

## Problem Set 5

### Q1 – Learning from Noisy Labels

#### Overview

In this problem, you will build on the proofs for learning from noisy labels we worked through during class. Specifically, you will be investigating the anchor-and-learn approach as well as how to leverage noisy labels at prediction time, if they're available.

#### Learning Goals

Medical data is messy and true gold labels are often hard or prohibitively expensive to obtain in bulk. As a result, it is often necessary to leverage noisy labels in the training process. In this problem, we hope you:

- Solidify your understanding of how training from noisy labels works,
- Recognize scenarios in which noisy labels may be available at prediction time,
- And understand both theoretically and intuitively why noisy labels at prediction time can lead to more accurate performance.

#### Background

In medical data, truly gold data labels are often hard and/or expensive to come by, since there is a limited pool of qualified experts. Even with experts, labels can be imperfect. As a result, we often have to train on labels with some noise. In class, we examined the problem as training on a set of labels  $(X, \tilde{Y})$  where  $\tilde{Y}$  are our noisy labels.

**[10 points] 1.1**

In the anchor-and-learn work, the authors make the assumption that if an anchor is present, the true label must be 1. For 1.1, we lift that assumption. For example, a patient may be taking Metformin for one of its other indications (e.g. PCOS) or 'DM2' might be mentioned in the notes because a patient's parent has diabetes. Therefore,  $p(\tilde{Y} = 1|Y = 0)$  can be nonzero, like in the noisy label example we did in class. Furthermore, when deploying this model, we do in fact have  $\tilde{Y}$  available to us, in addition to  $X$ , since we can search back in the EHR. As a result, we want you to show how you would leverage the knowledge of the noisy label  $\tilde{Y}$  to improve your prediction. Concretely, we want you to show how you would estimate  $p(Y = 1|X, \tilde{Y})$  instead of just  $p(Y = 1|X)$ . In particular, under the class-conditional independence assumption,  $\tilde{Y} \perp X|Y$ , do the following:

**a) [5 points]** Express  $p(Y = 1|X, \tilde{Y})$  in terms of  $p(Y|X)$ ,  $p(\tilde{Y}|Y)$ , and  $p(\tilde{Y}|X)$ .

**b) [5 points]** Explain how you would estimate each of these quantities:  $p(Y|X)$ ,  $p(\tilde{Y}|Y)$ , and  $p(\tilde{Y}|X)$ . Do any require gathering more data? Are these extra estimation tasks feasible? (Hint: review your notes from lecture.)

**[10 points] 1.2**

Now let us again assume that the presence of an anchor does mean that  $Y = 1$ , as in the anchor-and-learn paper. Concretely, that means  $p(Y = 1|\tilde{Y} = 1) = 1$ . However, as before, an anchor is only present in true cases part of the time, e.g.  $p(\tilde{Y} = 1|Y = 1) = \alpha$ . This is identical to the scenario provided in the Learning Classifiers from Only Positive and Unlabeled Data paper. With this new information about  $p(\tilde{Y}|Y)$ , plug those values into your answer for Part 1, and provide the probabilities for  $p(Y = 1|X, \tilde{Y} = 1)$  and  $p(Y = 1|X, \tilde{Y} = 0)$ . These should be expressed only in terms of  $p(Y|X)$  and  $\alpha$ .