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Shear velocity criterion for incipient motion of sediment

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Abstract: The prediction of incipient motion has had great importance to the theory of sediment transport. The most commonly used methods are based on the concept of critical shear stress and employ an approach similar, or identical, to the Shields diagram. An alternative method that uses the movability number, defined as the ratio of the shear velocity to the particle's settling velocity, was employed in this study. A large amount of experimental data were used to develop an empirical incipient motion criterion based on the movability number. It is shown that this approach can provide a simple and accurate method of computing the threshold condition for sediment motion.

Key words: incipient motion; sediment transport; Shields diagram; critical shear stress; critical shear velocity; movability number

1 Introduction

The concept of excess shear stress has played a major role in the prediction of sediment transport rates. It is also used in problems involving channel erosion and stable channel design. Underlying this concept is the phenomenon of incipient motion, i.e., the transition from a stationary state to a state of initial (incipient) motion of the sediment particles in response to an increase in the hydrodynamic forces acting on a bed of loose sediment. This hard-to-define critical threshold condition has been approached using diverse physical parameters, such as the shear velocity (U^*) and depth-mean velocity (U), but none has proven as popular as the traditional Shields (1936) curve based on the threshold shear stress.

Shields (1936) expressed the critical shear stress for the initiation of motion as a relation between the nondimensional shear stress θ (also called the Shields parameter or the Shields entrainment function) and the grain Reynolds number based on the shear velocity, R^* , defined as

$$\theta = \frac{\tau}{\left(\rho_{\rm s} - \rho\right)gd}, \quad R^* = \frac{U^*d}{V} \tag{1}$$

where τ is the bottom shear stress; ρ and $\rho_{\rm s}$ are the water and sediment densities, respectively; ν is the kinematic viscosity of water; g is the acceleration due to gravity; d is the diameter of the sediment particle; and U^* is the shear velocity, defined as $U^* = \sqrt{\tau/\rho}$. The original relation suffered from some limitations, due to a limited amount of data used in its

derivation and to the choice of independent variables: both θ and R^* depend on the shear velocity, resulting in the need for an iterative procedure to find the incipient motion condition θ_c , defined as $\theta_c = \frac{\tau_c}{(\rho_c - \rho) gd}$, where τ_c is the critical bottom shear stress for the initiation

of motion. Later studies significantly extended the scope of the original relation with additional data collected both in the lower (fine sediment) and upper (coarse sediment) ranges of R^* . Other researchers adopted different independent variables. Yalin (1972) suggested eliminating U^* from the abscissa through a combination of θ and R^* , the Yalin parameter: $\Xi = R^{*2}/\theta = d^{*3}$, with d^* being the dimensionless grain diameter defined as

$$d^* = \left\lceil \frac{\left(s - 1\right)g}{v^2} \right\rceil^{\frac{1}{3}} d \tag{2}$$

where s is the specific gravity of the sediment, and $s = \rho_s/\rho$. The use of d^* eliminates the simultaneous use of U^* in the abscissa and the ordinate of the Shields diagram, reducing data scatter and eliminating the need for an iterative process to find θ_c for a particular set of hydraulic and sediment conditions.

Substantially more data has been collected subsequent to Shields' work, significantly expanding the range of experimental conditions. One of the issues that became significant with the arrival of these new experimental sets was the scatter of the data. This scatter is apparent in Fig. 1, where the empirical threshold curves of Paphitis (2001) are plotted against measurement data. Some authors, such as Zanke (2003) and Vollmer and Kleinhans (2007), attempted to explain and predict the disperse nature of the data. However, their analyses are complex and depend on variables that are unknown in most practical applications. Others suggest the use of different dependent variables that are better able to collapse the data into narrower bands, and consequently, are more amenable to conversion to analytic expressions.

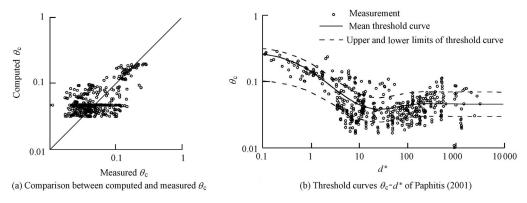


Fig. 1 Shields diagram for incipient motion of Paphitis (2001) and its comparison with measurements

Liu (1958) proposed the use of the movability number of the sediment particle, defined as $\Lambda = U^*/w$, where w is the settling velocity of the individual sediment particle, as an alternative to the Shields parameter, and developed a Λ_c - R^* relation, where Λ_c is the movability number

for the threshold of motion, defined as $\Lambda_{\rm c} = U_{\rm c}^*/w$, with $U_{\rm c}^*$ being the critical shear velocity. Beheshti and Ataie-Ashtiani (2008) also found Λ to be a more suitable parameter for determining the threshold of motion, but used instead a $\Lambda_{\rm c}$ - d^* curve. Unfortunately, the $\Lambda_{\rm c}$ - d^* curve shows the wrong behavior for large values of d^* . The analysis presented herein extends the work of these researchers by using a more comprehensive amount of experimental data to derive a new empirical $\Lambda_{\rm c}$ - d^* relation that is more accurate than that of Beheshti and Ataie-Ashtiani (2008) and that is valid for a larger range of d^* . A succinct theoretical basis is provided in the next section, which is followed by the derivation of a new relation in section 3. It is shown that a better agreement between measurements and predictions is achieved by this new equation when compared to the original Beheshti and Ataie-Ashtiani (2008) equation and to the usual Shields nomograph. Independent validation of the equation is provided, together with a comparison with other equations based on the Shields parameter.

2 Previous analyses

While searching for a criterion for the initiation of ripple formation, Liu (1957, 1958) proposed the movability number Λ of the sediment particle. The relation between Λ and θ can be easily shown for spherical particles. For spherical grains,

$$w = \left\lceil \frac{4(s-1)gd}{3C_{\rm d}} \right\rceil^{\frac{1}{2}} \tag{3}$$

where $C_{\rm d}$ is the drag coefficient. With Eq. (3), we can obtain

$$\left(\rho_{\rm s} - \rho\right)gd = \frac{3}{4}\rho C_{\rm d}w^2 \tag{4}$$

According to the definition of θ , the relation between Λ and θ can be obtained:

$$\theta = \frac{4}{3C_A} \Lambda^2 \tag{5}$$

This implies that if θ_c has a universal curve as a function of R^* (or d^*), Λ must be Λ_c for incipient motion conditions. Furthermore, the fact that Λ is proportional to the square root of θ naturally results in a reduction of data scatter around the curve for Λ_c .

The movability number has been shown to be an effective alternative to the Shields parameter. Liu (1958) was the first to recast the original Shields diagram into a Λ_c - R^* curve that resulted in narrower bands of data scatter. Collins and Rigler (1982) argued that any method for estimating the threshold of motion should incorporate information about the particle shape and specific gravity, and recommended the particle's settling velocity as a means to accomplish that. Komar and Clemens (1986) showed that the computation of w for sediment grains is at least as accurate as the determination of the threshold of motion, which relies on a somewhat subjective measurement, and developed a mechanical model of grain pivoting relating the threshold of motion to Λ . They also proposed Λ_c - R^* and Λ_c -E curves,

but a limited amount of data were used, therefore limiting the range of application of their results.

Paphitis (2001) analyzed different types of empirical threshold curves and showed that the use of Λ offers a clear advantage over the use of the Shields parameter and the critical shear velocity. Using the most extensive dataset, he derived a new relation for Λ_c as a function of the grain Reynolds number:

$$\Lambda_{\rm c} = \frac{0.75}{R^*} + 14e^{-2R^*} + 0.01\ln R^* + 0.115 \tag{6}$$

Using this type of threshold curve, motion is determined to take place when the hydraulic and sediment conditions are such that $\Lambda > \Lambda_c$; otherwise, there is no sediment motion. Eq. (6), which is Eq. (20) of Paphitis (2001), is valid in the range of $0.1 < R^* < 10^5$, and it is shown in Fig. 2 along with experimental data. Fig. 2(b) shows an improved collapse of the measurements along the analytic curve when compared to the θ -based curve of Fig. 1(b) (the same experimental dataset is used in Figs. 1 and 2). There is, however, still a significant deviation between the experimental data and Eq. (6), especially in the lower range of R^* . This may be attributed to the more limited range of data used by Paphitis (2001) in the derivation of Eq. (6), which was limited to the range of $R^* > 0.1$. Another limitation of Eq. (6) resides in the use of R^* as the independent variable, whereby U^* is present in both Λ and R^* .

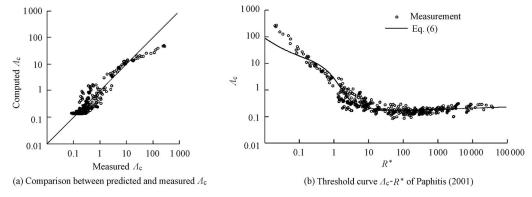


Fig. 2 Threshold for incipient motion of Paphitis (2001) and its comparison with measurements

Beheshti and Ataie-Ashtiani (2008), who also found Λ to be a more suitable parameter for determining the threshold of motion, tried to eliminate the latter limitation by deriving the following $\Lambda_c - d^*$ curve:

$$\Lambda_{c} = \begin{cases} 9.667 \, 4d^{*-1.57} & d^{*} \leq 10 \\ 0.473 \, 8d^{*-0.226} & d^{*} > 10 \end{cases} \tag{7}$$

This equation, which is valid in the approximate range of $0.4 < d^* < 1000$, is shown in Fig. 3. As can be seen from Fig. 3, agreement between measurements and predictions is fair, but this equation shows the wrong behavior for large values of d^* ($d^* > 500$) and overpredicts Λ_c in the lower range of d^* .

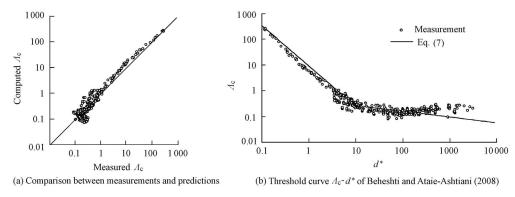


Fig. 3 Threshold for incipient motion of Beheshti and Ataie-Ashtiani (2008) and comparison with measurements

3 Derivation of new incipient motion equation

The work presented herein is based on experimental data collected independently by many researchers. There are important considerations concerning the definition of the sediment threshold that result in subjectivity and consequential uncertainty associated with such data. It is beyond the scope of the present work to dwell on these issues and the reader is referred to section 6 of Paphitis (2001) for more detailed comments.

In this study, 517 sets of data obtained from many different sources and distinct physical settings were used. The origin of the data and their main characteristics are presented in Table 1, which includes the data used in the original work of Shields (1936) and plotted in Figs. 1 through 3. Not all the data presented in the original sources were used: the sets that did not contain enough information for an accurate calculation of the particle's settling velocity were discarded. Nonetheless, the sediments associated with the data sets in Table 1, made of natural and artificial grains, offer a variety in shape and density and a sufficient number for statistical significance. Bed configurations also varied from grains of almost a uniform size to mixtures with relatively large sorting coefficients. Most data were collected in controlled laboratory settings, but some were collected in the field. The criterion used for the definition of incipient motion was also varied: visual inspection (a few or all particles moving), extrapolation methods, and stochastic approaches. The reader is referred to the original publications for further details.

Settling velocities were calculated using the procedure given by Dietrich (1982). This method requires knowledge of water temperature, the sediment particles' shape (the Corey shape factor and Powers' roundness factor P), and their nominal diameter $d_{\rm N}$ (the diameter of a sphere with the same volume as the particle). The shape parameters had to be estimated (e.g., P=6 for spheres and well rounded particles, P=3.5 for natural sediments, and P=2 for crushed sediments), and data without enough information for an adequate estimate were discarded. Similarly, when sediment mixtures were used, some authors provided information about the nominal diameter of the mixture, and others did not. In the latter case, a nominal diameter $d_{\rm N}=d_{50}/0.9$ was used (d_{50} is the sieve size through which 50% of the sediment passes). Note, however, that d_{50} was always used for calculating d^* .

Table 1 Sources of data used in this study

Data source	Number of data point	Sediment material	Particle characteristic
Ashworth et al. (1992)	2	Natural gravel	Naturally worn grains
Bathurst et al. (1987)	12	Natural gravel	Naturally worn grains
Carling (1983)	3	Natural gravel	Naturally worn grains
Casey (1935a, 1935b)	9	River sand	Subangular and rounded grains
Collins and Riegler (1982) †	58	Particles of ilmenite, zircon, rutile, cassiterite, and quartz	
Dey and Debnath (2000)	6	Natural sand	Naturally worn grains
Dey and Raju (2002)	33	Natural gravel	Naturally worn grains
Everts (1973)	38	Natural quartz and ilmenite	Naturally worn grains
Ferguson (1994)	1	Natural gravel	Naturally worn grains
Ferguson et al. (1989)	5	Natural gravel and boulder	Naturally worn grains
Gilbert (1914)	24	Natural quartz (sand and gravel)	Subrounded and subangular grains
Grass (1970)	7	Natural quartz	Naturally worn grains
Hammond et al. (1984)	1	Natural gravel	Naturally worn grains
Komar and Carling (1991)	3	Natural gravel	Naturally worn grains
Kramer (1932, 1935)	15	Natural quartz	Well rounded grains
Liu (1935)	24	Natural quartz	Naturally worn grains
Luque and van Beek (1976) [‡]	16	Sand and magnetite	Naturally worn grains and rounded grains
Mantz (1975)	27	Quartz and mica	Naturally worn grains and flakes
Meyer-Peter and Müller (1948)	21	Natural quartz	Rounded grains
Milhous (1973)	9	Natural gravel	Naturally worn grains
Misri et al. (1984)	3	Natural quartz	Naturally worn grains
Mizuyama (1977)	15	Natural quartz	Naturally worn grains
Neill (1967)	26	Natural gravel and glass	Naturally worn grains and rounded grains
Petit (1994)	4	Natural gravel	Naturally worn grains
Pilotti and Menduni (2001)	51	Marble powder, limestone, quartzite, silica, and sand	Spheres and naturally worn grains
Powell and Ashworth (1995)	4	Natural gravel	Subangular grains
Rao and Sitaram (1999)	5	River and quartz silica sands	Naturally worn grains
Shields (1936)	15	Amber, barite, coal, and granite	Angular grains
Talapatra and Ghosh (1983)	15	Natural gravel	Naturally worn grains
USWES (1935)	26	Natural quartz	River sand with subrounded, rounded, subangular, and angular grains
Ward (1968)	11	Sand, lead, steel, and taconite	Multiple shapes
Wathen et al. (1995)	2	Natural gravel	Naturally worn grains
White (1970)*	16	Natural quartz, glass, silica, polystyrene, PVC	Spheres, crushed grains, and naturally worn grains
Wilcock (1987)	4	Natural quartz	Naturally worn grains
Yalin and Karahan (1979)*	6	Natural sand and glass	Spheres and naturally worn grains

Notes: † These authors carried out measurement of the particles' settling velocities, which were used directly in the calculation of Λ . ‡ Data on crushed walnut shell grains were not used due to the difficulty in estimating particle characteristics for settling velocity computations. * Data in which the fluid phase was oil and/or water-glycerin mixture were discarded due to the absence of information about the fluid viscosity. The term "gravel" is used generally to denote grain sizes larger than 2 mm.

The data in Table 1 were randomly divided into two approximately equal groups in the following manner: the data sets were sorted by their sizes and numbered accordingly (the data set of Collins and Riegler (1982) was assigned number 1, the data set of Pilotti and Menduni (2001) was assigned number 2, etc.), and the data sets with odd numbering were assigned to group 1, while the data sets with even numbering were assigned to group 2. Group 1 is used in this section and group 2 is set aside for validating the new derivation, which is done in the next section.

A nonlinear least-squares procedure was used to accomplish the fit of a curve to the data. The final expression found is

$$\Lambda_{\rm c} = 0.215 + \frac{6.79}{d^{*1.70}} - 0.0750 \,\mathrm{e}^{-2.62 \times 10^{-3} d^{*}}$$
 (8)

Eq. (8) is plotted in Fig. 4 with the data used for its derivation. Better agreement between the analytic curve represented by Eq. (8) and the experimental data is achieved as compared with the previous alternatives displayed in Figs. 1 through 3. Further confirmation of the fit is given by statistical goodness-of-fit indicators. The main indicators used are the mean discrepancy ratio \overline{R} , which is defined as the mean of the ratio of the computed to the measured values of coefficient r. The mean discrepancy ratio should be 1 for a perfect fit and is also used to compute the sample standard deviation σ , which in turn is an indicator of the scatter of the measurement data around the analytic curve of Eq. (8). The magnitude of the mean error is given by \overline{E} , which is normalized with the experimental values, thus providing a percentage value. Finally, Pearson's correlation coefficient r provides a measure of the fit of the curve to the experimental data in a least-squares sense and its magnitude should be equal to 1 for a perfect fit. The obtained statistical goodness-of-fit parameters for the derivation of Eq. (8) are $\overline{R} = 1.0813$, $\overline{E} = 0.2278$, $\sigma = 0.3196$, and r = 0.9973, showing the excellent agreement between the analytic curve of Eq. (8) and the experimental data.

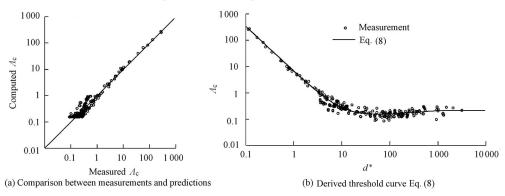


Fig. 4 Derived threshold for incipient motion Eq. (8) and its comparison with measurements

4 Validation of proposed equation

The results shown in Fig. 4 present the goodness-of-fit of the derived curve to the data.

However, Eq. (8) represents an empirical fit, and its validity is limited to the specific hydraulic conditions and particle characteristics associated with the data sets used for its derivation. Therefore, this analytic formula must be treated with caution. To determine its predictive ability, it must be validated using data sets that are independent from those used for its derivation. Here, data group 2 is used for that purpose.

The statistical analysis presented in the previous section represents the goodness-of-fit of Eq. (8) to the data, i.e., how good the match is between the curve and the data used for its derivation. A similar analysis can be carried out for the validation of Eq. (8), where the same parameters are used, but their interpretation is now different. In the latter case, the values of the statistical parameters \overline{R} , \overline{E} , σ , and r give instead a measure of the predictive ability of Eq. (8), because they are calculated from measured data that were not used in its derivation. The values of these statistical parameters are shown in Table 2 and the comparison between measurements and calculations is plotted in Fig. 5. In spite of an apparent low bias, agreement is good, being comparable to that for the data group used for derivation. This analysis reinforces the quality of the predictions, which can be found in Fig. 5, indicating that the low bias seen in this figure is not significant and can be attributed to the randomness of data.

Curve \overline{R} \bar{E} 1.0897 0.2329 Eq. (8) of this study 0.3295 0.9983 Eq. (7) of Beheshti and Ataie-Ashtiani (2008) 1.1940 0.3873 0.5264 0.9964 Mean threshold curve of Paphitis (2001) 1.2352 0.41570.5266 0.8201 Curve of Yalin and da Silva (2001) 1.1634 0.3989 0.5152 0.8154

Table 2 Statistical goodness-of-fit parameters for different curves

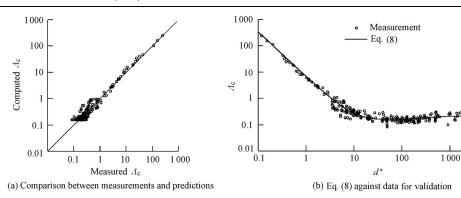


Fig. 5 Validation of Eq. (8) using independent data

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It is apparent that the proposed equation provides a statistically significant improvement over the equation of Beheshti and Ataie-Ashtiani (2008), as demonstrated by the respective values of the mean discrepancy ratio and the mean normalized error in Table 2. Additionally, the value of the standard deviation also reflects a larger amount of data scatter present in Beheshti and Ataie-Ashtiani's (2008) equation. This scatter is also easily discovered by comparing the plots in Fig. 3 with those in Fig. 5.

To provide a comparison with Shields parameter-based methods, the statistical analysis above was extended to the explicit curves of Paphitis (2001) (only the mean threshold curve was considered, which is shown as a solid line in Fig. 1(b)) and Yalin and da Silva (2001) (curve was not shown). The corresponding values of the respective statistical parameters for these two curves are presented in rows 3 and 4 of Table 2. The values of \overline{R} show a significantly larger bias for these two curves than for Eq. (8). Based on the standard deviation, this bias is statistically significant. The larger errors associated with these curves are also reflected in the values of \overline{E} and σ , which are nearly twice as large as the corresponding values for Eq. (8). These and the results presented above show that Eq. (8) provides an accurate technique for the computation of the incipient motion threshold, offering significant advantages over the more common Shields parameter-based methods.

5 Conclusions

In spite of significant data scatter, empirical threshold-of-motion curves based on the Shields parameter are commonly used in sediment transport theories. Several researchers addressed the issue by replacement of the Shields parameter θ with the movability number Λ . The use of Λ over θ offers several advantages: it incorporates particle shape information and specific density via the use of the settling velocity w; Λ is proportional to $\theta^{1/2}$, therefore reducing data scatter; and Λ is related to turbulence (i.e., to upward and downward turbulent fluctuations), therefore naturally incorporating its effects in the initiation of the motion of sediment particles.

It is necessary to compute the settling velocity for some of the irregularly shaped sediment particles used in this study. The computation of w was done using Dietrich's (1982) method due to its flexibility in incorporating particle shape and roundness. There are other simpler methods of calculating the sediment particle settling velocity. However, they have smaller ranges of applicability.

This investigation corroborated the view that using Λ does improve the collapse of measured data into a line that is very well defined in a Λ_c - d^* diagram. An empirical expression, Eq. (8), was derived by data fitting. Statistical parameters show a high degree of agreement between the analytic expression and experimental data. We therefore established that this new equation can be used effectively for the computation of the threshold of incipient sediment motion, providing a simple and practical calculation procedure that is more accurate than those based on the traditional Shields parameter.

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