```
64
    sm = rp2.StateMachine(0, blink_1hz, freq=20000, set_base=Pin(20))
66
   # Set the IRQ handler to print the millisecond timestamp.
67
   #sm.irq(lambda p: print("sm1:"+str(time.ticks_ms())))
68
69
    # Start the StateMachine.
70
   sm.active(1)
71
72
    # Each PIO instance has a 32-slot instruction memory
    sm2 = rp2.StateMachine(1, blink_0_1hz, freq=2000, set_base=Pin(19))
73
74
75
    # Set the IRQ handler to print the millisecond timestamp.
    sm2.irq(lambda p: print("sm2:"+str(time.ticks_ms())))
76
77
    sm2.active(1)
hell 🛚
ype "help()" for more information.
>> %Run -c $EDITOR_CONTENT
D>sm2:33356258
sm2:33366258
sm2:33376258
sm2:33386258
sm2:33396258
sm2:33406258
sm2:33416258
sm2:33426258
sm2:33436258
             W 5 s 🚺 99.98 mHz duty 50 % 🚺 10 s⁻
```