

Interpolation of Molecular Dynamics Trajectories with Bi-Directional Neural Networks

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- Solution is a trajectory in phase space

$$x(t) = \begin{bmatrix} r(t) \\ p(t) \end{bmatrix} = \int_{t_0}^t f \left(\begin{bmatrix} r(t) \\ p(t) \end{bmatrix}, t \right) dt$$

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Can we learn the phase space dynamics with a ML algorithm?

Learning Dynamical Systems

- Given true dynamics f , learn dynamics f_θ with NN

Learning Dynamical Systems

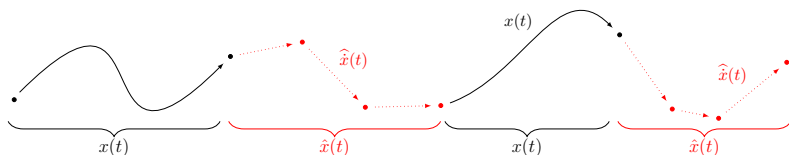
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Learning Dynamical Systems

Model Architectures

- ODENetwork

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- HamiltonianNetwork

$$\dot{x}(t) = \begin{bmatrix} \dot{r}(t) \\ \dot{p}(t) \end{bmatrix} = \begin{bmatrix} \frac{\partial \mathcal{H}(r(t), p(t), t)}{\partial p(t)} \\ -\frac{\partial \mathcal{H}(r(t), p(t), t)}{\partial r(t)} \end{bmatrix}$$

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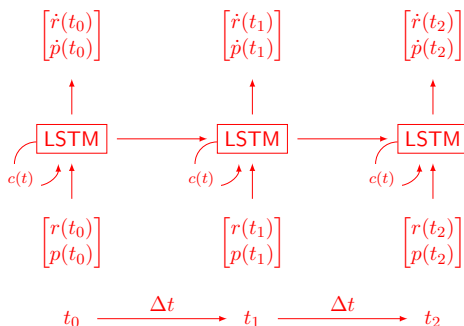
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- RNN and LSTM

$$\dot{x}(t) = \begin{bmatrix} \dot{r}(t) \\ \dot{p}(t) \end{bmatrix} = f_{\theta} \left(\begin{bmatrix} r(t_0) \\ p(t_0) \end{bmatrix}, \dots, \begin{bmatrix} r(t) \\ p(t) \end{bmatrix} \right), t$$

Learning Dynamical Systems with LSTM

- Best performing due to fewest assumptions and flexible parameterization
- Memory cell $c(t)$ to selectively read and write information
- Outputs $[\dot{r}(t), \dot{p}(t)]^T$ are integrated to obtain solution $\hat{x}(t)$



Bi-Directional Interpolation of Differential Equation

- Analytical simulation provides most accurate solution

Bi-Directional Interpolation of Differential Equation

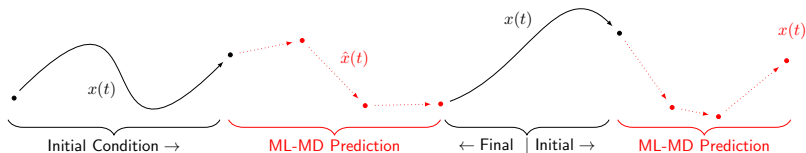
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- Predict **forward solution** $\overrightarrow{\hat{x}(t)}$ and **backward solution** $\overleftarrow{\hat{x}(t)}$ with the **same** dynamics f_θ

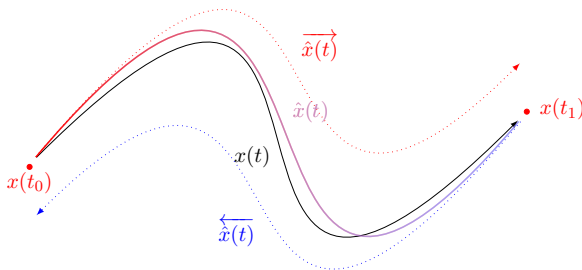
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$$\hat{x}(t) = (1 - \lambda(t)) \overrightarrow{\hat{x}(t)} + \lambda(t) \overleftarrow{\hat{x}(t)} \quad (1)$$

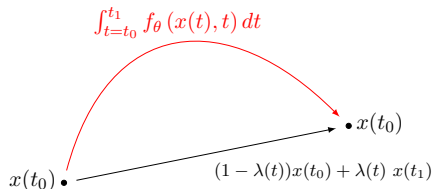


Bi-Directional Interpolation of Differential Equation

- For time-reversible solutions, we obtain

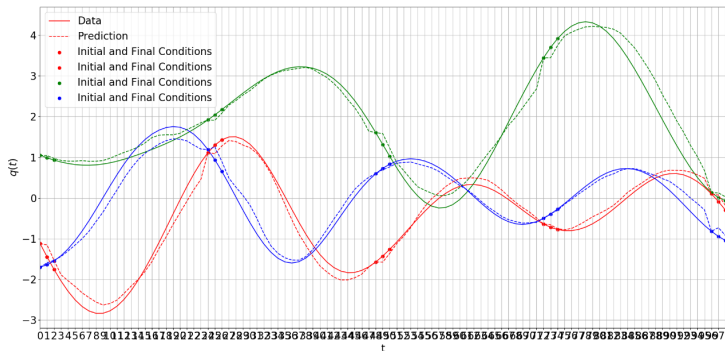
$$\begin{aligned}\hat{x}(t) &= (1 - \lambda(t)) \overrightarrow{\hat{x}(t)} + \lambda(t) \overleftarrow{\hat{x}(t)} \\ &= \underbrace{(1 - \lambda(t))x(t_0) + \lambda(t)x(t_1)}_{\text{low frequency components}} + \underbrace{\int_{t=t_0}^{t_1} f_{\theta}(x(t), t) dt}_{\text{high frequency components}}\end{aligned}$$

- Adiabatic connection frees the ML model to model high frequency signals



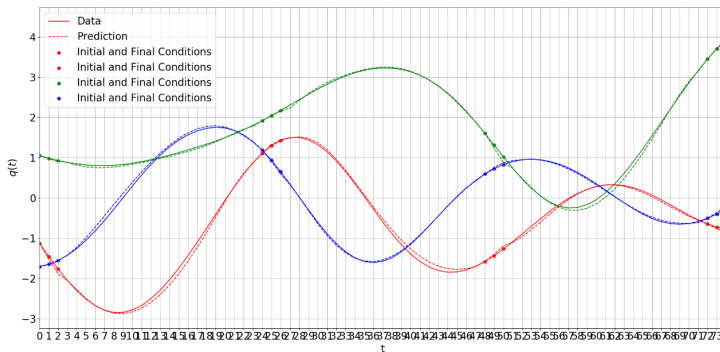
Bi-Directional Interpolation of Differential Equation

- Unidirectional LSTM architecture for Benzene MD trajectory interpolating over 20 time steps



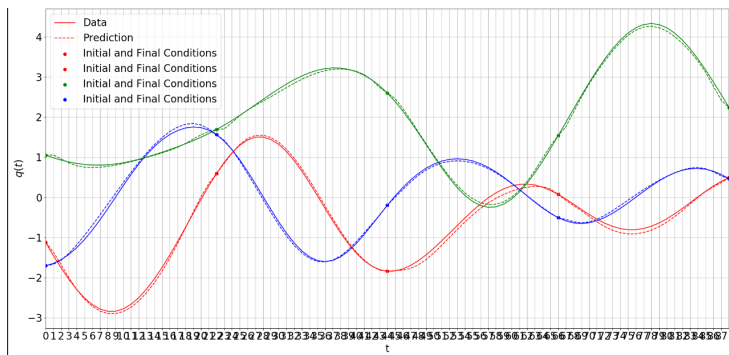
Bi-Directional Interpolation of Differential Equation

- Bidirectional LSTM architecture for Benzene MD trajectory interpolating over 20 time steps
- Final condition and additional bidirectional training smooth trajectories significantly



Bi-Directional Interpolation of Differential Equation

- Single initial and final condition already good for sufficient performance by bidirectional LSTM



Analysis of Interpolations

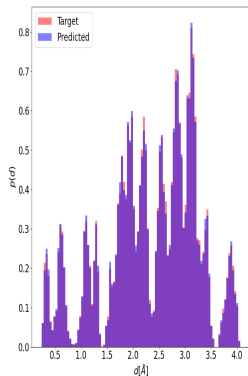


Figure:
Keto-Malonaldehyde
(100K)

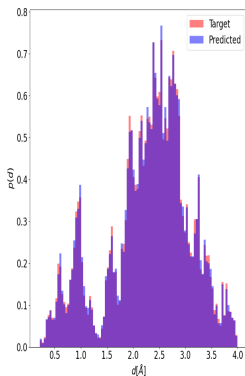


Figure:
Keto-Malonaldehyde
(300K)

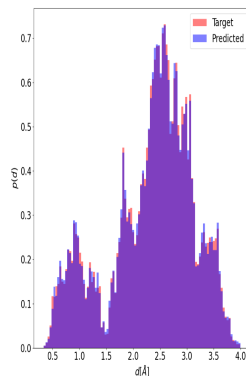


Figure:
Keto-Malonaldehyde
(500K)

Analysis of Interpolations

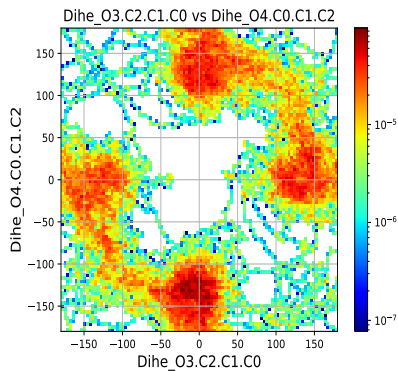


Figure: Ground Truth Free Energy
Keto-Malonaldehyde (300K)

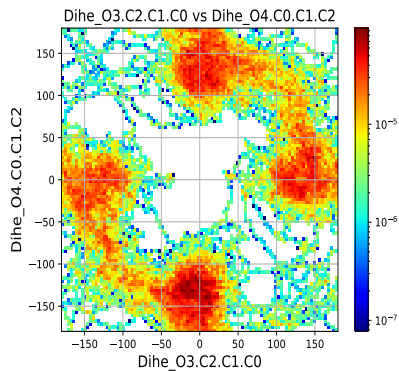


Figure: Predicted Free Energy
Keto-Malonaldehyde (300K)