

LUCA CASTRI

AI & Robotics Researcher | Intelligent Autonomy & Robot Learning

Researcher in Embodied AI with extensive experience deploying data-driven learning and reasoning frameworks on real-world mobile platforms. Expert in navigation, spatial HRI, and fleet coordination using ROS/ROS2. Proven track record in EU-funded research ([DARKO](#)), bridging the gap between theoretical AI models and robust physical deployment.

Nationality Italian Languages Italian (native), English (fluent) 📍 Rome, IT

🌐 [lcastri.github.io](#) 📄 [lcastri](#) 🗣️ [lcastri](#) ✉️ lucacastri94@gmail.com 📞 [+39 3341011284](#)/[+44 07763735768](#) 📖 [List of Publications](#)

ACADEMIC EXPERIENCE

Postdoctoral Research Associate

University of Lincoln (Partnered with [JABAS AI](#))

📅 Jul 2025 – Present 📍 Lincoln, UK

- Architected multi-robot coordination algorithms on a heterogeneous fleet, optimizing path planning and collision avoidance in dynamic shared environments
- Developed a fleet management system dashboard for real-time monitoring, task allocation, and remote intervention of the robot fleet

Research Associate

University of Lincoln ([EU H2020 DARKO Project](#))

📅 Jul 2021 – Jul 2025 📍 Lincoln, UK

- Pioneered Causal Inference frameworks to enhance robot decision-making in human-shared environment
- Bridged the Sim-to-Real gap by developing containerized (Docker) ROS/ROS2 software stacks on real mobile robots ([TIAGo](#), [RB-KAIROS+](#))

TEACHING & SUPERVISION

- **B.Sc. Thesis Co-Supervisor** *Present*
Research project on Causal Continual Learning
- **M.Sc. Thesis Co-Supervisor** *Jan 2024 – Jun 2024*
RL strategies (QN and DQN) for robot task planning
- **Teaching Assistant** *Oct 2021 – Jun 2022*
Advanced AI; Autonomous and Mobile Robotics

PROFESSIONAL EXPERIENCE

Industrial Automation Engineer

Metapack Engineering

📅 Jan 2020 – Jun 2021 📍 Rome, Italy

- Led the full-cycle deployment of automated lines, engineering real-time protocols (TCP/IP, UDP) to integrate vision systems, motors, and PLCs

Embedded System Validation Engineer

Ferrari

📅 Apr 2019 – Dec 2019 📍 Maranello, Italy

- Validated safety-critical embedded software for ADAS ECUs. Conducted HIL testing and analyzed CAN bus data for fault detection in real-time systems

EDUCATION

Ph.D. in AI and Robotics

University of Lincoln

📅 Jul 2021 – Sept 2025 📍 Lincoln, UK

- My research focused on exploiting causal inference to advance intelligent mobile robotics in dynamic interaction settings, enabling robots to improve prediction, decision-making, and overall autonomy in human-shared environments
- Thesis: “*Causal Inference for Intelligent Mobile Robots in Dynamic Interaction Settings*”
- Ph.D. Advisors: [Nicola Bellotto](#) and [Marc Hanheide](#)

M.Sc. in Control Engineering

La Sapienza, University of Rome

📅 Oct 2016 – Jan 2019 📍 Rome, Italy

- Thesis: “*Autonomous car driving systems: new control strategy*” – Advised by [Antonio Carcaterra](#)
- Final Mark: 110/110 (Italian grading system)
- Awarded with the **Honors Program** (“*Percorso d'Eccellenza*”) for graduating in 2 years with high honors

B.Sc. in Information and Control Engineering

La Sapienza, University of Rome

📅 Sep 2013 – Oct 2016 📍 Rome, Italy

- Thesis: “*Modeling and Control of Robot KUKA LWR4+ in Simulink / VRML*” – Advised by [Alessandro De Luca](#)
- Final Mark: 101/110 (Italian grading system)

SKILLS



- **Languages:** Python, C++, C, SQL
- **AI & Robotics:** ROS, ROS2, Tensorflow, Keras, Scikit-learn, Gazebo, pyBullet
- **Robots & Sensors:** [TIAGo](#), [RB-KAIROS+](#), [HUNTER 2.0](#), 3D LiDAR
- **DevOps & Tools:** Docker, Git, GitHub Actions, CI/CD

EVENT PARTICIPATION

- **Peer Reviewer:** IEEE ICRA, IEEE IROS, Knowledge-Based Systems, CLeaR
- Attended the Advanced Course on AI (ACAI 2021)

PUBLICATIONS

Journal Articles

- [L. Castri](#), G. Beraldo and N. Bellotto. (2026), "Causality-enhanced Decision-Making for Autonomous Mobile Robots in Dynamic Environments," *Expert Systems with Applications*.  [Project Website](#)
- [L. Castri](#), S. Mghames, M. Hanheide and N. Bellotto. (2024), "CANDOIT: Causal Discovery with Observational and Interventional Data from Time-Series," *Advanced Intelligent Systems*.  [GitHub repo](#)

Conference and Workshops Proceedings

- A. Rudenko, Y. Zhu, T. Rodrigues de Almeida, T. Schreiter, [L. Castri](#), N. Bellotto, T. Linder, N. Vaskevicius, L. Palmieri, M. Magnusson, A. J. Lilienthal. (2025), "Hierarchical System to Predict Human Motion and Intentions for Efficient and Safe Human-Robot Interaction in Industrial Environments," *German Robotics Conference (GRC)*.
- E. Stracca, A. Rudenko, L. Palmieri, P. Salaris, [L. Castri](#), N. Mazzi, V. Rakcevic, N. Vaskevicius, T. Linder, N. Bellotto, T. Schreiter, Y. Zhu, M. Castellano-Quero, O. Napolitano, E. Stefanini, L. Heuer, M. Magnusson, A. Swikir and A. Lilienthal (2025), "DARKO-Nav: Hierarchical Risk- and Context-aware Robot Navigation in Complex Intralogistic Environments," *European Robotics Forum (ERF)*.
- S. Mghames, [L. Castri](#), M. Hanheide and N. Bellotto. (2024), "neuROSym: Deployment and Evaluation of a ROS-based Neuro-Symbolic Model for Human Motion Prediction," *IEEE International Conference on Cybernetics and Intelligent Systems (CIS) and IEEE Conference on Robotics, Automation and Mechatronics (RAM)*.  [GitHub repo](#)
- [L. Castri](#), G. Beraldo, S. Mghames, M. Hanheide and N. Bellotto. (2024), "Experimental Evaluation of ROS-Causal in Real-World Human-Robot Spatial Interaction Scenarios," *IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)*.  [Project Website](#)
- [L. Castri](#), G. Beraldo, S. Mghames, M. Hanheide and N. Bellotto. (2024), "ROS-Causal: A ROS-based Causal Analysis Framework for Human-Robot Interaction Applications," *Causal-HRI Workshop, ACM/IEEE International Conference on Human-Robot Interaction (HRI)*.  [Project Website](#)
- [L. Castri](#), S. Mghames and N. Bellotto. (2023), "Efficient Causal Discovery for Robotics Applications," *Italian Conference on Robotics and Intelligent Machines (I-RIM 3D)*.
- S. Mghames, [L. Castri](#), M. Hanheide and N. Bellotto. (2023), "Qualitative Prediction of Multi-Agent Spatial Interactions," *IEEE International Conference on Robot and Human Interactive Communication (RO-MAN)*.
- S. Mghames, [L. Castri](#), M. Hanheide and N. Bellotto. (2023), "A Neuro-Symbolic Approach for Enhanced Human Motion Prediction," *International Joint Conference on Neural Networks (IJCNN)*.
- [L. Castri](#), S. Mghames, M. Hanheide and N. Bellotto. (2023), "Enhancing Causal Discovery from Robot Sensor Data in Dynamic Scenarios," *Conference on Causal Learning and Reasoning (CLear)*.  [GitHub repo](#)
- [L. Castri](#), S. Mghames and N. Bellotto. (2023), "From Continual Learning to Causal Discovery in Robotics," *AAAI Bridge Program "Continual Causality"*.
- [L. Castri](#), S. Mghames, M. Hanheide and N. Bellotto. (2022), "Causal Discovery of Dynamic Models for Predicting Human Spatial Interactions," *International Conference on Social Robotics (ICSR)*.
- S. Ghidoni, M. Terreran, D. Evangelista, E. Menegatti, C. Eitzinger, E. Villagrossi, N. Pedrocchi, N. Castaman, M. Malecha, S. Mghames, [L. Castri](#), M. Hanheide and N. Bellotto. (2022), "From Human Perception and Action Recognition to Causal Understanding of Human-Robot Interaction in Industrial Environments," *Convegno Nazionale CINI sull'Intelligenza Artificiale (Ital-IA)*.

INVITED TALKS

- [Causal Inference for Intelligent Mobile Robots in Dynamic Interaction Settings](#), University of Oxford, Jun 2025
- [Causalflow: A Unified Framework for Causality in Time-Series](#), sktime Meetup Series (Online), Jun 2025
- [Enhancing Human-Robot Spatial Interaction through Causal Inference](#), University of Padua, Oct 2023
- Guest lectures on *Causal Discovery for Time-Series*, University of Padua, Nov ([2023](#), [2024](#), [2025](#)), Apr ([2024](#))

OPEN-SOURCE CONTRIBUTIONS

 [lcastri/causalflow](#)

☆ 66  5

A unified framework for causality in time-series, with a suite of methods for causal discovery from both observational and interventional data.