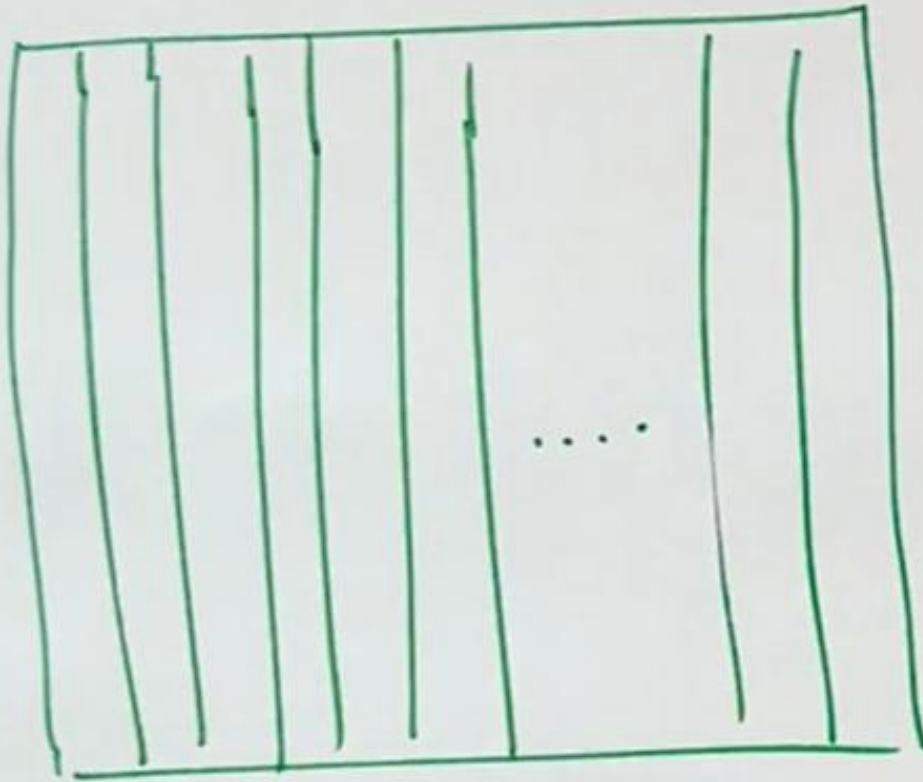
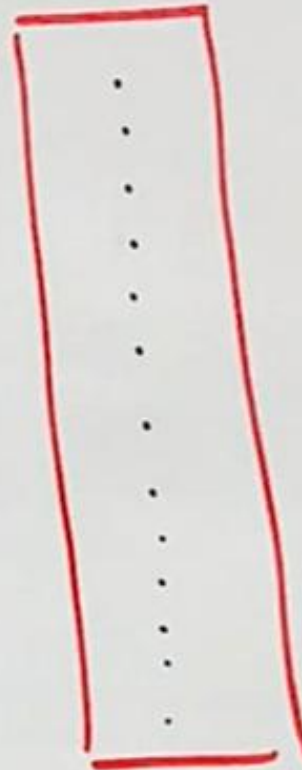


X

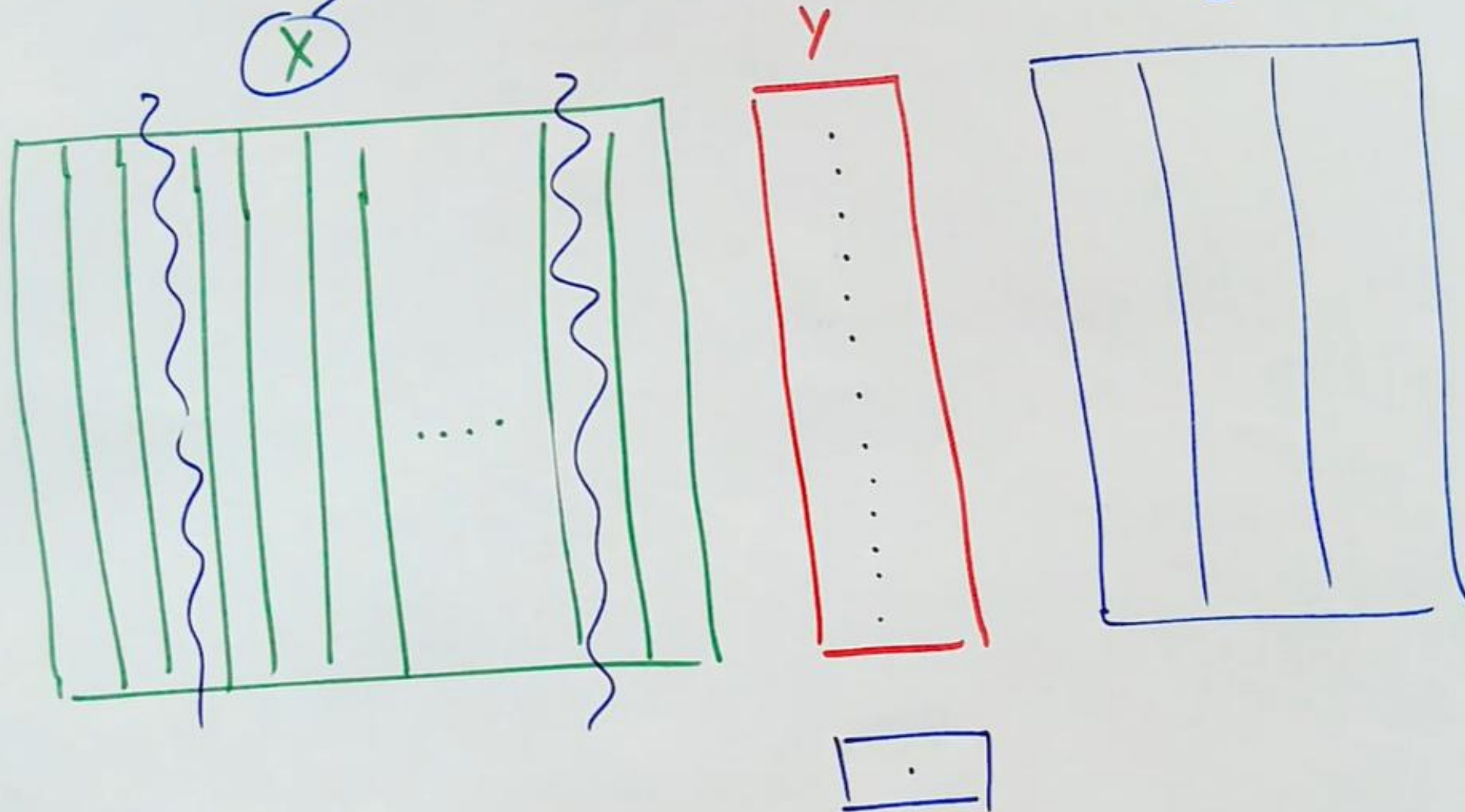


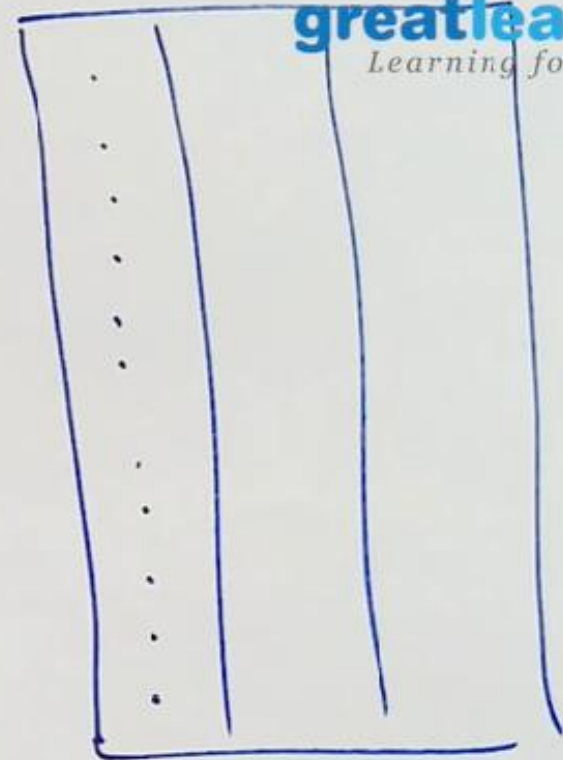
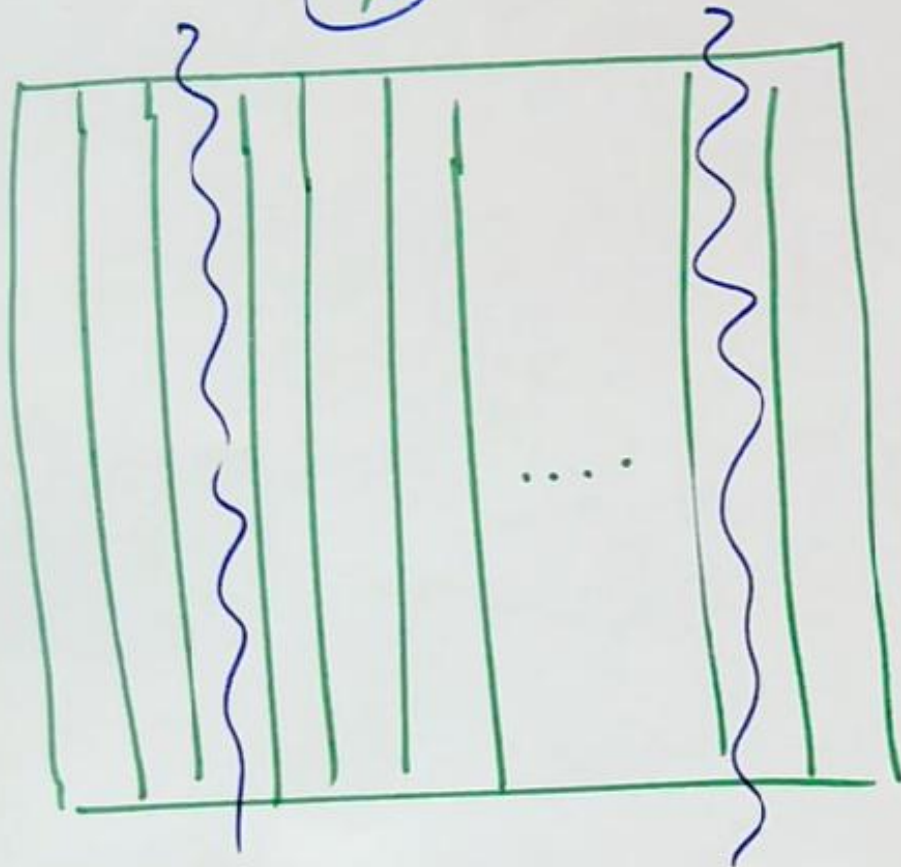
Y



- The process of reducing the number of independent variables
- Reducing dimensionality of independent variables helps in many ways
 - ➔ removes multi-collinearity to improve ML model performance
 - ➔ decreases computational times for fitting models
 - ➔ makes visualization easier
 - ➔ decreases storage requirements
 - ➔ avoids curse of dimensionality
 - ➔ helps reduce over fitting
- Hence dimensionality reduction plays a significant role in analyzing data

- Feature elimination
 - Simply identify and remove variables (columns) that are not important
 - The disadvantage is that we would gain no insight from those dropped variables and lose any information they contain
- Feature extraction
 - Create a few new variables from the old variables
 - **PCA** Principal Component Analysis: is the most popular feature extraction technique



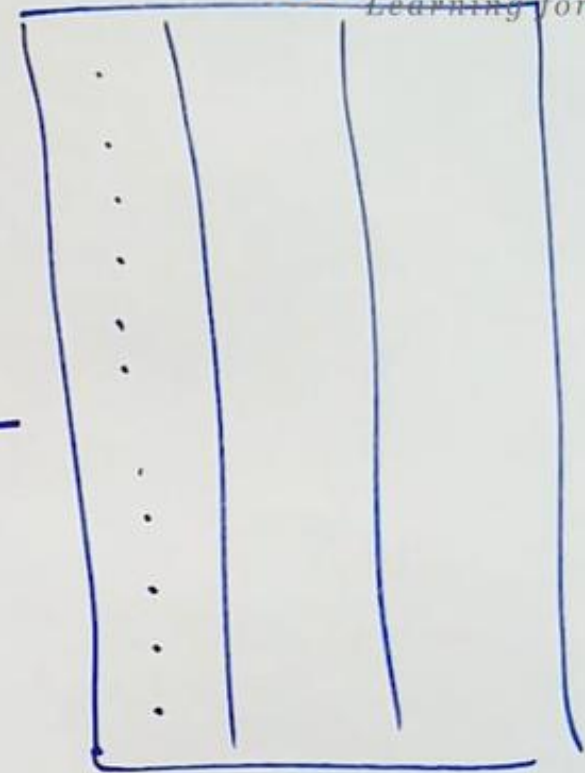
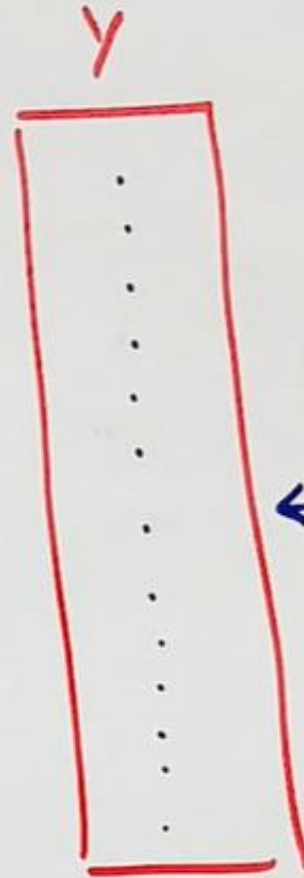
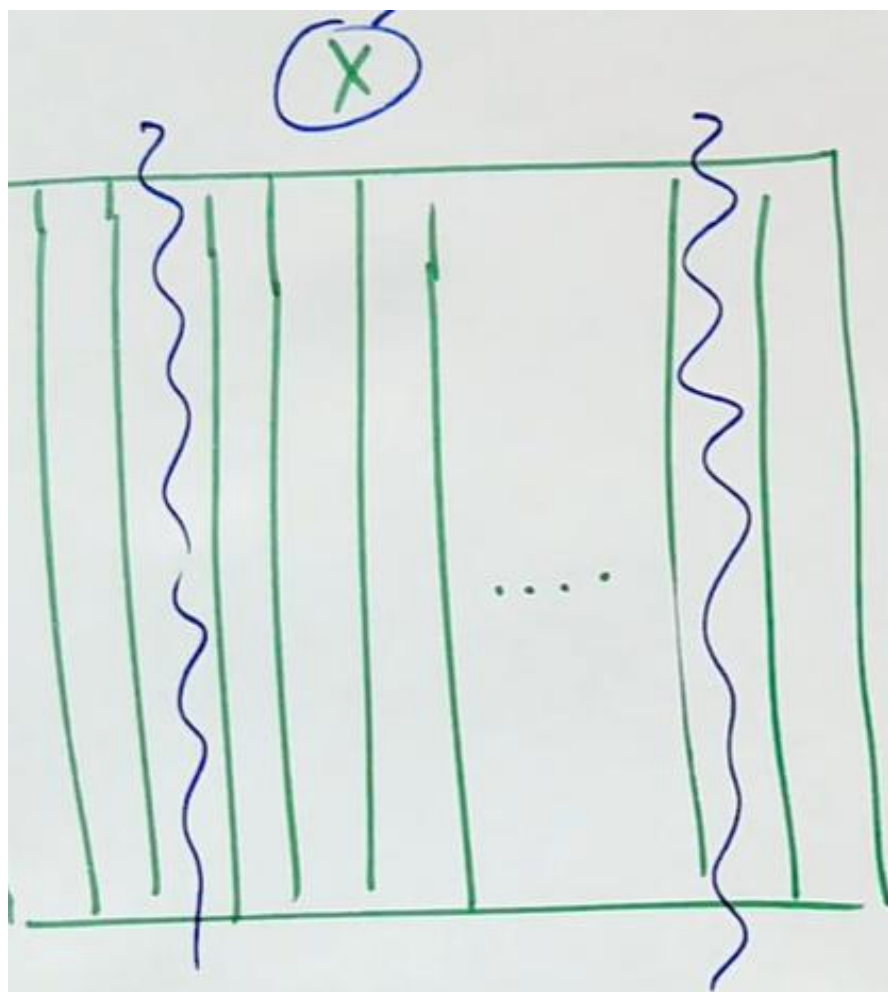


$$Z_1 = 0.2x_1 + 0.4x_2 + 0.4x_7$$

~~$$Z_1 = x_3 \times x_7$$~~

$$Z_2 = x_3^{0.2} \times x_4^{0.5} \times \dots \times x_6^{0.3}$$

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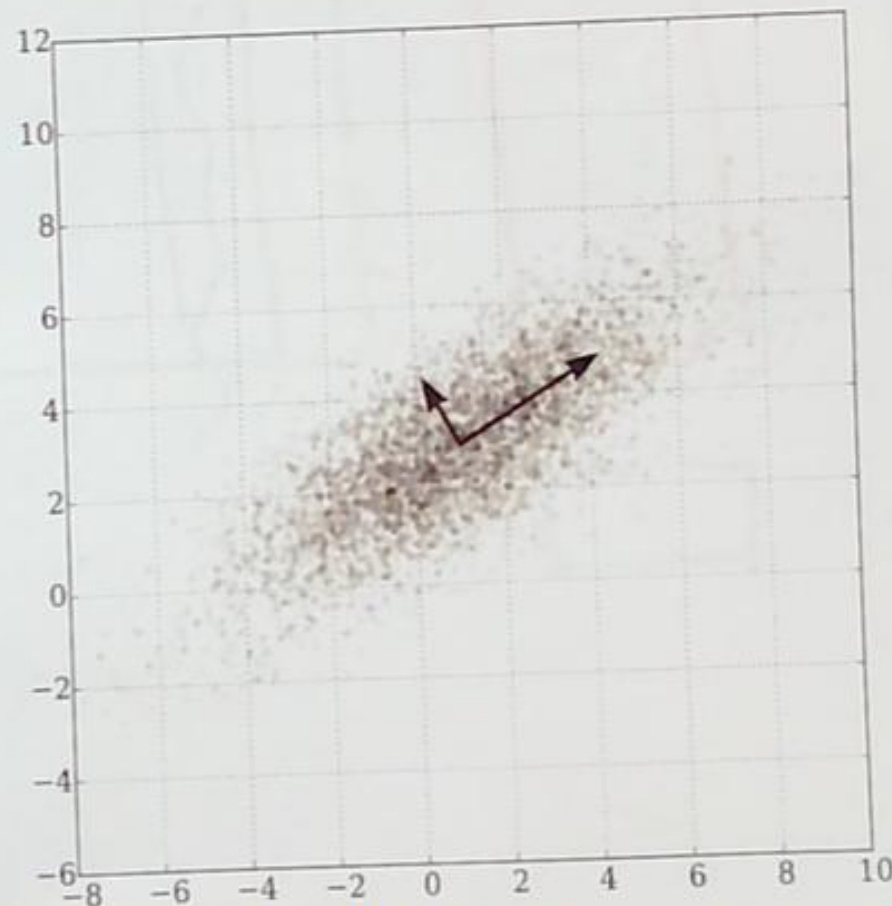


$$Z_1 = \underline{0.2x_1 + 0.4x_2} + \underline{0.4x_7}$$

~~$$Z_2 = x_3 \times x_4$$~~

$$Z_2 = \underline{x_3^{0.2} \times x_4^{0.5} \times \dots \times x_6^{0.3}}$$

- creates new variables using linear combinations of old variables
- is designed to create variables that are independent of one another
- also manages to tell us how important each of these new variables are
- this "importance", helps us to choose how many variables we will use





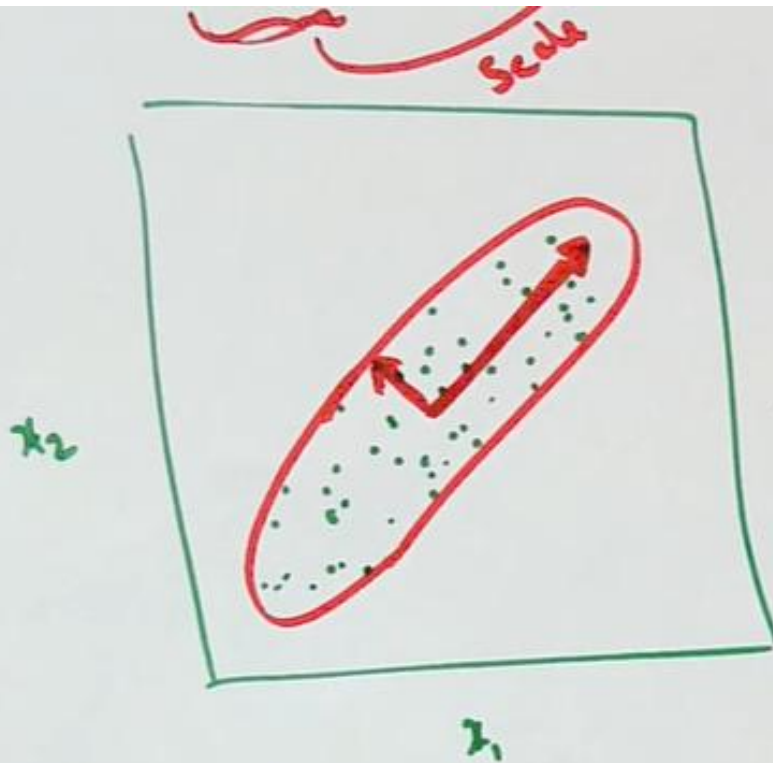


Cov Matrix C

eigen vect. ←
eigen value

$$z_1 = a_{11}x_1 + a_{12}x_2$$

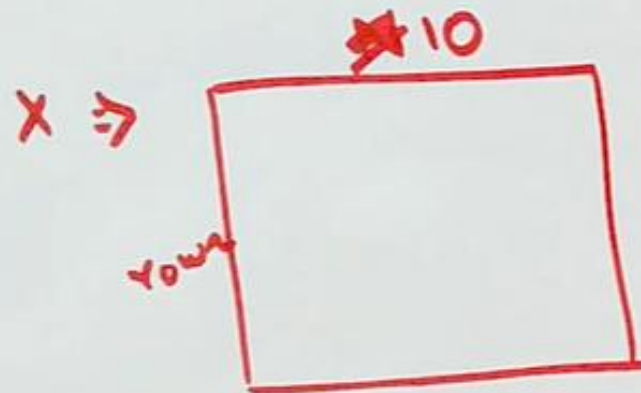
$$z_2 = a_{21}x_1 + a_{22}x_2$$



eigen
eigen values

$$z_1 = a_{11}x_1 + a_{12}x_2$$

$$z_2 = a_{21}x_1 + a_{22}x_2$$



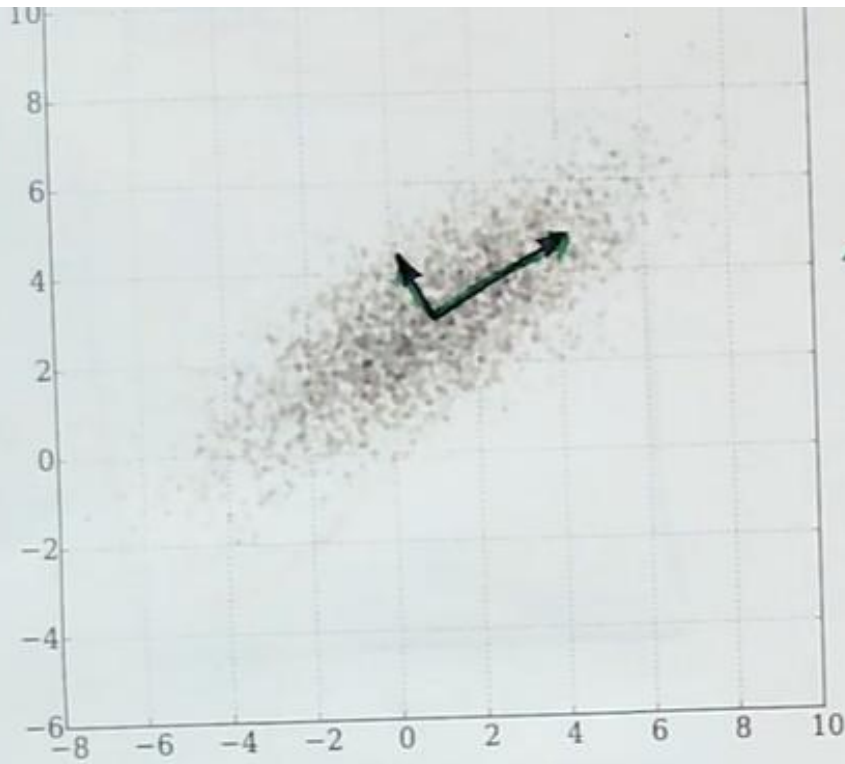
10 x 3

$$V = \begin{pmatrix} | & | & | \\ v_1 & v_2 & v_3 \\ | & | & | \end{pmatrix}$$

$$Z = V^T \cdot X^T$$

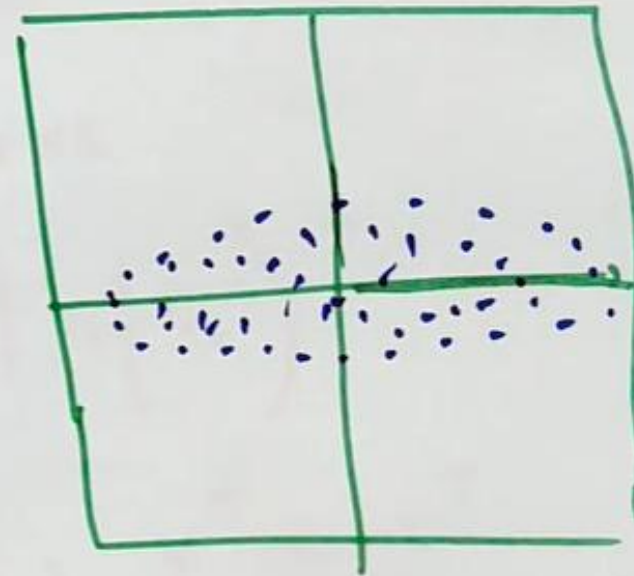
3×10 10×1000

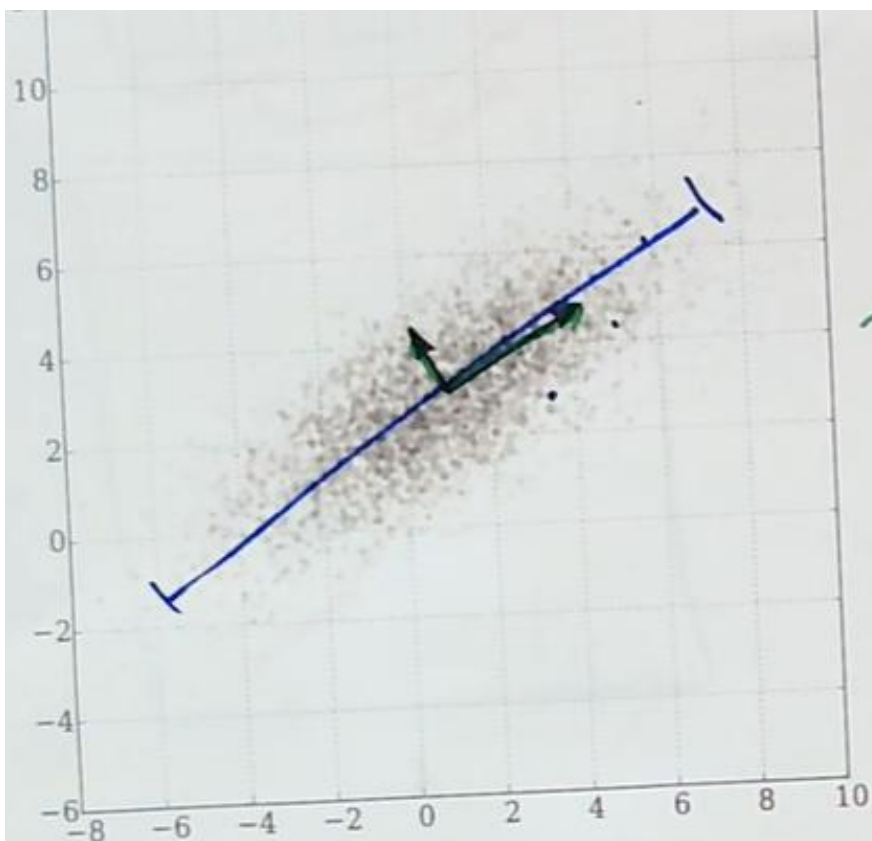
$$\rightarrow Z = \underline{\underline{3}} \times \underline{\underline{1000}}$$



$$z_1 = a_{11}x_1 + a_{12}x_2$$

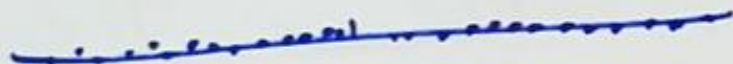
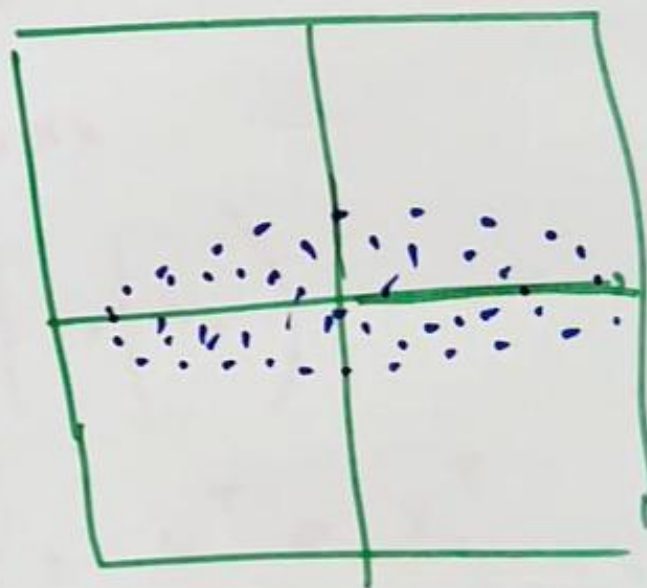
$$z_2 = a_{21}x_1 + a_{22}x_2$$





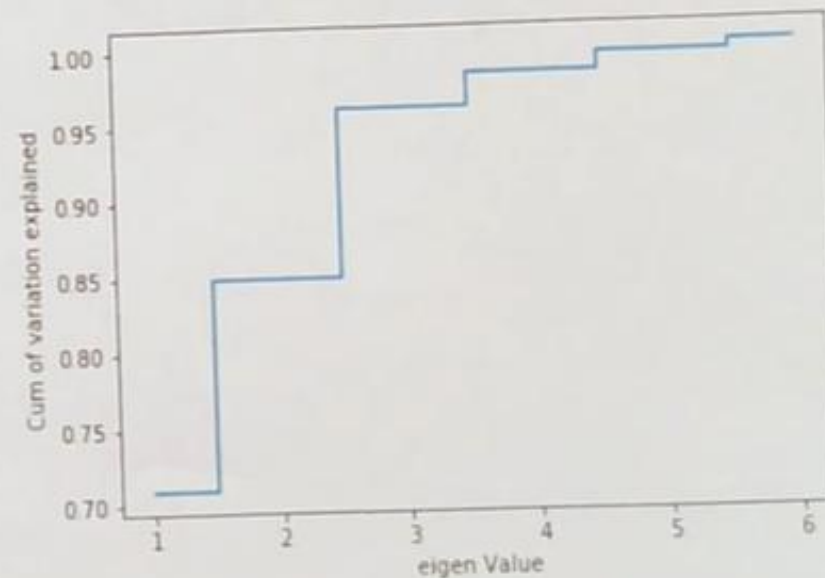
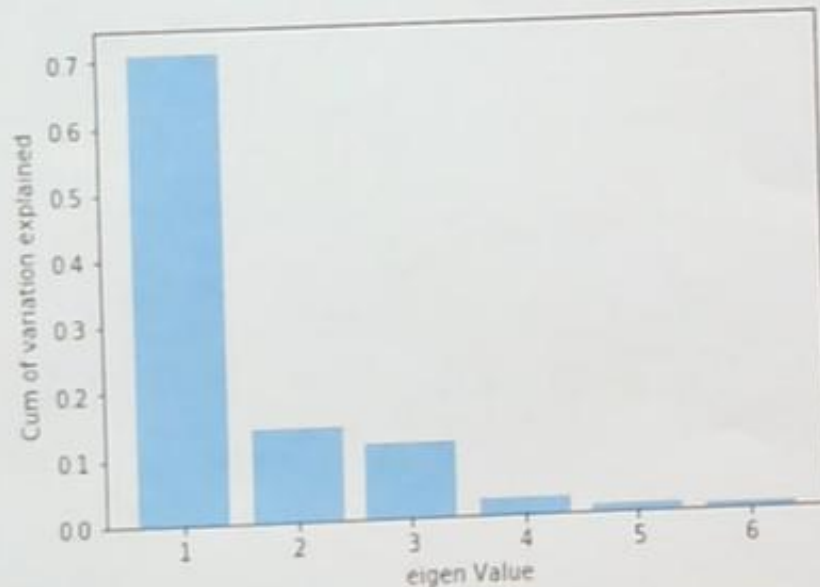
$$\begin{aligned} z_1 &= a_{11}x_1 + a_{12}x_2 \\ z_2 &= a_{21}x_1 + a_{22}x_2 \end{aligned} \quad \left. \vphantom{\begin{aligned} z_1 &= a_{11}x_1 + a_{12}x_2 \\ z_2 &= a_{21}x_1 + a_{22}x_2 \end{aligned}} \right\} 2$$

↓ 2D



z_1

- Break the covariance matrix into magnitude and direction. Eigen Vectors and the Eigen Values of the covariance matrix can be thought of as the natural axis and magnitudes along those axis
- Eigen Values of the covariance matrix are the principal components
- They are all orthogonal to each other - independent
- The eigen Values also can be used to calculate the percentage of variation explained by each direction
- Sort in the Eigen values in descending order and calculate the cumulative percentage of variation explained
- Pick the number of principal components you will use
- Transform to new variables

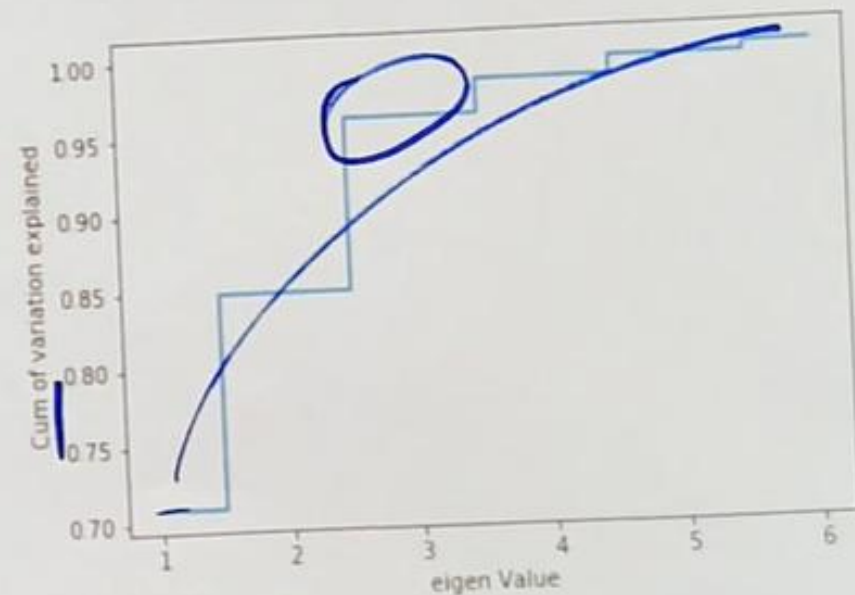
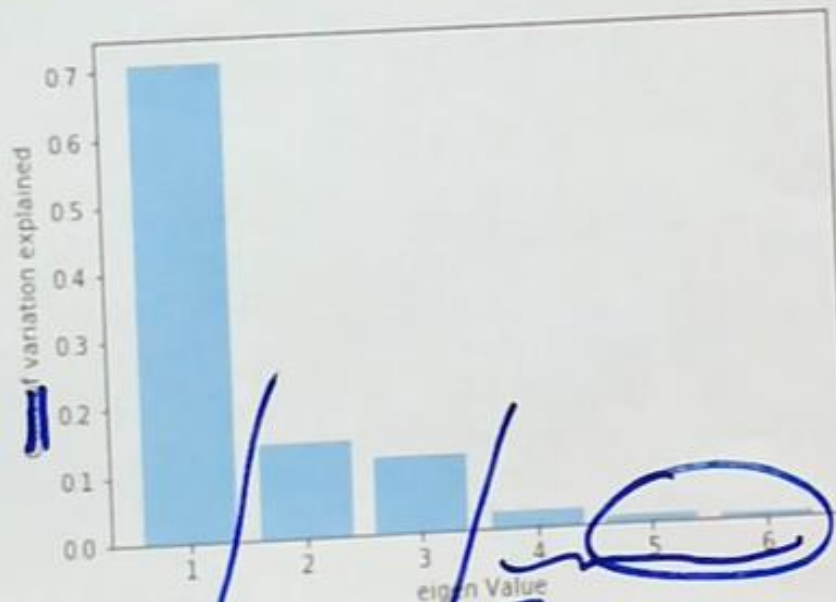


$\lambda_1, \dots, \lambda_{10}$

$$\left. \begin{array}{l} \% \text{ of var. expl} \\ \text{by the } i\text{th} \\ \text{eigen vector} \end{array} \right\} = \frac{\lambda_i}{\sum_{j=1}^n \lambda_j}$$

- Break the covariance matrix into magnitudes and directions. The covariance matrix can be thought of as the natural axis and magnitudes along those axis $\lambda_1, \dots, \lambda_n$
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$$\% \text{ of var. expl. by } i^{\text{th}} = \frac{\lambda_i}{\sum \lambda_j}$$



$$y = a + \underbrace{b_1}_{\text{circled}} x_1 + \underbrace{b_2}_{\text{underlined}} x_2 + \cancel{b_3 x_3}$$

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$$y = a + \underbrace{b_1}_{\text{circled}} \underline{x_1} + \underline{b_2 x_2} + \cancel{b_3 x_3}$$

- Feature elimination
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$$\textcircled{z_1} \quad \textcircled{z_2} \quad \textcircled{z_3}$$

$$y = a + \underline{b_1 z_1} + b_2 z_2$$