## TDT4136 – Introduction to Artificial Intelligence

## Assignment 1 - Al fundamentals and intelligent agents

Deadline: 09.09.2022, 23:59 hrs

## **Theoretical Questions**

- 1. What is Artificial Intelligence (AI)? Include at least 3 definitions of AI that are not covered in the lecture.
- 2. What is the Turing test? What is its purpose and how is it conducted?
- 3. What is rationality?
- 4. What is the difference between thinking rationally and acting rationally? Is rational thinking an absolute condition for acting rationally?
- 5. What is the connection between knowledge and action according to Aristotle? How can his argument be used to implement his idea in AI?
  - (a) Who was (or were) the first Al researcher(s) to implement these ideas?
  - (b) What is the name of the program or system they developed? Write a short description about it.
- 6. Consider a robot with the task of crossing the road, and an action portfolio A:
  - $A = \{lookBack, lookForward, lookLeft, lookRight, goForward, goBack, goLeft, goRight\}$
  - While crossing the road, an elk crashes on the robot and smashes it. Is the robot rational?
  - While crossing the road on a green light, a passing car drives into the robot and crashes, preventing the robot from crossing to the other side. Is the robot rational?
- 7. Consider the **vacuum cleaner world** described in Figure 2.2 (Chapter 2.1 of AIMA 4th Ed.). Let us modify this vacuum environment such that the agent is penalized 1 point for each movement:
  - Could a simple reflex agent be rational for this environment? Why?
  - Could a reflex agent with state be rational in this environment? Why?
  - Assume now that the simple reflex agent (i.e. no internal state) can perceive the *clean* status of both locations at the same time. Could this agent be rational? Why? In case it could be rational, write the agent function using mathematical notation.
- 8. Consider the **original vacuum cleaner environment** shown in Figure 2.2. Describe the environment using the properties from Chapter 2.3.2 (e.g. episodic/sequential, deterministic/stochastic, etc.) Explain why you chose such values and properties.
- 9. Write both advantages and limitations of the following types of agents:
  - · Simple reflex agents
  - · Model-based reflex agents
  - · Goal-based agents
  - · Utility-based agents

## **Deliverables**

Deliver a report (txt or typeset pdf) on Blackboard with answers to the questions above. Remember to properly cite your sources.