Still water and other hard-to-model systems

Martin Büttner Supervisor: Prof. Ted Johnson

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 - ► Incompressible
 - Inviscid
 - ► Shallow (horizontal length scale ≫ typical depth)
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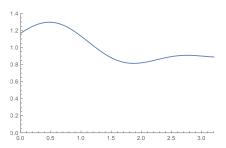
$$h_t + (hu)_x = 0 (1)$$

$$(hu)_t + \left(hu^2 + \frac{1}{2}h^2\right)_x = 0 \tag{2}$$

$$(hv)_t + (huv)_x = 0 (3)$$

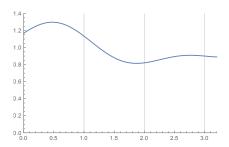
▶ Developed for *hyperbolic conservation laws*:

$$\mathbf{q}_t + \mathbf{f}(\mathbf{q})_x = 0 \tag{4}$$



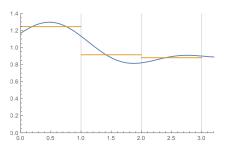
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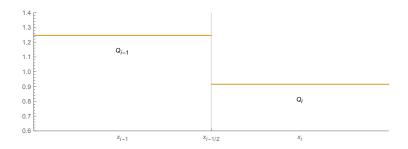


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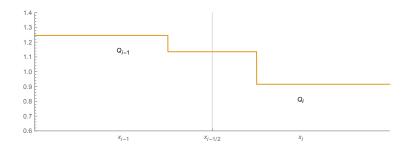


Riemann Problems



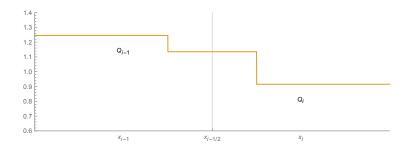
Initial value problem: step function

Riemann Problems



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Riemann Problems



- Initial value problem: step function
- Decompose into waves
- lacktriangle Finite speeds \Rightarrow only affect neighbouring cells

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- Riemann solvers in Fortran 90
 - ► Take grid data, compute wave decomposition
- Configuration in Python 2
 - Grid setup
 - Initial conditions
 - Boundary conditions
 - Plotting instructions

Modelling additional effects:

$$h_t + (hu)_x = 0 (5)$$

$$(hu)_t + \left(hu^2 + \frac{1}{2}h^2\right)_x = 0$$
(6)

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Full form of conservation law:

$$\mathbf{q}_t + \mathbf{f}(\mathbf{q})_x = \mathbf{s}(\mathbf{q}, x) \tag{8}$$

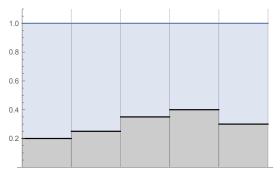
Split into two steps:

$$\mathbf{q}_t + \mathbf{f}(\mathbf{q})_x = 0 \tag{9}$$
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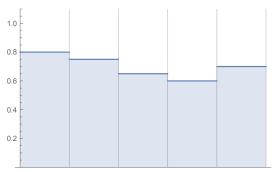
► The still water system:



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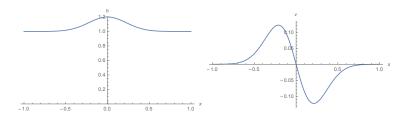
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Geostrophic Equilibria

Coriolis force admits non-trivial equilibria when

$$u = 0, \quad v = \frac{h(h_s)_x}{K} \tag{11}$$



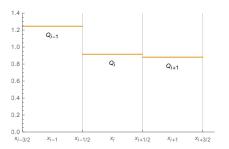
► Geophysical flows close to geostrophic equilibrium at all times

LeVeque

 LeVeque, 1998, "Balancing Source Terms and Flux Gradients in High-Resolution Godunov Methods: The Quasi-Steady Wave-Propagation Algorithm"

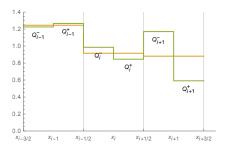
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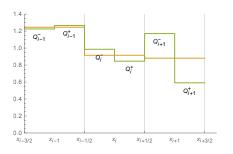
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$$\mathbf{f}(Q_i^+) - \mathbf{f}(Q_i^-) = \mathbf{s}(Q_i, x_i) \Delta x \tag{12}$$

Rogers et al.

 Rogers, Borthwick, Taylor, 2003, "Mathematical balancing of flux gradient and source terms prior to using Roe's approximate Riemann solver"

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- Change of variables: deviations from equilibrium

$$\mathbf{q}_t + \mathbf{f}(\mathbf{q})_x = \mathbf{s}(\mathbf{q}, x) \tag{13}$$

$$\rightarrow (\mathbf{q} - \mathbf{q}_{eq})_t + (\mathbf{f}(\mathbf{q}) - \mathbf{f}(\mathbf{q}_{eq}))_x = \mathbf{s}(\mathbf{q}, x) - \mathbf{s}(\mathbf{q}_{eq}, x) \quad (14)$$

or
$$\mathbf{q}_t^* + \mathbf{f}_x^* = \mathbf{s}^*$$
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- ► At equilibrium, all terms vanish
- Jacobian of f remains unchanged
 - easy to adapt existing solver

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$$\mathbf{q}_t^* + \mathbf{f}'(\mathbf{q})\mathbf{q}_x^* = \mathbf{s}^* \tag{16}$$

Implementation based on this failed away from equilibrium

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- Implementation based on this failed away from equilibrium
- Derived alternative form:

$$\mathbf{q}_{t}^{*} + \mathbf{f}'(\mathbf{q})\mathbf{q}_{x}^{*} = \mathbf{s}^{*} - \frac{\partial \mathbf{f}^{*}}{\partial \mathbf{q}_{eq}}(\mathbf{q}_{eq})_{x}$$
(17)

This does work!

Project work

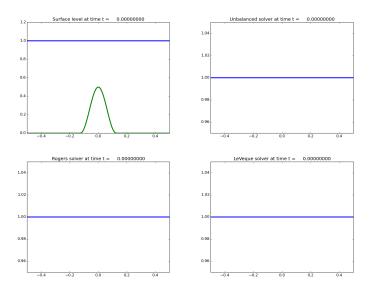
Extend these methods the full SWEs with Coriolis force

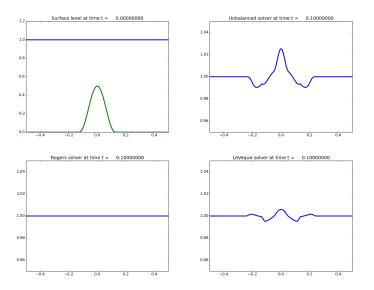
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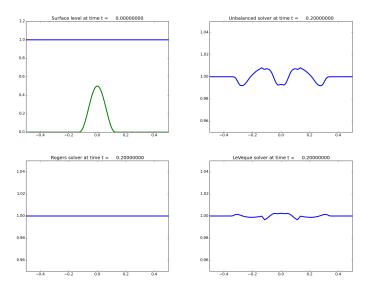
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- Also, derived a Rogers solver for geostrophic equilibria
 - Unfortunately, implementation is work in progress.

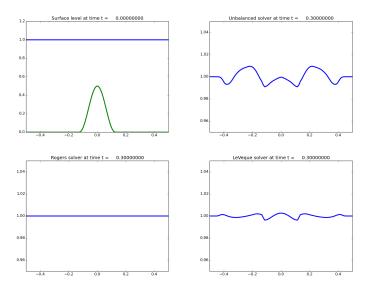
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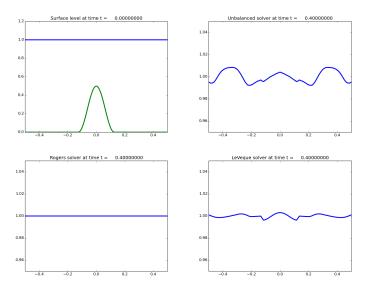
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- Evaluation
 - Implemented evaluation framework in Clawpack (Python)
 - Supports 7 different bathymetries and 5 initial conditions
 - Implemented 4 Riemann solvers in Fortran (unbalanced, LeVeque, Rogers for still water, Rogers for geostrophic equilibrium)

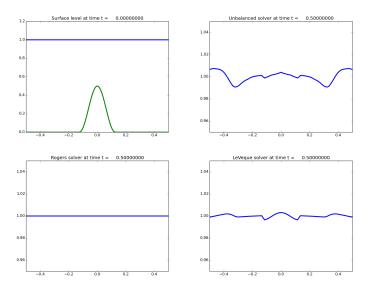


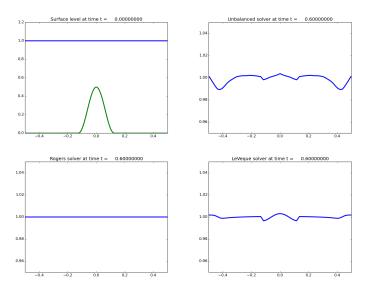


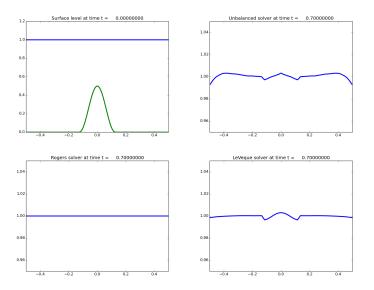


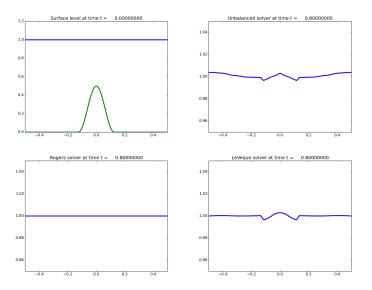


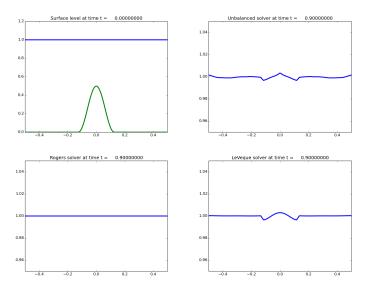


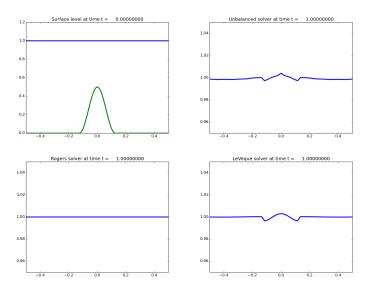


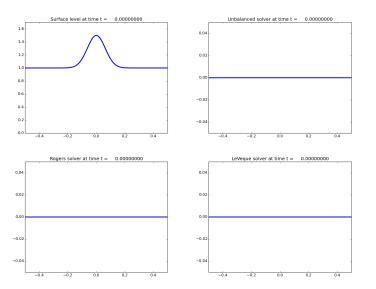


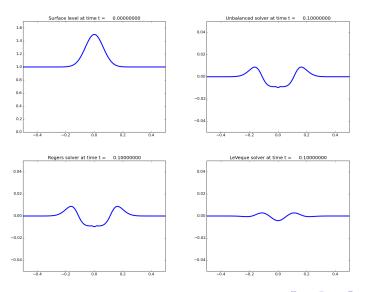


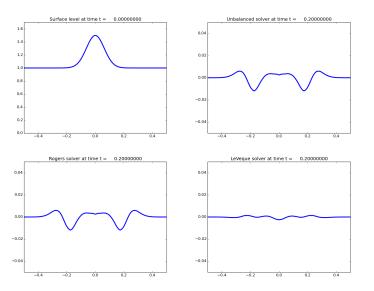


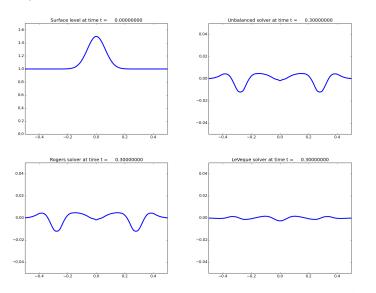


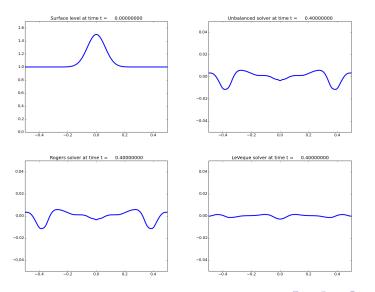


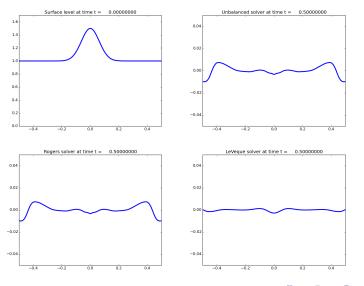


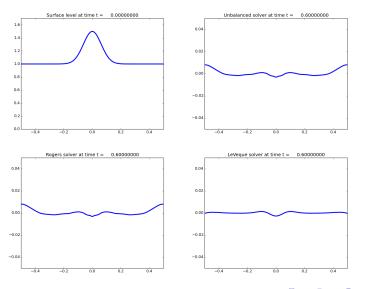


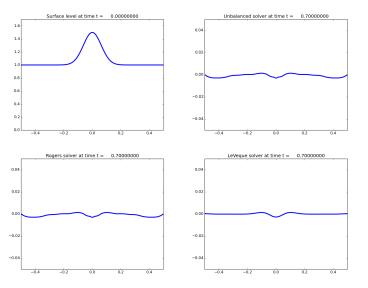


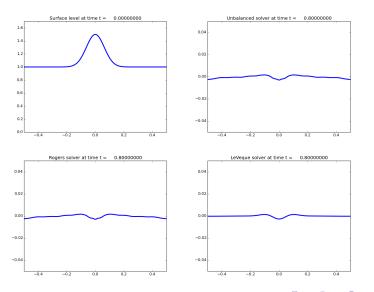


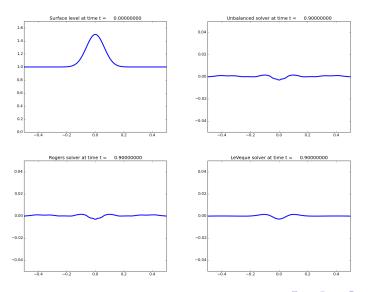


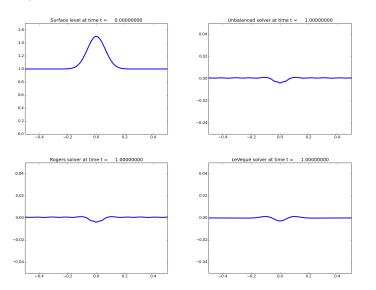












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- There is no free lunch!

Further work

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- Future research
 - Allow for dry states
 - Look at non-Godunov type methods (Chertock et al., 2014, "Well-Balanced Schemes for the Shallow Water Equations with Coriolis Forces")

Questions?

Godunov's Method

Wave propagation form:

$$Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} (\mathcal{A}^+ \Delta Q_{i-1/2} + \mathcal{A}^- \Delta Q_{i+1/2})$$
 (18)

$$\mathcal{A}^{-}\Delta Q_{i-1/2} = \sum_{p=1}^{M_w} (s_{i-1/2}^p)^{-} \mathcal{W}_{i-1/2}^p$$
 (19)

$$\mathcal{A}^{+}\Delta Q_{i+1/2} = \sum_{p=1}^{M_w} (s_{i+1/2}^p)^{+} \mathcal{W}_{i+1/2}^p$$
 (20)