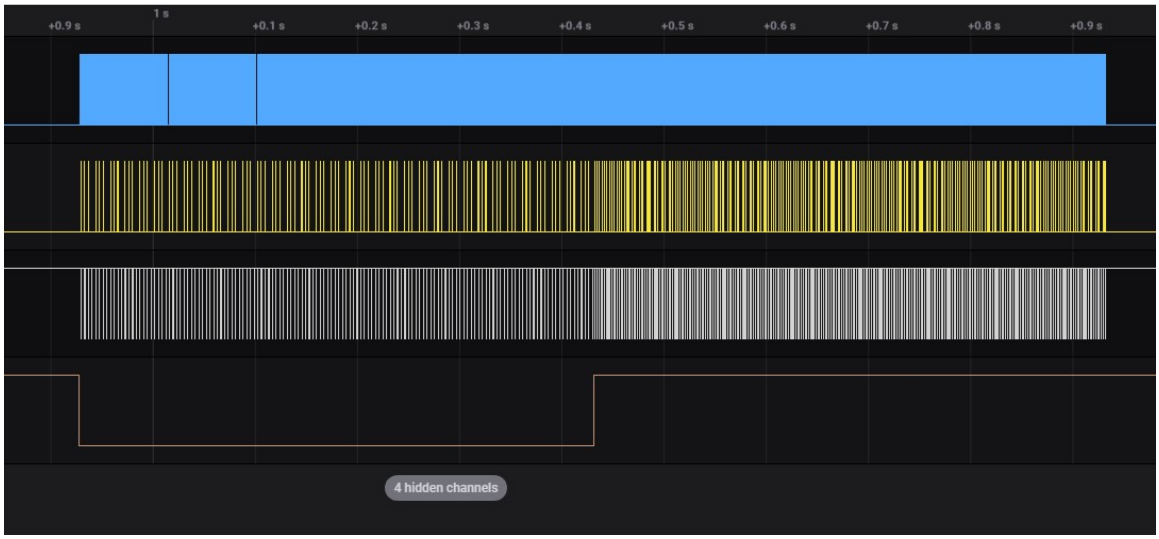


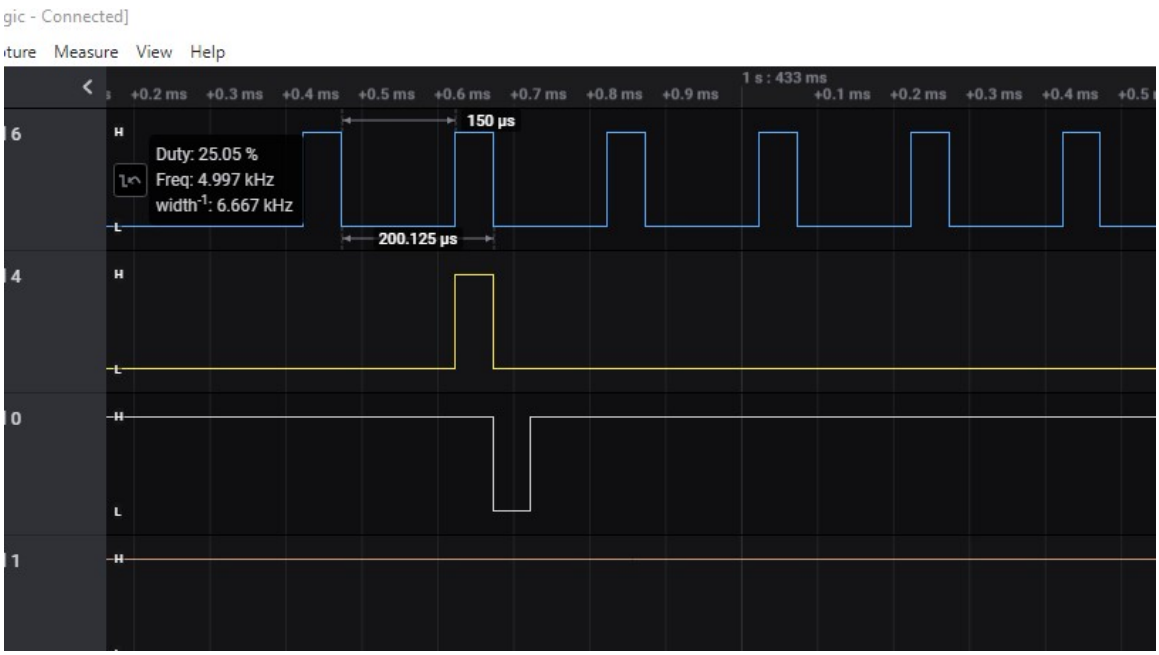

```
signals are shifted by:
d = 4
d2 = 5
d3 = 0

sm = rp2.StateMachine(1, nockenwelle, freq=1_0_000,
set_base=Pin(18))
sm2 = rp2.StateMachine(0, zuendsignal2, freq=1_0_000,
set_base=Pin(17))
sm3 = rp2.StateMachine(2, kurbelwelle, freq=1_0_000,
set_base=Pin(19))

first half of second is 10kHz second half is 20 kHz
```


asure View Help
+7 ms
+8 ms
+9 ms
0 s : 930 ms
+1 ms
H
L
H
L
H
L
H
L
4 hidden channels


Measure View Help
+8 ms
+9 ms
1 s : 430 ms
+1 ms
+2 ms
+3 ms
+4 ms
+5 ms
+6 ms
+7 ms
+8 ms
+9 ms
H
L
H
L
H
L
H
L
4 hidden channels


gic - Connected]
ıture Measure View Help
1 s : 433 ms
+0.2 ms +0.3 ms +0.4 ms +0.5 ms +0.6 ms +0.7 ms +0.8 ms +0.9 ms +0.1 ms +0.2 ms +0.3 ms +0.4 ms
6
4
0
1
H
L
150 µs
200.125 µs
Duty: 25.05 %
Freq: 4.997 kHz
width-1: 6.667 kHz