Graph

Clase que representa un grafo. Por sí solo no hace nada.

REQUIERE: NaturalNumber

REQUERIDO POR: Bipartite, MinSpanningTree, Shortest Paths, etc.

```
#pragma once
#include <algorithm>
#include <cassert>
#include <iostream>
#include <vector>
#include "NaturalNumber.hpp"
template <class Iter, class T>
Iter find binary(const Iter& first, const Iter& last, const T& t)
    auto it = std::lower bound(first, last, t);
    if (it == last || *it != t)
        return last;
   return it;
}
// simple undirected graph
class Graph
{
public:
   using size_type = long long;
    using Vertex = std::int64 t;
    static constexpr Vertex INVALID_VERTEX{-1};
   using weight_t = std::int64_t;
    // something larger than weight_t, for when you have that weight_t doesn't
    // properly hold a sum of weight_t (for example, if weight_t = char).
    using sumweight t = std::int64 t;
    struct Neighbor; // Represents a half-edge (vertex, weight)
    struct Edge; // (from, to, weight)
```

```
using neighbor list = std::vector<Neighbor>;
using neighbor_const_iterator = neighbor_list::const_iterator;
using neighbor_iterator = neighbor_list::iterator;
explicit Graph(Vertex numberOfVertices = 0)
    : m_numvertices(std::max<Vertex>(0, numberOfVertices))
    , m_graph(m_numvertices)
{}
size_type degree(Vertex a) const { return m_graph[a].size(); }
// Graph modification functions
Vertex add_vertex()
₹
   m graph.emplace back(); // empty vector
   return m numvertices++;
}
void add edge(Vertex from, Vertex to, weight t w = 1)
   m_graph[from].emplace_back(to, w);
   m_graph[to].emplace_back(from, w);
   ++m numedges;
   m_neighbors_sorted = false;
}
void add_edge(const Edge& e) { add_edge(e.from, e.to, e.weight()); }
template <class EdgeContainer>
void add edges(const EdgeContainer& edges)
{
   for (auto& e : edges)
        add_edge(e);
}
void add_edges(const std::initializer_list<Edge>& edges)
{
   for (auto& e : edges)
        add edge(e);
}
bool add_edge_no_repeat(Vertex from, Vertex to, weight_t w = 1)
{
    if (is_neighbor(from, to))
```

```
return false;
   add_edge(from, to, w);
   return true;
}
void sort_neighbors()
    if (m_neighbors_sorted)
        return;
   for (auto& adj_list : m_graph)
        sort(adj list.begin(), adj list.end());
   m_neighbors_sorted = true;
}
// Get Graph Info
Vertex num_vertices() const { return m_numvertices; }
size_type num_edges() const { return m_numedges; }
inline const neighbor_list& neighbors(Vertex n) const { return m_graph[n]; }
inline const neighbor list& outneighbors(Vertex n) const
   return m graph[n];
inline const neighbor_list& inneighbors(Vertex n) const
{
   return m_graph[n];
}
using all vertices = basic natural number<Vertex>;
auto vertices() const { return all_vertices(num_vertices()); }
std::vector<Edge> edges() const
{
   std::vector<Edge> total;
   for (auto u : vertices())
        for (auto v : m_graph[u])
        {
            if (v > u)
                total.emplace_back(u, v, v.weight());
        }
```

```
}
    return total;
}
bool is_neighbor(Vertex from, Vertex to) const
    if (degree(from) > degree(to))
        std::swap(from, to);
    auto& NF = neighbors(from);
    if (m neighbors sorted)
        return std::binary_search(NF.begin(), NF.end(), to);
    for (auto& a : NF)
        if (a == to)
            return true;
    }
    return false;
}
weight_t edge_value(Vertex from, Vertex to) const
{
    if (degree(from) > degree(to))
        std::swap(from, to);
    auto neigh = get_neighbor(from, to);
    if (neigh == neighbors(from).end() || *neigh != to)
        return 0;
    return neigh->weight();
}
neighbor_const_iterator get_neighbor(Vertex from, Vertex to) const
{
    auto first = m graph[from].begin();
    auto last = m_graph[from].end();
    if (m_neighbors_sorted)
        return find_binary(first, last, to);
```

```
return std::find(first, last, to);
}
neighbor_iterator get_neighbor(Vertex from, Vertex to)
   auto first = m graph[from].begin();
   auto last = m_graph[from].end();
   if (m neighbors sorted)
        return find_binary(first, last, to);
   return std::find(first, last, to);
}
// Start class definitions
struct Neighbor
{
   explicit Neighbor() : vertex(INVALID_VERTEX), m_weight(0) {}
   explicit Neighbor(Vertex v, weight t w = 1) : vertex(v), m weight(w) {}
   inline operator Vertex() const { return vertex; }
   weight t weight() const { return m weight; }
   void set_weight(weight_t w) { m_weight = w; }
   Vertex vertex{INVALID VERTEX};
private:
   // comment out if not needed, and make set_weight do nothing, and make
   // weight() return 1
   weight_t m_weight{1};
};
struct Edge
   Vertex from;
   Vertex to;
   Edge() : from(INVALID_VERTEX), to(INVALID_VERTEX), m_weight(0) {}
   Edge(Vertex f, Vertex t, weight t w = 1) : from(f), to(t), m weight(w)
   {}
   Vertex operator[](bool i) const { return i ? to : from; }
```

```
// replace by "return 1" if weight doesn't exist
        weight_t weight() const { return m_weight; }
        void change_weight(weight_t w) { m_weight = w; }
        bool operator==(const Edge& E) const
        {
            return ((from == E.from && to == E.to) ||
                    (from == E.to && to == E.from)) &&
              m_weight == E.m_weight;
        }
    private:
        weight_t m_weight{1};
    };
private:
    // Graph member variables
    size_type m_numvertices{0};
    size_type m_numedges{0};
    std::vector<neighbor_list> m_graph{};
    bool m_neighbors_sorted{false};
};
```