

Firn densification model

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1 Introduction

The top layer of snow on a glacier or ice sheet increases in density as depth increases; newly accumulated snow builds up and compresses the layers below. *Herron and Langway* [1980] developed a firn densification model based on Arrhenius-type equations with variable rate constants, and found that the densification rate decreased suddenly around 550 kg m^{-3} . *Zwally and Li* [2002] expanded upon this model and found an alternate temperature-dependent value for the rate constant. *Arthern et al.* [2010] developed yet another set of equations based from their in situ measurements of Antarctic snow compaction. *Ligtenberg et al.* [2011] modified the *Arthern et al.* [2010] parametrization to better fit areas with a higher average annual temperature.

We have re-created a number of these models and integrated them with an enthalpy-formulation proposed by *Aschwanden et al.* [2012] which accounts for melting of firn layers in percolation zones. The model simulates ice lenses formed from within the firn column, and work is currently being done to allow the movement of water through the column. The model has been created with the finite-element software package FEniCS; an explanation of its usage and flexibility will be made clear.

2 Temperature Solution

We begin with the standard heat-transport equation as explained by *Patterson* [2001]

$$\rho c_i \frac{\partial T}{\partial t} = k_i \frac{\partial^2 T}{\partial z^2} + \left(\frac{dk_i}{dt} - \rho c_i w \right) \frac{\partial T}{\partial z}$$

with heat sources from the deformation of ice omitted, ρ density, c_i heat capacity, k_i thermal conductivity, w vertical velocity, and T temperature of firn. To solve the total derivative dk_i/dt we must apply the chain rule

$$\frac{dk_i}{dz} = \frac{\partial k_i}{\partial \rho} \frac{\partial \rho}{\partial z} + \frac{\partial k_i}{\partial T} \frac{\partial T}{\partial z}.$$

The thermal conductivity of ice is defined by *Arthern et al.*, 1998 as

$$k_i = 2.1 \left(\frac{\rho}{\rho_i} \right)^2,$$

from which we find

$$\frac{\partial k_i}{\partial \rho} = 4.2 \frac{\rho}{\rho_i^2}$$

and

$$\frac{\partial k_i}{\partial T} = \frac{4.2}{\rho_i^2} \left(\frac{\partial \rho}{\partial T} \right).$$

Patterson [2001] defined ρ in terms of T and from this can be derived

$$\frac{\partial \rho}{\partial T} = (5.6 \times 10^{-2}) \exp((-5.7 \times 10^{-3})T).$$

The vertical velocity of ice, w , is directly proportional to the accumulation, \dot{b} ,

$$w = -\frac{\dot{b}}{\rho}$$

with \dot{b} in units of $\text{kg m}^{-2} \text{ s}^{-1}$. The densification process is defined with the material derivative

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + w \frac{\partial \rho}{\partial z}.$$

Arthern et al. [2010] described this derivative differently for density values above and below a critical value, ρ_m :

$$\frac{d\rho}{dt} = \begin{cases} c_0(\rho_i - \rho), & \rho \leq \rho_m \\ c_1(\rho_i - \rho), & \rho > \rho_m \end{cases}.$$

Zwally and Li [2002] defined a single multiplying constant c with an Arrhenius-type relation

$$c_0 = c_1 = \dot{b}\beta(T) \left(\frac{\rho_i}{\rho_w} \right) K_{0G}(T) \exp\left(-\frac{E(T)}{RT}\right),$$

with $K_{0G}(T) \exp(-E(T)/(RT)) = 8.36T^{-2.061}$ as described in *Reeh* [2008], and $\beta(T)$ a smoothing function to match a desired density rate. *Arthern et al* [2010] developed a semi-empirical formula by coupling the rate equations for Nabarro-Herring creep and normal grain-growth:

$$\begin{cases} c_0 = M_0 \dot{b} g^{\frac{k_{c0}}{k_g}} \exp\left(-\frac{E_c}{RT} + \frac{E_g}{RT_{avg}}\right) \\ c_1 = M_1 \dot{b} g^{\frac{k_{c1}}{k_g}} \exp\left(-\frac{E_c}{RT} + \frac{E_g}{RT_{avg}}\right) \end{cases},$$

with the creep coefficients defined as

$$\begin{cases} k_{c0} = 9.2 \times 10^{-9} \text{ m}^3 \text{ s kg}^{-1} \\ k_{c1} = 3.7 \times 10^{-9} \text{ m}^3 \text{ s kg}^{-1} \end{cases}$$

and M defined in *Ligtenberg et al.* [2011] to better fit with observed densification rates in higher-temperature environments:

$$\begin{cases} M_0 = 2.366 - 0.293 \ln(\dot{b} * 1 \times 10^3) \\ M_1 = 1.435 - 0.151 \ln(\dot{b} * 1 \times 10^3) \end{cases}.$$

Within the same paper a firn surface-density expression from data was given:

$$\rho_s = -151.94 + 1.4266(73.6 + 1.06T_s + 0.0669A + 4.77V_a).$$

3 Enthalpy Solution

As stated in *Aschwanden et al.* [2012], we take 'enthalpy' to be synonymous with 'internal energy' due to the exclusion of work done with changing volume. The equation used here is the shallow-enthalpy:

$$\rho \frac{\partial H}{\partial t} = \frac{\partial}{\partial z} \left(\left\{ \begin{matrix} K_i, & \text{Temperate} \\ K_0, & \text{Cold} \end{matrix} \right\} \frac{\partial H}{\partial z} \right) + w\rho \frac{\partial H}{\partial z}.$$

Strain heating has been neglected and the advective term $w\rho \partial H / \partial z$ has been added. The coefficient for temperate ice is

$$K_i = \frac{k_i}{c_i},$$

and the coefficient for cold ice is

$$K_0 = \frac{1}{10} K_i.$$

Temperate firm is defined as firm with $H > H_s$, cold firm with $H \leq H_s$, where

$$H_s = \int_{T_0}^{T_m} c_i(T) dT,$$

with $T_m = 273.15$ K and $T_0 = 0.0$ K. The enthalpy can be found with a constant heat capacity of $2009 \text{ J kg}^{-1} \text{ K}^{-1}$ by the linear equation

$$H = \begin{cases} c_i(T - T_0), & \text{where } T \leq T_m \\ c_i(T_w - T_0) + \omega L_f, & \text{where } T > T_m \end{cases}$$

where L_f is the latent heat of fusion and ω represents the water content percentage of firm given by

$$\omega L_f = H - c_i(T_w - T_0).$$

Temperature may be derived from enthalpy easily:

$$T = \frac{H}{c_i}.$$

The densification equations remain the same as in the temperature solution, but the density of the firm column changes with the percentage of water content:

$$\rho^n = \begin{cases} \rho^{n-1} + \Delta\omega(\rho_w - \rho_i) \text{ kg m}^{-3}, & \Delta\omega \leq 0 \\ \rho^{n-1} + \Delta\omega\rho_w \text{ kg m}^{-3}, & \Delta\omega > 0 \end{cases},$$

where $\Delta\omega = \omega^n - \omega^{n-1}$ is the change in water content and superscripts refer to the time index. This has the effect of adding water to the firm column and refreezing the portion of firm with decreasing water content. The surface-density at time index $n + 1$ can be described as:

$$\rho_s^{n+1} = \rho_b^{n+1} d_p + \rho_s^n (1 - d_p),$$

where

$$\rho_b^{n+1} = \rho_b^{n-1} + \Delta\omega_s \rho_b^n,$$

$$\Delta\omega_s = \omega_s^n - \omega_s^{n-1},$$

$$d_p = \frac{d_n}{l_s},$$

$$d_n = w_s dt, \text{ and}$$

l_s is the length of the surface node.

If $T_s \geq T_w$, the density of surface snow while taking into account re-freezing is simulated making

$$\rho_b^n = \begin{cases} \rho_w - \rho_i \text{ kg m}^{-3}, & \Delta\omega_s < 0 \\ \rho_w \text{ kg m}^{-3}, & \Delta\omega_s > 0 \end{cases},$$

but when $T_s < T_w$, ρ_b^n is simply made to be ρ_{si} .

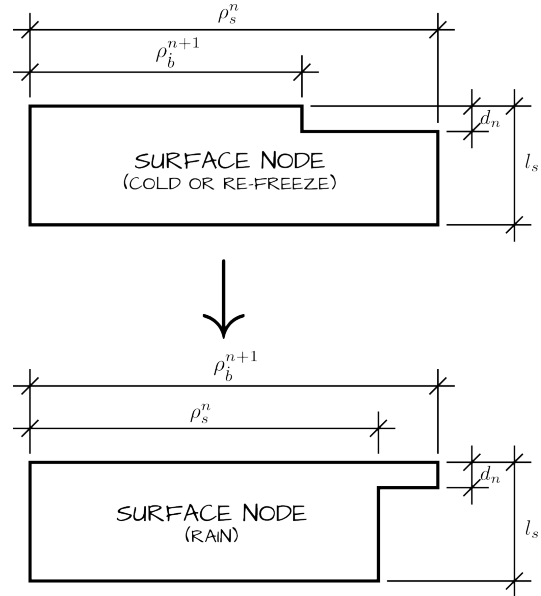


Figure 1: Evolution of surface node density

4 Finite Element Method

This section will focus on the enthalpy solution. Solving these equations with FEniCS is done with Galerkin's method and requires finding the weak formulation:

$$0 = \int_{\Omega} \left\{ \begin{matrix} K_i \\ K_0 \end{matrix} \right\} \nabla^2 H \psi d\Omega + \int_{\Omega} w\rho \nabla H \psi d\Omega - \int_{\Omega} \rho \frac{\partial H}{\partial t} \psi d\Omega.$$

Here we have integrated the enthalpy equation over the entire domain, Ω , and multiplied by a test function ψ . After integrating the diffusive term by parts this becomes

$$f_H = - \int_{\Omega} \left\{ \begin{matrix} K_i \\ K_0 \end{matrix} \right\} \nabla H \nabla \psi d\Omega + \int_{\Omega} w\rho \nabla H \psi d\Omega$$

$$- \int_{\Omega} \rho \frac{\partial H}{\partial t} \psi d\Omega.$$

We can discretize the enthalpy time-differential with the second-order accurate backward-difference formula

$$\frac{\partial H}{\partial t} = \frac{H^{k-2} - 4H^{k-1} + 3H^k}{2dt},$$

with superscripts referring to time index. This equation can be represented in FEniCS as:

```
f_H = rho*(H_2 - 4*H_1 + 3*H)/(2*dt)*psi*dx
      + k/c*Kcoef*inner(grad(H), grad(psi))*dx
      + rho*w*grad(H)*psi*dx
```

The variable `Kcoef` is a coefficient vector which will be updated dynamically depending on the temperature of firm (either 1.0 or 0.1 corresponding to K_i and K_0).

The weak form for density is found similarly:

$$f_{\rho} = \int_{\Omega} \frac{\partial \rho}{\partial t} \phi d\Omega + \int_{\Omega} w \nabla \rho \phi d\Omega - \int_{\Omega} \frac{d\rho}{dt} \phi d\Omega.$$

With the partial-time differential of density defined identically to the enthalpy equation, this can be represented in FEniCS including the *Arthern et al.* [2010] densification equation as:

```
c      = b*g*rhoCoef/kg *
          exp(-Ec/(R*T) + Eg/(R*Tavg))
drhodt = c*(rhoi - rho)
f_rho   = ((rho_2 - 4*rho_1 + 3*rho)/(2*dt)
          - drhodt + w*grad(rho))*phi*dx
```

The variable `rhoCoef` is another dynamically-updated-coefficient vector and is either k_{c0} or k_{c1} depending upon the density at the node.

We can define the function space for the entire non-linear problem as

$$U = \Omega \times \Omega,$$

with corresponding trial and test functions respectively defined as

$$v, u \subset U.$$

The test functions for each function can now be described as

$$\psi, \phi \subset u.$$

In FEniCS these spaces can be defined by this:

```
mesh      = Interval(n, zb, zs)
V          = FunctionSpace(mesh, 'Lagrange', 1)
MV         = V*V
h          = Function(MV)
H,rho     = split(h)
dh         = TrialFunction(MV)
dH, drho  = split(dh)
j          = TestFunction(MV)
psi, phi  = split(j)
```

The variable `zb` is the z-position of the base of the firm column which does not change and `n` is the number of nodes; the `mesh` variable defines the spacial dimensions of the system to be solved and is here created in one dimension. The mesh may also be created in three dimensions if desired, or made to fit a custom grid. The variables `dH` and `drho` are the trial functions for the enthalpy and density functions and are not utilized in this code, but are included for reference later on.

We define the entire function as

$$f = f_H + f_{\rho}.$$

Solving this system can be accomplished with *Newton's Method* which requires derivation of the Jacobian:

$$J = \frac{\partial f}{\partial v}.$$

In FEniCS this is done with:

```
f = f_H + f_rho
J = derivative(f, h, dh)
```

5 Boundary Conditions

A cyclical enthalpy boundary condition for the surface can be simulated with

$$H_s = c_i(T_s - T_0),$$

$$T_s = T_{avg} + \alpha \sin(\omega t),$$

where α is the amplitude of temperature variation and $\omega = 2\pi/spy$ is the frequency. The surface-density boundary condition can be likewise described as (see Figure 1):

$$\rho_s^{n+1} = \rho_b^{n+1} d_p + \rho_s^n (1 - d_p).$$

Both of these can be created with FEniCS by

```
code = 'c*(Tavg + 9.9*sin(omega*t) - T0)'
Hs   = Expression(code, c=cp, Tavg=Tavg,
                  omega=freq, t=t0, T0=T0)
```

```
code = 'dp*rhon + (1 - dp)*rhoi'
rhoS = Expression(code, rhon=rhosi,
                  rhoi=rhosi, dp=1.0)
```

```
def surface(x, on_boundary):
    return on_boundary and x[0] == zs
```

```
Hbc = DirichletBC(MV.sub(0), Hs, surface)
Dbc = DirichletBC(MV.sub(1), rhoS, surface)
```

Within the time-loop the variables `t`, `rhon`, `rhoi`, and `dp` can be updated as needed.

Now all that is left is to iterate through time and call the `solve` method at each step:

```
solve(f == 0, h, [Hbc, Dbc], J=J)
```

The use of the `solve` function in this way chooses *Newton's Method* by default and minimizes the residual of `f`. The boundary conditions are updated by specifying the list `[Hbc, Dbc]`.

6 Model Parameters

Within the time-loop there are a number of parameters which need to be updated. Taking into account conservation of mass, the height l of each node must be re-calculated:

$$l_{new} = l_{ini} \frac{\rho_{ini}}{\rho},$$

where ρ_{ini} and l_{ini} are the density and height vectors of the firn column when the system was initialized. With the height of the nodes calculated, the z-positions may be found by iterating through the heights and setting the z vector's corresponding cell equal to the current sum. After successful calculation the FEniCS `mesh` object must have its coordinates refreshed. These tasks may be completed with the following code:

```
lnew      = l*rho_in[index] / firn.rho[index]
zSum      = zb
zTemp     = zeros(n)
for i in range(n)[1:]:
    zTemp[i] = zSum + lnew[i]
    zSum     += lnew[i]
firn.z[index] = zTemp
mesh.coordinates()[0,:] = firn.z
```

The variable `index` is an array of positions corresponding to the correct ordering of the nodes, necessary after mesh refinement.

The height s at time index n of the original surface may be calculated as follows:

$$s^n = (z_s - z_b) \frac{s^{n-1} - z_b}{z_s - z_b} + w_s dt.$$

This maintains the relative location of the original surface to the current surface and moves downward proportional to w . This is accomplished in Python with

```
interp     = interp1d(firn.z[index],
                      firn.w[index],
                      bounds_error=False,
                      fill_value=firn.w[index][0])
zint       = array([firn.origZ])
wOrigZ     = interp(zint)
firn.origZ = (firn.z[index][-1] - zb) *
              (firn.origZ - zb) /
              (zs_0 - zb) + wOrigZ[0] * dt
```

The second index for `firn.z` refers to the surface, `[-1]`, or the base, `[0]`. For all operations it is convenient to store all the state data from the simulation in an object for ease of access. It was for this purpose the `firn` class was created and contains the signature

```
firn(H, T, rho, omega, w, k, c, z, index)
```

with `z` the node z-positions as defined above, `index` the index of re-ordered mesh locations, and all other variables as described earlier in the paper.

The variables for accumulation and surface temperature are the main driving forces in the simulation, and data from a specific site may be used in the model by interpolating the data in increments of dt and inserting the values into the equations. This may be accomplished with the `set_local(n)` method of the `vector` class, which takes as input a NumPy array `n` with indexes corresponding to node positions within the `mesh` object. If the variable is used in the surface boundary condition, this may be updated within the FEniCS `Expression` object with the dot operator.

A function has been provided (`set_ini_conv`) which initializes the density to a previously derived density. The density may also be initialized to a set of real-world data if desired, and is demonstrated in the temperature equation model, `objModel.py`.

The `plot.py` file contains the class `firn` and the previously undescribed `plot` class. This class uses the plotting package `Matplotlib` to display the data contained in the `firn` object. The method `plot_all_height()` plots the height history for a group of simulations and is useful for comparing the effects of model parameters.

Another version of `enthModel`, the main simulation class, has been created which uses collected data for density and surface temperature. When using this version, it is important to make dt less than or equal to the time interval of recorded events so all data points are included.

7 Variable Definitions

Many variable are used in this simulation and many do not change. These are defined below:

Constants :

Var.	Value	Units	Description
g	9.81	m s^{-2}	gravitational acceleration
R	8.3144621	$\text{J mol}^{-1} \text{K}^{-1}$	gas constant
spy	31556926	s	seconds per year
ρ_i	917	kg m^{-3}	density of ice
ρ_w	1000	kg m^{-3}	density of water
ρ_m	550	kg m^{-3}	critical density value
k_i	2.1	$\text{W m}^{-1} \text{K}^{-1}$	thermal conductivity of ice
c_i	2009	$\text{J kg}^{-1} \text{K}^{-1}$	heat capacity of ice
L_f	3.34×10^5	J kg^{-1}	latent heat of fusion
H_s	$c_i(T_w - T_0)$	J kg^{-1}	Enthalpy of ice at T_w
T_w	273.15	K	triple point of water
T_0	0.0	K	reference temperature
k_g	1.3×10^{-7}	$\text{m}^2 \text{s}^{-1}$	grain growth coefficient
E_c	60×10^3	J mol^{-1}	act. energy for water in ice
E_g	42.4×10^3	J mol^{-1}	act. energy for grain growth

Variables used by the model can be specified to suit simulation requirements:

Model Specific :

Var.	Units	Description
ρ_{si}	kg m^{-3}	initial density at surface
\dot{b}	$\text{kg m}^{-2}\text{s}^{-1}$	surface accumulation
A	mm a^{-1}	surface accumulation
V_a	m s^{-1}	mean annual wind speed
T_{avg}	K	average annual temperature
T_s	K	firm surface temperature
z_s	m	surface start z-location
z_b	m	firm base z-location
z_{s0}	m	previous time-step's surface
dz	m	initial z-spacing
l	m	vector of node heights
dt	s	time-step
t_0	s	begin time
t_f	s	end-time

8 Verification of Program

A converging run of the program was done quickly by making dt equal spy : this has the effect of producing a steady-state solution. After the density-profile converged the data was saved to a text file in the `data` folder. The script was run again with the average surface air temperature T_{avg} made so that the surface temperature peaks at 8°C if $t < 10$ years, and 0°C if $t \geq 10$ years. This has the effect of halting any melting and refreezing after this time period. For this run the method `set_ini_conv` was called to initialize the previous runs data and dt was set to $0.0025 * spy$; the results are shown in Figures 2 and 3.

9 Interpretation

The surface-density equation has two values for new accumulation: ρ_{si} and ρ_w depending on the 2-meter average surface air temperature. This is quite simplified; a better approach that models real-life circumstances can be found.

Testing with real-world temperature and accumulation data-sets is required to validate the model. The simulation's surface-height- and density-profile outputs while using these data may then be compared against cataloged surface-height and density-profile data to verify its accuracy.

Above the ice lens in Figure 2 you will see numerical distortion: this is caused by the sudden rise in density where the lens begins. This distortion is a source of inaccuracies and needs also to be corrected.

10 Work in Progress

At its current state of development the model does not take into account water transport through the firm column, describable with the Darcy flow equations:

$$q = \frac{-k}{\mu} \nabla P, \quad v = \frac{q}{\phi},$$

where k is permeability, $\mu = 1.787 \times 10^{-3} \text{ Pa}\cdot\text{s}$ is the viscosity of water at 0°C , ∇P is the pressure gradient vector, and $\phi = \rho/\rho_i$ is porosity.

Waldner *et al.* [2002] introduces this issue and provides references to numerous models which simulate this phenomenon. Coleou *et al.* [1998] supplies an equation for the irreducible water content of snow

$$S_0 = \frac{0.0057}{1 - \phi} + 0.0017,$$

which may be used with the expression for permeability from Bozhinskiy & Krass [1989] :

$$k = k_0 \exp(m\phi) \left(\frac{S - S_0}{\phi - S_0} \right)^2,$$

where S is the relative water content and k & m are empirical constants.

11 Concluding Remarks

This model is a good start towards accurately modeling the densification of firm: it uses the work of many established models and has the potential to expand; The simulation is able to assimilate data easily, is mathematically easy to interpret, and runs efficiently. This subject is a worthy candidate for further study.

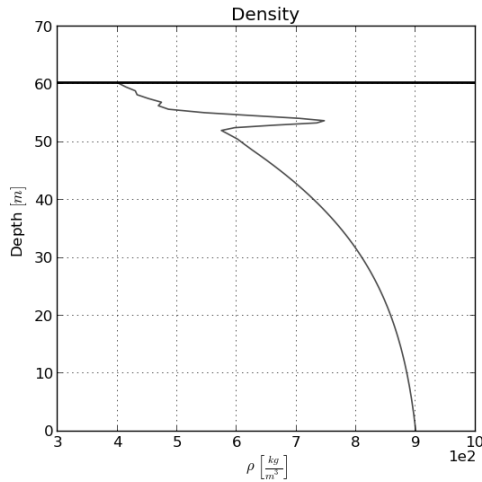


Figure 2: Density profile after 40 years with an ice lens approximately 7 meters below the surface

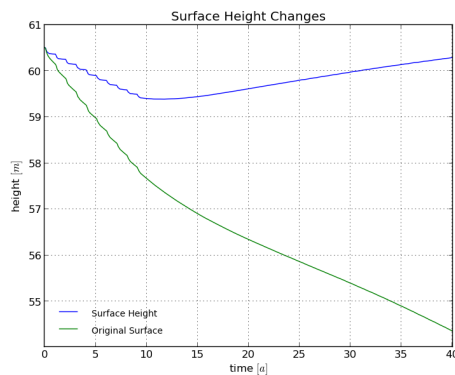


Figure 3: 40-year height history of the column (blue) and original surface (green) resulting in the previous figure. This shows a rapid decrease in height as the lens is formed in the first ten years of simulation. The fluctuations in height show an increase in height with winter temperatures.

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