Chapter I Linearized gravity

References: Bardeen 1980 PRD 22, 1882 [Ma & Bertschinger [astro-ph/9506072]

I.1.) The gauge ambiguity

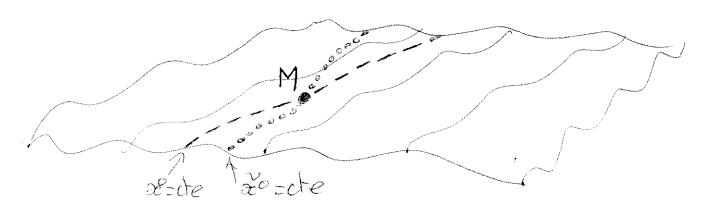
Decomposition in background + (small) perturbations

physical quantities.

Well-known effect of changing coordinates:

Sur(2) = 22 22 22 828(2)

spatial average over each time-slice. Since time-slicing is coordinate-dependent, this introduces some ambiguity in relation between gur and ze, and in definition of Squr!



In system &, perturbation in M=quantity in M-) along ---

" M=quantity in M-Salong...

- > a change of coordinates induces a different correspondance between partierbed and homogeneous quantities (beet only if it changes the time-slicing).
- To Sgur >> Ser and STur >> Ten (departure from linear perturbation theory): eminteresting. However, there exist an infinite number of "Small" change of coordinates changing time-string and preserving smallness of perturbations: called "gauge transfor-mation":

 Example 2.4.

 Example 2.4.

 Example 2.4.

 Example 2.4.

 Example 2.4.

 Automation

 Example 2.4.

 **Exa

Simplistic example:

2D tog-universe described by gur and e in coordinate system (t,x):

 $\int ds^2 = dt^2 + 2\varepsilon \cos \alpha \, d\alpha \, dt + \left(\varepsilon^2 \cos 2\alpha - 2\varepsilon t \sin \alpha - t^2\right) d\alpha^2$ $\int c^2 = t + \varepsilon \sin \alpha \, (\text{with } \varepsilon \text{ small})$

Seems to be a universe with FLRW background (8uv = (0-12), 0=+) and small periodic perturbations.

We decide to change to coordinates (E',x'):

$$\begin{cases} t' = t + \epsilon \sin \alpha \\ \alpha' = \alpha \end{cases}$$

Then $dt' = dt + \varepsilon \cos x dx$, dx' = dx, $+ \varepsilon \cos x' dx' + 2\varepsilon \cos x' +$

~ P =+'

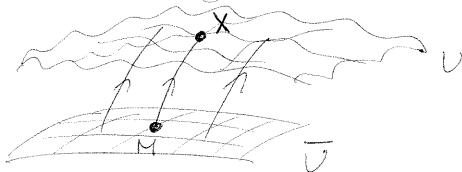
In new system, this seniverse tooks like perfectly homogeneous FLRW! Perterbations "absorbed" en coordinate transformation.

In real 4D Universe: number of perturbed d.o.f. (degrees of freedom) are seich that a gauge transf. can absorb some perturbations, but not all of them semultaneousles.

II 2) Mathematical definition of gauge transformation: let's call U the variety describing the real

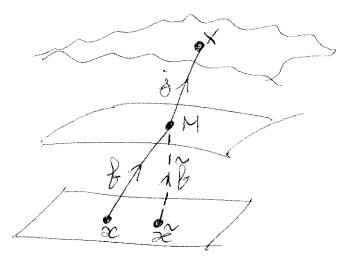
(perturbed) reviverse let's introduce a fictions homogeneous reviverse T. A given gange is

a given massing between U and T.



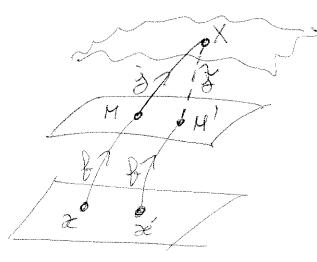
let us describe T with a system of coordinate (= magging between R4 and T).

va change of coordinates with fixed gauge is a change in maying between R' and U, but not U and U:



Perturbation en x system = perturbation en the same poeel H en x' system (although coordinate of X and M dranged)

No a "piere" gauge transformation es the orthogonal transformation: change à vohile f es fixed:



After transformation, perterbation en X defend les comparing X with different poient M' (although the masping between R4 and U did not change).

Infenitesimal transformations of this second tispe are defende mathematically as "Lie derevation". The change from à le J enduces a vector field & en R4: Ele = 2le - 2 sech that physical points associated previously to xe are now associated to x'^{u} $(X = jof(x^{u}) = j'of(x^{u}))_{-}$

D'Gauge transformation / Lie derivative for lovents scalar Let S(2) be a lorentz scalar (application: en est order pertarbation theores, the denseties e(x) transforms like a lorentz scalar, although formally (12)=Tols

Before sauge transformation, perturbation en posset X given leg: $\delta S(x) = S(x) - \overline{S}(x)$

value in X value in M

After gange transformation, perturbation en same noent X geven by: SS(xx) = S(xx) - S(x) value in X value in M1

- * Since S is a loventy ocaler, in a given physical goint S is always the same number: S(2) = S'(2)
- * Since we did not change the mapping between Rand V, the functions S and S are identical

 $-\infty SS'(x) = S(x) - \overline{S}(x)$

Now, we taylor-expand at first order en en en en xel

 $\delta S'(x'u) = S(x'u) - \overline{S}(x'u) - \overline{S}(x'u)$ $= S(x'u) - \overline{S}(x'u) - \varepsilon u \partial_u S(x'u)$

= SS(x') - Ender S(x')

We infer the following equatily (at the level of Functions): SS'= SS - Empes

Moreover: * E e is 1st order in perturbations

* 205 has a backround component 205 and a 1st order component (205-25)

i=1,2,3
= sportial indices *0; S is 1st order since 0; S =0 (S=homgener

... so Eid; S is 2nd order in perturbations.

At 1st order: SS'=SS-EDS TRANSFORMATION FOR LORENTZ

D Gauge transformation / Lie derivative for Lorentz vectors

-- can be computed as an exercise

Stiw (a) e) = (Su - du Ex) (SP - du E) (Tew (a) e) - E), Tapal - The Keep only first order:

Equality at the functional level:

exercise: the density is defined as $\rho = 76$. Raise indices in previous result in order to show that at first order in perturbations, $\delta \rho$ transforms as if ρ was a scalar: $\delta \rho' = \delta \rho - \epsilon \delta \rho = \delta \rho - \epsilon \delta \rho$

II.3.) Classification of metric perturbations

Sour is symmetric with 40 independent components.

Bardeen 9880 => these 40 d.o.f. can be classified

in scalars /vectors /tensors under

3D spatial rotations (not Lorentz transformations!

=> those 3 sectors are NOT COUPLED at 1st order in perturbation theory (although Einstein equations are non-linear)

Most general metric perturbations read: $ds^{2} = a^{2}(z) \left[(4+24) dz^{2} + B; dz^{2} dz - (4-24) \delta_{ij} + H_{ij} \right] dz^{2} d$

where &, B;, Y and His depend on (z, zei)

Bi and His can be further decomposed:

Hij must be traceless:

outomatic for first part (this is the reason for the $\frac{1}{3}Sijd$) imposes $\partial_i A_i = 0$: Air contains 2 d.o.f.(imposes $H_i' = 0$: $H_i = 0$: H_i

SCALAR SECTOR = $\{\phi, \Psi, b, \mu\} \rightarrow J+J+J+J=4 d.o.f.$ VECTOR SECTOR = $\{b_i, h_i\} \rightarrow 2+2 = 4 d.o.f.$ TENSOR SECTOR = H_0^2 = gravitational waves $\rightarrow 2 d.o.f.$

The impact of gauge transformations can be computed from previous formula for tensors of Lorentz. E.g: $Sgoo = Sgoo - 2(\partial_0 E^2)goo - E^0\partial_0 goo$ $(a) 2a^2 d = 2a^2 d - 2 E^0 a^2 - E^0 2aa keeping only 4st order$

In this way one can compute general transformation laws (induced by infinitesimal vector En(20):

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where we decomposed ϵ^i (spatial transformation) as: $\epsilon^i \equiv \partial_i \beta + \epsilon_{ijk} \partial_j \beta_k$ with $\partial_k \beta_{k} = 0$

It is possible to derive similar laws for the vector components, and to show that the tensor component Hij is gauge-invariant.

Gauge transformations have 4 def. (En). Two of Hem (Eo and B) can always cancel two scalar perturbations; the other two (Bk with 2kBk=0) can cancel two vector perturbations. Hence, the three sectors all contain two gauge-independent degrees of freedom.

For instance, $(4,4,b,\mu)$ can be combined in two independent gauge-invariant quantities; a particular choice is the two "Bardeen potentials" Φ_A, Φ_H (see exercises).

In order to carry calculations, the simplest approach consists in fixing the gauge (i.e. use a prescription such that the time-slicing is fixed and two scalar metric perturbations vanish), studying /integrating the equations, and translate the final result in terms of gouge-inveriont quantities. However, observable quantities are naturally gauge-invariant, because they refer to small distance scales where the time-slicing is not ambiguous. For instance, the total matter perturbation in two gauges (Sem and Sem) are significantly different only on super-Hubble scales (k CaH), but we can observe them only for know, so Som can be computed in any gauge in order to derive the observable power spectrum P(k) = <1 SPM (k, 20) > measured for kny Ho only.

In the rest of the course we will use the gauge-fixing prescription $Sgoi = Sgi \neq j = 0$ (a) $u = B_i = 0$) which defines the "Newtonian" or "longitudinal" gauge. Then, scalar sector described by $ds^2 = a^2 \left[(4+24) dz^2 - (4-24) dz^2 \right]$

II.4) Linearized Einstein equations

* scalar sector: in Newtonian gauge, one obtains

(1)
$$SG_0^2 = 2a^2 \left\{ -3(\frac{a}{2})^2 \phi - 3(\frac{a}{2})^2 \phi - 3(\frac{a}{2})^2 \phi - 3(\frac{a}{2})^2 \phi - 3(\frac{a}{2})^2 \phi \right\} = 8\pi G ST_0^2$$

(2)
$$\delta G_{i}^{\circ} = 2\alpha^{2} \partial_{i} \left\{ \frac{\partial}{\partial x} \phi + \Psi^{i} \right\} = 8\pi G S_{i}^{\circ}$$

(3)
$$SG_{j}^{2} = -2\alpha^{2} \left\{ \left[\left(2\frac{q''}{q} - \left(\frac{q}{q} \right)^{2} \right) + \frac{q'}{q} \left(\frac{d}{r} + 24 \right) + \psi'' + \frac{1}{2} \Delta \left(\frac{d}{r} + \psi \right) \right] S_{j}^{2} - \frac{1}{2} \partial_{j}^{2} \partial_{j}^{2} \left(\frac{d}{r} - \psi \right) \right\} = 8\pi G ST_{j}^{2}$$

with) = de (conformal time).

From these equations one can read directly which components of STU are coupled with scalar parturbations

• SG° coupled with density perturbation Sp=ST° • SG° " component of the energy

Flux ST? which is the gradient of some function v: ST? = D; v _ Conventionally people

use variable @ instead of v:

$$\Theta = \frac{20.879}{6+p} = \frac{\Delta V}{6+p}$$
 (O colled "velocity" by convention)

· SG; couples with diagonal component of ST; and with component such that ST; = 2/3; s. Alternatively this ST; can be decomposed in pressure perturbation plus a traceless longitudinal divergence term Ti;

 $ST_{i}^{2} = -SPS_{i}^{2} + T_{i}^{2}$ = traceless longitudinal divergence: $T_{i}^{2} = (\partial_{i}\partial_{j} - \frac{1}{3}S_{ij}\Delta)\mathcal{F}$

ensures that Til=0

Conventionally people use the variable of instead of ?:

 $(\mathbb{Q} + \mathbb{P} \mathbf{W} = -\frac{2}{3}(\partial_{1}\partial_{3} - \frac{1}{3}S_{1}\Delta)\Pi_{3}^{2} = -\frac{2}{3}\Delta(\Delta \mathcal{F})$

or is called the "shear" or "anisotropic stress".

Note that θ and σ are dimensionless. Physically, they can be seen as "potentials" giving raise to some energy flux (876) and anisotropic pressure (17;).

Hence STY has 4 d.o.f. which can source scalar metric perturbations, through the 4 equations:

- (4) $-3(a')^2 + 3(a')^2 +$
- (5) $\Delta(a'+4') = 4\pi Ga^2(P+P) \Theta$
- (6) $\left(2\frac{a''}{a} \left(\frac{a'}{a}\right)^2\right) + \frac{a'}{a'}(4+24) + 4'' + \frac{1}{3} \Delta(4-4) = 4\pi G a' S p$
- (7) a (4-4) = 12 mG a (P+P) o

(Note: (5) comes from $\partial_i(SG_i^0) = 8\pi G \partial_i(ST_i^0)$; (6) and (7) come from the decomposition of (3) into trace part and traceless longitudinal divergence part; for getting (3) one must apply the operator $S(\partial_i\partial_i - \frac{1}{3}S_{ij}G_i)$ to this second part, and use the identity

高(0:05-35-355A)A=35AA)

Hhis shows that the Laplacien of (7) is true; Hence (7) is true modulo a linear function of coordinates x', x', x'' which must vanish, since it would diverge at infinity and violate the condition for small perturbations).

These equations can be used in order to prove that in absence of source (Sp=0=Sp=5=0), band 4 must either vanish, or be equal to a function of time which could be absorbed in a redefinition of the background. Hence the scalar metric perturbation do not propagate: they only follow scalar matter perturbations.

*vector sector: equations are easy to derive, but usually useless for standard cosmology (for "usual" source terms ST, the vector perturbations are driven to zero).

* tensor sector: The two degrees of freedom contained in Hij (traceless transverse part of the metric) can be written as $H_{ij} = h_4 e_{ij}^4 + h_2 e_{ij}^2$

where hy and hz are functions of zer (the two degrees of polarisation of the graviton), and the two polarisation tensors eiz (independent of zer) are normalized in such way that

(zeizeiz=zeiz=z (so zeizeiz=1)

zeizeiz=0 (orthogonal)

Here we do not give the expircit expression of e_{ij}^{λ} . Starting from $Sg_{av} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & a^{2}H_{ij}^{-1} \end{pmatrix}$ one obtains the Einstein equations for tensor, which can be decomposed in two identical equations for h_{ij} and h_{ij} : $h_{ij}^{\mu} + 2\frac{a^{2}}{a^{2}}h_{ij}^{\lambda} + \Delta h_{ij} = source term$ (some components of ST_{ij}^{μ})

Even when the source term vanishes, he obey to a wave equation: tensor perturbations of the metric do propagate.