

Max load voltage: 40V

0UT5 0UT4 0UT3 OUT! 0UT8 0UT7 OUT6 0UT5 0UT4 0UT3 0UT2 OUT! GND 0UT8 0UT7 0UT6 0UT2 GND SCL SDA +5 SCL SDA +5∨ S0-2+ S0-2-50-3+ S0-3 -S0-4 + S0-2+ S0-2-S0-3+ S0-3 -S0-4 + S0-1-S0-1-S0-4 · S0-4 · Ĭ3 Ž. Ξ Z Ξ N2 <u>8</u> N N 0UT9 PWM2 PWM1 0UT16 0UT15 0UT14 0UT13 **0UT12** OUT! 0LT10 OUT9 PWM2 PWM1 91TU0 0UT15 0UT14 0UT13 **0UT12** 0UTI1 OUT10 GND GND <u>N</u> N N IN12 IN13 IN14 IN15 IN16 IN12 IN13 IN 14 IN15 N16 Ē Ξ ٤ ڏ Ž <u>8</u> ٤ 9NI ž 8 Z

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github.com/pilotak/eth-io

Proudly designed in Czech Republic



ETH IO ESP32 based ethernet I/O Input: 6-32V == 0.6A MAX Max output current: 0.7A

Max load voltage: 40V







github.com/pilotak/eth-io Proudly designed in Czech Republic

0 UT8 0 UT7 0 UT6 0 UT7 0 UT7 0 UT7 6 N D S C L S S D A	00178 00174 00175 00173 00173 00171 6ND SCL SDA +5V
N 3 2 N 1 N 3 2 N 1 N 3 N 3 N 1 N 3 N 3 N 1 N 3 N 1 N 1	IN 1 IN 2 IN 3
0UT16 0UT15 0UT14 0UT12 0UT11 0UT10	PWM2 PWM1 0UT16 0UT15 0UT13 0UT12 0UT10 0UT10
IN 5 IN 6 IN 13 IN 13 IN 15 IN 15 IN 15	IN 6 IN 7 IN 10 IN 11 IN 12 IN 13 IN 15 IN 15