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WEEK 1: 9/17/18 - 9/24/18	
Previous goals (met or outstanding):	N/A
Current week progress/blockers:	<ul style="list-style-type: none"><li>— We submitted the project proposal</li><li>— I set up Ben/Dave's ip address and dns, need to change to a static ip</li><li>— I installed latest ROS version, may need different version later</li><li>— We started backlog for first sprint</li><li>— I did some more CV research, a few additions to the reading log</li><li>— Signed up for scrumdesk</li></ul>
Plan for this week:	<ul style="list-style-type: none"><li>— Turn in hard copy of proposal</li><li>— Create scrum backlog on scrumdesk</li><li>— Research CV implementations in ROS and OpenCV</li></ul>
Team summary:  Stand ups (~ 15 minutes)	<ul style="list-style-type: none"><li>— Monday stand up (9/17):<ul style="list-style-type: none"><li>— Discussed our project proposal</li><li>— I promised some Dave set up</li></ul></li><li>— Thursday stand up (9/20):<ul style="list-style-type: none"><li>— We decided to finish proposal over the weekend</li><li>— We briefly discussed Programming Robots with ROS book</li></ul></li><li>— Monday stand up (9/24)<ul style="list-style-type: none"><li>— We discussed Mariah's trip and the backlog</li><li>— I communicated that I needed to give Dave a static ip</li></ul></li></ul>

WEEK 2: 9/24/18 - 10/1/18	
Previous goals (met or outstanding):	<ul style="list-style-type: none"><li>✓ — Turn in hard copy of proposal</li><li>✓ — Create scrum backlog on scrumdesk</li><li>✓ — Research CV implementations in ROS and OpenCV</li></ul>
Current week progress/blockers:	<ul style="list-style-type: none"><li>— We created the scrum backlog in class (and out of class also)</li><li>— I read a couple sections of the Programming with ROS book</li><li>— I gave Dave a static IP and proved one could ssh into it</li><li>— I emailed Shereen about user story feedback</li></ul>
Plan for this week:	<ul style="list-style-type: none"><li>— Make sure first sprint is finalized on scrumdesk</li><li>— Continue reading Programming with ROS book</li><li>— Finish any additional tasks assigned tomorrow (Tuesday 10/2) in our sprint revisions.</li><li>— A code repository will be created</li></ul>
Team summary:	<ul style="list-style-type: none"><li>— Thursday stand up (9/27):</li></ul>

Stand ups (~ 15 minutes)	<ul style="list-style-type: none"> <li>— Messaged about the progress on scrumdesk</li> <li>— We both made sure we were on track and weren't blocked</li> <li>— Monday stand up (10/1): <ul style="list-style-type: none"> <li>— Mariah shared thoughts on user stories</li> <li>— Mariah filled me in on meeting with Shereen</li> <li>— We discussed what can be done in the second half of sprint 1</li> </ul> </li> </ul>
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WEEK 3:10/1/18 - 10/8/18	
Previous goals (met or outstanding):	<ul style="list-style-type: none"> <li>✓ — Make sure first sprint is finalized on scrumdesk</li> <li>✓ — Continue reading Programming with ROS book</li> <li>✓ — Finish any additional tasks assigned tomorrow (Tuesday 10/2) in our sprint revisions.</li> <li>✓ — A code repository will be created</li> </ul>
Current week progress/blockers:	<ul style="list-style-type: none"> <li>— Set up the ROS Hello World program</li> <li>— Read more of the Programming with ROS book</li> </ul>
Plan for this week:	<ul style="list-style-type: none"> <li>— Set up next sprint tomorrow (10/9)</li> <li>— Do tasks assigned in sprint (TBD)</li> <li>— Continue reading ROS book</li> </ul>
Team summary:  Stand ups (~ 15 minutes)	<ul style="list-style-type: none"> <li>— Thursday stand up (10/4): <ul style="list-style-type: none"> <li>— Just a check in. Nothing much to report.</li> </ul> </li> <li>— Monday stand up (10/8): <ul style="list-style-type: none"> <li>— Mariah told me about some ideas from Grace Hopper Conference</li> <li>— Keep in mind left handed people exist when designing gestures</li> <li>— We may need the Kinect to usb adapter</li> </ul> </li> </ul>

WEEK 4:10/8/18 - 10/15/18	
Previous goals (met or outstanding):	<ul style="list-style-type: none"> <li>✓ — Set up next sprint tomorrow (10/9)</li> <li>✓ — Do tasks assigned in sprint (TBD)</li> <li>— Continue reading ROS book</li> </ul>
Current week progress/blockers:	<ul style="list-style-type: none"> <li>— Set up sprint 2!</li> <li>— Got USB Camera to pull images and video</li> <li>— Discovered ffmpeg could be used to collect video</li> </ul>
Plan for this week:	<ul style="list-style-type: none"> <li>— Continue to play around with the input from the USB camera to determine if it is suitable for the project</li> <li>— Work on a demo using OpenCV</li> <li>— Attempt to use OpenCV with the video collected from the USB camera</li> <li>— Research existing implementations of gesture recognition</li> </ul>

<p>Team summary:</p> <p>Stand ups (~ 15 minutes)</p>	<ul style="list-style-type: none"> <li>— Thursday stand up (10/11): <ul style="list-style-type: none"> <li>— Planned out the sprint with Mariah</li> <li>— Met with Shereen to learn more about the grading criteria for sprints</li> </ul> </li> <li>— Monday stand up (10/15): <ul style="list-style-type: none"> <li>— Mariah is continuing to read the ROS book</li> <li>— Mariah is working on set up for the Raspberry Pi next</li> <li>— Discussed demos of OpenCV and ROS for next Tuesday</li> <li>— Hannah suggests that we pivot the project</li> <li>— We consider the idea of 3D printing some parts for a future sprint</li> </ul> </li> </ul>
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WEEK 5:10/15/18 - 10/22/18	
Previous goals (met or outstanding):	<ul style="list-style-type: none"> <li>✓ — Continue to play around with the input from the USB camera to determine if it is suitable for the project</li> <li>✓ — Work on a demo using OpenCV</li> <li>✓ — Attempt to use OpenCV with the video collected from the USB camera</li> <li>✓ — Research existing implementations of gesture recognition</li> </ul>
Current week progress/blockers:	<ul style="list-style-type: none"> <li>— Still working on researching different implementations of gesture recognition</li> <li>— Thinking about what needs to happen next sprint has been difficult</li> <li>— A monitor/keyboard has been set up for the Raspberry Pi</li> <li>— Wifi is working on the Pi</li> <li>— A couple demo programs using OpenCV are working on Dave</li> </ul>
Plan for this week:	<ul style="list-style-type: none"> <li>— Going to OSU tomorrow (10/23)</li> <li>— Plan sprint 3</li> <li>— Get ROS/OpenCV demos on the Pi</li> </ul>
<p>Team summary:</p> <p>Stand ups (~ 15 minutes)</p>	<ul style="list-style-type: none"> <li>— Thursday stand up (10/18): <ul style="list-style-type: none"> <li>— Mariah updated me on progress on setting up the Pi</li> <li>— I updated Mariah on the OpenCV demos</li> </ul> </li> <li>— Monday stand up (10/22): <ul style="list-style-type: none"> <li>— We discussed our visit to OSU tomorrow (10/23)</li> </ul> </li> </ul>

WEEK 6:10/22/18 - 10/29/18	
Previous goals (met or outstanding):	<ul style="list-style-type: none"> <li>✓ — Going to OSU tomorrow (10/23)</li> <li>✓ — Plan sprint 3</li> <li>✓ — Get ROS/OpenCV demos on the Pi</li> </ul>
Current week progress/blockers:	<ul style="list-style-type: none"> <li>— Started sprint 3</li> <li>— Looked at the different ROS installations for Dave</li> <li>— Looked into some of the OpenCV functionality</li> </ul>
Plan for this week:	<ul style="list-style-type: none"> <li>— Install the correct version of ROS on Dave</li> <li>— Report on the OpenCV API</li> <li>— Work on programmatically collecting video data with OpenCV</li> </ul>
Team summary:  Stand ups (~ 15 minutes)	<ul style="list-style-type: none"> <li>— Thursday stand up (10/25): <ul style="list-style-type: none"> <li>— Went over our demos</li> <li>— Briefly discussed sprint 3</li> </ul> </li> <li>— Monday stand up (10/29): <ul style="list-style-type: none"> <li>— Just checked in with each other</li> </ul> </li> </ul>