Del. no.	Deliverable name	WP	Type	Date	Respon sible	Person Month
D1.2	Software for controlling of balancing and reaching with multiple contacts.	1	SW	M24	UB	16
D3.1	Local solver in rigid-world cases.	3	R	M24	UPMC	18
D4.2	Learning of tasks with multiple contacts by imitation and reinforcement learning.	4	R	M24	TUD	30
D5.2	Validation scenario2: balancing on feet while performing goal directed actions.	5	R	M24	IIT	13

R = Report, **P** = Prototype, **D** = Demonstrator, **SW** = Software, **O** = Other