



# ETC3550/ETC5550 Applied forecasting

Week 6: Exponential smoothing



# **Historical perspective**

- Developed in the 1950s and 1960s as methods (algorithms) to produce point forecasts.
- Combine a "level", "trend" (slope) and "seasonal" component to describe a time series.
- The rate of change of the components are controlled by "smoothing parameters":  $\alpha$ ,  $\beta$  and  $\gamma$  respectively.
- Need to choose best values for the smoothing parameters (and initial states).
- Equivalent ETS state space models developed in the 1990s and 2000s.

General notation ETS: ExponenTial Smoothing

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Error Trend Season

**Error:** Additive ("A") or multiplicative ("M")

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Trend: None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

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General notation ETS: ExponenTial Smoothing

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Error Trend Season
```

**Error:** Additive ("A") or multiplicative ("M")

Trend: None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

Seasonality: None ("N"), additive ("A") or multiplicative ("M")

Additive Error		Seasonal Component			
	Trend	N	Α	M	
	Component	(None)	(Additive)	(Multiplicative)	
N	(None)	A,N,N	A,N,A	A,N,M	
Α	(Additive)	A,A,N	A,A,A	A,A,M	
$A_d$	(Additive damped)	$A,A_d,N$	$A,A_d,A$	A,A <sub>d</sub> ,M	

<b>Multiplicative Error</b>		Seasonal Component			
	Trend	N	Α	M	
	Component	(None)	(Additive)	(Multiplicative)	
N	(None)	M,N,N	M,N,A	M,N,M	
Α	(Additive)	M,A,N	M,A,A	M,A,M	
$A_{d}$	(Additive damped)	M,A <sub>d</sub> ,N	M,A <sub>d</sub> ,A	$M,A_d,M$	

Additive Error		Seasonal Component			
	Trend	N	Α	M	
	Component	(None)	(Additive)	(Multiplicative)	
N	(None)	A,N,N	A,N,A	<u> </u>	
Α	(Additive)	A,A,N	A,A,A	<u>^,^,M</u>	
$A_d$	(Additive damped)	$A,A_d,N$	A,A <sub>d</sub> ,A	^,^ <sub>d</sub> ,M	

<b>Multiplicative Error</b>		Seasonal Component			
	Trend	N	Α	M	
	Component	(None)	(Additive)	(Multiplicative)	
Ν	(None)	M,N,N	M,N,A	M,N,M	
Α	(Additive)	M,A,N	M,A,A	M,A,M	
$A_d$	(Additive damped)	M,A <sub>d</sub> ,N	$M,A_d,A$	$M,A_d,M$	

## **AIC and cross-validation**

Minimizing the AIC assuming Gaussian residuals is asymptotically equivalent to minimizing one-step time series cross validation MSE.

## **Automatic forecasting**

## From Hyndman et al. (IJF, 2002):

- Apply each model that is appropriate to the data. Optimize parameters and initial values using MLE (or some other criterion).
- Select best method using AICc:
- Produce forecasts using best method.
- Obtain forecast intervals using underlying state space model.

Method performed very well in M3 competition.

## Residuals

## **Response residuals**

$$\hat{e}_t = y_t - \hat{y}_{t|t-1}$$

#### **Innovation residuals**

Additive error model:

$$\hat{\varepsilon}_t = y_t - \hat{y}_{t|t-1}$$

Multiplicative error model:

$$\hat{\varepsilon}_t = \frac{y_t - \hat{y}_{t|t-1}}{\hat{y}_{t|t-1}}$$

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#### **Your turn**

Try forecasting the Chinese GDP from the global\_economy data set using an ETS model.

Experiment with the various options in the ETS() function to see how much the forecasts change with damped trend, or with a Box-Cox transformation. Try to develop an intuition of what each is doing to the forecasts.

[Hint: use h=20 when forecasting, so you can clearly see the differences between the various options when plotting the forecasts.]

#### **Your turn**

- Find an ETS model for the Gas data from aus\_production and forecast the next few years.
  - Why is multiplicative seasonality necessary here?
  - Experiment with making the trend damped. Does it improve the forecasts?