WEEK6 - PRESENTED BY NOLLEH

LEARN U ERLANG

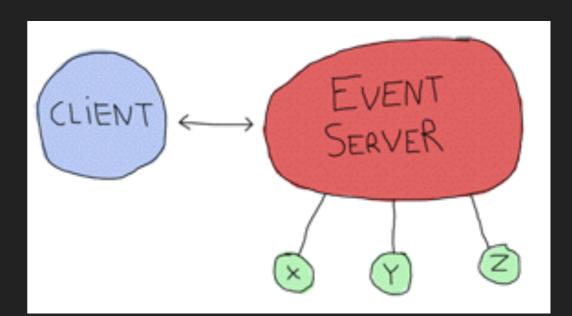


CHAPTER.13

DESIGNING A CONCURRENT PROGRAM

- roles
 - add event (event contains deadline / name / desc)
 - show an warning when time has comes up
 - cancel event
 - no persistent disk storage
 - update while it is running
 - interaction via command line

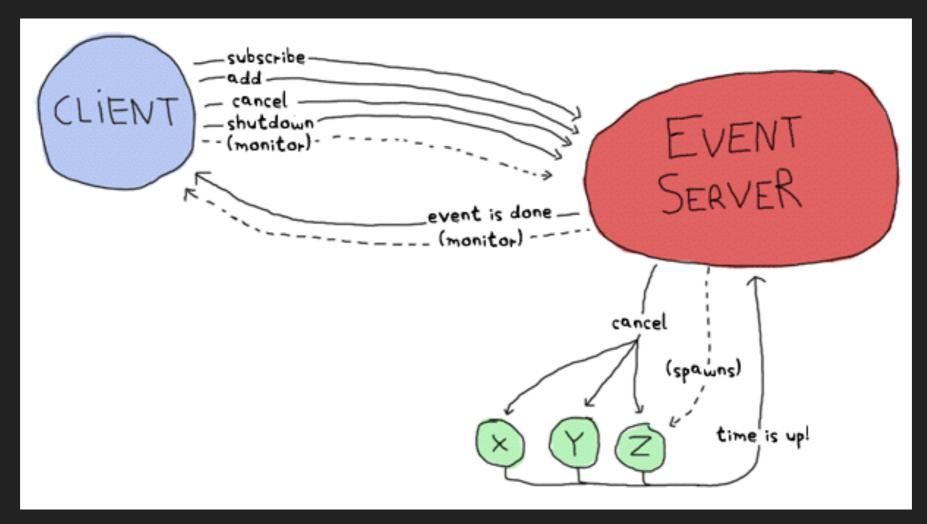
- event server
 - Accepts subscriptions from clients



- Forwards notifications from event processes to each of the subscribers
- Accepts messages to add events (and start the x, y, z processes needed)
- Can accept messages to cancel an event and subsequently kill the event processes
- Can be terminated by a client
- Can have its code reloaded via the shell.

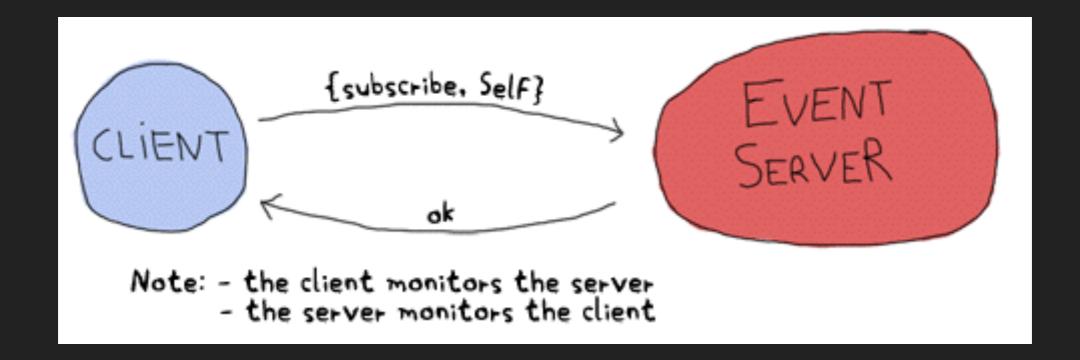
- client
 - Subscribes to the event server and receive notifications as messages. Each of these could potentially be a gateway to the different interaction points mentioned above (GUI, web page, instant messaging software, email, etc.)
 - Asks the server to add an event with all its details
 - Asks the server to cancel an event
 - Monitors the server (to know if it goes down)
 - Shuts down the event server if needed

- x, y and z:
 - Represent a notification waiting to fire (they're basically just timers linked to the event server)
 - Send a message to the event server when the time is up
 - Receive a cancellation message and die

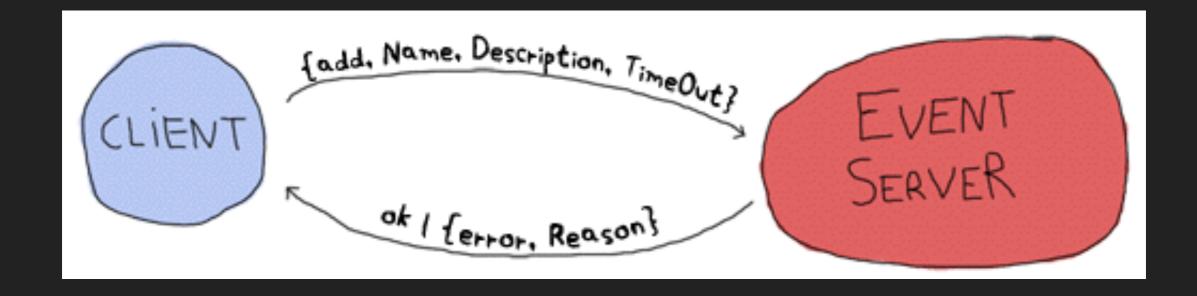


- for real program,
 - timer:send_after/2-3 to avoid spawning too many processes.

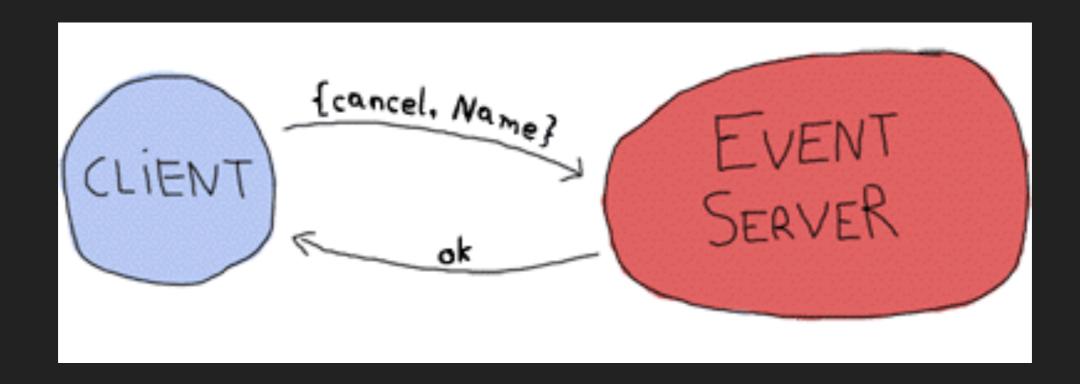
subscribe



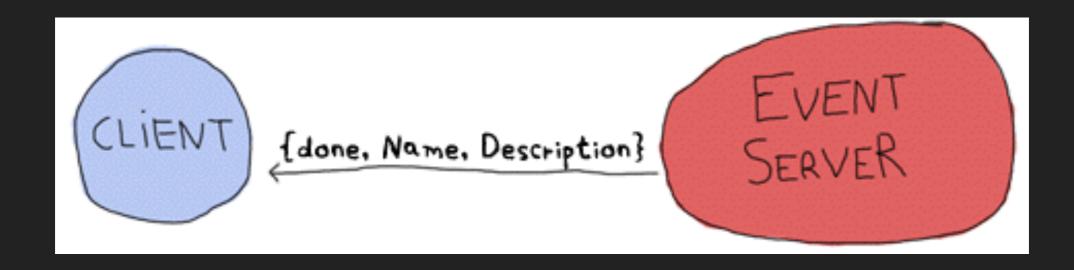
add



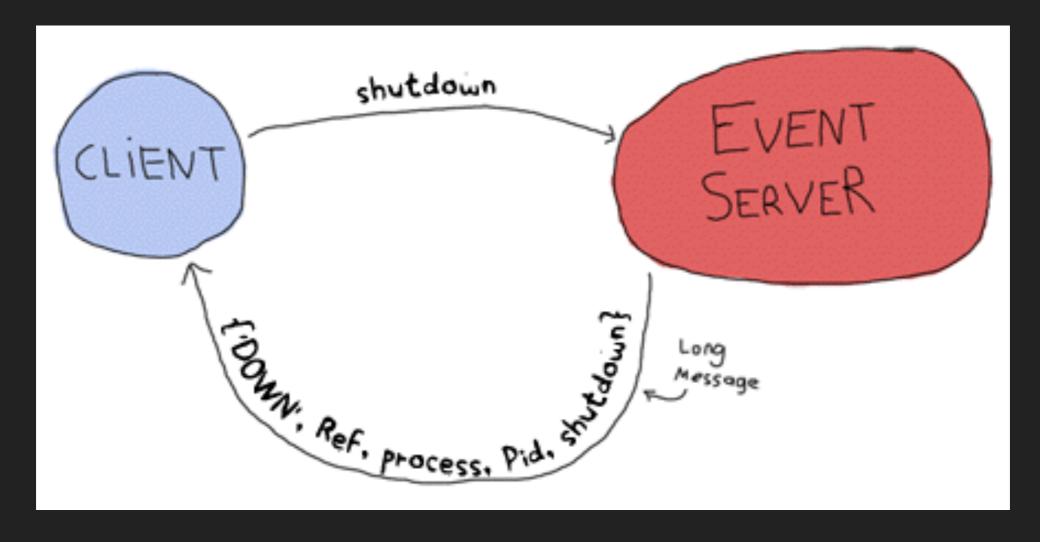
cancel



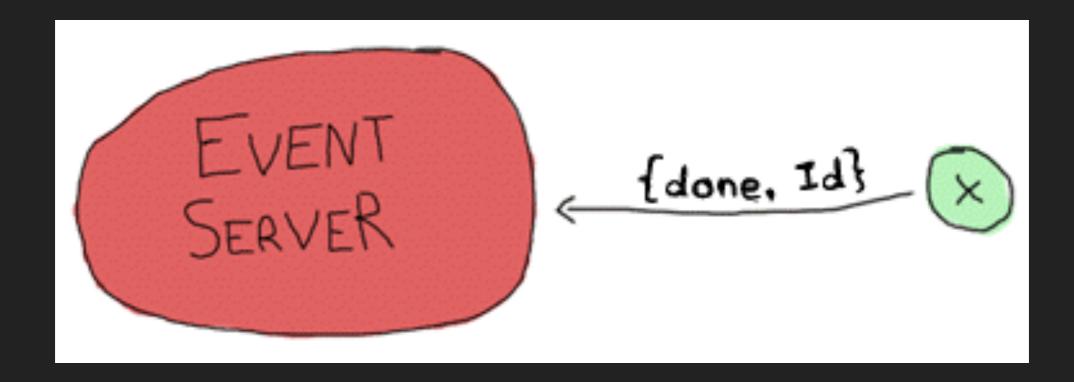
notification



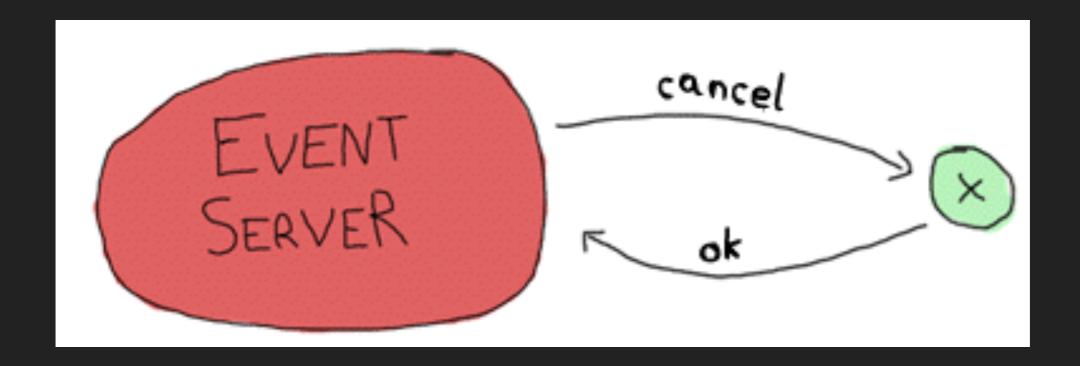
shutdown



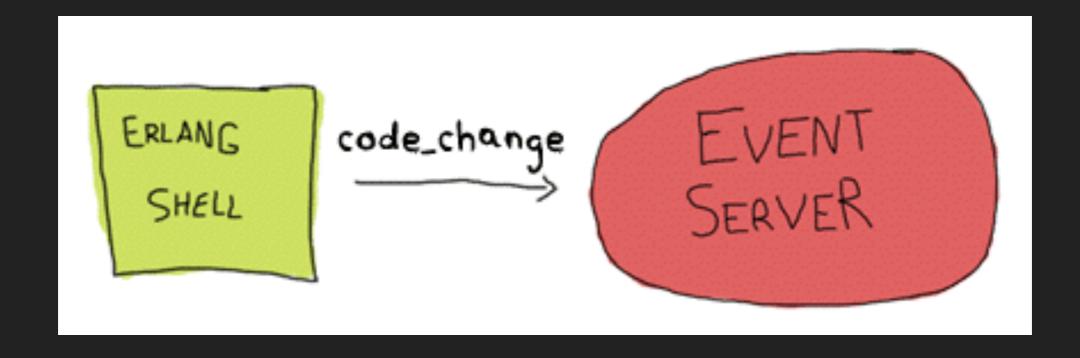
notification



cancel



code change



LAY THEM FOUNDATION

- project
 - ebin/(compiled)
 - include/ (header)



- priv/ (executables that might have to interact with Erlang, such as specific drivers and whatnot)
- src/ (private hrl, erl)

- project
 - Pid, Ref, Message}, where Pid is the sender and Ref is a unique message identifier to help know what reply came from who.

```
loop(State) ->
receive
{Server, Ref, cancel} ->
...
after Delay ->
...
end.
```

- state
 - contains
 - timeout / name of event / event server pid (for noti)

```
-module(event).
-compile(export_all).
-record(state, {server,
    name="",
    to_go=0}).
```

- state
 - contains
 - timeout / name of event / event server pid (for noti)

```
loop(S = #state{server=Server}) ->
  receive
  {Server, Ref, cancel} ->
    Server ! {Ref, ok}
  after S#state.to_go*1000 ->
    Server ! {done, S#state.name}
  end.
```

test event

```
6> c(event).
 {ok,event}
7> rr(event, state).
 [state]
8> spawn(event, loop, [#state{server=self(), name="test", to_go=5}]).
 <0.60.0>
9> flush().
 ok
10> flush().
 Shell got {done,"test"}
 ok
```

test event

```
11> Pid = spawn(event, loop, [#state{server=self(), name="test", to_go=500}]).
  <0.64.0>
12> ReplyRef = make_ref().
  #Ref<0.0.0.210>
13> Pid ! {self(), ReplyRef, cancel}.
  {<0.50.0>,#Ref<0.0.0.210>,cancel}
14> flush().
  Shell got {#Ref<0.0.0.210>,ok}
  ok
```

we don't expect it to come from anywhere specific (any place will do, we won't match on the receive) nor should we want to reply to it

limit of timer

```
15> spawn(event, loop, [#state{server=self(), name="test", to_go=365*24*60*60}]).
  <0.69.0>
16>
=ERROR REPORT==== DD-MM-YYYY::HH:mm:SS ===
Error in process <0.69.0> with exit value: {timeout_value,[{event,loop, 1}]}
```

split it

```
%% Because Erlang is limited to about 49 days (49*24*60*60*1000) in %% milliseconds, the following function is used normalize(N) ->
Limit = 49*24*60*60,
[N rem Limit | lists:duplicate(N div Limit, Limit)].
```

• ex. 98*24*60*60+4 -> [4,4233600,4233600]

split it

```
loop(S = #state{server=Server, to_go=[T|Next]}) ->
 receive
   {Server, Ref, cancel} ->
    Server! {Ref, ok}
   after T*1000 ->
    if Next =:= [] ->
        Server ! {done, S#state.name};
      Next =/= [] ->
        loop(S#state{to_go=Next})
    end
 end.
```

normalize helper

```
start(EventName, Delay) ->
 spawn(?MODULE, init, [self(), EventName, Delay]).
start_link(EventName, Delay) ->
 spawn_link(?MODULE, init, [self(), EventName, Delay]).
%%% Event's innards
init(Server, EventName, Delay) ->
 loop(#state{server=Server,
   name=EventName,
   to_go=normalize(Delay)}).
```

cancel helper

```
cancel(Pid) ->
 %% Monitor in case the process is already dead
 Ref = erlang:monitor(process, Pid),
 Pid! {self(), Ref, cancel},
 receive
   {Ref, ok} ->
    erlang:demonitor(Ref, [flush]),
    ok;
   {'DOWN', Ref, process, Pid, _Reason} ->
    ok
 end.
```

test

```
19> event:start("Event", 0).
 <0.103.0>
20> flush().
 Shell got {done,"Event"}
 ok
21> Pid = event:start("Event", 500).
 <0.106.0>
22> event:cancel(Pid).
 ok
```

I don't want noti-time as second

```
time_to_go(TimeOut={{_,_,_}}, {_,_,_}}) ->
 Now = calendar: local_time(),
 ToGo = calendar:datetime_to_gregorian_seconds(TimeOut) -
   calendar:datetime_to_gregorian_seconds(Now),
 Secs = if ToGo > 0 -> ToGo;
         ToGo = < 0 -> 0
        end,
 normalize(Secs).
```

init function using time_to_go

skeleton

```
-module(evserv).
-compile(export_all).
loop(State) ->
 receive
   {Pid, MsgRef, {subscribe, Client}} ->
   {Pid, MsgRef, {add, Name, Description, TimeOut}} ->
   {Pid, MsgRef, {cancel, Name}} ->
```

skeleton

```
{done, Name} ->
 shutdown ->
 {'DOWN', Ref, process, _Pid, _Reason} ->
 code_change ->
 Unknown ->
  io:format("Unknown message: ~p~n",[Unknown]),
  loop(State)
end.
```

declare state

declare state

```
loop(S = #state{}) ->
receive
...
end.
```

implement subscribe

```
{Pid, MsgRef, {subscribe, Client}} ->
Ref = erlang:monitor(process, Client),
NewClients = orddict:store(Ref, Client, S#state.clients),
Pid ! {MsgRef, ok},
loop(S#state{clients=NewClients});
```

implement add event

```
valid_datetime({Date,Time}) ->
 try
   calendar:valid_date(Date) and also valid_time(Time)
 catch
   error:function_clause -> %% not in {{Y,M,D},{H,Min,S}} format
    false
 end;
valid_datetime(_) ->
 false.
```

implement add event

implement add event

```
{Pid, MsgRef, {add, Name, Description, TimeOut}} ->
 case valid_datetime(TimeOut) of
   true ->
    EventPid = event:start_link(Name, TimeOut),
    NewEvents = orddict:store(Name,
            #event{name=Name,
                   description=Description,
                   pid=EventPid,
                   timeout=TimeOut},
                   S#state.events),
    Pid! {MsgRef, ok},
    loop(S#state{events=NewEvents});
```

implement add event

```
false ->
Pid ! {MsgRef, {error, bad_timeout}},
loop(S)
end;
```

implement cancel event

implement handle done

```
{done, Name} ->
 case orddict:find(Name, S#state.events) of
   {ok, E} ->
    send_to_clients({done, E#event.name, E#event.description},
            S#state.clients),
    NewEvents = orddict:erase(Name, S#state.events),
    loop(S#state{events=NewEvents});
   error ->
    %% This may happen if we cancel an event and
    %% it fires at the same time
    loop(S)
 end;
```

implement send_to_client

```
send_to_clients(Msg, ClientDict) -> orddict:map(fun(_Ref, Pid) -> Pid! Msg end, ClientDict).
```

others

```
shutdown ->
exit(shutdown);

{'DOWN', Ref, process, _Pid, _Reason} ->
loop(S#state{clients=orddict:erase(Ref, S#state.clients)});

code_change ->
?MODULE:loop(S);

Unknown ->
io:format("Unknown message: ~p~n",[Unknown]),
loop(S)
```

HOT CODE LOVING

- code server
 - basically a VM process in charge of an ETS table
 - ETS table : in-memory database table
 - A new version of a module is <u>automatically loaded</u> when compiling it with <u>c(Module)</u>, loading with <u>l(Module)</u> or <u>loading it with one of</u> <u>the many functions of the code module</u>.
- local and external call
 - external calls are always done on the newest version of the code available in the code server

HOT CODE LOVING

code server

```
loop(S) ->
myfun(),
?MODULE:myfun(),
if Cand -> loop(S);
not Cand -> ?MODULE:loop(S)
end.

'new' becomes the default
```

HOT CODE LOVING

more generic code update

```
-module(hotload).
-export([server/1, upgrade/1]).
server(State) ->
 receive
  update ->
    NewState = ?MODULE:upgrade(State),
    ?MODULE:server(NewState);
  SomeMessage ->
    %% do something here
    server(State) %% stay in the same version no matter what.
 end.
```

hiding

```
start() ->
register(?MODULE, Pid=spawn(?MODULE, init, [])),
Pid.
start_link() ->
register(?MODULE, Pid=spawn_link(?MODULE, init, [])),
Pid.
terminate() ->
?MODULE! shutdown.
```

we should only have one running at a time

subscribe

```
subscribe(Pid) ->
 Ref = erlang:monitor(process, whereis(?MODULE)),
 ?MODULE! {self(), Ref, {subscribe, Pid}},
 receive
   {Ref, ok} ->
    {ok, Ref};
   {'DOWN', Ref, process, _Pid, Reason} ->
    {error, Reason}
 after 5000 ->
   {error, timeout}
 end.
```

add_event

```
add_event(Name, Description, TimeOut) ->
 Ref = make_ref(),
 ?MODULE! {self(), Ref, {add, Name, Description, TimeOut}},
 receive
   {Ref, Msg} -> Msg
 after 5000 ->
   {error, timeout}
 end.
```

add_event

```
add_event2(Name, Description, TimeOut) ->
 Ref = make_ref(),
 ?MODULE! {self(), Ref, {add, Name, Description, TimeOut}},
 receive
   {Ref, {error, Reason}} -> erlang:error(Reason);
   {Ref, Msg} -> Msg
 after 5000 ->
   {error, timeout}
 end.
```

cancel

```
cancel(Name) ->
 Ref = make_ref(),
 ?MODULE! {self(), Ref, {cancel, Name}},
 receive
   {Ref, ok} \rightarrow ok
 after 5000 ->
   {error, timeout}
 end.
```

accumulate all messages during a given period of time

```
listen(Delay) ->
 receive
   M = {done, _Name, _Description} ->
   [M | listen(0)]
 after Delay*1000 ->
 end.
```

A TEST DRIVE

vim Emakefile

- erl -make
- erl -pa ebin/
 - add path for look in erlang module
- make:all([load])
 - find Emakefile -> recompile -> load

A TEST DRIVE

```
1> evserv:start().
 <0.34.0>
2> evserv:subscribe(self()).
 {ok,#Ref<0.0.0.31>}
3> evserv:add_event("Hey there", "test", FutureDateTime).
 ok
4> evserv:listen(5).
5> evserv:cancel("Hey there").
 ok
6> evserv:add_event("Hey there2", "test", NextMinuteDateTime).
ok
7> evserv:listen(2000).
 [{done, "Hey there2", "test"}]
```

supervisor

```
-module(sup).
-export([start/2, start_link/2, init/1, loop/1]).
start(Mod,Args) ->
 spawn(?MODULE, init, [{Mod, Args}]).
start_link(Mod,Args) ->
 spawn_link(?MODULE, init, [{Mod, Args}]).
init({Mod,Args}) ->
 process_flag(trap_exit, true),
 loop({Mod,start_link,Args}).
```

supervisor

```
loop({M,F,A}) ->
 Pid = apply(M,F,A),
 receive
   {'EXIT', _From, shutdown} ->
    exit(shutdown); % will kill the child too
   {'EXIT', Pid, Reason} ->
    io:format("Process ~p exited for reason ~p~n",[Pid,Reason]),
    loop({M,F,A})
 end.
```

using supervisor

```
1> c(evserv), c(sup).
 {ok,sup}
2> SupPid = sup:start(evserv, []).
 <0.43.0>
3> whereis(evserv).
 <0.44.0>
4> exit(whereis(evserv), die).
 true
 Process <0.44.0> exited for reason die
5> exit(whereis(evserv), die).
 Process <0.48.0> exited for reason die
 true
```

using supervisor

```
6> exit(SupPid, shutdown).
true
7> whereis(evserv).
undefined
```

The supervisor demonstrated here is only the most basic form that exists and is not exactly fit for production environments compared to the real thing.

NAMESPACES (OR LACK THERE OF)

- using prefix
 - renamed to reminder_evserv, reminder_sup and reminder_event.
- Some programmers then decide to <u>add a module</u>, named after the application itself, which wraps common calls
- No need to synchronize them, no locks, no real main loop



CHAPTER.14

WHAT IS OTP?

IT'S THE OPEN TELECOM PLATFORM!

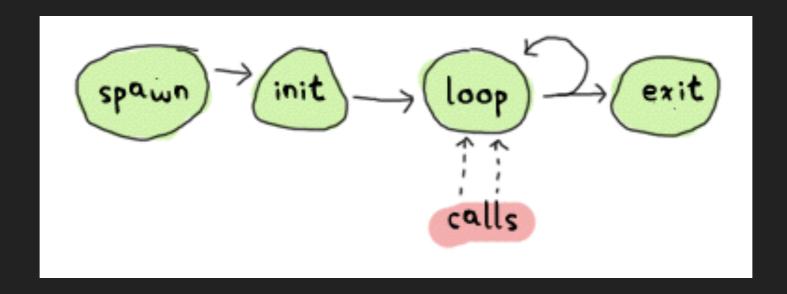
- meaning?
 - OTP stands for <u>Open Telecom Platform</u>, although it's not that much about telecom anymore (it's more about software that has <u>the property of telecom applications</u>)
- erlang's greatness comes from
 - concurrency + distribution + error handling capabilities,
 and otp

IT'S THE OPEN TELECOM PLATFORM!

- There were a few 'gotchas' here and there
 - on how to avoid <u>race conditions</u> or to always <u>remember</u> that a process could <u>die</u> at any time. There was also hot code loading, <u>naming processes</u> and <u>adding</u> <u>supervisors, to name a few.</u>
- The OTP framework takes care of this by grouping these essential practices
 - Every Erlang programmer should use them

THE COMMON PROCESS, ABSTRACTED

- In most processes, we had a function in charge of spawning the new process, a function in charge of giving it its initial values, a main loop, etc.
 - these parts are usually present

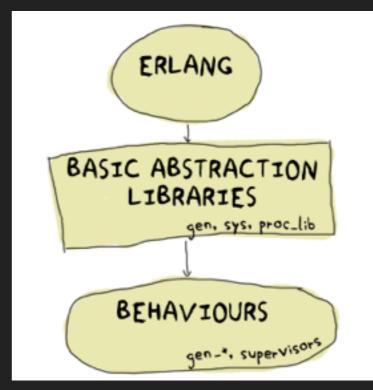


THE COMMON PROCESS, ABSTRACTED

- crafted code
 - with the <u>advantage of being used for years</u> in the field
 - also being <u>built with far more caution</u> than we were with

our implementations.

fault-tolerant manner



kitty_server

```
%%%% Naive version
-module(kitty_server).
-export([start_link/0, order_cat/4, return_cat/2, close_shop/1]).
-record(cat, {name, color=green, description}).
%%% Client API
start_link() -> spawn_link(fun init/0).
```

kitty_server - api, order_cat

```
%% Synchronous call
order_cat(Pid, Name, Color, Description) ->
 Ref = erlang:monitor(process, Pid),
 Pid! {self(), Ref, {order, Name, Color, Description}},
 receive
   {Ref, Cat} ->
    erlang:demonitor(Ref, [flush]),
    Cat;
   {'DOWN', Ref, process, Pid, Reason} ->
    erlang:error(Reason)
 after 5000 ->
   erlang:error(timeout)
 end
```

kitty_server - api, return_cat

```
%% This call is asynchronous
return_cat(Pid, Cat = #cat{}) ->
 Pid! {return, Cat},
 ok.
close_shop(Pid) ->
 Ref = erlang:monitor(process, Pid),
 Pid! {self(), Ref, terminate},
 receive
   {Ref, ok} -> erlang:demonitor(Ref, [flush]), ok;
   {'DOWN', Ref, process, Pid, Reason} -> erlang:error(Reason)
 after 5000 -> erlang:error(timeout)
end.
```

kitty_server - server_fun, init, loop

```
%%% Server functions
init() -> loop([]).
loop(Cats) ->
 receive
   {Pid, Ref, {order, Name, Color, Description}} ->
     if Cats =:= [] ->
      Pid! {Ref, make_cat(Name, Color, Description)},
      loop(Cats);
     Cats =/= [] -> % got to empty the stock
      Pid! {Ref, hd(Cats)},
      loop(tl(Cats))
     end;
```

kitty_server - server_fun, loop2

```
{return, Cat = #cat{}} ->
 loop([Cat|Cats]);
{Pid, Ref, terminate} ->
 Pid! {Ref, ok},
 terminate(Cats);
Unknown ->
 %% do some logging here too
 io:format("Unknown message: ~p~n", [Unknown]),
 loop(Cats)
end.
```

kitty_server - private server_fun

```
%%% Private functions
make_cat(Name, Col, Desc) ->
 #cat{name=Name, color=Col, description=Desc}.
terminate(Cats) ->
 [io:format("~p was set free.~n",[C#cat.name]) || C <- Cats],
 ok.
```

kitty_server - private server_fun

```
1> c(kitty_server).
 {ok,kitty_server}
2> rr(kitty_server).
 [cat]
3> Pid = kitty_server:start_link().
 <0.57.0>
4> Cat1 = kitty_server:order_cat(Pid, carl, brown, "loves to burn
             bridges").
 #cat{name = carl,color = brown,
 description = "loves to burn bridges"}
5> kitty_server:return_cat(Pid, Cat1).
 ok
```

kitty_server - private server_fun

```
6> kitty_server:order_cat(Pid, jimmy, orange, "cuddly").
 #cat{name = carl,color = brown,
 description = "loves to burn bridges"}
7> kitty_server:order_cat(Pid, jimmy, orange, "cuddly").
 #cat{name = jimmy,color = orange,description = "cuddly"}
8> kitty_server:return_cat(Pid, Cat1).
 ok
9> kitty_server:close_shop(Pid).
 carl was set free.
 ok
10> kitty_server:close_shop(Pid).
 ** exception error: no such process or port
 in function kitty_server:close_shop/1
```

- we can see patterns we've previously applied
 - The sections where we set monitors up and down, apply timers, receive data, use a main loop, handle the init function, etc.

let's generic~

```
-module(my_server).
-compile(export_all).
call(Pid, Msg) ->
 Ref = erlang:monitor(process, Pid),
 Pid! {self(), Ref, Msg},
 receive
   {Ref, Reply} -> erlang:demonitor(Ref, [flush]), Reply;
   {'DOWN', Ref, process, Pid, Reason} ->
    erlang:error(Reason)
 after 5000 ->
   erlang:error(timeout)
 end.
```

let's generic~

```
%% Synchronous call
order_cat(Pid, Name, Color, Description) ->
 my_server:call(Pid, {order, Name, Color, Description}).
%% This call is asynchronous
return_cat(Pid, Cat = #cat{}) ->
 Pid! {return, Cat},
 ok.
%% Synchronous call
close_shop(Pid) ->
 my_server:call(Pid, terminate).
```

- next generic chunk is not obvious...
 - Note that every process we've written so far has a loop where all the messages are pattern matched

```
loop(Module, State) ->
receive
Message -> Module:handle(Message, State)
end.
```

```
handle(Message1, State) -> NewState1;
handle(Message2, State) -> NewState2;
...
handle(MessageN, State) -> NewStateN.
```

- async call / sync call
 - It would be pretty helpful if our generic server implementation could <u>provide a clear way to know which kind of call is which</u>.
 - we will need to match different kinds of messages in my_server:loop/2
 - add atom sync

async call / sync call

```
call(Pid, Msg) ->
 Ref = erlang:monitor(process, Pid),
 Pid! {sync, self(), Ref, Msg},
 receive
   {Ref, Reply} ->
    erlang:demonitor(Ref, [flush]),
    Reply;
   {'DOWN', Ref, process, Pid, Reason} ->
    erlang:error(Reason)
   after 5000 ->
    erlang:error(timeout)
 end.
```

async call / sync call

```
cast(Pid, Msg) ->
Pid ! {async, Msg},
ok.
```

```
loop(Module, State) ->
receive
{async, Msg} ->
loop(Module, Module:handle_cast(Msg, State));
{sync, Pid, Ref, Msg} ->
loop(Module, Module:handle_call(Msg, Pid, Ref, State))
end.
```

- disappointing thing
 - The programmers who will <u>use my_server will still need</u> to know about references when sending synchronous messages and replying to them.

```
loop(Module, State) ->
receive
{async, Msg} ->
loop(Module, Module:handle_cast(Msg, State));
{sync, Pid, Ref, Msg} ->
loop(Module, Module:handle_call(Msg, {Pid, Ref}, State))
end.
```

- and now,
 - they can be passed as a <u>single argument</u> to the other function as a variable <u>with a name like From</u>.
 - we'll provide a function to send replies that should understand what From contains.

```
reply({Pid, Ref}, Reply) ->
Pid! {Ref, Reply}.
```

and now our code is,

```
-module(my_server).
-export([start/2, start_link/2, call/2, cast/2, reply/2]).
start(Module, InitialState) ->
 spawn(fun() -> init(Module, InitialState) end).
start_link(Module, InitialState) ->
 spawn_link(fun() -> init(Module, InitialState) end).
...call.. cast... reply...
init(Module, InitialState) ->
 loop(Module, Module:init(InitialState)).
...loop...
```

kitty server 2 as, callback module

```
-record(cat, {name, color=green, description}).
start_link() -> my_server:start_link(?MODULE, []).
order_cat(Pid, Name, Color, Description) ->
 my_server:call(Pid, {order, Name, Color, Description}).
return_cat(Pid, Cat = #cat{}) ->
 my_server:cast(Pid, {return, Cat}).
close_shop(Pid) ->
 my_server:call(Pid, terminate).
```

kitty server 2 as, callback module

```
%%% Server functions
init([]) -> []. %% no treatment of info here!
handle_call({order, Name, Color, Description}, From, Cats) ->
 if Cats =:= [] ->
    my_server:reply(From, make_cat(Name, Color, Description)),
    Cats;
   Cats =/= [] ->
    my_server:reply(From, hd(Cats)),
    tl(Cats)
 end;
```

kitty server 2 as, callback module

```
handle_call(terminate, From, Cats) ->
 my_server:reply(From, ok),
 terminate(Cats).
handle_cast({return, Cat = #cat{}}, Cats) ->
 [Cat|Cats].
%%% Private functions
make_cat(Name, Col, Desc) ->
 #cat{name=Name, color=Col, description=Desc}.
terminate(Cats) ->
 [io:format("~p was set free.~n",[C#cat.name]) || C <- Cats],
 exit(normal).
```

SPECIFIC VS GENERIC

- now you understand OTP!
 - taking all generic component
 - extracting library...
- If you're going to have larger applications then it might be worth it to separate generic parts of your code from the specific sections.
- U have many server client...
 - if all these servers share the same common my_server abstraction, you substantially reduce that complexity

SPECIFIC VS GENERIC

- This means you reduce a lot of time tracking and solving bugs
- when separating the generic from the specific is that we instantly made it much easier to test our individual modules.
 - first kitty server need to spawn,..give right state...
 - on the otherhand, requires us to <u>run the function calls</u>
 over the 'handle_call/3' and 'handle_cast/2'

SPECIFIC VS GENERIC

- when someone optimizes that single backend
 - every process using it become faster!
 - that's what happens with the OTP framework.
- we need to also consider to our module, (kitty)
 - named processes, configuring the timeouts, adding debug information, what to do with unexpected messages, how to tie in hot code loading, handling specific errors, abstracting away the need to write most replies, handling most ways to shut a server down, making sure the server plays nice with supervisors, etc.
- the Erlang/OTP team managed to handle all of that for you with the gen_server behaviour