## 13.1 Show from first principles that $P(a \mid b \land a) = 1$ .

A fully specified **probability model** associates a numerical probability  $P(\omega)$  with each possible world. The basic axioms of probability theory say that every possible world has a probability between 0 and 1 and that the total probability of the set of possible worlds is 1:

Being  $\Omega$  the sample space (conformed by all the possible worlds):

$$0 \le P(\omega) \le 1$$
 for every  $\omega$  and  $\sum_{\omega \in \Omega} P(\omega) = 1$ 

For any proposition  $\varphi$ :

$$P(\varphi) = \sum_{\omega \in \varphi} P(\omega)$$

Conditional Probabilities:

$$P(a|b) = \frac{P(a \land b)}{P(b)}$$

## **Proof**

Using the conditional probability definition:

$$P(a \mid b \land a) = \frac{P(a \land b \land a)}{P(b \land a)}$$

By commutative law of intersection  $(a \land b = b \land a)$ 

$$\frac{P(a \land b \land a)}{P(b \land a)} = \frac{P(a \land a \land b)}{P(a \land b)}$$

By associative law of intersection  $(a \land a \land b = (a \land a) \land b = a \land (a \land b))$ 

$$\frac{P(a \land a \land b)}{P(a \land b)} = \frac{P((a \land a) \land b)}{P(a \land b)} =$$

By indempotent law of intersection  $(a \land a = a)$ 

$$\frac{P((a \land a) \land b)}{P(a \land b)} = \frac{P(a \land b)}{P(a \land b)} = 1$$

So, we can say that:

$$P(a \mid b \land a) = 1$$

 $P(b \land a)$  is required to be not zero and this is given by hypothesis

Q.E.D.