## Tool info

Serial API: Board: Firmware: Commit:

## Measurement info

Motor: Generic Motor

 $\begin{array}{ll} {\rm KV:} & 0 \\ {\rm Magnet~poles:} & 14 \end{array}$ 

Propeler:

Blade count: 2

Note:

## Measurement Results 1:

Output	Thrust [G]		Torque [G cm]		RPM [1/min]		Voltage [V]		Current [A]		Pin [W]	ThrustEff
[%]	mean	std dev	mean	std dev	mean	std dev	mean	std dev	mean	std dev	FIII [W]	[G/W]
20	70.24	0.323	107.74	2.373	5496	46.7	14.736	0.0057	0.745	0.0289	10.977	6.399
40	205.06	0.344	270.71	2.376	8753	39.3	14.471	0.0069	2.398	0.0293	34.701	5.909
45	250.83	0.585	330.44	2.421	9594	44.7	14.340	0.0075	3.120	0.0498	44.743	5.606
50	301.62	0.747	394.87	2.535	10477	64.2	14.193	0.0091	3.969	0.0653	56.334	5.354
55	355.54	0.714	461.58	2.437	11337	77.5	14.018	0.0101	4.977	0.0818	69.771	5.096
60	410.97	0.735	532.45	2.432	12162	92.4	13.821	0.0118	6.037	0.0778	83.441	4.925

## Plots for Measurement Results:

