_{i+\frac{1}{2}} = f_{i} + \frac{1}{2} \Delta x \frac{\partial f}{\partial x} \Big|_{i} \Delta x + \frac{1}{2} \left( \frac{1}{2} \Delta x \right)^{2} \frac{\partial^{2} f}{\partial x^{2}} \Big|_{i} + \mathcal{O}(\Delta x^{3})$$

$$f_{i-\frac{1}{2}} = f_{i} - \frac{1}{2} \Delta x \frac{\partial f}{\partial x} \Big|_{i} \Delta x + \frac{1}{2} \left( \frac{1}{2} \Delta x \right)^{2} \frac{\partial^{2} f}{\partial x^{2}} \Big|_{i} + \mathcal{O}(\Delta x^{3})$$

$$f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}} = \Delta x \frac{\partial f}{\partial x} + \mathcal{O}(\Delta x^3)$$

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$$f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}} = \Delta x \frac{\partial f}{\partial x} + \mathcal{O}(\Delta x^3)$$

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Symmetric discretization yields second order!

Substitution of spatial derivatives yields:

$$\frac{dc_i}{dt} = \mathcal{D}\frac{c_{i-1} - 2c_i + c_{i+1}}{\Delta x^2} \quad \text{for } i = 0, \dots, N$$

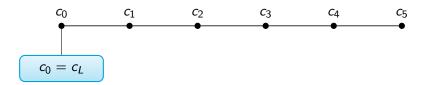
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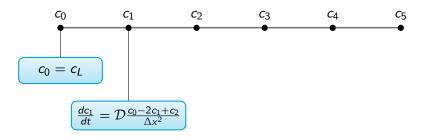
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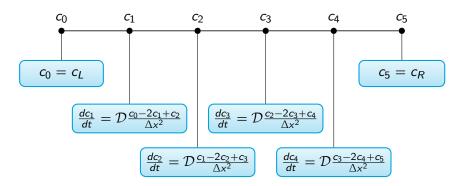
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#### Instationary diffusion equation: boundary conditions

#### Two options:

1 Keep boundary conditions as additional equations:

$$c_{0} = c_{L}, \frac{dc_{1}}{dt} = \mathcal{D}\frac{c_{0} - 2c_{1} + c_{2}}{\Delta x^{2}}, \frac{dc_{2}}{dt} = \mathcal{D}\frac{c_{1} - 2c_{2} + c_{3}}{\Delta x^{2}},$$

$$\frac{dc_{3}}{dt} = \mathcal{D}\frac{c_{2} - 2c_{3} + c_{4}}{\Delta x^{2}}, \frac{dc_{4}}{dt} = \mathcal{D}\frac{c_{3} - 2c_{4} + c_{5}}{\Delta x^{2}}, c_{5} = c_{R}$$

2 Substitute boundary conditions to reduce number of equations:

$$\frac{dc_1}{dt} = \mathcal{D}\frac{c_L - 2c_1 + c_2}{\Delta x^2}, \frac{dc_2}{dt} = \mathcal{D}\frac{c_1 - 2c_2 + c_3}{\Delta x^2}, 
\frac{dc_3}{dt} = \mathcal{D}\frac{c_2 - 2c_3 + c_4}{\Delta x^2}, \frac{dc_4}{dt} = \mathcal{D}\frac{c_3 - 2c_4 + c_R}{\Delta x^2}$$

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# Instationary diffusion equation: temporal discretization

$$\frac{dc_i}{dt} = \mathcal{D}\frac{c_{i-1} - 2c_i + c_{i+1}}{\Delta x^2}$$

#### Time discretization: forward Euler (explicit)

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = \mathcal{D}\frac{c_{i-1}^n - 2c_i^n + c_{i+1}^n}{\Delta x^2}$$

$$\Rightarrow c_i^{n+1} = Foc_{i-1}^n + (1 - 2Fo)c_i^n + Foc_{i+1}^n \quad \text{with } Fo = \frac{\mathcal{D}\Delta t}{\Delta x^2}$$

Straightforward updating (explicit equation), simple to implement in a program but stability constraint  $Fo = \frac{D\Delta t}{\Delta v^2} < \frac{1}{2}!$ 

Small  $\Delta x \Rightarrow$  small  $\Delta t \Rightarrow$  patience required  $\odot$ 

## Instationary diffusion equation: temporal discretization

$$\frac{dc_i}{dt} = \mathcal{D}\frac{c_{i-1} - 2c_i + c_{i+1}}{\Delta x^2}$$

Time discretization: backward Euler (implicit)

$$\begin{split} \frac{c_{i}^{n+1} - c_{i}^{n}}{\Delta t} &= \mathcal{D} \frac{c_{i-1}^{n+1} - 2c_{i}^{n+1} + c_{i+1}^{n+1}}{\Delta x^{2}} \\ \Rightarrow &- Foc_{i-1}^{n+1} + (1 + 2Fo)c_{i}^{n+1} - Foc_{i+1}^{n+1} = c_{i}^{n} \quad \text{with } Fo = \frac{\mathcal{D}\Delta t}{\Delta x^{2}} \end{split}$$

Requires the solution of a system of linear equations, but no stability constraints!

Note: extension to higher order schemes (with time step adaptation) straightforward. Often second or third order optimal, because for each Euler-like step in the additional order an often large system needs to be solved (not treated in this course).

Solve the diffusion problem using explicit discretization:

$$\frac{\partial c_i}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} \quad \text{with} \quad \begin{aligned} 0 &\leq x \leq \delta, \ \delta = 5 \cdot 10^{-3} \text{ m} \\ \delta/\Delta x &= 100 \text{ grid cells} \\ \mathcal{D} &= 1 \cdot 10^{-8} \text{ m}^2 \text{ s}^{-1} \\ t_{\text{end}} &= 5000 \text{ s} \\ c_{\text{L}} &= 1 \text{ mol m}^{-3} \ c_{\text{R}} = 0 \text{ mol m}^{-3} \end{aligned}$$

Solve the diffusion problem using explicit discretization:

$$\frac{\partial c_i}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} \quad \text{with} \quad \begin{aligned} 0 &\leq x \leq \delta, \ \delta = 5 \cdot 10^{-3} \text{ m} \\ \delta/\Delta x &= 100 \text{ grid cells} \\ \mathcal{D} &= 1 \cdot 10^{-8} \text{ m}^2 \text{ s}^{-1} \\ t_{\text{end}} &= 5000 \text{ s} \\ c_{\text{L}} &= 1 \text{ mol m}^{-3} \ c_{\text{R}} = 0 \text{ mol m}^{-3} \end{aligned}$$

$$c_i^{n+1} = Foc_{i-1}^n + (1 - 2Fo)c_i^n + Foc_{i+1}^n$$
 with  $Fo = \frac{\mathcal{D}\Delta t}{\Delta x^2}$ 

Solve the diffusion problem using explicit discretization:

$$\frac{\partial c_i}{\partial t} = \mathcal{D} \frac{\partial^2 c}{\partial x^2} \quad \text{with} \quad \begin{aligned} 0 &\leq x \leq \delta, \ \delta = 5 \cdot 10^{-3} \text{ m} \\ \delta/\Delta x &= 100 \text{ grid cells} \\ \mathcal{D} &= 1 \cdot 10^{-8} \text{ m}^2 \text{ s}^{-1} \\ t_{\text{end}} &= 5000 \text{ s} \\ c_{\text{L}} &= 1 \text{ mol m}^{-3} \ c_{\text{R}} = 0 \text{ mol m}^{-3} \end{aligned}$$

$$c_i^{n+1} = Foc_{i-1}^n + (1 - 2Fo)c_i^n + Foc_{i+1}^n$$
 with  $Fo = \frac{\mathcal{D}\Delta t}{\Delta x^2}$ 

- Initialise variables
- 2 Compute time step so that  $Fo \leq \frac{1}{2} \Rightarrow \Delta t = 0.125$ s!
- 3 Compute 40000 time steps times 100 grid nodes!
- 4 Store solution

Initialise the variables and matrices:

```
Nx = 100; % Nc grid points
Nt = 40000; % Nt time steps
         % m/s
D = 1e-8;
c_L = 1.0; c_R = 0; \% mol/m3
t_end = 5000.0; % s
x_{end} = 5e-3; % m
% Time step and grid size
dt = t end/Nt:
dx = x_end/Nx;
% Fourier number
Fo=D*dt/dx/dx
% Initial matrices for solutions (Nx times Nt)
c = zeros(Nt+1,Nx+1);  % All concentrations are zero
% Grid node and time step positions
x = linspace(0, x_end, Nx+1);
```

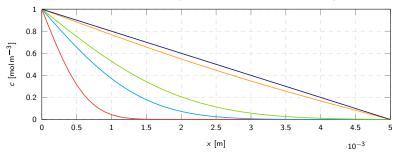
Compute the solution (nested time-and-grid loop):

```
for n = 1:Nt % time loop
    for i = 2:Nx % Nested loop for grid nodes
        c(n+1,i) = Fo*c(n,i-1) + (1-2*Fo)*c(n,i) + ...
        Fo*c(n,i+1);
    end
end
```

#### Compute the solution (nested time-and-grid loop):

```
for n = 1:Nt % time loop
    for i = 2:Nx % Nested loop for grid nodes
        c(n+1,i) = Fo*c(n,i-1) + (1-2*Fo)*c(n,i) + ...
            Fo*c(n,i+1);
    end
end
```

## Plotting the solution at $t = \{12.5, 62.5, 125, 625, 5000\}$ s.



Linear system 
$$Ax = b$$
 from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$ 

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ -Fo & (1+2Fo) & -Fo & 0 & \cdots & 0 \\ 0 & -Fo & (1+2Fo) & -Fo & \cdots & 0 \\ 0 & 0 & -Fo & (1+2Fo) & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ \vdots \\ c_n^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ \vdots \\ c_m^n \end{pmatrix}$$

Linear system 
$$A\mathbf{x} = \mathbf{b}$$
 from  $-Foc_{i-1}^{n+1} + (1+2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$ 

$$\begin{pmatrix} \mathbf{1} & 0 & 0 & 0 & \cdots & 0 \\ -Fo & (1+2Fo) & -Fo & 0 & \cdots & 0 \\ 0 & -Fo & (1+2Fo) & -Fo & \cdots & 0 \\ 0 & 0 & -Fo & (1+2Fo) & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \cdot \begin{pmatrix} \mathbf{c}_0^{n+1} \\ \mathbf{c}_1^{n+1} \\ \mathbf{c}_2^{n+1} \\ \vdots \\ \mathbf{c}_m^{n+1} \end{pmatrix} = \begin{pmatrix} \mathbf{c}_0^n \\ \mathbf{c}_1^n \\ \mathbf{c}_2^n \\ \vdots \\ \mathbf{c}_m^n \end{pmatrix}$$

 $1 \times c_0^{n+1} = c_0^n$  (boundary condition)

Linear system 
$$A\mathbf{x} = \mathbf{b}$$
 from  $-Foc_{i-1}^{n+1} + (1+2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$ 

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ -Fo & (1+2Fo) & -Fo & 0 & \cdots & 0 \\ 0 & -Fo & (1+2Fo) & -Fo & \cdots & 0 \\ 0 & 0 & -Fo & (1+2Fo) & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ \vdots \\ c_m^n \end{pmatrix}$$

$$1 \times c_0^{n+1} = c_0^n$$
 (boundary condition)  
 $-Foc_0^{n+1} + (1 + 2Fo)c_1^{n+1} - Foc_2^{n+1} = c_1^n$ 

Linear system 
$$Ax = b$$
 from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$ 

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ -Fo & (1+2Fo) & -Fo & 0 & \cdots & 0 \\ 0 & -Fo & (1+2Fo) & -Fo & \cdots & 0 \\ 0 & 0 & -Fo & (1+2Fo) & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ \vdots \\ c_m^n \end{pmatrix}$$

$$\begin{split} &1\times c_0^{n+1}=c_0^n \text{ (boundary condition)}\\ &-Foc_0^{n+1}+(1+2Fo)c_1^{n+1}-Foc_2^{n+1}=c_1^n\\ &-Foc_1^{n+1}+(1+2Fo)c_2^{n+1}-Foc_3^{n+1}=c_2^n \end{split}$$

Linear system 
$$A\mathbf{x} = \mathbf{b}$$
 from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$ 

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ -Fo & (1+2Fo) & -Fo & 0 & \cdots & 0 \\ 0 & -Fo & (1+2Fo) & -Fo & \cdots & 0 \\ 0 & 0 & -Fo & (1+2Fo) & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ \vdots \\ c_m^n \end{pmatrix}$$

$$\begin{split} &1\times c_0^{n+1}=c_0^n \text{ (boundary condition)}\\ &-Foc_0^{n+1}+(1+2Fo)c_1^{n+1}-Foc_2^{n+1}=c_1^n\\ &-Foc_1^{n+1}+(1+2Fo)c_2^{n+1}-Foc_3^{n+1}=c_2^n\\ &-Foc_2^{n+1}+(1+2Fo)c_3^{n+1}-Foc_4^{n+1}=c_3^n \end{split}$$

Linear system 
$$A\mathbf{x} = \mathbf{b}$$
 from  $-Foc_{i-1}^{n+1} + (1 + 2Fo)c_i^{n+1} - Foc_{i+1}^{n+1} = c_i^n$ 

$$\begin{pmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ -Fo & (1+2Fo) & -Fo & 0 & \cdots & 0 \\ 0 & -Fo & (1+2Fo) & -Fo & \cdots & 0 \\ 0 & 0 & -Fo & (1+2Fo) & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 \end{pmatrix} \cdot \begin{pmatrix} c_0^{n+1} \\ c_1^{n+1} \\ c_2^{n+1} \\ \vdots \\ c_m^{n+1} \end{pmatrix} = \begin{pmatrix} c_0^n \\ c_1^n \\ c_2^n \\ \vdots \\ c_m^n \end{pmatrix}$$

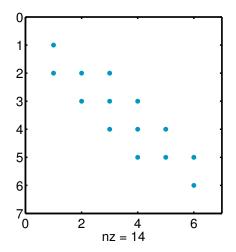
$$\begin{split} &1\times c_0^{n+1}=c_0^n \text{ (boundary condition)}\\ &-Foc_0^{n+1}+(1+2Fo)c_1^{n+1}-Foc_2^{n+1}=c_1^n\\ &-Foc_1^{n+1}+(1+2Fo)c_2^{n+1}-Foc_3^{n+1}=c_2^n\\ &-Foc_2^{n+1}+(1+2Fo)c_3^{n+1}-Foc_4^{n+1}=c_3^n\\ &1\times c_m^{n+1}=c_m^n \text{ (boundary condition)} \end{split}$$

To solve the linear system, we need to define matrix A. It is clear that storing many zeros is not efficient in terms of memory. We use a sparse matrix format:

```
% Bands in matrix (internal cells)
A = sparse(Nx+1, Nx+1);
for i=2:Nx
   A(i,i-1) = -Fo;
   A(i,i) = (1+2*Fo);
   A(i,i+1) = -Fo;
end
% Set boundary cells, independent on neighbors:
A(1,1) = 1; % Left
A(Nx+1,Nx+1) = 1; % Right
```

# Solving the diffusion equation implicitly in Matlab

The command spy(A) shows a figure with the non-zero positions.



## Solving the diffusion equation implicitly in Matlab

The concentration matrix is initialised and the boundary conditions are set as follows:

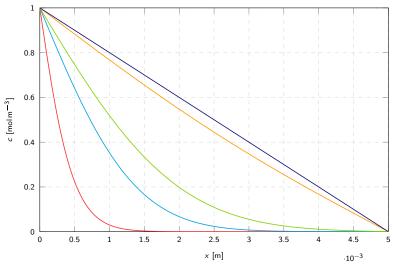
```
% Initial matrices for solutions (Nx times Nt)
c = zeros(Nt+1,Nx+1);  % All concentrations are zero
c(:,1) = c_L;
                % Concentration at left side
c(:,Nx+1) = c_R;
               % Concentration at right side
```

The right hand side vector (**b**) can now be set during the time-loop:

```
for n = 1:Nt-1
                      % time loop
   b = c(n,:)'; % Set right hand side
   solX = A \setminus b;
              % Solve linear system
   c(n+1,:) = solX; % Store solution each time step
end
```

# Solving the diffusion equation implicitly in Matlab

Plotting the solution at  $t = \{12.5, 62.5, 125, 625, 5000\}$  s.



## About explicit vs. implicit solutions

- Explicit solution:
  - Easy to implement
  - Very small time steps required.
  - This problem took about 0.5 s.
- Implicit solution:
  - Harder to implement, needs sparse matrix solver
  - No stability constraint
  - This problem took about 0.05 s
- The difference will become much larger for systems with e.g. more grid nodes!

$$\frac{\partial c}{\partial t} = \mathcal{D}\frac{\partial^2 c}{\partial x^2} + R(c) \quad \text{with} \quad \begin{array}{l} t = 0; 0 \le x \le \ell \Rightarrow c = c_0 \\ t > 0; x = 0 \Rightarrow c = c_L \\ t > 0; x = \ell \Rightarrow c = c_R \end{array}$$

$$\frac{\partial c}{\partial t} = \mathcal{D}\frac{\partial^2 c}{\partial x^2} + R(c) \quad \text{with} \quad \begin{array}{l} t = 0; \ 0 \le x \le \ell \Rightarrow c = c_0 \\ t > 0; \ x = 0 \Rightarrow c = c_L \\ t > 0; \ x = \ell \Rightarrow c = c_R \end{array}$$

• Forward Euler (explicit): simply add to right-hand side

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = \mathcal{D}\frac{c_{i-1}^n - 2c_i^n + c_{i+1}^n}{\Delta x^2} + R(c_i^n)$$

$$\Rightarrow c_i^{n+1} = Foc_{i-1}^n + (1 - 2Fo)c_i^n + Foc_{i+1}^n + R_i^n \Delta t$$

## Extension with non-linear source terms

$$\frac{\partial c}{\partial t} = \mathcal{D}\frac{\partial^2 c}{\partial x^2} + R(c) \quad \text{with} \quad \begin{array}{l} t = 0; 0 \le x \le \ell \Rightarrow c = c_0 \\ t > 0; x = 0 \Rightarrow c = c_L \\ t > 0; x = \ell \Rightarrow c = c_R \end{array}$$

• Forward Euler (explicit): simply add to right-hand side

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = \mathcal{D}\frac{c_{i-1}^n - 2c_i^n + c_{i+1}^n}{\Delta x^2} + R(c_i^n)$$

$$\Rightarrow c_i^{n+1} = Foc_{i-1}^n + (1 - 2Fo)c_i^n + Foc_{i+1}^n + R_i^n \Delta t$$

Backward Euler (implicit): linearization required

$$R(c_{i}^{n+1}) = R(c_{i}^{n}) + \frac{dR}{dc} \Big|_{i}^{n} (c_{i}^{n+1} - c_{i}^{n})$$

$$\frac{c_{i}^{n+1} - c_{i}^{n}}{\Delta t} = \mathcal{D} \frac{c_{i-1}^{n+1} - 2c_{i}^{n+1} + c_{i+1}^{n+1}}{\Delta x^{2}} + R(c_{i}^{n+1})$$

$$\Rightarrow -Foc_{i-1}^{n+1} + (1 + 2Fo - \frac{dR}{dc} \Big|_{i}^{n} \Delta t)c_{i}^{n+1} - Foc_{i+1}^{n+1} = c_{i}^{n} + \left( R_{i}^{n} - \frac{dR}{dc} \Big|_{i}^{n} c_{i}^{n} \right) \Delta t$$

## Extension with convection terms

$$\frac{\partial c}{\partial t} = \mathcal{D}\frac{\partial^2 c}{\partial x^2} - u\frac{\partial c}{\partial x} + R$$

Discretization of first derivative  $\frac{dc}{dx}$ , looks simple but is numerical headache!

Central discretization:

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

⇒ simple and easy, too bad it doesn't work: yields unstable solutions if convection dominated.

Unsteady convection:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Central difference for first derivative:

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

Unsteady convection:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Central difference for first derivative:

Convection

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = -u \frac{c_{i+1} - c_{i-1}}{2\Delta x} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_{i+1}^n - c_{i-1}^n}{2\Delta x} \Delta t$$

Unsteady convection:

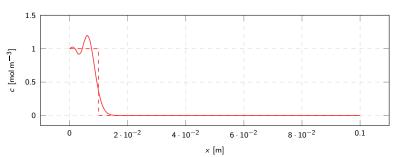
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Central difference for first derivative:

Convection

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = -u \frac{c_{i+1} - c_{i-1}}{2\Delta x} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_{i+1}^n - c_{i-1}^n}{2\Delta x} \Delta t$$



Unsteady convection:

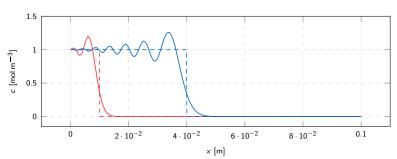
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Central difference for first derivative:

Convection

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = -u \frac{c_{i+1} - c_{i-1}}{2\Delta x} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_{i+1}^n - c_{i-1}^n}{2\Delta x} \Delta t$$



Unsteady convection:

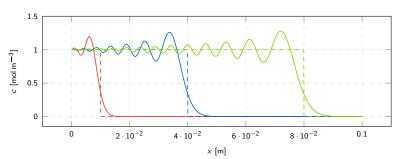
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Central difference for first derivative:

Convection

$$\frac{dc}{dx} = \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

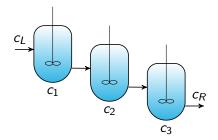
$$\frac{c_{i}^{n+1} - c_{i}^{n}}{\Delta t} = -u \frac{c_{i+1} - c_{i-1}}{2\Delta x} \Rightarrow c_{i}^{n+1} = c_{i}^{n} - u \frac{c_{i+1}^{n} - c_{i-1}^{n}}{2\Delta x} \Delta t$$



Convection 0000000

#### Extension with convection terms

Solution: upwind discretization, like CSTR's in series:

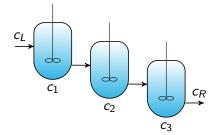


First order upwind: 
$$-u\frac{dc}{dx}\Big|_i = \begin{cases} -u\frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \ge 0\\ -u\frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

Convection

## Extension with convection terms

Solution: upwind discretization, like CSTR's in series:



First order upwind: 
$$-u\frac{dc}{dx}\Big|_i = \begin{cases} -u\frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \ge 0\\ -u\frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

Stable if  $Co = \frac{u\Delta t}{\Delta x} < 1$  (with Co the Courant number). However, only 1st order accurate (large smearing of concentration fronts). Higher order upwind requires TVD schemes (trick of the trade)...

## First order upwind scheme of 1st derivative

Unsteady convection:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

Upwind scheme for first derivative:

$$-u\frac{dc}{dx}\Big|_{i} = \begin{cases} -u\frac{c_{i} - c_{i-1}}{\Delta x} & \text{if } u \ge 0\\ -u\frac{c_{i+1} - c_{i}}{\Delta x} & \text{if } u < 0 \end{cases}$$

## First order upwind scheme of 1st derivative

Unsteady convection:

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$

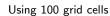
Upwind scheme for first derivative:

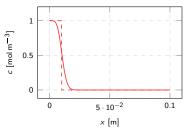
$$\frac{c_i^{n+1} - c_i^n}{\Delta t} = -u \frac{c_{i+1} - c_{i-1}}{2\Delta x}$$

$$\Rightarrow c_i^{n+1} = \begin{cases} c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} & \text{if } u \ge 0 \\ c_i^n - u \frac{c_{i+1} - c_i}{\Delta x} & \text{if } u < 0 \end{cases}$$

$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x}$$
 with  $u = 0.1 \text{m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$ 

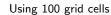
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

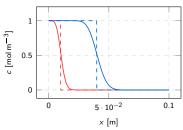






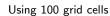
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

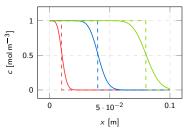






$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

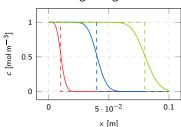






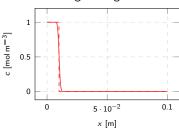
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells





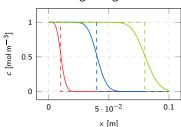
Using 1000 grid cells





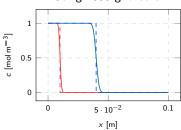
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells





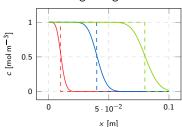
Using 1000 grid cells





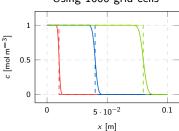
$$\frac{\partial c}{\partial t} = -u \frac{\partial c}{\partial x} \quad \text{with} \quad u = 0.1 \text{m s}^{-1} \Rightarrow c_i^{n+1} = c_i^n - u \frac{c_i - c_{i-1}}{\Delta x} \Delta t$$

Using 100 grid cells





Using 1000 grid cells





Convection 0000000

The results from the previous slides were computed using this script:

```
Nx = 1000:
             % Nc grid points
Nt = 10000; % Nt time steps
u = 0.001; % m/s
c_in = 1.0; % mol/m3
t_{end} = 100.0; % s
x_{end} = 0.1; % m
% Time step and grid size
dt = t_end/Nt; dx = x_end/Nx;
% Courant number
Co=u*dt/dx
% Initial matrices for solutions (Nx times Nt)
c1 = zeros(Nt+1,Nx+1); % All concentrations are zero
an = c1; c2 = c1; % Analytical and upwind solution
% Grid node and time step positions
x = linspace(0, x_end, Nx+1);
t = linspace(0,t_end,Nt+1);
```

Convection 0000000

#### (continued)

```
for n = 1:Nt % time loop
    for i = 2:Nx % Nested loop for grid nodes
        % Central difference
        c1(n+1,i) = c1(n,i) - u*((c1(n,i+1) - ...
            c1(n.i-1))/(2*dx))*dt:
        % Upwind
        c2(n+1,i) = c2(n,i) - u*((c2(n,i) - ...
            c2(n,i-1))/(dx))*dt;
        % Analytical
        an(n+1,i) = (x(i) < u*t(n+1))*c_in;
    end
end
```

- Explicit methods: straightforward extension
- Implicit methods: yields block-tridiagonal matrix (note ordering of equations: all variables per grid cell)

## Extension to 2D or 3D systems

#### Spatial discretization in 2 directions — different methods available:

- Explicit
- Fully implicit
  - 1D gives tri-diagonal matrix
  - 2D gives penta-diagonal matrix
  - 3D gives hepta-diagonal matrix

Use of dedicated matrix solvers (e.g. ICCG, multigrid, ...)

- Alternating direction implicit (ADI)
  - Per direction implicit, but still overall unconditionally stable

# Further extensions for parabolic PDEs

- Higher order temporal discretization (multi-step) with time step adaptation
- Non-uniform grids with automatic grid adaptation
- Higher-order discretization methods, especially higher order TVD (flux delimited) schemes for convective fluxes (e.g. WENO schemes)
- Higher-order finite volume schemes (Riemann solvers)

## Summary

- Several classes of PDEs were introduced.
  - Elliptic, Parabolic, Hyperbolic PDEs
- Diffusion equation: discretization of temporal and spatial domain was discussed
  - Solutions of the diffusion equation using explicit and implicit methods
  - How to add non-linear source terms
- Convection: upwind vs. central difference schemes