# **EECS 331: Introduction to Computational Photography**

HW3: Flash/No Flash Photography

#### 1. Write an Android Program to capture a Flash/No Flash pair

Backbone project was not used due to Tegra Tab's white balance issue, although the code has been included with this assignment.

\*\*The following are the images given in CANVAS.

Fig. 1: Image with flash

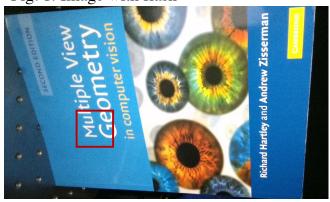
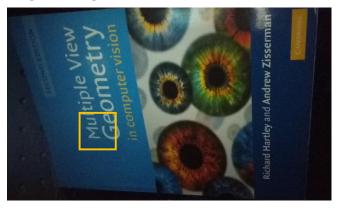




Fig. 2: Image without flash





### 2. De-noising the No-flash image captured previously

MATLAB program was created to de-noise the images (HW3.m)

#### Process:

- 1. Load images to MATLAB
- 2. Crop them to required sizes ( $\sim 1000 \times 800$ )
- 3. Convert to double using im2double function.
- 4. Separate RGB color channels from the image.
- 5. Apply bilateralFilter() to each channel individually using optimal filter settings.
- 6. Concatenate them to form the de-noised image.

#### **Optimal Filter Settings:**

Values for  $\sigma_s$  and  $\sigma_R$  are selected by fine-tuning for best results.

 $\sigma_s = 5$ 

 $\sigma_{R} = 0.05$ 

Fig.3: De-noised No-flash image



### 3. Extract the details from the flash image and fuse the images together

Bilateral filter applied to image with Flash.

#### Optimal Filter Settings (For Flash image):

Values for  $\sigma_s$  and  $\sigma_R$  are selected by fine-tuning for best results.

 $\sigma_s = 4$ 

 $\sigma_{\scriptscriptstyle R}=0.08$ 

F is flash image (say)

F<sub>D</sub> is the de-noised flash image (say)

A<sub>D</sub> is the de-noised no-flash image (say)

 $\varepsilon = 0.02$  (given)

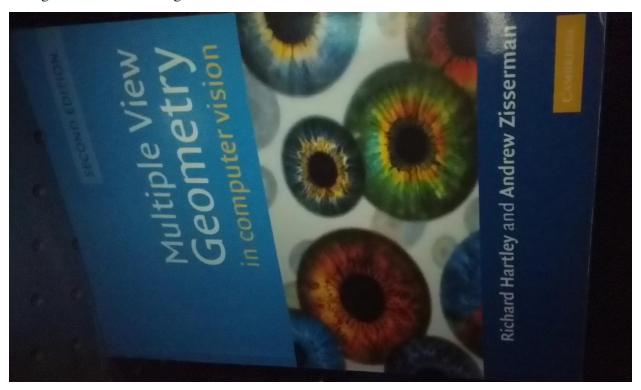
#### Fusing Image for result:

The images are fused together by using the following equation:

$$Fused = A_D * \frac{F + \varepsilon}{F_D + \varepsilon}$$

#### **RESULT:**

Fig.4: Final Fused Image



## **Comparison:**

No-Flash image with high noise



Flash image with high noise



Fused Image with Low Noise right colors

