

CS 181 Machine Learning

Practical 4 Report, Team *la Dernière Dame M*

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1 Problem Description

Set in a *Flappy Bird*-type game *Swingy Monkey*, our current learning goal is to estimate an optimal policy $\pi : \mathcal{S} \rightarrow \mathcal{A}$ such that the expectation of reward function $f : \mathcal{S} \times \mathcal{A} \rightarrow \mathcal{R}$ is maximized, i.e. we aim to identify a π^* such that

$$\pi^* = \arg \max_{\pi} \mathbb{E} \left(f(s, \pi(s)) | s \right)$$

State Space Action Space

Empirical Goal: Score Reward

2 Method

2.1 Rationale on Model Choice

2.1.1 State Reduction and Discretization

2.1.2 Exploration/Exploitation Parameters

Learning rate

ϵ -greedy

3 Result

3.1 State Exploration

3.2 Convergence Behavior

4 Discussion & Possible Directions

Reference

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