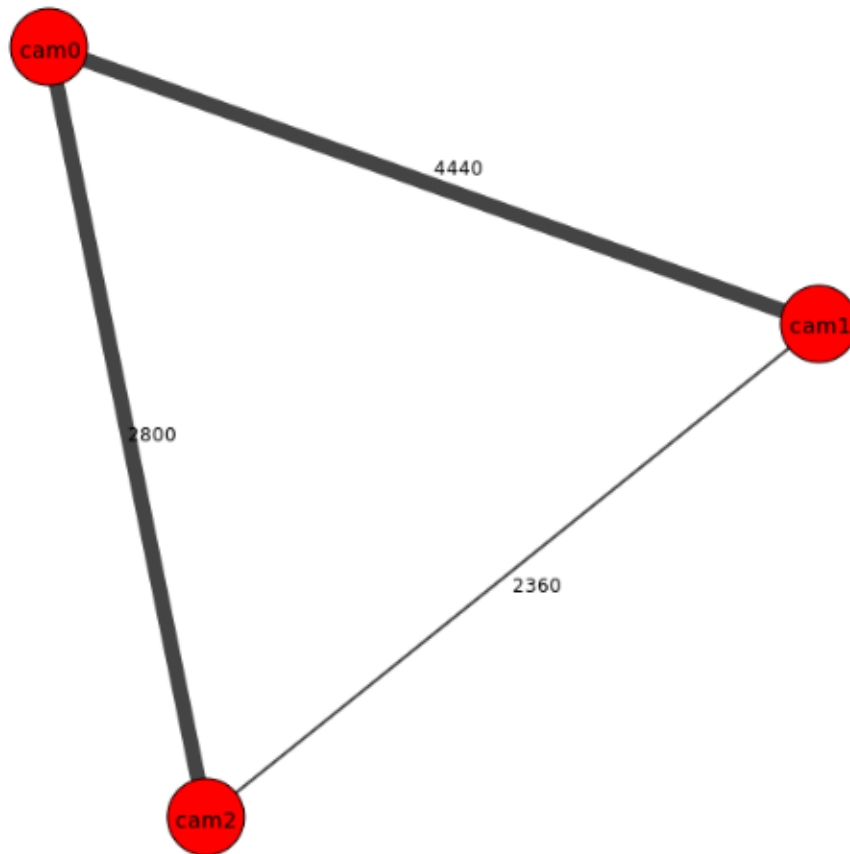
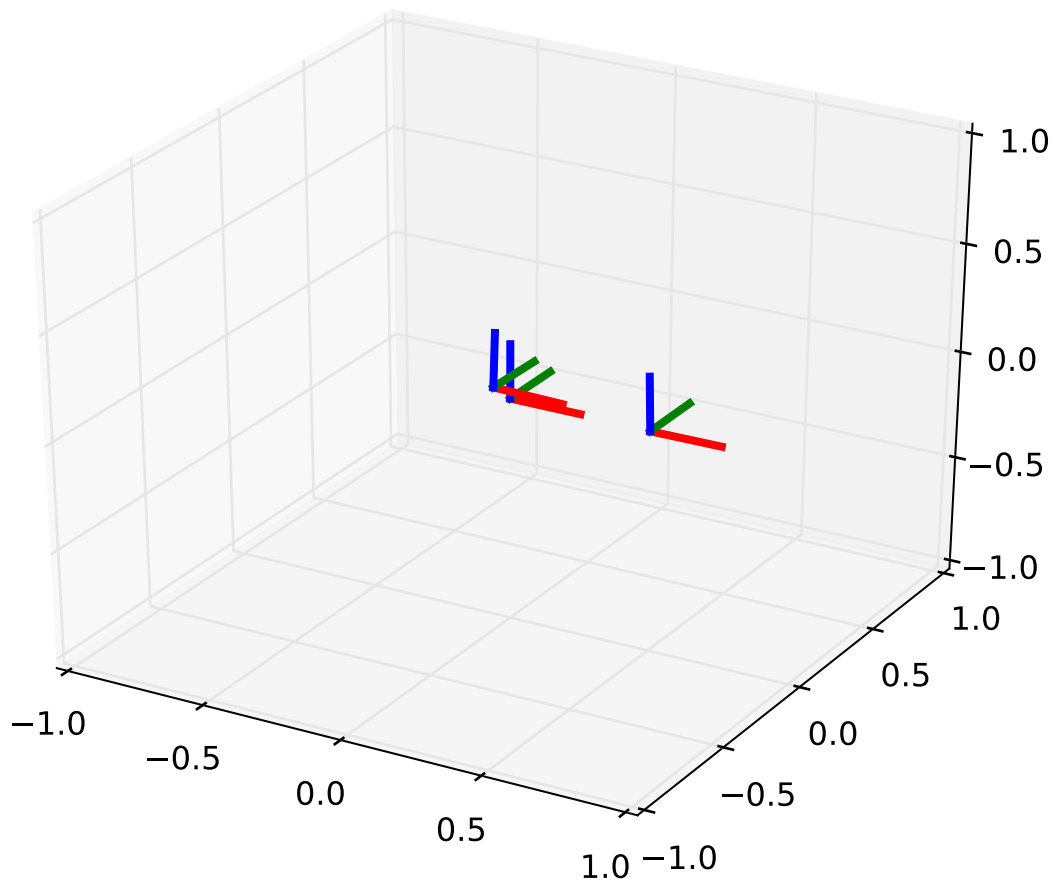


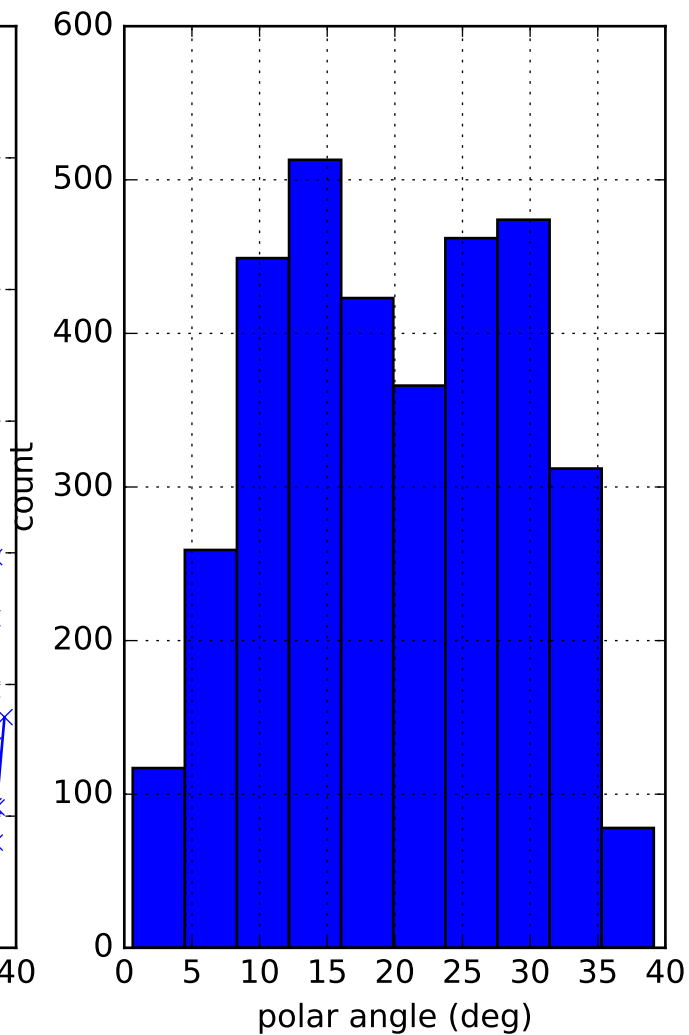
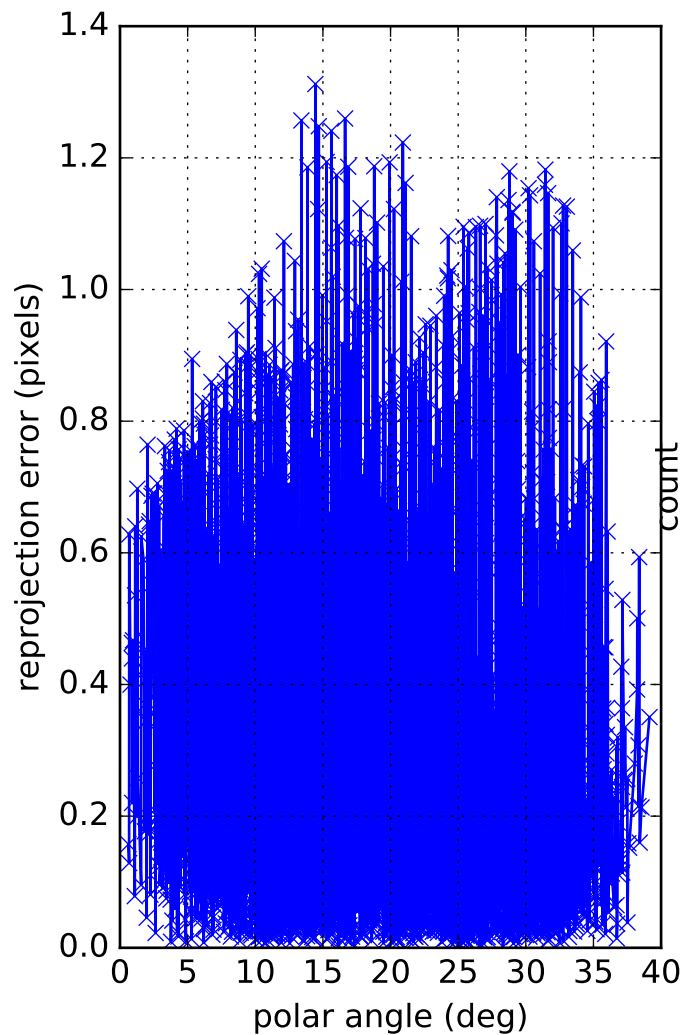
Inter-camera observations graph (edge weight=#mutual obs.)



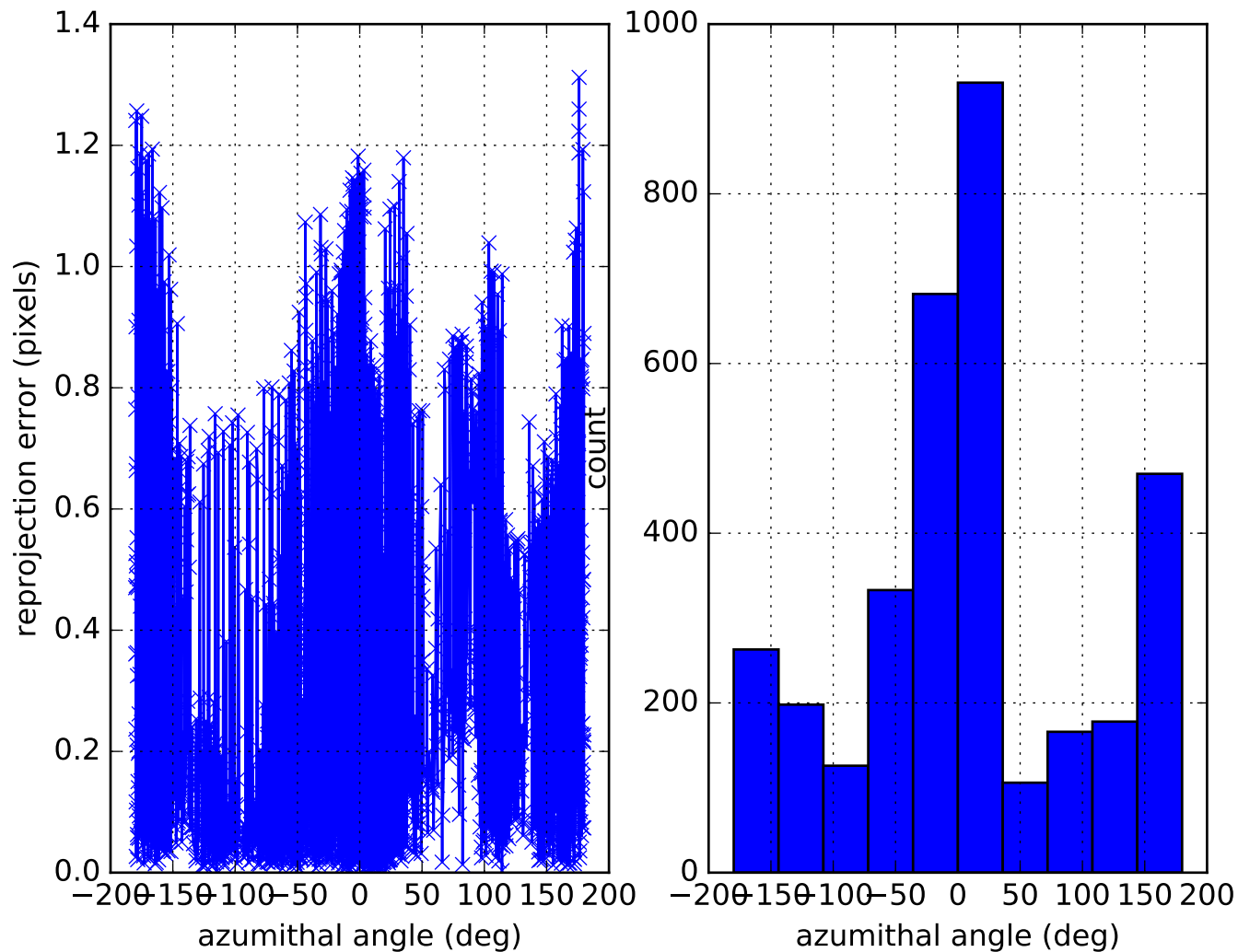
camera system



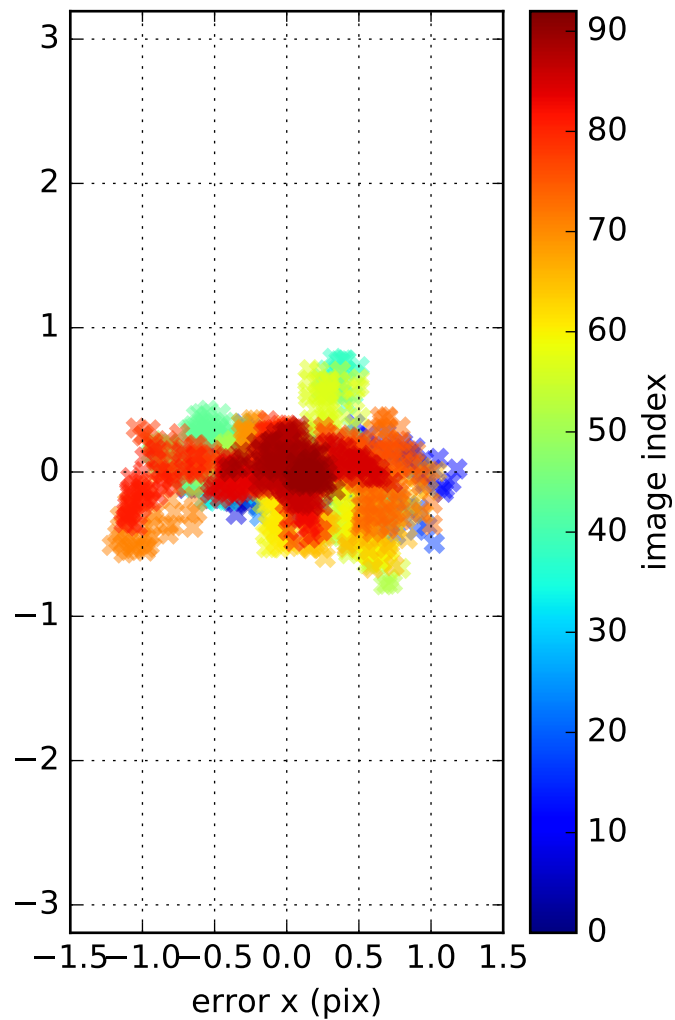
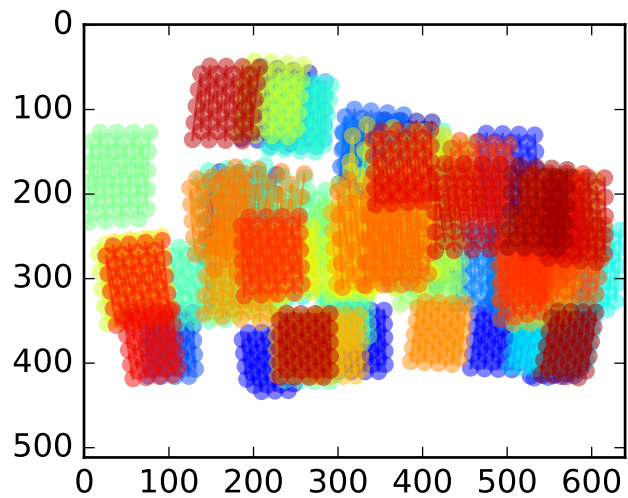
cam0: polar error



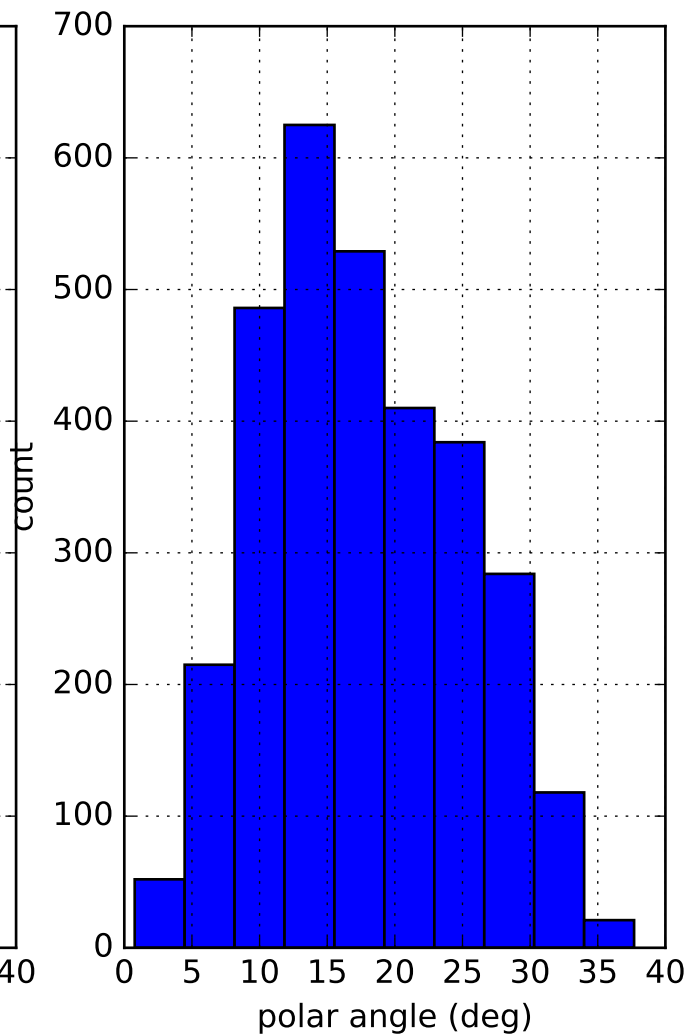
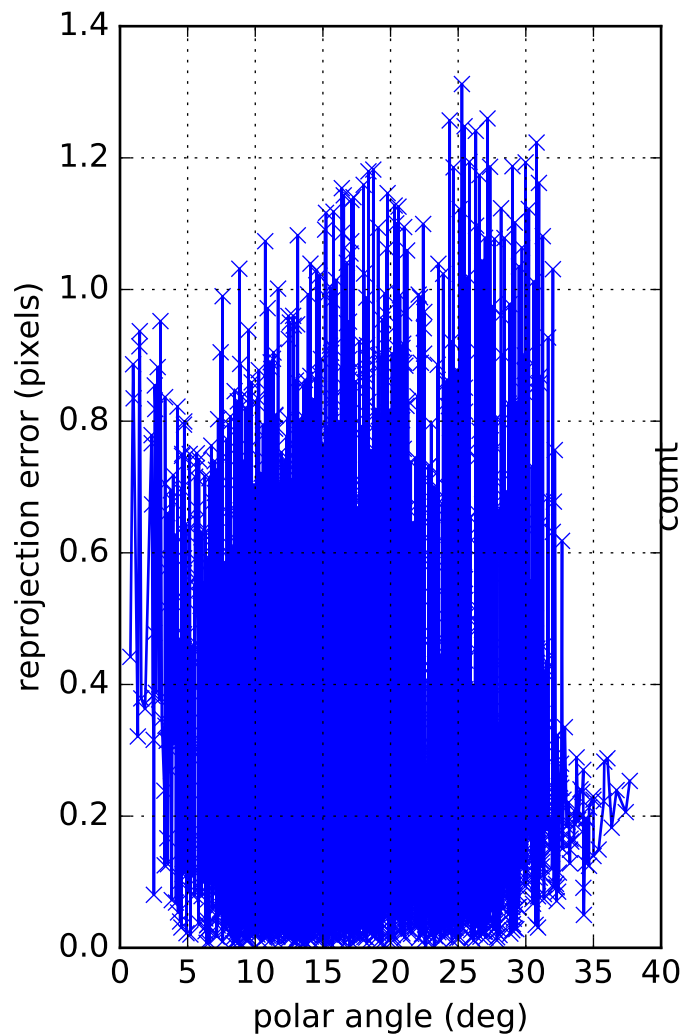
cam0: azimuthal error



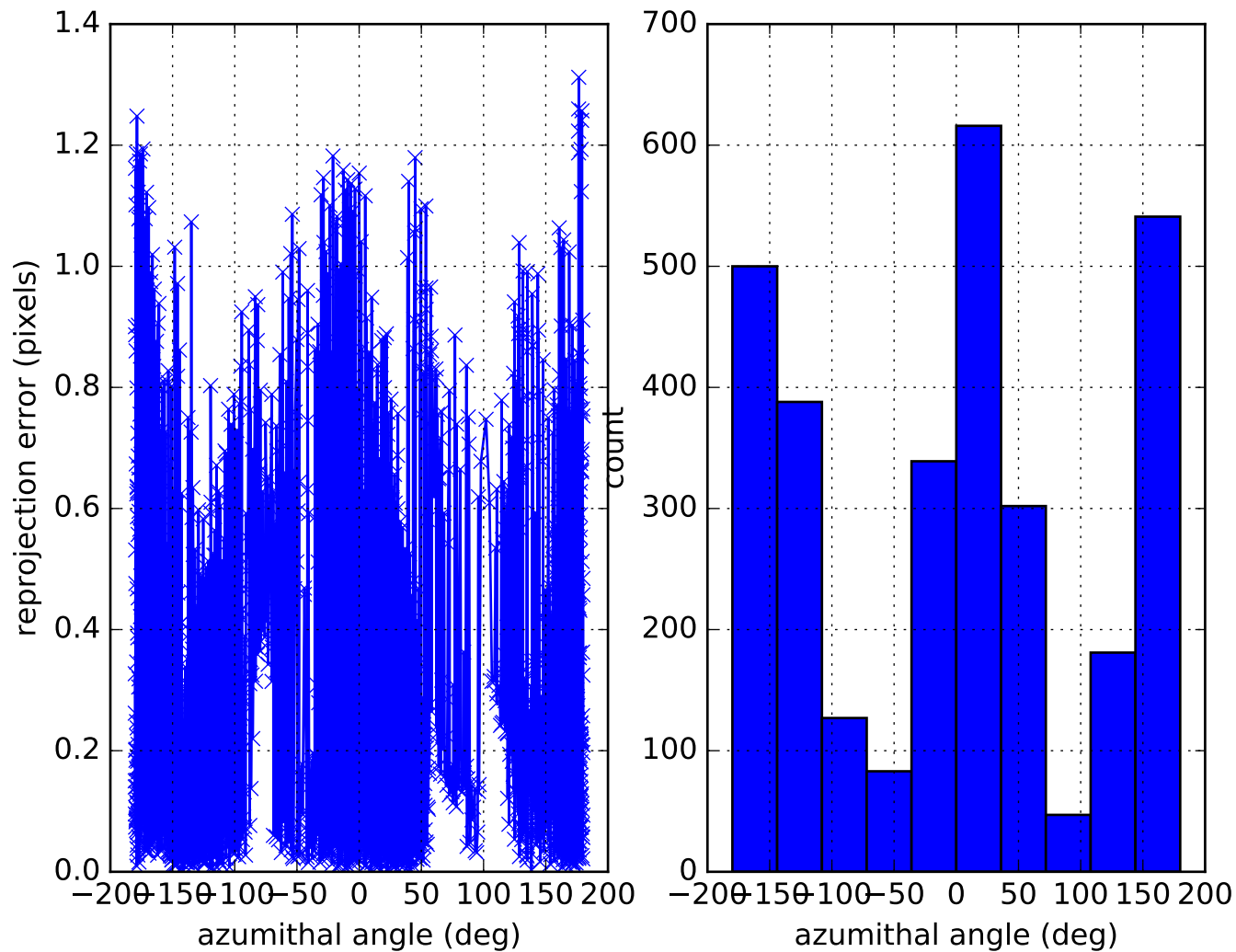
cam0: reprojection errors



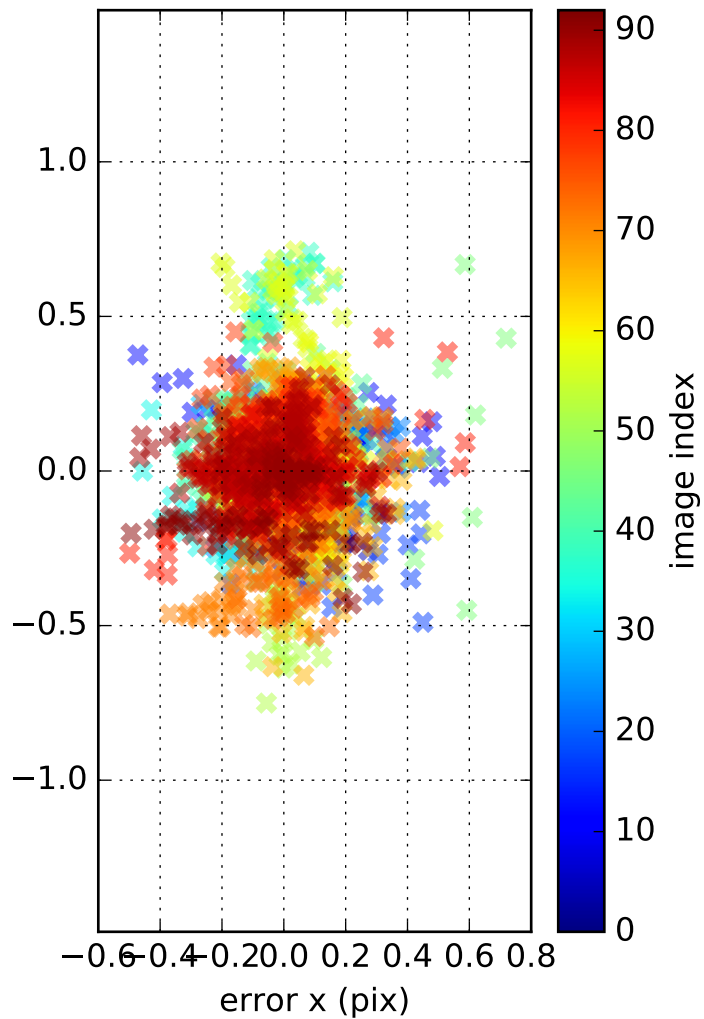
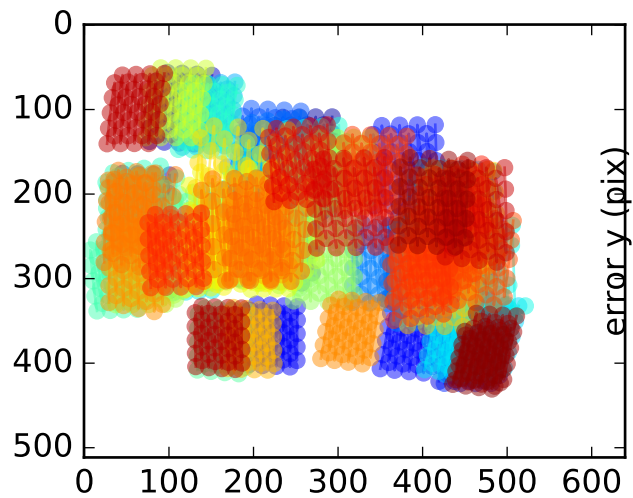
cam1: polar error



cam1: azimuthal error

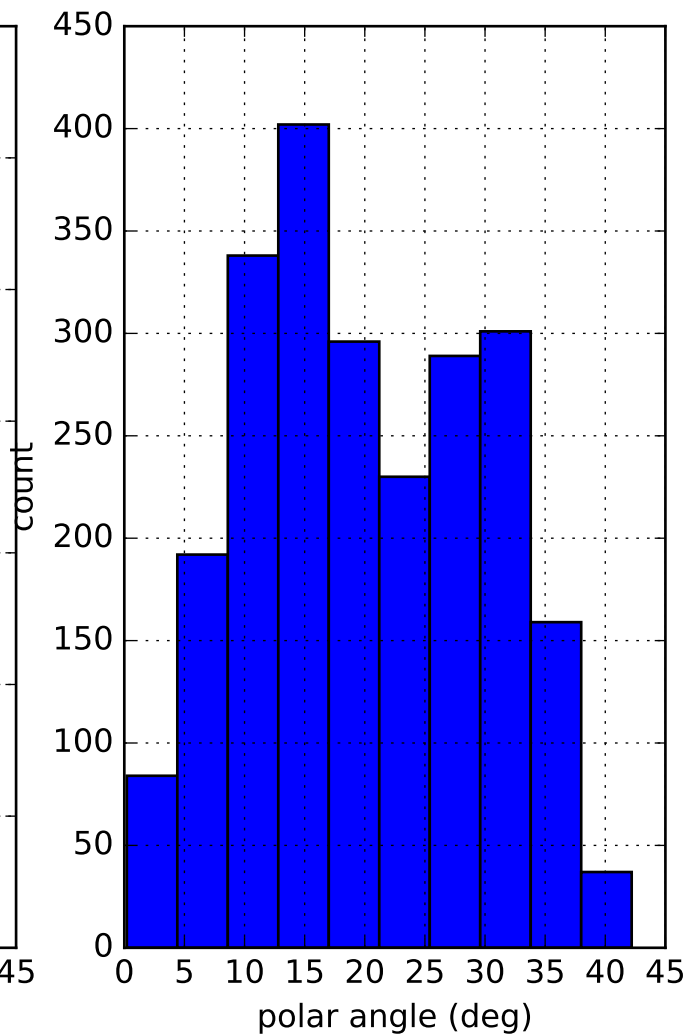
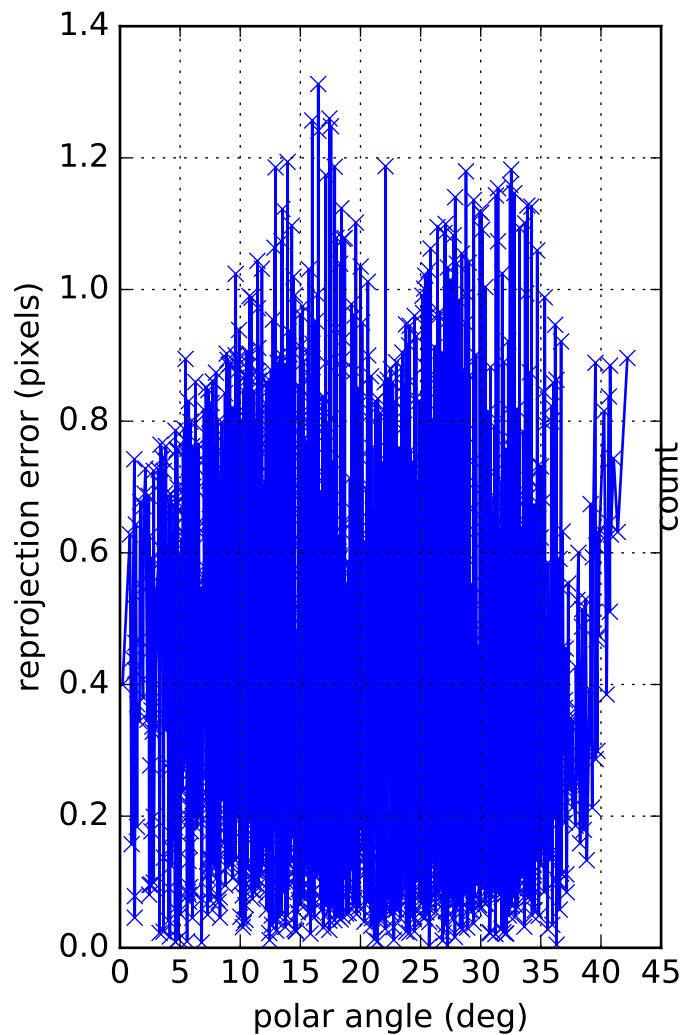


cam1: reprojection errors

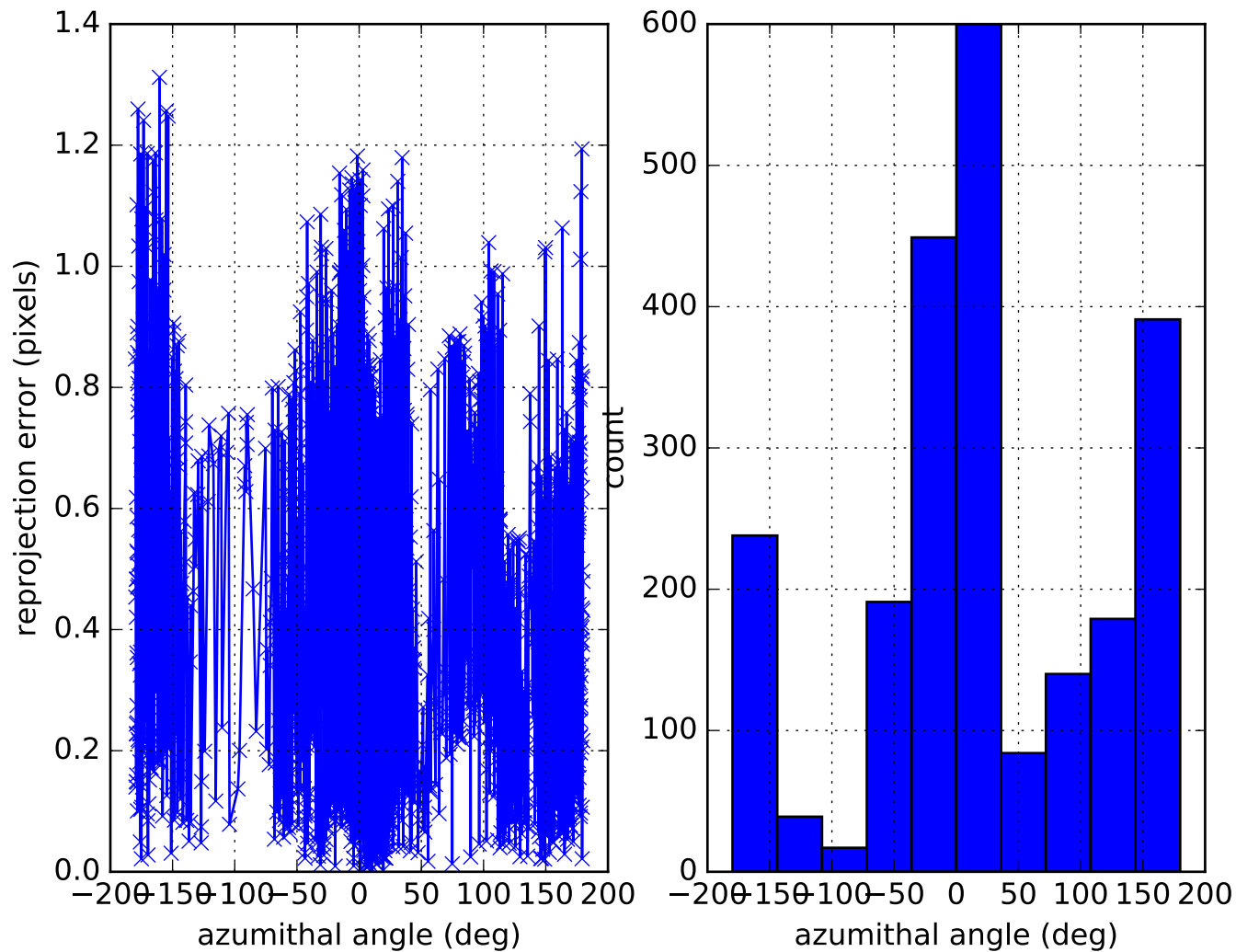




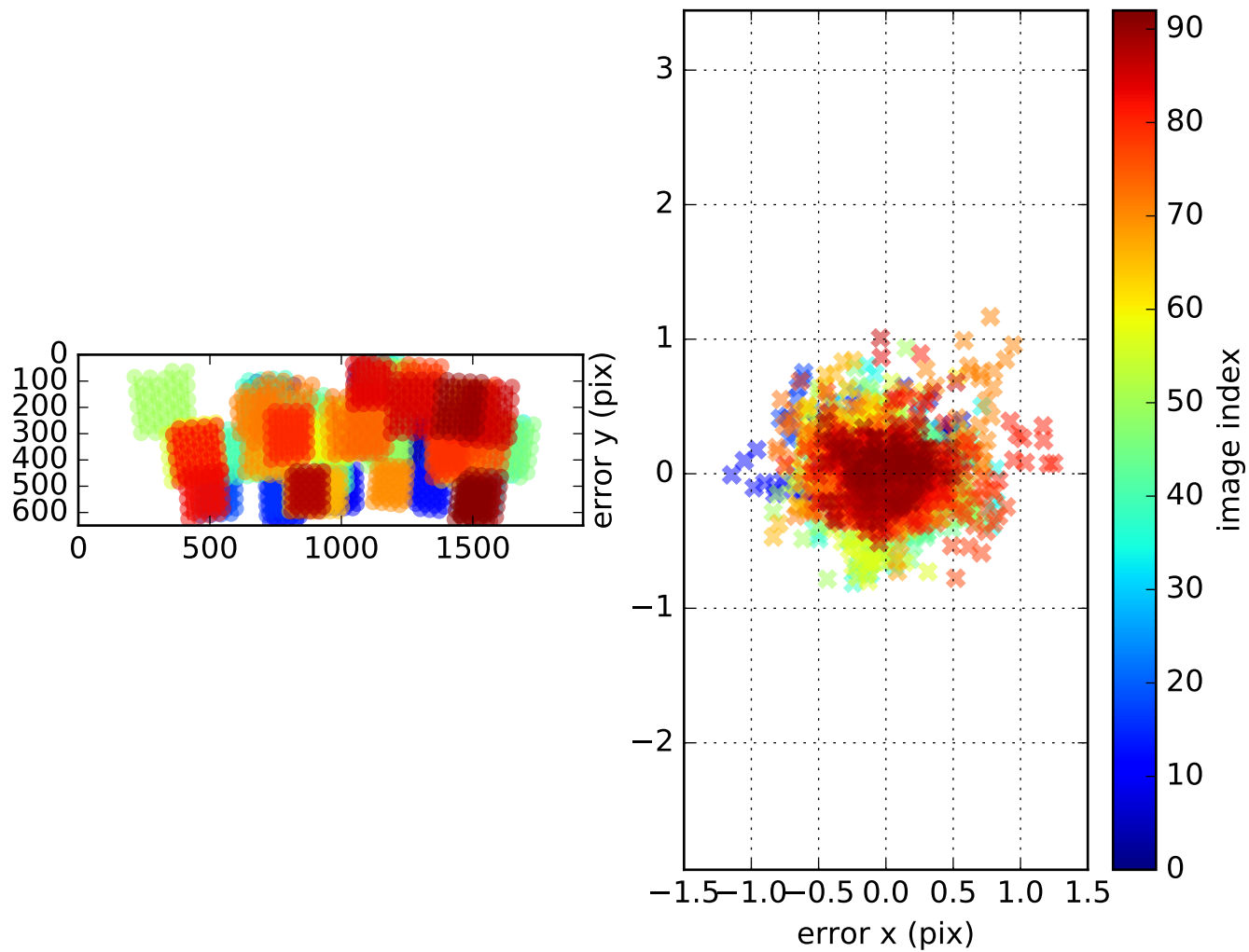
cam2: polar error



cam2: azimuthal error



cam2: reprojection errors



Location of removed outlier corners

