An O(NlogN) Fast Direct Solver for Partial Hierarchically Semi-Separable Matrices (Ambikasaran, Darve)

Overview

solvers for large dense linear systems mostly iterative based on Krylov subspaces (Arnoldi, Conjugate Gradients, GMRES, MINRES, Biconjugate Gradient stabilized methods, QHR, TFQHR)

- 1 preconditioning
- often used for boundary integral @ matrix-rector product using fast summation techniques (FAM, Barnes-Hut, panel clustering, FFT, wavelet based methods)
- => methods solve systems in linear or almost linear time

- does not scale well for multiple inversions - good preconditioner may be hard to find

=> fast direct solvers

Hierarchical Matrices

rank of matrix A: dimension of the image of A

sub-divide matrix into a hierarchy of rectangular blocks and approximate them by low rank matrices (Hachbusch)

(that means that A has all subblocks taken out of the matrix below a specific superdiagonal salisfying a certain rank hierarchically semi-separable matrix of separability p: constrain; similar for upper triangular part) HSS : L: lower triangular (Chandra -A = L + Urank L = rank U = p sehan)

U: upper triangular HODLR: hierarchical off-diagonal low-ranh matrix (often obtained from boundary integral equations)

HSS c p- HSS c HODLR

U, V unitary A=ULVT Chandra setran: O(N) salver for HSS systems: L lower triangular factorization O(N2)

Low rank approximation

fast low rank approximations: adaptive cross approximation (ACA), pseudo-shelek approximations, interpolatory decomposition, randomized algorithms, rank-revealing LU, QR

Algorithm

1) Factorization

3D boundary element methods $O(N^2)$, because rank p of interacting clusters $O(\sqrt{N})$

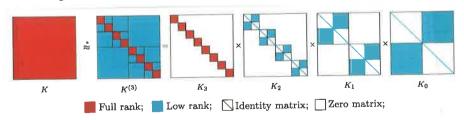


Fig. 1 Factorization of a three level HODLR/p-HSS matrix

2 Calculating determinant

det K = det K(3) = det K3 det K2 det K4 det K0