

A Comparison of Bootstrap Methods

Justin Papagelis *

Department of Mathematics and Statistics, Amherst College

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Abstract

For my project, I plan to explore different bootstrap methods for creating confidence intervals and then perform comparisons between a couple of the methods. My paper will re-introduce the idea of bootstrap to my peers and give some background on constructing confidence intervals. We will also go deeper into the theory behind the construction of confidence intervals from bootstrapped data. These various methods to create a confidence interval from a bootstrap can include the percentile method, bias-corrected method, accelerated method, and the studentized method, as well as others. I will demonstrate how these bootstrap methods work using “*toy* examples,” which will be datasets in which a specific bootstrap method is appropriate. To demonstrate my understanding of the methods, I will write a simulation to compare a few of them and determine how they perform against each other. I will show my understanding of the different methods of creating confidence intervals from bootstrapped data by communicating the statistical theory in a concise and accessible way to my peers. Writing the simulation and sharing conclusions will demonstrate my ability to implement statistical methods in practice as well as my ability to analyze the results of the simulation.

Keywords: 3 to 6 keywords, that do not appear in the title

*The authors gratefully acknowledge ...

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1 Introduction

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2 Exposition

2.1 The Non-Parametric Bootstrap

Bootstrapping is a statistical method of resampling that allows the estimation of a test statistic from an unknown distribution. In particular, bootstrapping is a computational heavy method which is useful for many different situations.

First, we will introduce the non-parametric bootstrap. Suppose we have a random sample $X = (x_1, x_2, \dots, x_n)$ from our unknown distribution, F and a statistic of interest $\hat{\theta} = \hat{\theta}(X)$ (Efron & Hastie 2021). Ideally, the desired test statistic could be found by repeatedly sampling new reproductions of X from F . However F is unknown, so this is not possible. The non-parametric bootstrap creates an estimate \hat{F} from F using our sample X without making any parametric assumptions (such as distribution). Therefore, the bootstrap sample could be represented as $X^* = (x_1^*, x_2^*, \dots, x_n^*)$ where each x_i^* is sampled randomly with equal probability and with replacement from $\{x_1, x_2, \dots, x_n\}$. From this bootstrap sample, a bootstrap replication of the test statistic can be computed using $\hat{\theta}^* = \hat{\theta}(X^*)$. A large number, B , of bootstrap samples are drawn independently and the corresponding bootstrap replication of the test statistic is calculated.

$$\hat{\theta}^{*b} = \hat{\theta}(X^{*b}) \text{ for } b = 1, 2, \dots, B.$$

The bootstrap estimate of the test statistic is the empirical value of the test statistic from all of the $\hat{\theta}^{*b}$ replications. As B increases, \hat{F} approaches F which means that the test statistic of interest approaches its true value as well.

2.2 Standard Confidence Interval

Confidence intervals are tools that are used to estimate a parameter. Specifically, a confidence interval gives a range in which the true value of the parameter may lie. An α -level

standard confidence interval is given by

$$\hat{\theta}_S[\alpha] = \hat{\theta} \pm z_\alpha \hat{\sigma},$$

where $\hat{\theta}$ is a point estimate of the parameter of interest θ , $\hat{\sigma}$ is the estimate of the standard deviation of $\hat{\theta}$ and z_α is the $(100*\alpha)$ th percentile of the normal deviation (Efron & Tibshirani 1986). We say that the confidence interval constructed in this manner has a chance of capturing the true parameter with a probability of α .

The standard confidence interval is built based on the assumption that the distribution from which we are sampling is Normal. This means that for an unknown distribution, the standard confidence interval could present an incorrect range. However, the same process can be used with bootstrap sampling to form the bootstrap percentile method. This means that an approximate bootstrap confidence interval will be created in the same automatic way that the standard confidence interval was created. For bootstrapped confidence intervals, the number of bootstrap replications B must be large (around 2000) due to the nature of confidence intervals requiring greater accuracy.

2.3 The Percentile Method

The percentile method interval is defined as the interval between the $100 * \alpha$ and the $100(1 - \alpha)$ percentiles of the bootstrap distribution of $\hat{\theta}$. That is, the $(1 - 2\alpha)$ coverage interval can be defined as $[\hat{\theta}_\alpha^*, \hat{\theta}_{1-\alpha}^*]$ (Efron & Tibshirani 1986, Efron & Hastie (2021)). To go further, we can define $\hat{G}(t)$ as the bootstrap cdf, or the proportion of bootstrap samples less than t .

$$\hat{G}(t) = \frac{\#\{\theta^{*b} \leq t\}}{B}.$$

Thus the α th percentile point of the distribution is given by

$$\hat{\theta}_p[\alpha] = \theta_\alpha^* = \hat{G}^{-1}(\alpha).$$

It follows that the percentile interval can be represented as

$$[\hat{G}^{-1}(\alpha), \hat{G}^{-1}(1 - \alpha)].$$

In the case that the bootstrap distribution of $\hat{\theta}^* \sim N(\hat{\theta}, \hat{\sigma}^2)$, the corresponding percentile interval would be equivalent to the standard interval. However, this is not usually the case. When the bootstrap distribution is non-normal, we can suppose that there exists, for all θ ,

$$\hat{\phi} \sim N(\phi, \tau^2),$$

for some monotone transformation $\hat{\phi} = g(\hat{\theta})$, $\phi = g(\theta)$, and τ is a constant. In other words, this transformation perfectly normalizes the distribution of $\hat{\theta}$. This transformation invariant can be applied to the bootstrap replications such that

$$\hat{\phi}^{*b} = g(\hat{\theta}^{*b}) \text{ for } b = 1, 2, \dots, B.$$

The corresponding percentiles of the distribution transform similarly, $\hat{\phi}_\alpha^* = g(\hat{\theta}_\alpha^*)$. Or we can say that the $(1 - 2\alpha)$ percentile interval is $\hat{\phi} \pm \tau z_\alpha$ which can also be represented as $[\hat{\phi}_\alpha^*, \hat{\phi}_{1-\alpha}^*]$. This means that the interval on the θ scale can be defined as

$$\hat{\theta}_\alpha^* = g^{-1}(\hat{\phi} \pm \tau z_\alpha).$$

This also can be represented as an interval,

$$\left[g^{-1}(\hat{\phi} \pm \tau z_{1-\alpha}), g^{-1}(\hat{\phi} \pm \tau z_\alpha) \right].$$

Cite where all this is from

Therefore, the percentile method produces a correct interval for ϕ and due to the transformation invariance, also produces a correct percentile interval for θ . This method assumes the existence of some monotone normalizing mapping $\hat{\phi} = g(\hat{\theta})$, $\phi = g(\theta)$ and relies on that to create a correct interval. Since the process is automatic, we do not need to know the transformation itself, only that it exists. However, in some cases, no monotone normalizing mapping will exist.

2.4 The Bias-Corrected (BC) Method

The next method we will be looking at is the bias-corrected percentile method (BC method) which is an improvement upon the previous percentile method because we now take into account the possibility of bias. It can be shown that $\hat{\theta}$ is biased upwards relative to θ which means that the confidence intervals should be adjusted downwards (Efron & Tibshirani)

[1986, Efron & Hastie (2021)]. From our simulated bootstrap replications $\hat{\theta}^{*1}, \hat{\theta}^{*2}, \dots, \hat{\theta}^{*B}$, define

$$p_0 = \frac{\#\{\hat{\theta}^{*b} \leq \hat{\theta}\}}{B},$$

and define the bias-correction value

$$z_0 = \Phi^{-1}(p_0),$$

where Φ^{-1} is the inverse function of the standard normal cdf. Thus we define a transformation $\hat{\phi} = g(\hat{\theta}), \phi = g(\theta)$ such that for any θ ,

$$\hat{\phi} \sim N(\phi - z_0\tau, \tau^2),$$

with z_0 and τ constants. This means that we can say the bias corrected method has an α -level endpoint can be represented as

$$\hat{\theta}_{BC}[\alpha] = \hat{G}^{-1}[\Phi(2z_0 + z_\alpha)].$$

If $\hat{G} = 0.50$, then half of the bootstrap distribution is less than $\hat{\theta}$ and our bias-correction value $z_0 = 0$. In this case, the confidence interval produced by BC would be the same interval produced by the percentile method.

2.5 The Bias-Corrected and Accelerated (BCa) Method

A further modification upon the BC interval is the bias corrected and accelerated method (BCa). For this method, we assume the standard error, τ , to be constant as we did in the BC interval ([Efron & Tibshirani 1986, Efron & Hastie (2021)]). Rather, we assume the existence of a monotone transformation $\hat{\phi} = g(\hat{\theta}), \phi = g(\theta)$ such that for any θ ,

$$\hat{\phi} \sim N(\phi - z_0\tau_\phi, \tau_\phi^2) \text{ where } \tau_\phi = 1 + a\phi.$$

The a is known as the acceleration and is a constant that describes how the standard deviation of $\hat{\phi}$ varies with ϕ . In other words, a is proportional to the skewness of the bootstrap distribution. For example, for one-parameter exponential families, $a = z_0$, however, there are many different algorithms to compute and estimate a ([Flowers-Cano et al. 2018]). Now, our α -level endpoint from BCa is

$$\hat{\theta}_{BCa}[\alpha] = \hat{G}^{-1}\left[\Phi\left(z_0 + \frac{z_0 + z_\alpha}{1 - a(z_0 + z_\alpha)}\right)\right].$$

If $a = 0$, then $\hat{\theta}_{BCa}[\alpha] = \hat{\theta}_{BC}[\alpha]$. When calculating a BCa interval, the acceleration value a is not a function of the bootstrap distribution and must be calculated separately, however the process is algorithmic and can be calculated without too much work. Each of the three previous methods (percentile, BC, and BCa) all build upon each other and have less restrictive assumptions, however computation increases as we loosen assumptions.

2.6 The Bootstrap-t (Studentized) Method

The bootstrap-t method is the bootstrap-t interval (or the studentized method). Recall from earlier, our sample, X from which we can calculate an estimate, $\hat{\theta}(X)$ of the parameter of interest θ (Efron & Tibshirani 1986, Puth et al. (2015)). We can also estimate $\hat{\sigma}(X)$ for the standard error of θ . We can use these parameters to find the Student's t -statistic defined as

$$T = \frac{\hat{\theta} - \theta}{\hat{\sigma}}.$$

As such, the α th percentile point of a confidence interval of θ would be $\hat{\theta} - \hat{\sigma}T_{(\alpha)}$ where $T_{(\alpha)}$ represents the α th percentile of the t -distribution, T . Unfortunately, the percentiles of the t -distribution are unknown in most cases, but we can use bootstrapping to estimate these percentiles. To do this, we perform a large number, B , of bootstrap samples, from which we can find the bootstrap replications of the parameter of interest, $\hat{\theta}^* = \hat{\theta}(X^*)$, and the standard error, $\hat{\sigma}^* = \hat{\sigma}(X^*)$. From these we can calculate a t -stat

$$T^* = \frac{\hat{\theta}^* - \hat{\theta}}{\hat{\sigma}^*}$$

for each bootstrap sample. Using a large number of these bootstrap samples, we can estimate the percentiles of the t -distribution such that:

$$\hat{T}_{(\alpha)} = B * \alpha\text{th ordered value of all the bootstrap replications of } T^*.$$

This means that for $B = 2000$ and $\alpha = 0.90$, then $\hat{T}_{(\alpha)}$ is the 1,800th ordered point of all of the bootstrap replications of T^* . It follows that the α th studentized confidence interval endpoint can be given with

$$\hat{\theta}_T[\alpha] = \hat{\theta} - \hat{\sigma}T_{(\alpha)},$$

where we can estimate the standard error using

$$\hat{\sigma} = \frac{1 - \hat{\theta}^2}{\sqrt{n}}.$$

Cix again)

One of the main factors why the studentized method is so popular is because we assume that our bootstrapped statistic is pivotal which means that the confidence interval does not depend on any other parameters. Instead, we can calculate the appropriate confidence interval for the parameter of interest specifically from the bootstrapped statistic.

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