
First-order methods in optimization - Evaluation

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1 Part 1 - Slide 45

1.1 6. (with code)

$$f(\mathbf{x}) = 2x_{[1]} + x_{[2]} = \max_{\mathbf{y}} \left\{ \sum_i y_i x_i; \sum_i y_i = 3, 0 \leq y_i \leq 2 \right\} = \sigma_{\{\mathbf{y} | \mathbf{1}^\top \mathbf{y} = 3, 0 \leq \mathbf{y} \leq 2\mathbf{1}\}}.$$

Hence,

$$\text{prox}_f(\mathbf{x}) = \mathbf{x} - \mathcal{P}_{\{\mathbf{y} | \mathbf{1}^\top \mathbf{y} = 3, 0 \leq \mathbf{y} \leq 2\mathbf{1}\}}(\mathbf{x}).$$

Writing $C = \{\mathbf{y} | \mathbf{1}^\top \mathbf{y} = 3, 0 \leq \mathbf{y} \leq 2\mathbf{1}\}$, it can be compared with $H_{\mathbf{a}, \mathbf{b}} \cap \text{Box}[\mathbf{l}, \mathbf{u}]$, with $\mathbf{a} = \mathbf{1}, \mathbf{b} = 3, \mathbf{l} = \mathbf{0}, \mathbf{u} = 2$.

```
import numpy as np

def f(x):
    xsorted = np.sort(x)
    return 2*xsorted[0] + xsorted[1]

def projbox(x, l, u):
    return np.minimum(np.maximum(x, l), u)

def projH_inter_box(x, a, b, l, u):
    mu = 1
    factor = 1
    val = 10

    while (np.abs(val) > 1e-8):
        val = a@projbox(x-mu*a, l, u) - b
        mu *= (1+factor)**(np.sign(val))
        factor /= 1.2

    return projbox(x-mu*a, l, u)

def proxf(x):
    return x - projH_inter_box(x, np.ones(len(x)), 3, np.zeros(len(x)), 2*np.ones(len(x)))

print(proxf(np.array([2,1,4,1,2,1])))
```

The output is : [1.49999994, 1., 2., 1., 1.49999994, 1.].

1.2 8.

$$f(t) = \begin{cases} 1/t, & t > 0, \\ \infty, & \text{else.} \end{cases}$$

$$\text{prox}_{\lambda f}(t) = \arg \min_u \begin{cases} 1/\lambda u, & u > 0, \\ \infty, & \text{else.} \end{cases} + \frac{1}{2} \|u - t\|_2^2$$

Hence,

$$\frac{-1}{\lambda u^2} + u - t = 0 \Leftrightarrow u^3 - \lambda t u^2 - \lambda = 0.$$

Finally,

$$\text{prox}_{\lambda f}(t) = \{u > 0 | u^3 - \lambda t u^2 - \lambda = 0\}. \quad (1)$$

1.3 9.

$$f(\mathbf{X}) = \begin{cases} \text{tr } \mathbf{X}^{-1}, & \mathbf{X} \succ 0, \\ \infty, & \text{else.} \end{cases} = \begin{cases} \sum_{i=1}^n \frac{1}{\lambda_i}, & \mathbf{X} \succ 0, \\ \infty, & \text{else.} \end{cases}$$

As $\mathbf{X} \in \mathbb{S}^n$, it is a *spectral function*. Hence one can write $f(\mathbf{X}) = g(\lambda_1(\mathbf{X}), \dots, \lambda_n(\mathbf{X})) = \sum_{i=1}^n h(\lambda_i)$. With the Singular Value Decomposition (SVD) of \mathbf{X} as $\mathbf{X} = \mathbf{U} \text{diag } \lambda(\mathbf{X}) \mathbf{U}^T$, this gives

$$\begin{aligned} \text{prox}_{\lambda f}(\mathbf{X}) &= \mathbf{U} \text{diag}(\text{prox}_{\lambda g}[\lambda_1, \dots, \lambda_n]) \mathbf{U}^T \\ &= \mathbf{U} \text{diag}(\text{prox}_{\lambda h}(\lambda_1), \dots, \text{prox}_{\lambda h}(\lambda_n)) \mathbf{U}^T \\ &= \mathbf{U} \text{diag}(\{u > 0 \mid u^3 - \lambda \lambda_i u^2 - \lambda = 0\}) \mathbf{U}^T. \end{aligned}$$

1.4 10.

$$\lambda f(\mathbf{x}) = \lambda(\|\mathbf{x}\|_2 - 1)^2 = \lambda \|\mathbf{x}\|_2^2 - 2\lambda \|\mathbf{x}\|_2 + \lambda.$$

Using the provided tables, one identifies it with $g(\mathbf{x}) + \frac{c}{2} \|\mathbf{x}\|_2^2 + \langle \mathbf{a}, \mathbf{x} \rangle + \gamma$, with $g(\mathbf{x}) = -2\lambda \|\mathbf{x}\|_2$, $c = 2\lambda$, $\mathbf{a} = \mathbf{0}$, $\gamma = 0$. Hence,

$$\text{prox}_{\lambda f}(\mathbf{x}) = \text{prox}_{\frac{-2\lambda \|\cdot\|_2}{1+2\lambda}}\left(\frac{\mathbf{x}}{1+2\lambda}\right) = \left(1 + \frac{2\lambda}{\|\mathbf{x}\|_2}\right) \frac{\mathbf{x}}{1+2\lambda}, \quad \mathbf{x} \neq \mathbf{0}.$$

2 Part 2 - Exercise 0 - p40

$$\min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2 + \underbrace{\frac{\lambda_1}{2} \|\mathbf{x}\|_2^2 + \lambda_2 \|\mathbf{x}\|_1}_{\text{elastic net}},$$

where $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{b} \in \mathbb{R}^m$ and $\lambda_1, \lambda_2 > 0$. Choosing $f(\mathbf{x}) = \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2 + \frac{\lambda_1}{2} \|\mathbf{x}\|_2^2$ as the σ -strongly convex and differentiable part and $g(\mathbf{x}) = \lambda_2 \|\mathbf{x}\|_1$ as the closed convex but non differentiable part, one has $\nabla f(\mathbf{x}) = \mathbf{A}^T(\mathbf{A}\mathbf{x} - \mathbf{b}) + \lambda_1 \mathbf{I}\mathbf{x}$ and $\text{prox}_{\lambda g}(\mathbf{x}) = \mathcal{T}_{\lambda_2}(\mathbf{x})$.

- (*Proximal Gradient*)

$$\begin{aligned} \mathbf{x}^{k+1} &= \text{prox}_{\frac{1}{L}g}(\mathbf{x}^k - \frac{1}{L}\nabla f(\mathbf{x}^k)) \\ &= \mathcal{T}_{\frac{\lambda_2}{L}}\left(\mathbf{x}^k - \frac{1}{L}(\mathbf{A}^T \mathbf{A} + \lambda_1 \mathbf{I})\mathbf{x}^k + \frac{1}{L}\mathbf{A}^T \mathbf{b}\right), \end{aligned}$$

$$\text{with } L = \|\mathbf{A}^T \mathbf{A} + \lambda_1 \mathbf{I}\| = \lambda_{\max}(\mathbf{A}^T \mathbf{A}) + \lambda_1 = \|\mathbf{A}\|_2^2 + \lambda_1.$$

- (*FISTA*)

$$\begin{cases} \mathbf{x}^{k+1} &= \mathcal{T}_{\frac{\lambda_2}{L}}\left(\mathbf{y}^k - \frac{1}{L}(\mathbf{A}^T \mathbf{A} + \lambda_1 \mathbf{I})\mathbf{y}^k + \frac{1}{L}\mathbf{A}^T \mathbf{b}\right) \\ t_{k+1} &= \frac{1 + \sqrt{1 + 4t_k^2}}{2} \\ \mathbf{y}^{k+1} &= \mathbf{x}^{k+1} + \left(\frac{t_k - 1}{t_{k+1}}\right)(\mathbf{x}^{k+1} - \mathbf{x}^k) \end{cases}$$

- (*V-FISTA*)

$$\begin{cases} \mathbf{x}^{k+1} &= \mathcal{T}_{\frac{\lambda_2}{L}}\left(\mathbf{y}^k - \frac{1}{L}(\mathbf{A}^T \mathbf{A} + \lambda_1 \mathbf{I})\mathbf{y}^k + \frac{1}{L}\mathbf{A}^T \mathbf{b}\right) \\ \mathbf{y}^{k+1} &= \mathbf{x}^{k+1} + \left(\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1}\right)(\mathbf{x}^{k+1} - \mathbf{x}^k), \end{cases}$$

$$\text{with } \kappa = L/\sigma, \text{ and } \sigma = 1.$$

Now, if one chooses $f(\mathbf{x}) = \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2$ as the differentiable (but not strongly convex) part and $g(\mathbf{x}) = \frac{\alpha\lambda_1}{2} \|\mathbf{x}\|_2^2 + \alpha\lambda_2 \|\mathbf{x}\|_1$ as the closed convex but non differentiable part, one has $\nabla f(\mathbf{x}) = \mathbf{A}^T(\mathbf{A}\mathbf{x} - \mathbf{b})$ and, by identification with $g'(\mathbf{x}) + \frac{c}{2} \|\mathbf{x}\|_2^2 + \langle \mathbf{a}, \mathbf{x} \rangle + \gamma$ with $g'(\mathbf{x}) = \alpha\lambda_2 \|\mathbf{x}\|_1$, $c = \alpha\lambda_1$, $\mathbf{a} = \mathbf{0}$, $\gamma = 0$, $\text{prox}_{\alpha g}(\mathbf{x}) = \text{prox}_{\frac{\alpha}{\alpha\lambda_1+1}\lambda_2 \|\cdot\|_1}\left(\frac{\mathbf{x}}{\alpha\lambda_1+1}\right) = \mathcal{T}_{\frac{\alpha\lambda_2}{\alpha\lambda_1+1}}\left(\frac{\mathbf{x}}{\alpha\lambda_1+1}\right)$.

- (*V-FISTA2*)

$$\begin{cases} \mathbf{x}^{k+1} &= \mathcal{T}_{\frac{\lambda_2/L_2}{\lambda_1/L_2+1}} \left(\mathbf{y}^k - \frac{1}{L_2} (\mathbf{A}^\top \mathbf{A}) \mathbf{y}^k + \frac{1}{L} \mathbf{A}^\top \mathbf{b} \right) \\ \mathbf{y}^{k+1} &= \mathbf{x}^{k+1} + \left(\frac{\sqrt{\kappa_2}-1}{\sqrt{\kappa_2}+1} \right) (\mathbf{x}^{k+1} - \mathbf{x}^k), \end{cases}$$

with $L_2 = \|\mathbf{A}\|_2^2$, $\kappa_2 = L_2/\sigma$, and $\sigma = 1$.

One notices the only difference between *V-FISTA* and *V-FISTA2* occurs in the second line, with $\kappa_2 \neq \kappa$.

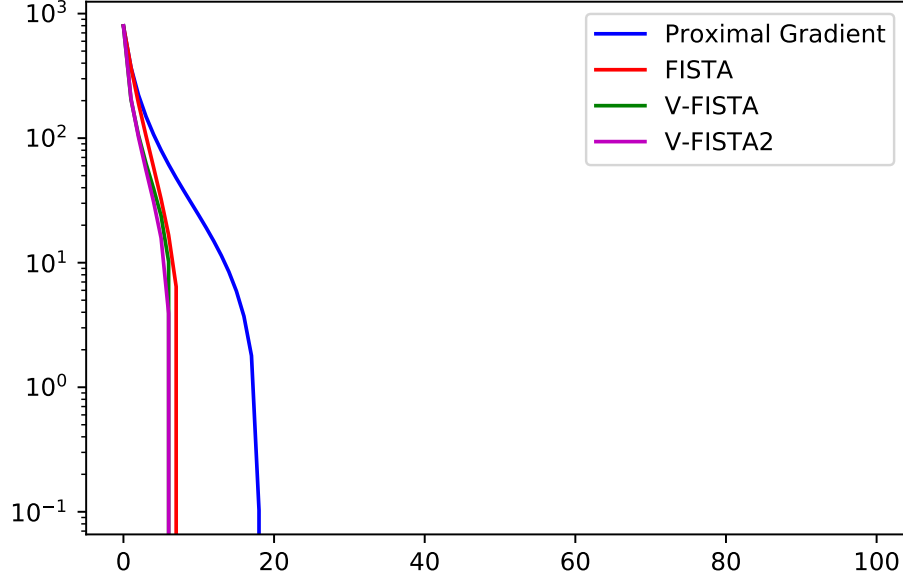


Figure 1: $F(\mathbf{x}^k) - F_{\text{opt}}$ in log-scale along the y-axis for the first 100 iterations of each of the methods with all-zeros vectors and a constant stepsize.

As can be observed in Fig. 1, the V-FISTA methods worked the best, with a slight improvement in V-FISTA which does not follow the theory. The four first elements are:

- (-0.40403765 0.18475212 0.97264407 -0.99645397)
- (-0.43969331 0.01974521 1.42280231 -0.87819581)
- (-0.4319773 0.02881602 1.43373682 -0.9066518)
- (-0.43207117 0.02954933 1.43438138 -0.9058778)
- (-0.43210892 0.02959727 1.43437048 -0.9058291)

for the Ground truth, and the four methods, PG, FISTA, V-FISTA, V-FISTA2, respectively.

3 Part 2 - Exercise 1 - p41

$$\min_{\mathbf{x} \in \mathbb{R}^{30}} \sqrt{\mathbf{x}^\top \mathbf{Q} \mathbf{x} + 2\mathbf{b}^\top \mathbf{x} + c} + 0.2 \|\mathbf{D} \mathbf{x}\|_1$$