

Millop improves L^AT_EX level of physicists

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Introduction

The idea is to have a \LaTeX -documentation for the whole departement of physics at the ETH Zürich. If this works well, maybe D-MATH or D-CHAB will follow etc. As a student I don't know how this is handled within the groups but all scripts given to me to study with have not been written with the best and/or the most modern \LaTeX -style. Also there are professors that don't do at all their scripts with \LaTeX . So I'd like this to change.

\LaTeX is really nice but whenever one wants something or to improve something, one has to google a long time through stuff that doesn't work or isn't compatible with each other. So far, I haven't found any satisfying documentation for \LaTeX for physicists so I will start from zero. This document should contain as few as possible solutions but always the best known one compatible with standard packages as AMSmath, etc. Whenever a package is added, it should be documented why.

This should be built up in chapters that everybody uses like maths (integrals etc.) and chapters specific to research groups.

Chapter 1

Maths

1.1 Equation formats

1.2 align

Align to the =

$$\begin{array}{l} a = b \\ \leadsto caoeuuu = d \end{array}$$

Something like this looks confusing

$$\begin{array}{l} a = b \\ \leadsto aoeuou = d \end{array}$$

1.3 Integrals

Needs fix. Need to put the right negative space to make it look right. Put a grid in background in some way.

1.3.1 Simple integral

$$\int dx \, x = x^2 \tag{1.1a}$$

$$\int_0^1 dx \, x = 1 \tag{1.1b}$$

$$\int dx \, x = x^2 \tag{1.1c}$$

$$\int_0^{10} dx \, x = 100 \tag{1.1d}$$

$$\int dx \, x = x^2 \tag{1.1e}$$

$$\int_0^{100} dx \, x = 100 \tag{1.1f}$$

1.3.2 With fractions

Use thick space between two roman variables or between a roman variable and a fraction.

$$\int d^3\mathbf{r} \, \mathbf{j}(\mathbf{r}, t) = \int d^3\mathbf{r} \, \frac{1}{2m} [\psi^* (-i\hbar\nabla) \psi + \psi (i\hbar\nabla) \psi^*] \quad (1.2)$$

$$\int d^3\mathbf{r} \, \mathbf{j}(\mathbf{r}, t) = \int d^3\mathbf{r} \, \frac{1}{2m} [\psi^* (-i\hbar\nabla) \psi + \psi (i\hbar\nabla) \psi^*] \quad (1.3)$$

1.3.3 Multiple integrals

$$\iiint_V dV \, \nabla \cdot F = \iint_S dS \, F \quad (1.4)$$

1.4 Derivatives

$$\frac{d}{dx} x^2 = x \quad (1.5a)$$

1.5 Functions

Examples of separations and their importance.

$$\sin 2\pi \cos \theta = 0 \quad (1.6a)$$

$$\sin(\theta x) = \sin \theta x \neq \sin \theta x = \sin(\theta) x \quad (1.6b)$$

1.6 Multiplications

$$1 \cdot 1 \quad (1.7a)$$

$$1 \cdot 1 \quad (1.7b)$$

$$1 \cdot 1 \quad (1.7c)$$

$$0 \cdot 0 \quad (1.7d)$$

$$x \cdot x \quad (1.7e)$$

$$\nabla \cdot x \quad (1.7f)$$

$$x \cdot x \quad (1.7g)$$

$$\nabla \cdot x \quad (1.7h)$$

1.7 Hyphen

1.8 Braces

I recommend using dynamic sized braces like $()$. However when two nested braces have the same size the readability is increased if the exterior brace has a bigger size. It is very important if the nested braces are just next to each other. One possibility is to add a `vphantom` and don't forget to put a if needed.

$$\int d^3\mathbf{r} \mathbf{j}(\mathbf{r}, t) = \int d^3\mathbf{r} \frac{1}{2m} [\langle \psi, t | \mathbf{r} \rangle \langle \mathbf{r} | \mathbf{p} | \psi, t \rangle + \langle \psi, t | \mathbf{p} | \mathbf{r} \rangle \langle \mathbf{r} | \psi, t \rangle] \quad (1.8)$$

Without the `vphantom`:

$$\int d^3\mathbf{r} \mathbf{j}(\mathbf{r}, t) = \int d^3\mathbf{r} \frac{1}{2m} [\langle \psi, t | \mathbf{r} \rangle \langle \mathbf{r} | \mathbf{p} | \psi, t \rangle + \langle \psi, t | \mathbf{p} | \mathbf{r} \rangle \langle \mathbf{r} | \psi, t \rangle] \quad (1.9)$$

Alternative with

1.9 Prime

A' and A' look exactly the same.

1.10 Square root

1.11 Matrix

When there is an underbrace under the matrix, one needs a `on` both sides

$$\underbrace{\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}}_{blabla} = \begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix} \quad (1.10)$$

$$\underbrace{\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}}_{blabla} = \begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix} \quad (1.11)$$

$$\begin{pmatrix} \dots\dots\dots \\ \dots & 1 & \dots \\ \dots\dots\dots \end{pmatrix} \quad (1.12)$$

1.12 Miscellaneous

- i) Use ℓ instead of l . Increases readability.
- ii) \xrightarrow{T} instead of $\overset{T}{\rightarrow}$
- iii) $\dot{\cdot}$.

Chapter 2

Useful packages

2.1 `pgf/tikz`

2.2 `change`