Supplementary Material Scalable Gaussian Processes for Characterizing Multidimensional Change Surfaces

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Initialization of w(x) RKS Features

To initialize w(x) defined by RKS features we first simplify our change surface model and assume that each latent function $f_1, ..., f_r$ from Eq. 8 is drawn from a Gaussian process with an RBF kernel. Since RBF kernels have many fewer hyperparameters than spectral mixture kernels, this enables the initialization to focus on w(x). Algorithm 2 provides the procedure for initializing this simplified change surface model. Note that depending on the application domain, a model with latent functions defined by RBF kernels may be sufficient

Algorithm 2 Initialize RKS w(x) by optimizing a simplified model with RBF kernels

- 1: **for** i = 1 : g **do**
- 2: Draw a, ω, b for RKS features in w(x)
- 3: Draw h random values for RBF kernels. Choose the best with maximum marginal likelihood
- 4: Partial optimization of w(x) and RBF kernels
- 5: end for
- 6: Choose the best set of hyperparameters with maximum marginal likelihood
- 7: Optimize all hyperparameters until convergence

In the algorithm, we test multiple possible sets of values for w(x) by drawing the hyperparameters a, ω , and b from their respective prior distributions g number of times. To recall the prior distributions from Section 3.1 were,

$$a \sim \mathcal{N}(0, \frac{\sigma_0}{m}I)$$
 (1)

$$\omega_i \sim \mathcal{N}(0, \frac{1}{4\pi^2} \Lambda^{-1}) \tag{2}$$

$$b_i \sim \text{Uniform}(0, 2\pi)$$
 (3)

We set reasonable values for hyperparameters in the prior distributions. Specifically, we let $\Lambda = (\frac{range(x)}{2})^2$, $\sigma_0 = \operatorname{std}(y)$, and $\sigma_n = \frac{\operatorname{mean}(|y|)}{10}$. These choices are similar to those used in Lázaro-Gredilla et al. (2010).

For each set of w(x) hyperparameters that we sample, we sample sets of hyperparameters for the RBF kernels h number of times and select the set that yeilds the maximum marginal likelihood. Then we run an abbreviated optimization procedure over each set of w(x) and RBF hyperparameters and finally select the joint set that yeilds the maximum marginal likelihood. Finally, we optimize all the resulting parameters until convergence.

References

Lázaro-Gredilla, M., Quiñonero-Candela, J., Rasmussen, C. E., and Figueiras-Vidal, A. R. (2010). Sparse spectrum gaussian process regression. The Journal of Machine Learning Research, 11:1865–1881.