

CAReful

Mobile and Social Sensing Systems

Academic Year: 2021-22

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Overview

- Introduction
- Sensors
- Application
- Conclusions





Introduction

Among the wrong driving behaviours, the most frequent are the distraction, the lack of respect for precedence and too high speed. The three groups together make up 40.2% of cases (60,981).

Istat – Incidenti stradali [Published in July 2021]

Distractions

Despite the increasing automation of driving vehicles, we are so far from the full automation. So, the driver has to perform all the main tasks of driving with full attention.

Any non-driving activity is a potential distraction and increases the risk of crashing, in particular at high speed or curvy roads.

Examples of distractions are:

- Usage of the smartphone
- Looking away from the road
- Drowsiness
- Too much noise





Idea

Our idea is a simple application able to detect the different distractions while driving.

When you start a new trip, you have just simply to place the phone in front of you and the application performs by its own.

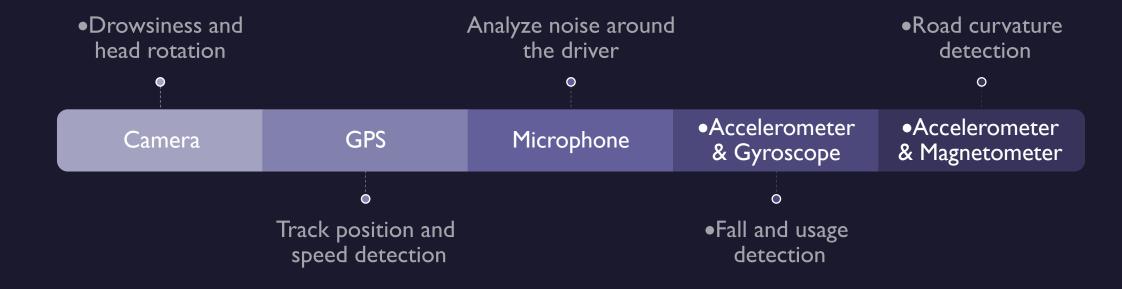




Various uses can be designed for the application:

- personal use to test your attention while driving
- monitor the attention of a bus driver in a company
- an insurance company to categorize drivers

Exploited sensors



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Sensors

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Sensors





Camera



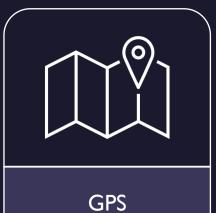
Accelerometer & Magnetometer



Microphone



Accelerometer & Gyroscope





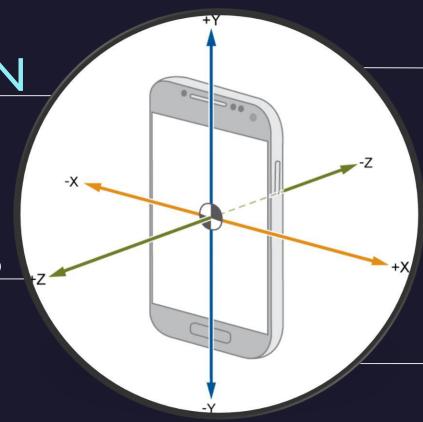








USAGE DETECTION



MAGNITUDE

 $m = \sqrt{x^2 + y^2 + z^2}$

THRESHOLDS

lowThreshold = 5.0 highThreshold = 18.0 gyroThreshold = 1.9

FALL DETECTION

arraySize = 8 samplingPeriod = 200 ms











RISK INDEX

 $sum < 10 \rightarrow 1$ $10 \le sum < 60 \rightarrow 2$ $sum \ge 60 \rightarrow 3$

AZIMUT

 $-\pi$, $+\pi$ arraySize = 300



SAMPLING PERIOD

~200 ms

ROAD CURVATURE







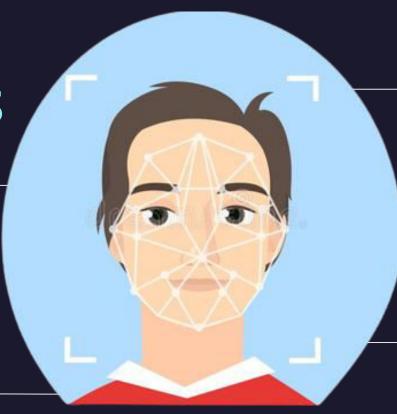




DROWSINESS DETECTION 2 s







THRESHOLD

P(left and right eye open) < 0,5

HEAD ORIENTATION

≥40° | 4 s





TIME THRESHOLD

5 s



DECIBEL DETECTION

NOISE DETECTION

 \geq 150.0 dB

















ROAD MAP

Google Maps API



AVERAGE SPEED

4 ranges

5 sec

SAMPLING PERIOD

TRIP INFO

Departure and arrival locations

Distraction Weights

	Role	Range	Description
Road curvature	Multiplier	I - 3	Difficulty of the road
Car speed	Multiplier	I - 4	Speed of the car
Drowsiness detection	Adder/Counter	0 - 30	How many times eyes are closed
Head Turned detection	Adder/Counter	0 - 12	How many times head is turned
Usage detection	Adder/Counter	0 - 1	How many times the phone is used
Fall detection	Adder/Counter	0 - 293	How many times the phone fall
Noise detection	Adder/Counter	0 - 12	How many times there is noise in the car

AttentionLevel Formula*

$$disattention = \left(\frac{speed}{4} + \frac{curvature}{3}\right) * \left(\frac{head}{12} + \frac{drowsiness}{30} + usage + \frac{noise}{12} + \frac{fall}{5}\right)$$

 $disattentionLevel_i = \alpha * disattention + (1 - \alpha) * disattentionLevel_{i-1}$

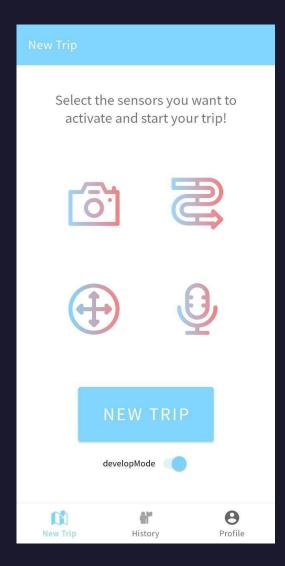
attentionLevel = 10 - disattentionLevel

Attention level

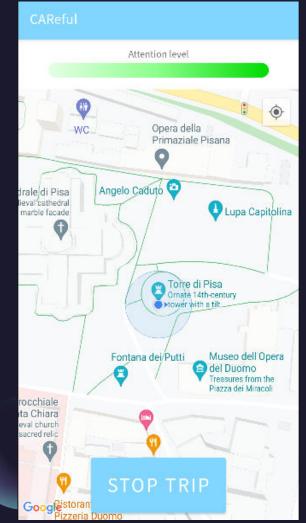
*computed every I min

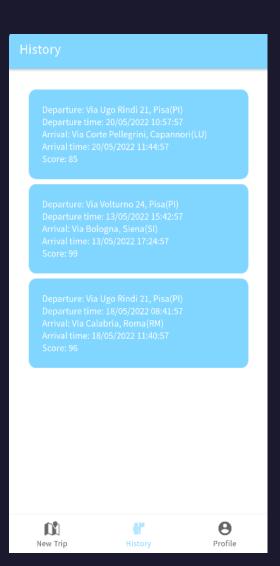


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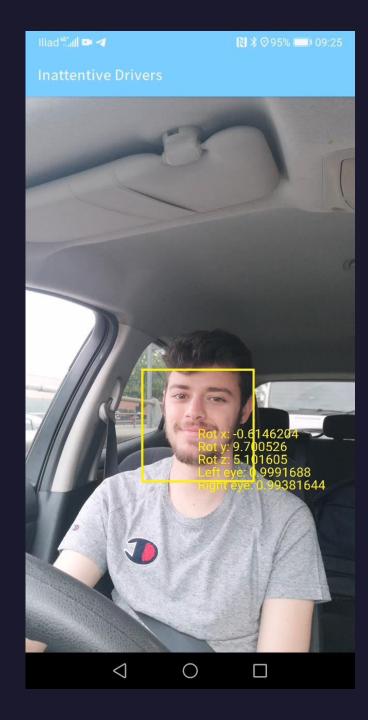




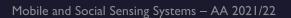


Video

Camera - Develop mode example





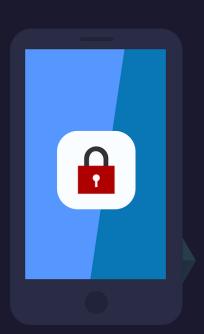


Privacy



- Real-time evaluation of sensors' information
- No sensitive data are stored (e.g. microphone/video recordings)
- Trip details stored:
 - departure and arrival location
 - departure and arrival time
 - score.
- Local SQLite db is used











- Does not detect the eyes if you wear sunglasses, but it works with eyeglasses
- Requires precise positioning of the phone
- Some threshold values may not be correct under particular conditions





- Detect if the driver has something in his hands and what it has (food, drink, cigarettes)
- Detect and classify noises, understanding if they are speeches, music or other.

Thanks for the attention

Questions are welcome!



