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WEEK 1: 9/17/18 - 9/24/18	
Previous goals (met or outstanding):	N/A
Current week progress/blockers:	 We submitted the project proposal I set up Ben/Dave's ip address and dns, need to change to a static ip I installed latest ROS version, may need different version later We started backlog for first sprint I did some more CV research, a few additions to the reading log Signed up for scrumdesk
Plan for this week:	— Turn in hard copy of proposal — Create scrum backlog on scrumdesk — Research CV implementations in ROS and OpenCV
Team summary: Stand ups (~ 15 minutes)	 Monday stand up (9/17): Discussed our project proposal I promised some Dave set up Thursday stand up (9/20): We decided to finish proposal over the weekend We briefly discussed Programming Robots with ROS book Monday stand up (9/24) We discussed Mariah's trip and the backlog I communicated that I needed to give Dave a static ip

WEEK 2: 9/24/18 - 10/1/18	
Previous goals (met or outstanding):	 ✓ — Turn in hard copy of proposal ✓ — Create scrum backlog on scrumdesk ✓ — Research CV implementations in ROS and OpenCV
Current week progress/blockers:	 We created the scrum backlog in class (and out of class also) I read a couple sections of the Programming with ROS book I gave Dave a static IP and proved one could ssh into it I emailed Shereen about user story feedback
Plan for this week:	 Make sure first sprint is finalized on scrumdesk Continue reading Programming with ROS book Finish any additional tasks assigned tomorrow (Tuesday 10/2) in our sprint revisions. A code repository will be created
Team summary:	— Thursday stand up (9/27):

Stand ups (~ 15 minutes)	 Messaged about the progress on scrumdesk We both made sure we were on track and weren't blocked Monday stand up (10/1): Mariah shared thoughts on user stories Mariah filled me in on meeting with Shereen We discussed what can be done in the second half of sprint 1
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WEEK 3:10/1/18 - 10/8/18	
Previous goals (met or outstanding):	 ✓— Make sure first sprint is finalized on scrumdesk ✓— Continue reading Programming with ROS book ✓— Finish any additional tasks assigned tomorrow (Tuesday 10/2) in our sprint revisions. ✓— A code repository will be created
Current week progress/blockers:	Set up the ROS Hello World program Read more of the Programming with ROS book
Plan for this week:	 Set up next sprint tomorrow (10/9) Do tasks assigned in sprint (TBD) Continue reading ROS book
Team summary: Stand ups (~ 15 minutes)	 Thursday stand up (10/4): Just a check in. Nothing much to report. Monday stand up (10/8): Mariah told me about some ideas from Grace Hopper Conference Keep in mind left handed people exist when designing gestures We may need the Kinect to usb adapter

WEEK 4:10/8/18 - 10/15/18	
Previous goals (met or outstanding):	 ✓ — Set up next sprint tomorrow (10/9) ✓ — Do tasks assigned in sprint (TBD) — Continue reading ROS book
Current week progress/blockers:	 Set up sprint 2! Got USB Camera to pull images and video Discovered ffmpeg could be used to collect video
Plan for this week:	 Continue to play around with the input from the USB camera to determine if it is suitable for the project Work on a demo using OpenCV Attempt to use OpenCV with the video collected from the USB camera Research existing implementations of gesture recognition

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Team summary:	— Thursday stand up (10/11):
Stand ups (~ 15 minutes)	 — Planned out the sprint with Mariah — Met with Shereen to learn more about the grading criteria for sprints — Monday stand up (10/15):
	— Mariah is continuing to read the ROS book— Mariah is working on set up for the Raspberry Pi next
	 — Discussed demos of OpenCV and ROS for next Tuesday — Hannah suggests that we pivot the project — We consider the idea of 3D printing some parts for a future sprint

WEEK 5:10/15/18 - 10/22/18		
Previous goals (met or outstanding):	 ✓— Continue to play around with the input from the USB camera to determine if it is suitable for the project ✓— Work on a demo using OpenCV ✓— Attempt to use OpenCV with the video collected from the USB camera ✓— Research existing implementations of gesture recognition 	
Current week progress/blockers:	 Still working on researching different implementations of gesture recognition Thinking about what needs to happen next sprint has been difficult A monitor/keyboard has been set up for the Raspberry Pi Wifi is working on the Pi A couple demo programs using OpenCV are working on Dave 	
Plan for this week:	— Going to OSU tomorrow (10/23) — Plan sprint 3 — Get ROS/OpenCV demos on the Pi	
Team summary: Stand ups (~ 15 minutes)	 Thursday stand up (10/18): Mariah updated me on progress on setting up the Pi I updated Mariah on the OpenCV demos Monday stand up (10/22): We discussed our visit to OSU tomorrow (10/23) 	

WEEK 6:10/22/18 - 10/29/18	
Previous goals (met or outstanding):	 ✓ — Going to OSU tomorrow (10/23) ✓ — Plan sprint 3 ✓ — Get ROS/OpenCV demos on the Pi
Current week progress/blockers:	— Started sprint 3 — Looked at the different ROS installations for Dave — Looked into some of the OpenCV functionality
Plan for this week:	Install the correct version of ROS on Dave Report on the OpenCV API Work on programmatically collecting video data with OpenCV
Team summary: Stand ups (~ 15 minutes)	— Thursday stand up (10/25): — Went over our demos — Briefly discussed sprint 3 — Monday stand up (10/29): — Just checked in with each other

WEEK 7:10/29/18 - 11/5/18		
Previous goals (met or outstanding):	Install the correct version of ROS on Dave Report on the OpenCV API Work on programmatically collecting video data with OpenCV	
Current week progress/blockers:	 Getting general consensus between Pi and Dave with running code Reported on the OpenCV library interface Investigated the performance issues on the Pi Found a better camera (yay) 	
Plan for this week:	— Plan sprint 4 — Start sprint 4	
Team summary: Stand ups (~ 15 minutes)	 Thursday stand up (11/1): Backlog refinement Monday stand up (11/5): Talked about sprint 4 	

WEEK 8:11/5/18 - 11/12/18		
Previous goals (met or outstanding):	— Plan sprint 4— Start sprint 4	

Current week progress/blockers:	 — Planned the sprint! — Discussed our initial gesture set — Discussed initial test gesture (peace sign) — Discussed the role of orientation of hands in gesture recognition — Read more about current gesture implementation strategies (ML is often used)
Plan for this week:	 Write a program that will recognize a gesture of our choosing (peace sign is the current goal) Make an effort to implement a few strategies so that we can assess how well various strategies work Put some more thought into our initial gesture set
Team summary: Stand ups (~ 15 minutes)	 Thursday stand up (11/8): Discussed a few gesture implementation details Discussed where we would each start in the sprint Mariah remembered (very cleverly) that we solved the problem of "start" and "stop" gestures in our design of Recipe Wizard with the idea of a toggling gesture Monday stand up (11/12): Talked about sprint progress Talked briefly about Hand and Mind and not finding much useful material from the text, at the moment