

<sub>1</sub> A Unified Modeling Framework to Abstract  
<sub>2</sub> Knowledge of Dynamically Adaptive Systems

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# 1 Abstract

2 **Vision:** As state-of-the-art techniques fail to model efficiently the evolution and the  
3 uncertainty existing in dynamically adaptive systems, the adaptation process makes  
suboptimal decisions. To tackle this challenge, modern modeling frameworks should  
efficiently encapsulate time and uncertainty as first-class concepts.

4 *Context* Smart grid approach introduces information and communication technolo-  
5 gies into traditional power grid to cope with new challenges of electricity distribution.  
6 Among them, one challenge is the resiliency of the grid: how to automatically re-  
7 cover from any incident such as overload? These systems therefore need a deep under-  
8 standing of the ongoing situation which enables reasoning tasks for healing operations.  
9 **Abstraction** is a key technique that provided an illuminating description of systems,  
10 their behaviors, and/or their environments alleviating their complexity. **Adaptation**  
11 is a cornerstone feature that enables reconfiguration at runtime for optimizing software  
12 to the current and/or future situation.

13 Abstraction technique is pushed to its paramountcy by the model-driven engineering  
14 (MDE) methodology. However, information concerning the grid, such as loads, is not  
15 always known with absolute confidence. Through the thesis, this lack of confidence  
16 about data is referred to as **data uncertainty**. They are approximated from the  
17 measured consumption and the grid topology. This topology is inferred from fuse  
18 states, which are set by technicians after their services on the grid. As humans are  
19 not error-free, the topology is therefore not known with absolute confidence. This data  
20 uncertainty is propagated to the load through the computation made. If it is neither  
21 present in the model nor not considered by the adaptation process, then the adaptation

1 process may make suboptimal reconfiguration decision.

2 The literature refers to systems which provide adaptation capabilities as dynamically  
3 adaptive systems (DAS). One challenge in the grid is the phase difference between the  
4 monitoring frequency and the time for actions to have measurable effects. Action with  
5 no immediate measurable effects are named **delayed action**. On the one hand, an  
6 incident should be detected in the next minutes. On the other hand, a reconfiguration  
7 action can take up to several hours. For example, when a tree falls on a cable and cuts  
8 it during a storm, the grid manager should be noticed in real time. The reconfiguration  
9 of the grid, to reconnect as many people as possible before replacing the cable, is done  
10 by technicians who need to use their cars to go on the reconfiguration places. In a fully  
11 autonomous adaptive system, the reasoning process should be considered the ongoing  
12 actions to avoid repeating decisions.

13 *Problematic* **Data uncertainty and delayed actions are not specific to smart**  
14 **grids.**

15 First, data are, almost by definition, uncertain and developers always work with  
16 estimates. Hardware sensors have by construction a precision that can vary accord-  
17 ing to the current environment in which they are deployed. A simple example is the  
18 temperature sensor which provides a temperature with precision of one Celsius degree.  
19 Software sensors approximate also values from these physical sensors and accentuate  
20 and have their uncertainty. For example, CPU usage is computed counting the cycle  
21 used by a program. As stated by Intel, this counter is not error-free <sup>1</sup>.

22 Second, it always exists a delay between the moment where a suboptimal state is  
23 detected by the adaptation process and the moment where the effects of decisions taken  
24 are measured. This delayed is due to the time needed by a computer to process a send  
25 and, eventually, to send orders or data through networks. For example, migrating a  
26 virtual machine from a server to another one can take several minutes.

27 **Through this thesis, I argue that this data uncertainty and this delay**  
28 **cannot be ignored for all dynamic adaptive systems.** To know if the data un-  
29 certainty should be considered, stakeholders should wonder **if this data uncertainty**

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<sup>1</sup><https://software.intel.com/en-us/itc-user-and-reference-guide-cpu-cycle-counter>

1 **affects the result of their reasoning process, like adaptation.** Regarding delayed  
2 action, they should verify **if the frequency of the monitoring stage is lower than**  
3 **the time of action effects to be measurable.** These characteristics are common  
4 to smart grids, cloud infrastructure or cyber-physical systems in general.

5 *Challenge* These problematics come with different challenges concerning the represen-  
6 tation of the knowledge for DAS. Solutions should be bring to developers to ease their  
7 definition and manipulation of uncertain and temporal data. In order to respect the  
8 real-time constraint of DAS, the read, write and process of this knowledge should be  
9 efficient in term of resources (memory, CPU) used and execution time.

10 *Vision* **This thesis defends the need of a unified modeling framework which**  
11 **includes, despite all traditional elements, temporal and uncertainty as first-**  
12 **class concepts.** Therefore, a developer will be able to easily abstract information  
13 related to the adaptation process, the environment as well as the system itself. This  
14 frameworks should enable efficient read and write operations and should provide data  
15 structures efficient to process in order to enable a real-time reasoning.

16 Concerning the adaption process, the framework should enable easy abstraction of  
17 the actions with their context and impact as well as the specification of this process (re-  
18 quirements and constraints). Concerning the environment of the system, the framework  
19 should enable easy abstraction of its behavior and its structure. Finally, the framework  
20 should represent the structure, behavior and specification of the system itself as well as  
21 the actuators and sensors.

22 *Contributions* Towards this vision, two contributions have been proposed: a temporal  
23 context model and a language for uncertain data.

24 The temporal context model allows to abstract past, on going and future actions  
25 with their impacts and context. First, a developer can use this model to know what are  
26 the ongoing actions with their expect future impacts on the system. Second, she/he can  
27 navigate through past decisions to understand why the system has taken some decisions  
28 which lead to a sub-optimal state.

29 The language, named Ain'tea, integrates data uncertainty as a first-class concept.

1 It allows developers to attach data with a probability distribution which represents  
2 their uncertainty. Plus, it mapped all arithmetic and boolean operators to uncertainty  
3 propagation operation. And so, developers will automatically propagate the uncertainty  
4 of data without additional effort, compared to an algorithm which manipulates certain  
5 data.

6 *Validation* Each contribution have been evaluated separately. The language has been  
7 evaluated through two axis: its ability to detect errors at development time and its  
8 expressiveness. Ain'tea can detect [...] and it is as expressive as any state of the art  
9 solution. Moreover, we use this language to implement the load approximation of a  
10 smart grid furnished by an industrial partner, Creos SA.

11 The context model, has been evaluated through the performance access. I show  
12 that it can be used to [...]

13 **Keywords:** dynamically adaptive systems, knowledge representation, model-driven  
14 engineering, uncertainty modeling, time modeling