

# Analysis 2

Lecture notes, University (of Technology) Graz  
based on the lecture by Wolfgang Ring

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May 3, 2018

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*This lecture took place on 2018/03/06.*

## Mathematical Redux and topological fundamentals

### Metric

**Definition 1.1.** Let  $X \neq \emptyset$  be a set. We define a map  $d : X \times X \rightarrow [0, \infty)$ .  $d$  should behave like a geometrical distance. We require  $\forall x, y, z \in X$ :

- $d(x, y) = d(y, x)$  [called symmetry]
- $d(x, y) = 0 \iff x = y$  [called positive definiteness]
- $\forall x, y, z \in X : d(x, z) \leq d(x, y) + d(y, z)$  [called triangle inequality]

Then  $d$  is called metric or distance function on  $X$ .  $(X, d)$  is called metric space.

#### Example 1.1.

- $X \subseteq \mathbb{C}$ ,  $d(x, y) = |x - y|$ . It satisfies  $|x - z| \leq |x - y| + |y - z|$
- $X \subseteq \mathbb{R}^n$ ,  $\|x - y\| = \langle x - y, x - y \rangle^{\frac{1}{2}}$

**Claim.**

$$\langle x, y \rangle = \sum_{i=1}^n x_i y_i$$

$$\|x\| = \langle x, x \rangle^{\frac{1}{2}} = \sqrt{\sum_{i=1}^n x_i^2}$$

$$\|x\| = \sqrt{x_1^2 + x_2^2}$$

It holds that  $\|x + y\| \leq \|x\| + \|y\|$  [triangle inequality].

*Proof.*

$$\begin{aligned}
\|x + y\|^2 &= \langle x + y, x + y \rangle \\
&= \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle \\
&= \|x\|^2 + 2\langle x, y \rangle + \|y\|^2 \\
&\leq \|x\|^2 + 2\|x\| \|y\| + \|y\|^2 && \text{[see Cauchy-Schwarz inequality]} \\
&= (\|x\| + \|y\|)^2 \\
\|x - y\|^2 &= \langle x - y, x - y \rangle \\
&= \|x\|^2 - 2\langle x, y \rangle + \|y\|^2 \\
\|x + y\|^2 + \|x - y\|^2 &= 2(\|x\|^2 + \|y\|^2)
\end{aligned}$$

□

## Cauchy-Schwarz inequality

**Theorem 1.1** (Cauchy-Schwarz inequality).

$$|\langle x, y \rangle| \leq \|x\| \|y\|$$

*Proof.*

$$0 \leq \langle x - \lambda y, x - \lambda y \rangle = \|x\|^2 - 2\lambda \langle x, y \rangle + \lambda^2 \|y\|^2 \quad \forall \lambda \in \mathbb{R}$$

Let  $\lambda = \frac{\langle x, y \rangle}{\|y\|^2}$ . Then,

$$\begin{aligned}
0 &\leq \|x\|^2 - 2 \frac{|\langle x, y \rangle|^2}{\|y\|^2} + \frac{|\langle x, y \rangle|^2}{\|y\|^4} \cdot \|y\|^2 \\
&\implies 0 \leq \|x\|^2 - \frac{|\langle x, y \rangle|^2}{\|y\|^2} \\
&\implies |\langle x, y \rangle|^2 \leq \|x\|^2 \cdot \|y\|^2
\end{aligned}$$

□

## Euclidean norm

**Definition 1.2.**  $\|x\| = \sqrt{\sum_{i=1}^n x_i^2}$  is called Euclidean norm (length) of vector  $x \in \mathbb{R}^n$ .

$\|x\| = \langle x, x \rangle^{\frac{1}{2}}$  It holds that

1.  $\|\lambda x\| = |\lambda| \|x\| \forall x \in \mathbb{R}^n, \lambda \in \mathbb{R}$
2.  $\|x\| = 0 \iff x = 0 \text{ in } \mathbb{R}^n$
3.  $\|x + y\| \leq \|x\| + \|y\|$

In general: Let  $V$  be a vector space over  $\mathbb{R}$ . A map  $\|\cdot\|$ , which assigns every vector  $x$  a non-negative real number satisfying the properties above, is called **norm** on  $V$ . Then  $(V, \|\cdot\|)$  is called a **normed vector space**.

Let  $X \subseteq \mathbb{R}^n$  ( $V$  is a normed vector space), then  $d(x, y) = \|x - y\|$  is a metric on  $X$ .

$$\|y - x\| = \|(-1)(x - y)\| = |-1| \cdot \|x - y\| = \|x - y\|$$

$$d(x, y) = 0 \iff \|x - y\| = 0 \iff x - y = 0 \iff x = y$$

$$d(x, z) = \|z - x\| = \|z - y + y - x\| \leq \|z - y\| + \|y - x\| = d(z, y) + d(y, x)$$

## Metric space

**Example 1.2** (metric space). Metric space, distance is not a norm. Consider an area in  $\mathbb{R}^3$ .

$d(x, y)$  is the shortest path, connecting  $x$  and  $y$  in  $X$ . See Figure 1

**Example 1.3** (French railway). All connections between two cities pass through Paris except one city is Paris.

**Example 1.4.**  $X = \mathbb{R}^2$ . Let  $p \in \mathbb{R}^2$  be fixed.

$$d(x, y) = \begin{cases} |x - y| & \text{if } x, y, p \text{ are on one line} \\ |x - p| + |p - y| & \text{if } x, y, p \text{ are not on one line} \end{cases}$$

## Open sets, convergence and accumulation points

Now we put some terminology into the context of a metric space.  $(X, d)$  is a metric space.

**Definition 1.3.** Let  $x \in X, r \geq 0$ .

$$K_r(x) = \{z \in X \mid d(x, z) < r\}$$

Is an open sphere with radius  $r$  and center  $x$ .

**Definition 1.4.**

$$\overline{K_r(x)} = \{z \in X \mid d(x, z) \leq r\}$$

Closed sphere with center  $x$  and radius  $r$ .

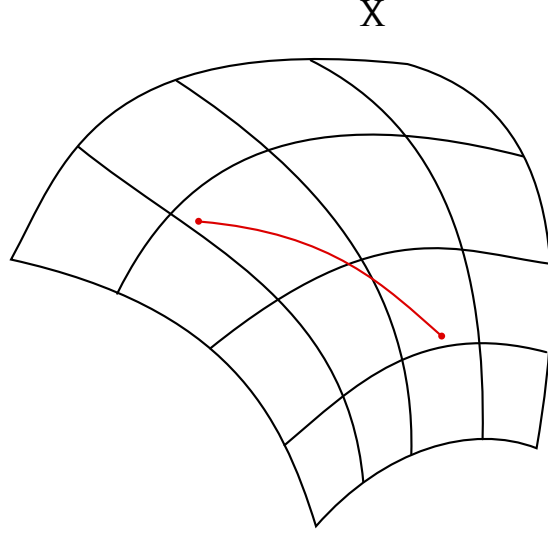


Figure 1: Example in  $\mathbb{R}^3$ . The red line illustrates the shortest path

**Definition 1.5** (Sequences in  $X$ ). Let  $(x_n)_{n \in \mathbb{N}}$  be a sequence in  $X$  (hence,  $x_n \in X \forall n \in \mathbb{N}$ )

1.  $(x_n)_{n \in \mathbb{N}}$  is called convergent and limit  $x \in X$  if

$$\forall \varepsilon > 0 \exists N \in \mathbb{N} : n \geq N \implies d(x_n, x) < \varepsilon$$

Denoted as  $\lim_{n \rightarrow \infty} x_n = x$ .

2.  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence if

$$\forall \varepsilon > 0 \exists N \in \mathbb{N} : n, m \geq N \implies d(x_n, x_m) < \varepsilon$$

Every convergent sequence is also a Cauchy sequence.

*Proof.* Let  $(x_n)_{n \in \mathbb{N}}$  be convergent with limit  $x$ . Let  $\varepsilon > 0$  be arbitrary. Because  $(x_n)_{n \in \mathbb{N}}$  is convergent, there exists  $N \in \mathbb{N}$  such that  $n \geq N \implies d(x_n, x) < \frac{\varepsilon}{2}$ . Now let  $n, m \geq N$ . Then it holds that

$$d(x_n, x_m) \leq \underbrace{d(x_n, x)}_{< \frac{\varepsilon}{2}} + \underbrace{d(x, x_m)}_{< \frac{\varepsilon}{2}} < \varepsilon$$

□

**Definition 1.6.**  $(X, d)$  is called complete metric space if every Cauchy sequence in  $X$  is also convergent (has a limit).

$\mathbb{R}$  is complete.  $\mathbb{R}^n$  is also complete.  $\mathbb{Q} \subseteq \mathbb{R}$  is incomplete.

**Definition 1.7.** Let  $(x_n)_{n \in \mathbb{N}}$  be a sequence of  $X$  is called "accumulation point" (dt. Häufungspunkt) of the sequence.  $\forall \varepsilon > 0$ , it holds that  $K_\varepsilon(x)$  contains infinitely many sequence elements.

This lecture took place on 2018/03/08.

TODO

$$\begin{aligned} d(x, y) = 0 &\iff x = y \\ \forall x, y \in X : d(x, y) &= d(y, x) \\ d(x, z) &\leq d(x, y) + d(y, z) \forall x, y, z \in X \end{aligned}$$

## Norm

Let  $V$  be a vector space.  $\|\cdot\|$  is called norm on  $V$ .

$$\begin{aligned} \|x\| = 0 &\iff x = 0 \\ \forall \lambda \in \mathbb{R}, \mathbb{C} : \forall x \in V : \|\lambda x\| &= |\lambda| \|x\| \\ \forall x, y, z \in V : \|x + y\| &\leq \|x\| + \|y\| \end{aligned}$$

Let  $X \subseteq V$  be a subset of normed vector space  $V$ . Then  $X$  is a metric space with  $d(x, y) = \|x - y\|$ .

For  $V = \mathbb{R}^n$ . Then

$$\|x\| = \left( \sum_{i=1}^n x_i^2 \right)^{\frac{1}{2}}$$

is a norm on  $\mathbb{R}^n$ .  $\|x\|_2$  is called Euclidean norm on  $\mathbb{R}^n$ .

Other norms in  $\mathbb{R}^n$ :

$$\|x\|_\infty = \max \{ |x_i| \mid i = 1, \dots, n \}$$

$$\|x\|_1 = \sum_{i=1}^n |x_i|$$

for  $1 \leq p < \infty$ .

$$\|x\|_p = \left( \sum_{i=1}^n |x_i|^p \right)^{\frac{1}{p}}$$

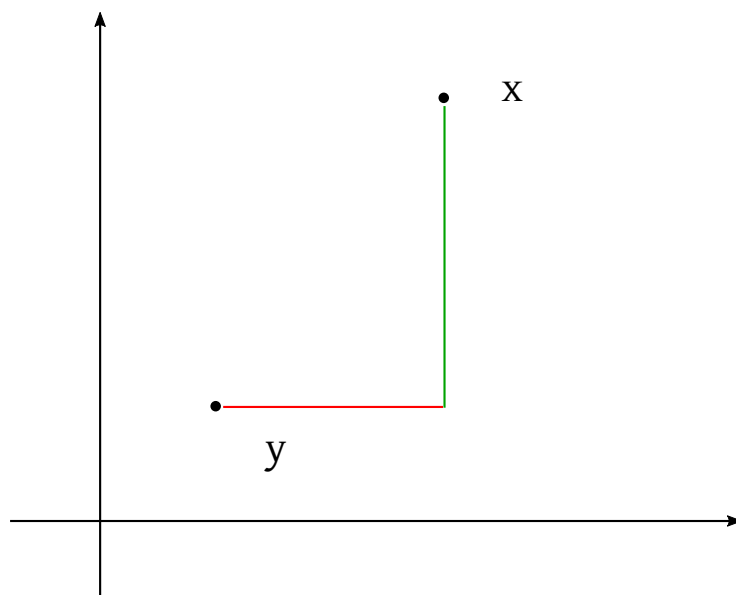


Figure 2: Visualizing  $\|x\|_1$

e.g.  $\|x\|_1$  in  $\mathbb{R}^2$

$$\|x - y\| = |x_1 - y_1| + |x_2 - y_2|$$

is the so-called *Manhattan metric*.

The concepts “subsequence”, “final element of a sequence”, “reordering of a sequence” correspond one-by-one to metric spaces.

**Definition 1.8** (Accumulation point). Let  $(x_n)_{n \in \mathbb{N}}$  be a sequence in  $X$ .  $x \in X$  is called accumulation point of sequence  $X$  if  $\forall \varepsilon > 0$  the sphere  $K_\varepsilon(x)$  contains infinitely many elements.

**Lemma 1.1.**  $x \in X$  is accumulation point of sequence  $(x_n)_{n \in \mathbb{N}}$  if and only iff there exists a subsequence  $(x_{n_k})_{k \in \mathbb{N}}$  such that  $x = \lim_{k \rightarrow \infty} x_{n_k}$ .

*Proof.* See Analysis 1 course

□

## Contact point

Let  $B \subseteq X$ ,  $X$  is a metric space. Then  $B$  with  $d$  is a metric space itself.

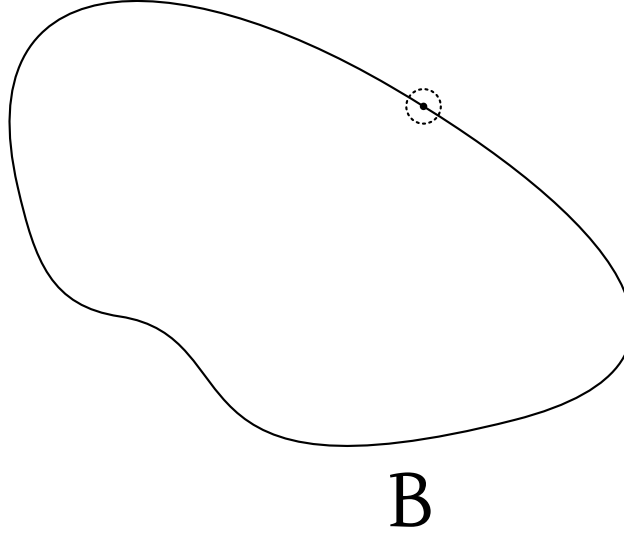


Figure 3: Contact points in set  $B$

**Definition 1.9.** Let  $B \subseteq X$  and  $x \in X$ . We say,  $x$  is a contact point of  $B$  if  $\forall \varepsilon > 0 : K_\varepsilon(x) \cap B \neq \emptyset$ .

[  $y \in X$  is not a contact point of  $B \iff \exists \varepsilon > 0 : K_\varepsilon(y) \cap B = \emptyset$  ]

See Figure 3.

We let  $\bar{B} = \{x \in X \mid x \text{ is contact point of } B\}$ .

$\bar{B}$  is called closed hull of  $B$ .

$B$  is called closed if  $B = \bar{B}$ , hence, every contact point is also element of  $B$ .

**Remark 1.1.** Because  $\forall x \in B$  holds  $K_r(x) \cap B \supseteq \{x\} \forall r > 0$  is  $x$  always contact point of  $B$ . Also  $B \subseteq \bar{B}$  (always)

**Lemma 1.2.**  $x$  is contact point of  $B \iff \exists (x_n)_{n \in \mathbb{N}}$  with  $x_n \in B$  and  $\lim_{n \rightarrow \infty} x_n = x$ .

*Proof.* Let  $x$  be a contact point of  $B$ .

Direction  $\Rightarrow$ : Because  $K_{\frac{1}{n}}(x) \cap B \neq \emptyset$ , choose  $x_n \in K_{\frac{1}{n}}(x) \cap B$ . The sequence  $(x_n)_{n \in \mathbb{N}}$  has property  $d(x_n, x) < \frac{1}{n}$ . Let  $\varepsilon > 0$  be arbitrary. Choose  $N \in \mathbb{N}$  sch that  $N > \frac{1}{\varepsilon}$  (consider the Archimedean axiom). Then for  $n \geq N$ ,  $d(x_n, x) < \frac{1}{n} \leq \frac{1}{N} < \varepsilon$ , hence  $\lim_{n \rightarrow \infty} x_n = x$ .



Direction  $\Leftarrow$ : Let  $x = \lim_{n \rightarrow \infty} x_n$  and  $x_n \in B$ . Let  $\varepsilon > 0$  be arbitrary and  $N \in \mathbb{N}$  such that  $d(x_n, x) < \varepsilon \forall n \geq N$ . Then  $d(x_N, x) < \varepsilon$ , hence

$$x_N \in \underbrace{K_\varepsilon(x) \cap B}_{\neq \emptyset}$$

So  $x$  is contact point of  $B$ . □

**Lemma 1.3.** *It holds that  $\forall B \subseteq X : \bar{B} = \overline{\bar{B}}$ , hence  $\bar{B}$  itself is closed.*

*Proof.* Show that  $x \in \bar{B}$ . Let  $x \in \bar{B}$ .

$$\iff \forall \varepsilon > 0 : K_\varepsilon(x) \cap \bar{B} \neq \emptyset$$

Therefore let  $\varepsilon > 0$  be arbitrary and  $x \in \bar{B}$ .

Show that  $K_\varepsilon(x) \cap B \neq \emptyset$ .

Because  $x \in \bar{B} : \exists y \in \bar{B} : y \in K_{\frac{\varepsilon}{2}}(x)$ . Because  $y \in \bar{B} : \exists z \in B : z \in K_{\frac{\varepsilon}{2}}(y)$ . Hence,

$$d(z, x) \leq \underbrace{d(z, y)}_{< \frac{\varepsilon}{2}} + \underbrace{d(y, x)}_{< \frac{\varepsilon}{2}} < \varepsilon$$

so  $z \in K_\varepsilon(x) \cap B$ . So  $x$  is contact point of  $B \implies x \in \bar{B}$ . □

**Lemma 1.4.** *Let  $X$  be a metric space.*

- $A_i \subseteq X$  be closed  $\forall i \in I$ . Then  $A = \bigcap_{i \in I} A_i = \{x \in X \mid x \in A_i \forall i \in I\}$  is closed itself.
- $A_1, \dots, A_n \subseteq X$  are closed. Then  $\bigcup_{k=1}^n A_k$  is closed in  $X$ .
- $\varphi$  is closed,  $X$  is closed.

*Proof.* See Analysis 1 course. □

**Definition 1.10.** Let  $x \in X$  is called accumulation point of set  $B \subseteq X$  if  $\forall \varepsilon > 0 : (K_\varepsilon(x) \setminus \{x\}) \cap B \neq \emptyset$ .

**Remark 1.2.** Accumulation points only exist in the context of sets. Accumulation values only exist in the context of sequences.

For example  $(+1, -1, +1, -1, +1, \dots)$  has accumulation values  $+1$  and  $-1$ .

**Lemma 1.5.** Let  $x \in X$  is accumulation point on  $B \iff$  every sphere  $K_\varepsilon(x)$  contains infinitely many points of  $B$ .

*Proof.* Direction  $\Leftarrow$  is trivial.

Direction  $\Rightarrow$ : Choose  $x_1 \in (K_1(x) \setminus \{x\}) \cap B$ , hence  $x_1 \neq x$ ,  $x_1 \in B$  and  $d(x_1, x) < 1$ . Let  $r_1 = 1$ .

Inductive: choose  $r_n = \min(\frac{1}{n}, d(x_{n-1}, x))$  and  $x_n \in (K_{r_n}(x) \setminus \{x\}) \cap B$ . Then  $d(x_n, x) > 0$  (because  $x_n \neq x$ ) where  $d(x_n, x) < r_n < \frac{1}{n}$ .

$$0 < d(x_n, x) < \frac{1}{n}$$

Furthermore,  $d(x_n, x) < r_n \leq d(x_{n-1}, x)$ . So  $x_n \neq x_{n-1}$ .

Inductive:  $x_n \neq x_{n-1} \neq x_{n-2} \neq \dots \neq x_1$ . Now consider arbitrary  $\varepsilon > 0$  and  $N$  large enough such that  $\frac{1}{N} < \varepsilon$ .

Then it holds that  $\forall n \geq N : 0 < d(x_n, x) < \frac{1}{n} \leq \frac{1}{N} < \varepsilon$ . So  $K_\varepsilon(x) \cap B$  contains infinitely many points  $x_N, x_{N+1}, x_{N+2}, \dots$   $\square$

**Definition 1.11.** Let  $U \subseteq X$  and  $x \in U$ . We say  $x$  is an inner point of  $U$  if  $\exists r > 0 : K_r(x) \subseteq U$ . We let  $\mathring{U} = \{x \in U \mid x \text{ is inner point of } U\}$  and call it interior of  $U$  (offenen Kern von  $U$  or das Innere von  $U$ ).  $O \subseteq X$  is called open (open set), if every point  $x \in O$  is also an inner point of  $O$ . Hence  $\mathring{O} = O$ .

**Example 1.5.** Let  $K_r(x)$  with  $r > 0$  be an open sphere in  $X$ . Then  $K_r(x)$  is an open set in  $X$ .

Why? Let  $y \in K_r(x)$ . Show that  $y$  is an inner point of the sphere.  $d(y, x) = s < r$ . Define  $r' = r - s > 0$ . Claim:  $K_{r'}(y) \subseteq K_r(x)$ .

TODO drawing

TODO

So it holds that  $z \in K_{r'}(y)$  and therefore  $K_{r'}(y) \subseteq K_r(x)$ .

**Lemma 1.6.** Let  $U \subseteq X$  be arbitrary. Then  $\mathring{U} \subseteq X$  be an open set in  $X$ .

*Proof.* Let  $x \in \mathring{U}$ , hence  $x$  is an inner point of  $U$ . Show that  $x$  is an inner point of  $\mathring{U}$ , also  $\exists r > 0 : K_r(x) \subseteq \mathring{U}$ .

Because  $x \in \mathring{U}$ ,  $r > 0$  exists:  $K_r(x) \subseteq U$ . Claim: Every point  $y \in K_r(x)$  is also an inner point of  $U$ . Obvious (previous example), because  $r' > 0$  exists such that  $K_{r'}(y) \subseteq K_r(x) \subseteq U$  so  $y \in \mathring{U}$  and  $K_r(x) \subseteq \mathring{U}$ .  $\square$

**Theorem 1.2.** Let  $X$  be a metric space.

$$A \subseteq X \text{ is closed in } X \iff O = X \setminus A = A^C \text{ is open}$$

*Proof.* Direction  $\Leftarrow$ . Let  $A$  be closed and  $O = A^C$ . We choose  $x \in O$  and show that  $x$  is in the interior of  $O$ .

Assume the opposite.

$$\forall \varepsilon > 0 : \neg (K_\varepsilon(x) \subseteq O) \\ \iff K_\varepsilon(x) \cap O^c \neq \emptyset$$

where  $O^c = A$ . So  $x$  is contact point of  $A$ . Because  $A$  is closed, it holds that  $x \in A$ . This contradicts with  $x \in O = A^c$ .

Direction  $\Rightarrow$ . TODO  $K_r(x) \cap \underbrace{A}_{=O^c} = \emptyset$ . Hence  $x$  is not a contact point of  $A$ .

So every contact point of  $A$  is also an element of  $A$  and  $A$  is closed.  $\square$

**Theorem 1.3.** *Let  $X$  be a metric space. Then it holds that*

- If  $O_i \subseteq X$  is open in  $X \forall i \in I$ . Then also  $O = \bigcup_{i \in I} O_i$  is open in  $X$ .
- If  $O_1, O_2, \dots, O_n$  is open in  $X$ , then  $\bigcap_{k=1}^n O_k$  is open in  $X$ .
- $X$  is open,  $\emptyset$  is open.

*Proof.* By Lemma 1.4, Theorem 1.2 and De Morgan's Laws:

$$\left( \bigcup_{i \in I} A_i \right)^c = \bigcap_{i \in I} A_i^c$$

$\square$

## Topology

**Definition 1.12.** *Given a set  $X$ . If a subset  $T \subseteq \mathcal{P}(X)$  is defined such that the elements  $O \in T$  (hence  $O \subseteq X$ ) satisfy the conditions of Theorem 1.3, then  $T$  is called topology on  $X$ .  $(X, T)$  is called topological space.*

*The sets  $O \in T$  are called open sets in terms of  $T$ . The complements  $A = O^c$  for  $O \in T$  are called closed sets.*

**Definition 1.13.** *Let  $x \in U \subseteq X$ . We claim that  $U$  is a neighborhood of  $x$ , if  $r > 0$  exists such that  $x \in K_r(X) \subseteq U$*

*See Figure 4*

**Remark 1.3.**  $O \subseteq X$  is open iff  $O$  is neighborhood of every point  $x \in O$ .

**Definition 1.14.** *Let  $X$  and  $Y$  be metric spaces and  $x_0 \in X$ . Let  $f : X \rightarrow Y$  be given. We say  $f$  is continuous in  $x_0$  if*

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall x \in X : d_X(x, x_0) < \delta \implies d_Y(f(x), f(x_0)) < \varepsilon$$

*Here,  $d_X$  is a metric on  $X$  and  $d_Y$  is a metric on  $Y$ .*

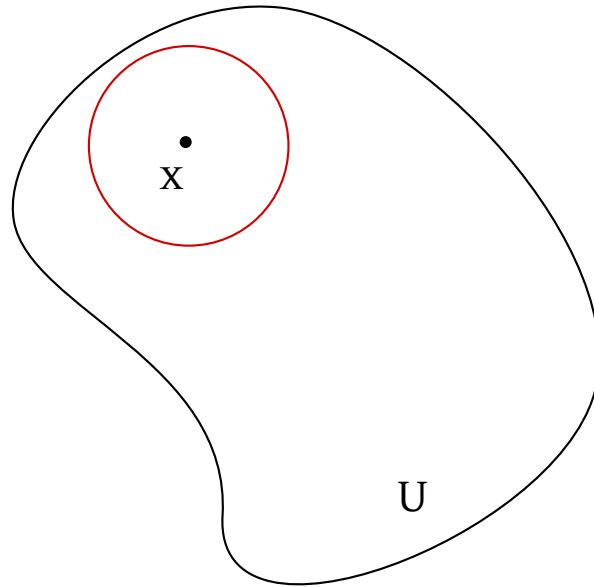


Figure 4: Neighborhood of  $x$

*This lecture took place on 2018/03/13.*

TODO I missed the first twenty minutes (including Satz 3 and 4)

*Proof.* Direction  $\Rightarrow$ .

Let  $f$  be continuous in  $X$  and let  $O \subseteq Y$  be open. Let  $U = f^{-1}(O)$  and choose  $x_0 \in U$ . Then  $f(x_0) \in O$ , hence  $O$  is a neighborhood of  $f(x_0)$ . By Theorem 5.2 (b), it follows that  $U = f^{-1}(O)$  is a neighborhood of  $x_0$ .

Hence,  $U$  is neighborhood of every of its points, hence open in  $X$ .

Direction  $\Leftarrow$ .

Let the preimages of open sets be open and  $x_0 \in X$  and  $y_0 = f(x_0)$ . Let  $V$  be a neighborhood of  $y_0 = f(x_0)$ , hence  $\exists \varepsilon > 0 : K_\varepsilon(f(x_0)) \subseteq V$ . Because  $K_\varepsilon(f(x_0))$  is an open set, it holds that  $f^{-1}(K_\varepsilon(f(x_0))) \in x_0$  is open in  $X$ .

Therefore, there exists  $\delta > 0$  such that  $K_\delta(x_0) \subseteq f^{-1}(K_\varepsilon(f(x_0))) \subseteq f^{-1}(V)$ . Hence,  $f^{-1}(V)$  is a neighborhood of  $x_0$ . Then by Theorem 5.2 (b), it follows that  $f$  is continuous in  $x_0$  (chosen arbitrarily). Hence  $f$  is continuous on  $X$ .  $\square$

## Variations of continuity notions

**Definition 2.1.** Let  $f : X \rightarrow Y$  be given. We call “ $f$  uniformly continuous on  $X$ ” if

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall x, y \in X \wedge d_X(x, y) < \delta \implies d_Y(f(x), f(y)) < \varepsilon$$

**Remark 2.1.** Compare it with the definition of “continuous in  $X$ ”:

$$\forall x \in X \forall \varepsilon > 0 \exists \delta > 0 : \forall y \in X : d_X(x, y) < \delta \implies d_Y(f(x), f(y)) < \varepsilon$$

The difference is the location of the  $\forall x \in X$  quantifier.

Every uniformly continuous map is continuous.

Example:  $f : (0, \infty) \rightarrow (0, \infty)$  with  $f(x) = \frac{1}{x}$  is continuous, but not continuously continuous.

**Definition 2.2.**  $f : X \rightarrow Y$  is called Lipschitz continuous with Lipschitz constant  $L \geq 0$  if  $\forall x, y \in X : d_Y(f(x), f(y)) \leq L \cdot d_X(x, y)$ .

Rudolf Lipschitz [1832–1903], University of Bonn

**Theorem 2.1.** Every Lipschitz continuous function is uniformly continuous.

*Proof.* For  $\varepsilon > 0$ , choose  $\delta = \frac{\varepsilon}{L+1}$ . Then it holds that  $d_X(x, y) < \delta = \frac{\varepsilon}{L+1} \implies d_Y(f(x), f(y)) \leq L \cdot d_X(x, y) < \frac{L}{L+1} \cdot \varepsilon < \varepsilon$ .  $\square$

- Most often  $X \subseteq V$ ,  $Y \subseteq W$ .  $V$  and  $W$  are normed vector spaces and  $d(x, y) = \|x - y\|$

**Definition 2.3.** A Lipschitz continuous map  $f : X \rightarrow X$  with Lipschitz constant  $L < 1$  is called contraction on  $X$ . Compare with Figure 5

**Theorem 2.2** (Banach fixed-point theorem). Let  $f : X \rightarrow X$  be a contraction and  $X$  be complete. Then there exists a uniquely defined  $\hat{x} \in X$  such that  $\hat{x} = f(\hat{x})$ .  $\hat{x}$  is called fixed point on  $f$ . Furthermore it holds that  $x_0 \in X$  is arbitrary and  $x_n = f(x_{n-1})$  for all  $n \geq 1$ .

$$\lim_{n \rightarrow \infty} x_n = \hat{x}$$

TODO drawing Banach’s fixed point theorem

*Proof.* Let  $x_0 \in X$  be arbitrary.  $x_n$  is constructed inductively by  $x_n = f(x_{n-1})$  for all  $n \geq 1$ .

**Claim.**  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence in  $X$ .

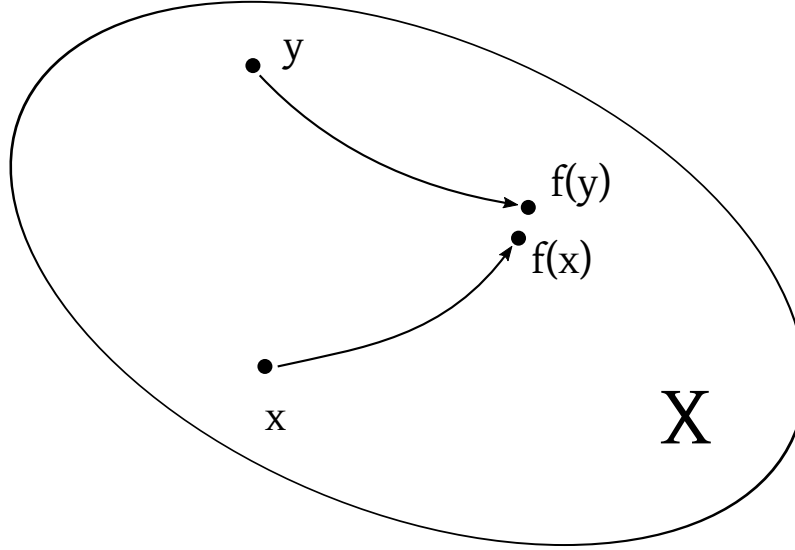


Figure 5: A contraction maps to points closer to each other

$$d(x_n, x_{n+k}) \leq d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \cdots + d(x_{n+k-1}, x_{n+k})$$

by triangle inequality

$$\begin{aligned} &= d(x_n, x_{n+1}) + d(f(x_n), f(x_{n+1})) + d(f(x_{n+1}), f(x_{n+2})) + \cdots + d(f(x_{n+k-2}), f(x_{n+k-1})) \\ &\leq d(x_n, x_{n+1}) + L(d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \cdots + d(x_{n+k-2}, x_{n+k-1})) \end{aligned}$$

this inequality is given by contraction

$$\begin{aligned}
&= d(x_n, x_{n+1})(1+L) + L(d(f(x_n), f(x_{n+1})) + \cdots + d(f(x_{n+k-3}), f(x_{n+k-2}))) \\
&\leq d(x_n, x_{n+1})(1+L) + L^2[d(x_n, x_{n+1}) + \cdots + d(x_{n+k-3}, x_{n+k-2})] \\
&\leq \cdots \leq d(x_n, x_{n+1})(1+L+L^2+\cdots+L^{k-1}) \\
&= d(f(x_{n-1}), f(x_n)) \left( \sum_{j=0}^{k-1} L^j \right) \leq Ld(x_{n-1}, x_n) \cdot \left( \sum_{j=0}^{k-1} L^j \right) \\
&\leq L^n d(x_0, x_1) \cdot \underbrace{\left( \sum_{j=1}^{k-1} L^j \right)}_{\leq \sum_{j=0}^{\infty} L^j = \frac{1}{1-L}} \\
&\leq \frac{L^n}{1-L} d(x_0, x_1) \\
d(x_n, x_{n+k}) &\leq \frac{L^n}{1-L} d(x_0, x_1) \forall n \in \mathbb{N} \forall k \in \mathbb{N}_0
\end{aligned}$$

with  $0 \leq L < 1$ .

$$\begin{aligned}
&\underbrace{\frac{L^n}{1-L} d(x_0, x_1)}_{>0} < \varepsilon \iff \\
L^n &< \frac{\varepsilon}{d(x_0, x_1) + 1} (1-L) \quad (L > 0) \\
\iff n \underbrace{\ln L}_{<0} &< \ln \frac{\varepsilon}{d(x_0, x_1) + 1} (1-L) \\
\iff n &> \frac{1}{\ln L} \ln \frac{\varepsilon}{d(x_0, x_1) + 1} (1-L)
\end{aligned}$$

Hence  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence in  $X$ .  $X$  is complete, hence  $\exists \hat{x} \in X$  :  $\hat{x} = \lim_{n \rightarrow \infty} x_n$ . Because  $\hat{x} = \lim_{n \rightarrow \infty} x_{n+1} = \lim_{n \rightarrow \infty} f(x_n) = f(\hat{x})$  where the last equality is given by continuity of  $f$ . Therefore  $\hat{x} = f(\hat{x})$  is a fixed point on  $f$ .

It remains to prove uniqueness:

Let  $\tilde{x} = f(\tilde{x})$ . Then it holds that  $d(\hat{x}, \tilde{x}) = d(f(\hat{x}), f(\tilde{x})) \leq Ld(\hat{x}, \tilde{x})$  with  $L < 1$ . If  $d(\hat{x}, \tilde{x}) > 0$ , then  $1 \leq L$ . This is a contradiction. Hence  $d(\hat{x}, \tilde{x}) = 0$  must hold, hence  $\hat{x} = \tilde{x}$ .  $\square$

**Remark 2.2.** • The Fixed Point Theorem provides an algorithm for numeric computation of  $\hat{x}$ .

- It can reformulate problems  $f(x) = 0$  (in  $\mathbb{R}^n$ ) to

$$f(x) + x = g(x) = x$$

- *Attention: The conditions of the Fixed Point Theorem cannot be changed to the structure*

$$d(f(x), f(y)) < L \cdot d(x, y) \wedge L \leq 1$$

or

$$d(f(x), f(y)) \leq L \cdot d(x, y) \wedge L < 1$$

*This will be discussed in the practicals.*

**Lemma 2.1.** *Let  $X$  be a complete metric space. Let  $A \subseteq X$  be closed. Then  $(A, d)$  is itself a complete, metric space.*

*Proof.* Let  $(x_n)_{n \in \mathbb{N}}$  be a Cauchy sequence in  $A$  ( $x_n \in A$ ). Then  $(x_n)_{n \in \mathbb{N}}$  is also a Cauchy sequence in  $X$ . Because  $X$  is complete, there exists  $\hat{x} = \lim_{n \rightarrow \infty} x_n$ . Therefore  $\hat{x}$  is a contact point of  $A$ . Because  $A$  is closed, it holds that  $\hat{x} \in A$ .

Therefore every Cauchy sequence in  $A$  has a limit point in  $A$ , hence  $A$  is complete.  $\square$

## Compactness

**Definition 3.1.** *A metric space  $(X, d)$  is called compact if every sequence  $(x_n)_{n \in \mathbb{N}}$  has a convergent subsequence.*

*Specifically, this definition is called sequence compactness. The other definition defines compactness as closed and bounded subset of an Euclidean space. The latter definition only works for a subset of branches in mathematics. Therefore the generalization is recommended to be remembered.*

**Lemma 3.1.** *Let  $X$  be a compact, metric space. Then  $X$  is complete.*

*Proof.* Let  $(x_n)_{n \in \mathbb{N}}$  be a Cauchy sequence in  $X$ . By compactness, it follows that  $\exists (x_{n_k})_{k \in \mathbb{N}}$  with  $\lim_{k \rightarrow \infty} x_{n_k} = \hat{x}$ . Choose  $\varepsilon > 0$  arbitrary and  $L$  large enough such that  $k \geq L \implies d(x_{n_k}, \hat{x}) < \frac{\varepsilon}{2}$ . Furthermore choose  $N \in \mathbb{N}$  large enough such that  $n, m \geq N \implies d(x_n, x_m) < \frac{\varepsilon}{2}$  (satisfied, because  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence). Choose  $K \geq L$  and  $n_k \geq N$ . Let  $n_k$  be fixed this way. Then it holds  $\forall n \geq N : d(x_n, \hat{x}) \leq d(x_n, x_{n_k}) + d(x_{n_k}, \hat{x}) < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon$ . The first summand  $\frac{\varepsilon}{2}$  results from the Cauchy sequence property, the second summand  $\frac{\varepsilon}{2}$  results by convergence of  $(x_{n_k})$ . Hence  $(x_n)_{n \in \mathbb{N}}$  is convergent with limit  $\hat{x}$ .  $\square$

**Definition 3.2.** *A metric space  $X$  is called bounded if there exists  $M \geq 0$ , such that  $d(x, y) \leq M \forall x, y \in X$ .*

It holds for arbitrary  $x \in X$  that  $\forall y \in X : y \in K_M(x)$ . So,  $X \subseteq K_M(x)$ . On the contrary, let  $X \subseteq \overline{K_M(x)}$  and let  $y \in X$  and  $z \in X$  be arbitrary. Then it holds that  $d(y, z) \leq d(y, x) + d(x, z) \leq M + M = 2M$ . Hence,  $X$  is bounded.

So,  $X$  is bounded  $\iff \exists x \in X \wedge M \geq 0 : X \subseteq \overline{K_M(x)}$ .



**Lemma 3.2.** *Every compact, metric space is also bounded.*

*Proof.* Assume  $X$  is unbounded.

We construct a sequence of points  $(x_n)_{n \in \mathbb{N}}$  with  $d(x_n, x_m) \geq 1 \forall n, m \in \mathbb{N}$  with  $n \neq m$ .

We use the following auxiliary result: Let  $B = \bigcup_{j=1}^n K_1(z_j)$  for arbitrary  $n \in \mathbb{N}$  and arbitrary  $z_j \in X$ . Then  $B$  is bounded. This result will be part of the practicals.

We construct  $(x_n)_{n \in \mathbb{N}}$  inductively. Choose arbitrary  $x_0 \in X$ . Assume  $(x_1, \dots, x_{n-1})$  are already found. Then it holds that

$$\underbrace{X}_{\text{unbounded}} \not\subseteq \underbrace{\bigcup_{j=1}^{n-1} K_1(x_j)}_{\text{bounded}}$$

hence  $\exists x_n \in X \setminus \bigcup_{j=1}^{n-1} K_1(x_j)$ . Because  $x_n \notin K_1(x_j)$  for  $j = 0, \dots, n-1$  it holds that  $d(x_n, x_j) \geq 1 \forall j < n$ . We get  $(x_n)_{n \in \mathbb{N}}$  with  $d(x_n, x_m) \geq 1 \forall n \in \mathbb{N} \forall m < n$ , hence  $m \neq n$ . Because  $d(x_n, x_m) \geq 1$ , i.e.  $(x_n)_{n \in \mathbb{N}}$  does not contain any Cauchy sequence as subsequence,  $(x_n)_{n \in \mathbb{N}}$  does not have a convergent subsequence. Therefore  $X$  is not compact.  $\square$

*This lecture took place on 2018/03/15.*

Every compact metric space is bounded. Every compact metric space is complete. In  $\mathbb{C}(\mathbb{R}^n)$  it holds that  $A \subseteq \mathbb{C}$  is closed. Then  $A$  with metric  $d(x, y) = |x - y|$  is complete as metric space.

If  $A$  is additionally bounded, then  $A$  is compact (see course Analysis 1, Bolzano-Weierstrass).

Attention! Let  $V$  be an infinite-dimensional, complete, normed vector space.

For example,  $V = C([a, b], \mathbb{R}) = \{f : [a, b] \rightarrow \mathbb{R} \mid f \text{ is continuous in } [a, b]\}$  with norm  $\|f\|_\infty = \max\{|f(x)| : x \in [a, b]\}$  and metric  $\|f - g\|_\infty = \max\{|f(x) - g(x)| : x \in [a, b]\}$ .

$C([a, b], \mathbb{R})$  is a complete, normed vector space. It holds that  $\overline{K_1(0)}$  is not compact in  $C([a, b], \mathbb{R})$  (i.e.  $V$ , for every infinite-dimensional vector space).

Again: do not remember "compactness" not as closed and bounded, as this only holds in the finite-dimensional case.

In the last proof, we have shown: If a sequence  $(x_n)_{n \in \mathbb{N}}$  with  $x_n \in X$  and  $d(x_n, x_m) \geq 1$  (or  $\geq \varepsilon$ )  $\forall n \neq m \implies X$  is not compact.

**Definition 3.3.**  $X$  is called *totally bounded*, if for every  $\varepsilon > 0$ , finitely many points  $X_1^\varepsilon, X_2^\varepsilon, \dots, X_{N(\varepsilon)}^\varepsilon$  such that  $X \subseteq \bigcup_{i=1}^{N(\varepsilon)} K_\varepsilon(X_i^\varepsilon)$ .

Hence, for every  $x \in X$ , there exists some  $X_j^\varepsilon$  such that  $d(X, X_j^\varepsilon) < \varepsilon$ .

**Remark 3.1** (For the practicals). Let  $X$  be totally bounded, then there does not exist some sequence  $(x_n)_{n \in \mathbb{N}}$  with  $d(x_n, x_m) \geq \varepsilon \forall n \neq m$ . It holds, that  $X$  is compact if and only if  $X$  is totally bounded and complete.

**Theorem 3.1.** Let  $f : X \rightarrow Y$  be continuous. Let  $X$  be compact. Then image  $f(X) \subseteq Y$  is also compact.

Be aware, that this proof is a common exam question and students often begin with the wrong order.

*Proof.* Let  $(y_n)_{n \in \mathbb{N}}$  be an arbitrary sequence in  $f(X)$ . Show that  $(y_n)_{n \in \mathbb{N}}$  has a convergent subsequence. Because  $y_n \in f(X)$ , there exists at least one  $x_n$  with  $y_n = f(x_n)$ . Then  $(x_n)_{n \in \mathbb{N}}$  is a sequence in  $X$ ,  $X$  is compact, hence there exists a subsequence  $(x_{n_k})_{k \in \mathbb{N}}$  with  $\lim_{k \rightarrow \infty} x_{n_k} = \hat{x} \in X$ . Because  $f$  is continuous, it holds that  $\lim_{k \rightarrow \infty} f(x_{n_k}) = \lim_{k \rightarrow \infty} y_{n_k} = f(\hat{x}) =: \hat{y}$ . So  $(y_n)_{n \in \mathbb{N}}$  has a convergent subsequence. Hence  $f(X) \subseteq Y$  is compact.  $\square$

**Theorem 3.2** (Conclusion). Let  $X$  be compact,  $f : X \rightarrow \mathbb{R}$  continuous on  $X$ . Then there exists  $\underline{x}$  and  $\bar{x} \in X$ , such that

$$f(\underline{x}) \leq f(x) \leq f(\bar{x}) \quad \forall x \in X$$

Hence,  $f$  has a maximum and a minimum.

*Proof.*  $f(X) \subseteq \mathbb{R}$  is compact (Theorem 3.1), hence  $f(X)$  is bounded and complete, hence closed in  $\mathbb{R}$ . There exists  $\xi \in \mathbb{R}$  with  $\xi = \sup f(X)$ , because  $f(X)$  is complete and  $\xi$  is a contact point of  $f(X)$ , it holds that  $\xi \in f(X)$ , hence  $\exists \bar{x} \in X : \xi = f(\bar{x})$ . Furthermore,  $\xi$  is an upper bound of  $f(X) \rightarrow f(x) \leq \xi = f(\bar{x}) \forall x \in X$ .

For  $\underline{x}$ , it works the same way.  $\square$

**Theorem 3.3.** Let  $f : X \rightarrow Y$  is continuous on  $X$  and  $X$  is compact. Then  $f$  is uniformly continuous on  $X$ .

*Indirect proof.* Assume  $X$  is compact,  $f : X \rightarrow Y$  is continuous, but not uniformly continuous. Uniform continuity:

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall x, y \in X : d_X(x, y) < \delta \implies d_Y(f(x), f(y)) < \varepsilon$$

Not uniformly continuous:

$$\exists \varepsilon > 0 \forall \delta_n = \frac{1}{n} (n \in \mathbb{N}) \exists x_n, y_n \in X : d_X(x_n, y_n) < \frac{1}{n} \wedge d_Y(f(x_n), f(y_n)) \geq \varepsilon$$

Now choose some  $(x_n)$  and  $(y_n)$ . We will use a specific  $\varepsilon$  later. Because  $X$  is compact, there exists a convergent subsequence of  $(x_n)_{n \in \mathbb{N}}$ , hence  $\lim_{k \rightarrow \infty} x_{n_k} = \hat{x}$ . The sequence  $(y_{n_k})_{k \in \mathbb{N}}$  has a convergent subsequence itself:

$$\lim_{l \rightarrow \infty} y_{(n_k)_l} = \hat{y}$$

Because  $(x_{n_k})_{k \in \mathbb{N}}$  is convergent, the subsequence  $(x_{(n_k)_l})_{l \in \mathbb{N}}$  converges towards the same limit  $\hat{x}$ .

$$\tilde{x}_l := x_{n_{k_l}} \quad \tilde{y}_l := y_{n_{k_l}}$$

because  $l \leq n_{k_l}$  and

$$d_X(\tilde{x}_l, \tilde{y}_l) = d_X(x_{n_{k_l}}, y_{n_{k_l}}) \underbrace{\quad}_{\text{by assumption}} < \frac{1}{n_{k_l}} \leq \frac{1}{l}$$

**Claim.** For  $\hat{x} = \lim_{l \rightarrow \infty} \tilde{x}_l$  and  $\hat{y} = \lim_{l \rightarrow \infty} \tilde{y}_l$ , it holds that  $\hat{x} = \hat{y}$ . Let  $\varepsilon' > 0$  be arbitrary,  $l$  large enough such that

- $\frac{1}{l} < \frac{\varepsilon'}{3}$
- $d_X(\tilde{x}_l, \hat{x}) < \frac{\varepsilon'}{3}$
- $d_X(\tilde{y}_l, \hat{y}) < \frac{\varepsilon'}{3}$

Therefore it holds that

$$d_X(\hat{x}, \hat{y}) \leq d_X(\hat{x}, \tilde{x}_l) + d_X(\tilde{x}_l, \tilde{y}_l) + d_X(\tilde{y}_l, \hat{y}) < \frac{\varepsilon'}{3} + \frac{1}{l} + \frac{\varepsilon'}{3} < \varepsilon'$$

Therefore it holds that  $d_X(\hat{x}, \hat{y}) = 0$ , hence  $\hat{x} = \hat{y}$ . Because  $f$  is continuous and  $\tilde{x}_l \rightarrow \hat{x}$  and  $\tilde{y}_l \rightarrow \hat{x}$ , there exists  $l \in \mathbb{N}$  such that

$$d_Y(f(\tilde{x}_l), f(\hat{x})) < \frac{\varepsilon}{2}$$

and also

$$d_Y(f(\tilde{y}_l), f(\hat{x})) < \frac{\varepsilon}{2}$$

where  $\varepsilon$  is the epsilon from the very beginning of the proof.

$$\implies d_Y(f(\tilde{x}_l), f(\hat{x})) + d_Y(f(\tilde{y}_l), f(\hat{x})) < \varepsilon$$

This contradicts to

$$d_Y(f(\tilde{x}_l), f(\tilde{y}_l)) = d_Y(f(x_{n_{k_l}}), f(y_{n_{k_l}})) \geq \varepsilon$$

Hence,  $f$  is uniformly continuous. □

Subsets of  $(\mathbb{R}^n, \|\cdot\|)$  (or  $(V, \|\cdot\|)$ ) as metric spaces.

We consider  $\Omega \subseteq V$  where  $V$  is a normed vector space.  $(\Omega, d)$  is  $d(x, y) = \|x - y\|$  is a metric space.

$$K_r^\Omega(x) = \{y \in \Omega \mid \|y - x\| < r\}$$

is a sphere with center  $x$  and radius  $r$  in  $\Omega$ .

$$K_r^V(x) = \{y \in V \mid \|y - x\| < r\}$$

obvious:  $K_r^\Omega(x) = \Omega \cap K_r^V(x)$ .

TODO drawing 08

**Lemma 3.3.** *Let  $O' \subseteq \Omega \subseteq V$ .*

*Then it holds that  $O'$  is open in  $\Omega \iff$  there exists  $O \subseteq V$  is open in  $V$  such that  $O' = O \cap \Omega$ .*

*Proof.*  $\Rightarrow$  Let  $O' \subseteq \Omega$  be open in  $\Omega$  and  $x \in O'$  be arbitrary. Then there exists  $r(x) > 0 : x \in K_{r(x)}^\Omega(x) = K_{r(x)}^V(x) \cap \Omega \subseteq O'$ . Then it holds that

$$O' = \bigcup_{x \in O'} \{x\} \subseteq \bigcup_{x \in O'} K_{r(x)}^\Omega(x) = \left( \bigcup_{x \in O'} (K_{r(x)}^V(x) \cap \Omega) \right) = \underbrace{\left( \bigcup_{x \in O'} K_{r(x)}^V(x) \right)}_{=O \subseteq V \text{ is open in } V} \cap \Omega \subseteq O'$$

So every  $\subseteq$  in this inclusion chain is actually an equality. So  $O' = O \cap \Omega$ .

$\Leftarrow$  Let  $O' = O \cap \Omega$  and  $x \in O'$  be chosen arbitrarily. Because  $x \in O$  and  $O$  is open in  $V$ .

$$\exists r > 0 : K_r^V(x) \subseteq O \implies \underbrace{K_r^V(x) \cap \Omega}_{=K_r^\Omega(x)} \subseteq O \cap \Omega = O'$$

So  $O'$  is open in  $\Omega$ .

□

**Remark 3.2.**  $A' \subseteq \Omega$  is closed in  $\Omega \iff \exists A \subseteq V$  closed in  $V$  with  $A' = A \cap \Omega$ .

**Remark 3.3.** Let  $T$  be an arbitrary topological space with topology  $\tau$  on  $T$  (a system of open sets). Furthermore let  $\Omega \subseteq T$ .

Then  $\Omega$  itself is a topological space with  $O' \subseteq \Omega$  is open  $\iff \exists O \subset T$  open in  $T$  with  $O' = O \cap \Omega$ .

Also called “subspace topology”, “trace topology” or “relative topology”.

Attention!

$$O' \subseteq \Omega \text{ open in } \Omega \implies O' \text{ open in } V$$

does *not* hold in general.

**Example 3.1.**

$$\Omega = [0, 1] \cap [0, 1)$$

$K_{\frac{1}{2}}(p) \cap \Omega$  is open in  $\Omega$  but not open in  $\mathbb{R}^2$ .

Analogously,

$$A' \subseteq \Omega \text{ is closed} \implies A' \text{ closed in } V$$

does *not* hold in general.

**Remark 3.4.**  $K$  is compact in  $\Omega \implies K$  is compact in  $V$

Let  $(x_n)_{n \in \mathbb{N}}$  is a sequence in  $K$ . Compactness  $\implies \exists (x_{n_k})_{k \in \mathbb{N}} : x_{n_k} \rightarrow \hat{x}$  for  $k \rightarrow \infty$  and  $K \subseteq \Omega \subseteq V$ .

Then  $(x_n)_{n \in \mathbb{N}}$  also has a convergent subsequence in  $V$ .

## Normed vector spaces

**Definition 3.4.** Let  $V$  be a vector space and  $\|\cdot\|_1$  and  $\|\cdot\|_2$  are normed on  $V$ . We say,  $\|\cdot\|_1$  is equivalent to norm  $\|\cdot\|_2$ , if  $0 < m \leq M$  exist such that

$$m \|v\|_1 \leq \|v\|_2 \leq M \|v\|_1 \quad \forall v \in V$$

**Remark 3.5.** Equivalence of norms is an equivalence relation.

**reflexivity** Let  $m = M = 1$ . TODO

**symmetry**

$$\begin{aligned} m \|v\|_1 \leq \|v\|_2 &\implies \|v\|_1 \leq \frac{1}{m} \|v\|_2 \wedge \|v\|_2 \leq M \cdot \|v\|_1 \implies \frac{1}{M} \|v\|_2 \leq \|v\|_1 \\ &\implies \underbrace{\frac{1}{M}}_{m'} \|v\|_2 \leq \|v\|_1 \leq \underbrace{\frac{1}{m}}_{M'} \|v\|_2 \end{aligned}$$

hence the equivalence relations of norms are symmetrical.

**transitivity** Let  $\|\cdot\|_1$  and  $\|\cdot\|_2$  be equivalent. Let  $\|\cdot\|_2$  and  $\|\cdot\|_3$  be equivalent.

$$\begin{aligned} m \cdot \|v\|_1 &\leq \|v\|_2 \leq M \|v\|_1 \quad \forall v \in V \\ m' \cdot \|v\|_2 &\leq \|v\|_3 \leq M' \|v\|_2 \quad \forall v \in V \\ \implies m \cdot m' \|v\|_1 &\leq m' \|v\|_2 \leq \|v\|_3 \leq M' \|v\|_2 \leq M \cdot M' \|v\|_1 \end{aligned}$$

This lecture took place on 2018/03/20.

Addendum:

- Let  $(x_n)_{n \in \mathbb{N}}$  be in  $(X, d)$ , then it holds that

$$\underbrace{x = \lim_{n \rightarrow \infty} x_n}_{\text{in } X} \iff \underbrace{\lim_{n \rightarrow \infty} d(x_n, x) = 0}_{\text{in } \mathbb{R}}$$

$$(\iff \lim_{n \rightarrow \infty} \|x_n - x\| = 0 \text{ in normed vector spaces } V)$$

- Inversed triangle inequality: Let  $V$  be a normed vector space. Let  $x, y \in V$ .

$$\|x\| = \|x - y + y\| \leq \|x - y\| + \|y\|$$

Hence,

$$\|x\| - \|y\| \leq \|x - y\|$$

By exchanging  $x$  and  $y$ ,

$$\|y\| - \|x\| \leq \|x - y\|$$

Hence, it holds that

$$\left| \|x\| - \|y\| \right| \leq \|x - y\|$$

- Define the map  $n : V \rightarrow [0, \infty)$  on  $(V, \|\cdot\|)$  with  $n(x) = \|x\|$ . Then  $n$  is continuous on  $V$  because

$$|n(x_1) - n(x_2)| = \left| \|x_1\| - \|x_2\| \right| \leq \|x_1 - x_2\|$$

Hence,  $n$  is Lipschitz continuous with constant 1.

Regarding the equivalence of norms:

**Lemma 3.4.** Let  $\|\cdot\|_1$  and  $\|\cdot\|_2$  be equivalent norms on  $V$ . Then it holds that

1.  $\lim_{n \rightarrow \infty} \|x_n - x\|_1 = 0 \iff \lim_{n \rightarrow \infty} \|x_n - x\|_2 = 0$ , hence  $(x_n)_{n \in \mathbb{N}}$  is convergent with limit  $x$  in regards of  $\|\cdot\|_1 \iff (x_n)_{n \in \mathbb{N}}$  is convergent with limit  $x$  in regards of  $\|\cdot\|_2$ .
2.  $O \subseteq V$  is open in regards of  $\|\cdot\|_1 \iff O$  is open in regards of  $\|\cdot\|_2$ , hence  $\tau_1 = \tau_2$  (topologies are equivalent).
3.  $K \subseteq V$  is compact in regards of  $\|\cdot\|_1 \iff K$  is compact in regards of  $\|\cdot\|_2$ .

*Proof.* Let  $\|\cdot\|_1$  and  $\|\cdot\|_2$  are equivalent, hence  $\exists m, M > 0 : m\|x\|_1 \leq \|x\|_2 \leq M\|x\|_1 \forall x \in V$ .

1. Let  $\varepsilon > 0$  and  $\lim_{n \rightarrow \infty} \|x_n - x\|_1 = 0$ . Choose  $N \in \mathbb{N}$  such that  $n \geq N \implies \|x_n - x\|_1 < \frac{\varepsilon}{M}$ . For those  $n$  it holds that

$$\|x_n - x\|_2 \leq M\|x_n - x\|_1 < \frac{\varepsilon}{M} \cdot M = \varepsilon$$

Hence,  $\lim_{n \rightarrow \infty} \|x_n - x\|_2 = 0$ .

2.  $K_r^2(x) = \{y \in V \mid \|y - x\|_2 < r\}$ . For  $y \in K_r^2(x)$  it holds that

$$m \|y - x\|_1 \leq \|y - x\|_2 < r$$

hence,

$$\|y - x\|_1 < \frac{r}{m} \implies y \in K_{\frac{r}{m}}^1(x)$$

hence  $K_r^2(x) \subseteq K_{\frac{r}{m}}^1(x)$ . Let  $y \in K_{\frac{r}{m}}^1(x)$ . Then it holds that,

$$\|y - x\|_2 \leq M \|y - x\|_1 < M \cdot \frac{r}{M} = r$$

hence  $y \in K_r^2(x) \implies K_{\frac{r}{M}}^1(x) \subseteq K_r^2(x)$ . Now let  $O$  be open in regards of  $\|\cdot\|_2$ , hence

$$\forall x \in O \exists r > 0 : K_r^2(x) \subseteq O \implies K_{\frac{r}{M}}^1(x) \subseteq K_r^2(x) \subseteq O$$

so  $O$  is open in regards of  $\|\cdot\|_1 \implies O$  is open in regards of  $\|\cdot\|_2$  analogously.

3. Let  $K$  be compact in regards of  $\|\cdot\|_1$  and  $(x_n)_{n \in \mathbb{N}}$  be a sequence in  $K$ . Then there exists a subsequence  $(x_{n_k})_{k \in \mathbb{N}}$  with  $\|x_{n_k} - x\|_1 \rightarrow 0$  for  $k \rightarrow \infty$   
by the first property  $\implies \|x_{n_k} - x\|_2 \rightarrow 0$ . Hence  $(x_{n_k})_{k \in \mathbb{N}}$  is also a convergent subsequence in regards of  $\|\cdot\|_2$ .

□

**Remark 3.6** (Proven in the practicals). Let  $(x_n)_{n \in \mathbb{N}}$  be a sequence in  $\mathbb{R}^k$

$$\|x\|_\infty = \max \{ |x^i| \mid i = 1, \dots, n \}$$

$$x = \begin{bmatrix} x^1 \\ x^2 \\ \vdots \\ x^k \end{bmatrix}$$

It holds that  $\lim_{n \rightarrow \infty} \|x_n - x\|_\infty = 0 \iff \lim_{n \rightarrow \infty} |x_n^i - x^i| = 0$  for all  $i \in \{1, \dots, k\}$ .

**Theorem 3.4** (Bolzano-Weierstrass theorem in  $\mathbb{R}^k$ ). Let  $K \subseteq \mathbb{R}^k$  be closed and bounded. Then  $K$  is compact in  $(\mathbb{R}^k, \|\cdot\|_\infty)$ .

*Proof.* Let  $\|x\|_\infty \leq M \forall x \in K \iff |x^i| \leq M \forall x \in K$  and  $i \in \{1, \dots, k\}$ . Choose  $(x_n)_{n \in \mathbb{N}}$  an arbitrary sequence in  $K$   $(x_n^i)_{n \in \mathbb{N}}$  is a bounded sequence in  $\mathbb{R}$ . Because  $(x_n^1)_{n \in \mathbb{N}}$  is bounded, there exists a convergent subsequence  $(x_{n_1}^1)_{l_1 \in \mathbb{N}}$

$$\lim_{l_1 \rightarrow \infty} x_{n_1}^1 = x^1$$

Consider  $(x_{n_{l_1}}^2)_{l_1 \in \mathbb{N}}$ , a subsequence of a bounded sequence, hence bounded itself. By the Bolzano-Weierstrass theorem in  $\mathbb{R}$ , there exists a convergent subsequence  $(x_{n_{l_1 l_2}}^2)_{l_2 \in \mathbb{N}}$  with  $\lim_{l_2 \rightarrow \infty} x_{n_{l_1 l_2}}^2 = x^2$ . Consider  $x_{n_{l_1 l_2}}^1$  as subsequence of  $x_{n_{l_1}}^1$  is already convergent, hence  $\lim_{l_2 \rightarrow \infty} x_{n_{l_1 l_2}}^1 = x^1$ . Furthermore, up to index  $i$ , it holds that:

$$\lim_{l_k \rightarrow \infty} x_{n_{l_1 l_2 \dots l_k}} = x^i \quad \text{for } i = 1, \dots, k$$

Hence, with  $\tilde{x}_{l_k} = x_{n_{l_1 l_2 \dots l_k}}$  gives a subsequence of  $x_n$ , converging by each coordinate. Thus,

$$\lim_{l_k \rightarrow \infty} \|\tilde{x}_{l_k} - x\|_\infty = 0$$

Because  $\tilde{x}_{l_k} \in K$  and  $K$  be closed, it holds that  $x \in K$ . Hence  $K$  is compact.  $\square$

**Theorem 3.5** (Norm equivalence in  $\mathbb{R}^k$ ). *In  $\mathbb{R}^k$ , all norms are equivalent.*

*Proof.* We show: Let  $\|\cdot\|$  be an arbitrary norm on  $\mathbb{R}^n$ . Then  $\|\cdot\|$  is equivalent to  $\|\cdot\|_\infty$ . By transitivity of norm equivalence, two arbitrary norms are equivalent to each other.

1. Let  $(e_1, e_2, \dots, e_k)$  be the canonical basis in  $\mathbb{R}^k$ .

$$x = \begin{bmatrix} x^1 \\ \vdots \\ x^k \end{bmatrix} = \sum_{j=1}^k x^j e_j$$

Furthermore let  $M' = \max \{\|e_j\| : j = 1, \dots, k\}$  with  $\|e_j\| \neq 0$  and  $M' > 0$ . Then it holds that

$$\|x\| = \left\| \sum_{j=1}^k x^j e_j \right\| \leq \sum_{j=1}^k \|x^j e_j\| = \sum_{j=1}^k |x^j| \|e_j\| \leq M' \sum_{j=1}^k \underbrace{|x_j|}_{\leq \|x\|_\infty} \leq \underbrace{M' \cdot k}_M \|x\|_\infty = M \|x\|_\infty$$

2. We consider  $v : \mathbb{R}^k \rightarrow [0, \infty)$ .  $v(x) = \|x\|$  as map on  $(\mathbb{R}^k, \|\cdot\|_\infty)$ .

**Claim.**  $v$  is continuous on  $(\mathbb{R}^k, \|\cdot\|_\infty)$ .

*Proof.* Show that,

$$|v(x) - v(y)| = \left| \|x\| - \|y\| \right| \underbrace{\leq}_{\text{inversed triangle ineq.}} \|x - y\| \underbrace{\leq}_{\text{because of (1)}} M \|x - y\|$$

Hence  $v$  is Lipschitz continuous.  $\square$



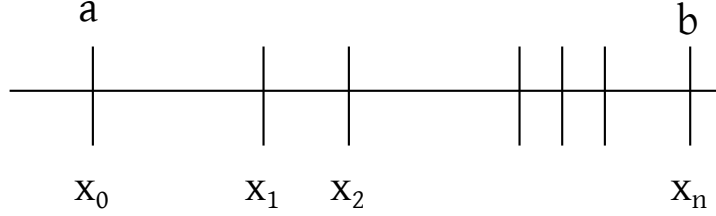


Figure 6: Illustration of a partition

We consider  $S_{\infty}^{k-1} = \{x \in \mathbb{R}^k \mid \|x\|_{\infty} = 1 = \text{boundary}(K_1^{\infty}(0))$ .  $S_{\infty}^{k-1}$  is bounded.

Let  $(x_n)_{n \in \mathbb{N}}$  is a sequence in  $S_{\infty}^{k-1}$  with  $x = \lim_{n \rightarrow \infty} x_n$ . Because  $n(x) = \|x\|_{\infty}$  is continuous, it holds that

$$\lim_{n \rightarrow \infty} \underbrace{\|x_n\|_{\infty}}_{=1} = \underbrace{\|x\|}_{=1}$$

Hence  $x \in S_{\infty}^{k-1}$ . Hence,  $S_{\infty}^{k-1}$  is closed in  $(\mathbb{R}^k, \|\cdot\|_{\infty})$ . Hence  $S_{\infty}^{k-1}$  is compact in  $(\mathbb{R}^k, \|\cdot\|_{\infty})$ ,  $\nu : S_{\infty}^{k-1} \rightarrow [0, \infty)$ , with  $S_{\infty}^{k-1}$  compact, is continuous. Has

a minimum  $n$  on  $S_{\infty}^{k-1}$ . Thus there exists  $\bar{x} \in S_{\infty}^{k-1} : \underbrace{m}_{>0} = \underbrace{\left\| \bar{x} \right\|}_{\neq 0} \leq$

$\|x\| \forall x \in S_{\infty}^{k-1}$ . Let  $x \in \mathbb{R}^k$  be arbitrary with  $x \neq 0$ . Then it holds that  $\frac{x}{\|x\|_{\infty}} \in S_{\infty}^{k-1}$  and it holds that

$$m \leq \left\| \frac{x}{\|x\|_{\infty}} \right\| = \frac{1}{\|x\|_{\infty}} \|x\| \implies m \|x\|_{\infty} \leq \|x\|$$

Inequality also holds true for  $x = 0$ .

□

## Integral calculus

**Definition 4.1.** Let  $a < b$  with  $a, b \in \mathbb{R}$ . We consider functions of  $[a, b]$ . We call  $(x_j)_{j=0}^n$  a partition of  $[a, b]$  if  $a = x_0 < x_1 < x_2 < \dots < x_n = b$ .  $x_j$  decomposes  $[a, b]$  in subintervals  $(x_{j-1}, x_j)$ .  $\varphi : [a, b] \rightarrow \mathbb{R}$  is called step function in  $[a, b]$  in regards of partition  $(x_j)_{j=0}^n$  if  $\varphi|_{(x_{j-1}, x_j)} = c_j$ , so constant for  $j = 1, \dots, n$ .

$\varphi$  is called step function in  $[a, b]$  if there exists a partition such that  $\varphi$  is a subsequence.

$$\tau[a, b] = \{\varphi : [a, b] \rightarrow \mathbb{R} : \varphi \text{ is subsequence}\}$$

- Let  $(\xi_i)_{i=0}^m$  be a partition of  $[a, b]$  and  $(x_j)_{j=0}^n$  is a partition as well. Then we call  $(\xi_i)_{i=0}^m$  a refinement of  $[a, b]$  and  $(x_j)_{j=1}^n$  as well. Then  $(\xi_i)_{i=0}^m$  is a refinement of  $(x_j)_{j=0}^k$  if  $\{x_0, x_1, \dots, x_n\} \subseteq \{\xi_0, \xi_1, \dots, \xi_m\}$

TODO drawing

Functions values in boundaries  $x_{j-1}$  and  $x_j$  do not have any constraints and will be relevant for an integral. A  $\varphi$  can be a step function in terms of many, various partitions.

**Lemma 4.1.** Let  $\varphi \in \tau[a, b]$  be a step function in terms of partition  $(x_j)_{j=0}^n$  and let  $(x_i)_{i=0}^n$  be a refinement of  $(x_j)_{j=0}^n$  in terms of  $(x_i)_{i=0}^m$ .

*Proof.* Refinement: For every  $j \in \{0, \dots, n\}$  there exists  $i_j \in \{0, \dots, m\}$  such that  $X_j = \xi_{i_j}$ ,  $i_0 = 0, i_n = m$ .  $i_{j-1} < i_j$ .

Let  $i \in \{1, \dots, m\}$ . Then there exists a uniquely determined  $j \in \{1, \dots, n\}$  such that  $\xi_{i_{j-1}} < \xi_i \leq \xi_{i_j}$

TODO drawing

Then it holds that  $(\xi_{i-1}, \xi_i) \subseteq \underbrace{(\xi_{i_{j-1}}, \xi_{i_j})}_{=(x_{j-1}, x_j)}$  and  $\varphi|_{(\xi_{i-1}, \xi_i)} = c_j = \text{const.}$  So  $\varphi$  is a

subsequence in regards of  $(\xi_i)_{i=0}^m$ . □

**Definition 4.2.** Let  $\varphi \in \tau[a, b]$  in terms of partition  $(X_j)_{j=0}^n$  with  $\varphi|_{(X_{j-1}, X_j)} = c_j$  and  $\Delta X_j = X_j - X_{j-1} > 0$  for  $g = 1, \dots, n$ . Then we define ...

$$\int_a^b \varphi dx = \sum_{j=1}^n c_j \Delta x_j$$

is called integral of  $\varphi$  in terms of partition  $(x_j)_{j=0}^n$

This lecture took place on 2018/03/22.

Step function  $\varphi$ .  $\varphi|_{x_{j-1}, x_j} = c_j$

$$\delta x_j = x_j - x_{j-1}$$

$$\int_a^b \varphi dx = \sum_{j=1}^n c_j \cdot \delta x_j$$

**Lemma 4.2.** Let  $(x_i)_{i=0}^n$  be a partition of  $[a, b]$  and  $(\xi_i)_{i=0}^m$  be a refinement of  $(x_j)_{j=0}^n$ . Furthermore let  $\varphi$  be a subsequence with respect to  $(x_j)_{j=0}^n$  (so also with respect to  $(\xi_j)_{i=0}^m$ ). Then the integrals of  $\varphi$  with respect to  $(x_j)_{j=0}^n$  and  $(\xi_i)_{i=0}^m$  are equal.

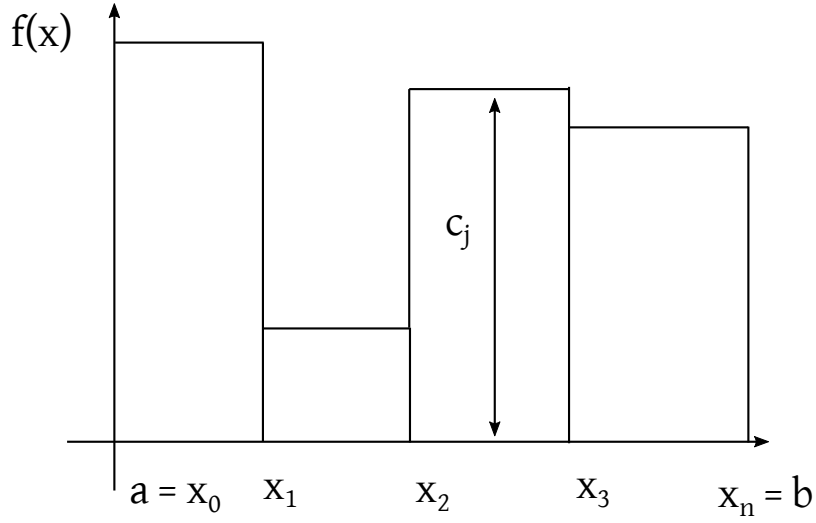


Figure 7: Integral of a step function as sum of areas of rectangles

*Proof.* There exist indices  $i_j$  for  $j = 0, n$  such that  $x_j = \xi_{i_j}$ .

$$i_0 = 0 \quad i_n = m \quad i_{j-1} < i_j$$

$$\delta x_j = x_j - x_{j-1} = \xi_{i_j} - \xi_{i_{j-1}} = \xi_{i_j} - \xi_{i_{j-1}} = \underbrace{\sum_{i=i_{j-1}+1}^{i_j} (\xi_i - \xi_{i-1})}_{\text{telescoping sum}} = \sum_{i=i_{j-1}+1}^{i_j} \delta \xi_i$$

$$\varphi|_{x_{j-1}, x_j} = c_j \implies \varphi|_{(\xi_{i-1}, \xi_i)} = c_j \text{ for } i = i_{j-1} + 1, \dots, i_j$$

$$\tilde{c}_i = \varphi|_{(\xi_{i-1}, \xi_i)}$$

$$\underbrace{\sum_{i=1}^m \tilde{c}_i \delta \xi_i}_{\text{integral of } \varphi \text{ w.r.t } (\xi_i)_{i=0}^m} = \sum_{j=1}^n \sum_{i=i_{j-1}+1}^{i_j} \tilde{c}_i \delta \xi_i = \sum_{j=1}^n c_j \underbrace{\sum_{i=i_{j-1}+1}^{i_j} \delta \xi_i}_{=x_j} = \sum_{j=1}^n c_j \delta x_j$$

This is the integral of  $\varphi$  with respect to  $(x_j)_{j=0}^n$ . □

**Lemma 4.3.** Let  $\varphi$  be a step function with respect to  $(x_j)_{j=0}^n$  and  $(w_i)_{i=0}^L$ . Then the integrals of  $\varphi$  with respect to  $(x_j)_{j=0}^n$  and with respect to  $(w_l)_{l=0}^L$  equal.

*Proof.* Let  $\{\xi_i | i = 1, \dots, m\} = \{x_j | j = 0, \dots, n\} \cup \{w_l | l = 0, \dots, L\}$  with  $\xi_0 = a$ ,  $\xi_m = x_n = w_L = b$  and  $\xi_{i-1} < \xi_i$  for  $i = 1, \dots, m$ . Then  $(\xi_i)_{i=0}^m$  is a refinement of  $(x_j)_{j=0}^n$  as well as  $(w_l)_{l=0}^L$ . By Lemma 4.2, the integral of  $\varphi$  with respect to  $(x_j)_{j=0}^n =$  integral of  $\varphi$  with respect to  $(\xi_i)_{i=1}^m =$  integral of  $\varphi$  with respect to  $(w_l)_{l=0}^L$ . Here we discard the statement “with respect to  $(x_j)_{j=0}^n$ ”.  $\square$

**Lemma 4.4.** Let  $f, g$  be step functions on  $[a, b]$ .  $f, g \in \tau[a, b]$ .

- for  $\alpha, \beta \in \mathbb{R}$ , let  $\alpha f + \beta g \in \tau[a, b]$  and

$$\int_a^b (\alpha f + \beta g) dx = \alpha \int_a^b f dx + \beta \int_a^b g dx$$

Hence, the integral is linear on  $[a, b]$ .  $\tau[a, b]$  is a vector space.

- $f \leq g$  in  $[a, b]$ , then  $\int_a^b f dx \leq \int_a^b g dx$  (monotonicity).
- $\left| \int_a^b f dx \right| \leq \int_a^b |f| dx$  ( $|f(x)|$  is also a step function)

*Proof.* 1. Let  $f, g \in \tau[a, b]$ . Let  $(\xi_i)_{i=0}^m$  be a partition such that  $f|_{(\xi_{i-1}, \xi_i)} = c_i$  and  $g|_{(\xi_{i-1}, \xi_i)} = d_i$ . Then

$$\int_a^b (\alpha f + \beta g) dx = \sum_{i=1}^m (\alpha c_i + \beta d_i) \delta \xi_i = \alpha \sum_{i=1}^m c_i \delta \xi_i + \beta \sum_{i=1}^m d_i \delta \xi_i = \alpha \int_a^b f dx + \beta \int_a^b g dx$$

Furthermore,

$$(\alpha f + \beta g)|_{(\xi_{i-1}, \xi_i)} = \alpha c_i + \beta d_i = \text{const.}$$

Thus,

$$\alpha f + \beta g \in \tau[a, b]$$

2. Let  $h \in \tau[a, b]$  with  $h(x) \geq 0 \forall x \in [a, b]$  be a step function and  $\int_a^b h dx =$

$$\sum_{i=1}^m \underbrace{h_i}_{\geq 0} \delta \xi_i \geq 0 \text{ TODO Hence, it holds that } 0 \leq \int_a^b h dx = \int_a^b (g - f) dx =$$

$$\int_a^b g dx - \int_a^b f dx.$$

3.  $f \leq |f|$ , hence  $\int_a^b f dx \leq \int_a^b |f| dx$  and also  $-f \leq |f|$ , so

$$\int_a^b (-f) dx = - \int_a^b f dx \leq \int_a^b |f| dx$$

$$\implies \left| \int_a^b f dx \right| \leq \int_a^b |f| dx$$

It is left to prove:  $|f| \in \tau[a, b]$  (i.e.  $|f|$  is a step function)

Let  $f|_{(\xi_{i-1}, \xi_i)} = c_i \implies |f|_{(\xi_{i-1}, \xi_i)} = |c_i| = \text{constant}$ . Hence  $|f| \in \tau[a, b]$ .

□

**Definition 4.3.** Let  $a \subseteq \mathbb{R}^k$ . We call  $\chi_A : \mathbb{R}^n \rightarrow \mathbb{R}$  with

$$\chi_A(x) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{else} \end{cases}$$

a characteristic function (indicator function) of set  $A$ . Often denoted as  $\chi_A = \mathbb{1}$ .

**Remark 4.1.** TODO drawings

Let  $A = (a', b')$  with  $a \leq a' < b' \leq b$ . Then  $\chi_{(a', b')} \in \tau[a, b]$ . Also for  $x \in [a, b]$ , it holds that  $\chi_{\{x\}} = \tau[a, b]$ . Therefore every linear combination of characteristic functions of open subintervals  $(a', b')$  of  $[a, b]$  as characteristic functions of one-point sets  $\chi_{\{x\}}, x \in [a, b]$  a step function on  $[a, b]$ .

$$\sum_{j=1}^n \alpha_j \chi_{(a_j, b_j)} + \sum_{k=1}^m \beta_k \chi_{\{x_k\}} \in \tau[a, b]$$

On the opposite,  $f \in \tau[a, b]$ , hence

$$f|_{(x_{j-1}, x_j)} \underbrace{=}_{j=1, \dots, n} c_j \text{ and } f(x_j) \underbrace{=}_{j=0, \dots, n} d_j$$

$$f = \sum_{j=1}^n c_j \chi_{(x_{j-1}, x_j)} + \sum_{j=0}^n d_j \chi_{\{x_j\}} = (*)$$

for  $x \in (x_{j-1}, x_j)$  it holds that  $\chi_{(x_{j-1}, x_j)}(x) = 1$ .

$$\chi_{(x_{l-1}, x_l)}(x) = 0 \text{ for } l \neq j$$

$$\chi_{\{x_l\}}(x) = 0 \text{ for } l = 0, \dots, n$$

i.e.  $\sum_{j=1}^n c_j \chi_{(x_{j-1}, x_j)}(x) + \sum_{l=0}^n d_l \chi_{\{x_l\}}(x) = c_j \cdot 1 + 0 = c_j$  hence  $(*) = c_j$  on  $(x_{j-1}, x_j)$ . Therefore  $f \in \tau[a, b] \iff f$  is linear combination of characteristic functions of open intervals or one-pointed sets.

## Regulated functions

**Definition 4.4.** Let  $X$  be a metric space  $A \subseteq X$  and  $x \in X$  is an accumulating point<sup>1</sup> of  $A$ . Let  $f : A \rightarrow \mathbb{R}$ . We say,  $f$  has limit  $c \in \mathbb{R}$  in  $x$  ( $\lim_{\xi \rightarrow x} f(\xi) = c$ ) if

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall \xi \in A, \xi \neq x \text{ and } d(\xi, x) < \delta : |f(\xi) - c| < \varepsilon$$

<sup>1</sup>An accumulation point has 3 equivalent definitions (sequence, intersection, infinitely many elements in sphere).

**Remark 4.2.**  $x \in A$  and  $c = f(x) \implies f$  is continuous in  $x$ .

We usually consider  $A = [a, b] \subseteq \mathbb{R}$ ,  $x \in [a, b]$ .

It is possible, that  $f$  in  $x$  has a limit,  $x \in A$  and  $c = \lim_{\xi \rightarrow x} f(\xi) \neq f(x)$ .

TODO drawing

**Definition 4.5.** Now let  $A \subseteq \mathbb{R}$  and  $x$  is a accumulation point of  $A$ . Let  $f : A \rightarrow \mathbb{R}$  be given. We say  $f$  has a right-sided limit  $c$  in  $x$  with  $c = \lim_{\xi \rightarrow x^+} f(\xi) = c$  if  $\forall \varepsilon > 0 \exists \delta > 0 : \forall \xi \in A, \xi > x$

$$\wedge |\xi - x| = \xi - x < \delta \implies |f(\xi) - c| < \varepsilon$$

The left-sided limit follows analogously.

$$c = \lim_{\xi \rightarrow x^-} f(\xi)$$

$$c = \lim_{\xi \rightarrow x^+} f(\xi) \quad d = \lim_{\xi \rightarrow x^-} f(\xi)$$

TODO drawing

**Lemma 4.5** (Sequence criterion for limits of functions). Let  $f : A \subseteq X \rightarrow \mathbb{R}$  be given.  $x$  is an accumulation point of  $A$ . Then it holds that

$$\lim_{\xi \rightarrow x} f(\xi) = c \iff \forall (\xi_n)_{n \in \mathbb{N}} : \xi_n \in A, \xi_n \neq x \text{ and } \lim_{n \rightarrow \infty} \xi_n = x \text{ it holds that } \lim_{n \rightarrow \infty} f(\xi_n) = c$$

For one-sided limits  $A \subseteq \mathbb{R}$  it holds that

$$c = \lim_{\xi \rightarrow x^+} f(\xi) \iff \forall (\xi_n)_{n \in \mathbb{N}} : \xi_n \in A \quad \xi_n > x \text{ with } \lim_{n \rightarrow \infty} \xi_n = x \text{ it holds that } \lim_{n \rightarrow \infty} f(\xi_n) = c$$

**Remark 4.3.** Attention! We, therefore, use two different definitions of limits.

**Lemma 4.6** (Cauchy criterion of limits of functions). Let  $f : A \subseteq X \rightarrow \mathbb{R}$ . Let  $x$  be an accumulation point of  $A$ . Let  $X$  be a metric space. Then it holds that  $f$  has a limit in  $x$  if and only if

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall \xi, \eta \in A : \xi \neq \eta : \eta \neq x :$$

with  $d(\xi, x) < \delta$  and  $d(\eta, x) < \delta$  it holds that  $|f(\xi) - f(\eta)| < \varepsilon$ . Analogously for one-sided limits with  $A \subseteq \mathbb{R}$ . Additionally, we need the constraint that  $\xi > x$  and  $\eta > x$  for  $\lim_{\xi \rightarrow x^+} f(\xi)$  or equivalently,  $\xi < x$  and  $\eta < x$  for  $\lim_{\xi \rightarrow x^-} f(\xi)$ .

TODO normalize and visualize equivalent statements for left-sided and right-sided limit (using Ring's notes)

*Proof.*  $\Leftarrow$  Let  $c = \lim_{\xi \rightarrow x} f(\xi)$  and let  $\varepsilon > 0$  be chosen arbitrarily. Then there exists  $\delta > 0$  such that  $d(\xi, x) < \delta$  and  $\xi \neq x$

$$\implies |f(\xi) - c| < \frac{\varepsilon}{2}$$

For  $\xi, \eta$ :  $d(\xi, x) < \delta$  and  $d(\eta, x) < \delta$  with  $\xi, \eta \neq x$  is therefore

$$|f(\xi) - f(\eta)| = |f(\xi) - c + c - f(\eta)| \leq |f(\xi) - c| + |f(\eta) - c| < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon$$

$\Rightarrow$  Assume the Cauchy criterion holds. We show that

1. for every sequence  $(\xi_n)_{n \in \mathbb{N}}$ ,  $\xi_n \in A \setminus \{x\}$  with  $\lim_{n \rightarrow \infty} \xi_n = x$  it holds that  $(f(\xi_n))_{n \in \mathbb{N}}$  is a Cauchy sequence in  $\mathbb{R}$  and therefore convergent in  $\mathbb{R}$ .
2. all Cauchy sequences have the *same* limit  $c$ .

We prove (1.)

Let  $(\xi_n)_{n \in \mathbb{N}}$  be as above. Let  $\varepsilon > 0$  be arbitrary. and  $N_\varepsilon$  large enough such that  $\forall n \in N_\varepsilon$  it holds that  $d(\xi_n, x) < \delta$  ( $\delta$  chosen appropriately to  $\varepsilon$  according to the Cauchy criterion).

By the Cauchy criterion,  $|f(\xi_n) - f(\xi_m)| < \varepsilon$  for all  $m, n \geq N_\varepsilon$ . Therefore  $(f(\xi_n))_{n \in \mathbb{N}}$  is a Cauchy sequence in  $\mathbb{R}$ . If  $\mathbb{R}$  is complete, then there exists  $c = \lim_{n \rightarrow \infty} f(\xi_n)$ . QED.

We prove (2.)

Let  $\xi_n \rightarrow x$  as above and  $\xi'_n \rightarrow x$  as above and  $c = \lim_{n \rightarrow \infty} f(\xi_n)$  as well as  $c' = \lim_{n \rightarrow \infty} f(\xi'_n)$ . Let  $\varepsilon > 0$  be arbitrary,  $N_\varepsilon$  such that  $n \geq N_\varepsilon \implies |f(\xi_n) - c| < \frac{\varepsilon}{3}$  and  $N'_\varepsilon \in \mathbb{N}$  such that  $n \geq N'_\varepsilon \implies |f(\xi'_n) - c'| < \frac{\varepsilon}{3}$ .

Furthermore choose  $\delta > 0$  such that

$$d(\xi, x) < \delta \wedge d(\eta, x) < \delta \implies |f(\xi) - f(\eta)| < \frac{\varepsilon}{3}$$

(because of the Cauchy criterion).  $M_\varepsilon$  such that

$$n \geq M_\varepsilon \implies d(\xi_n, x) < \delta \wedge M'_\varepsilon : n \geq M'_\varepsilon \implies d(\xi'_n, x) < \delta$$

Let  $n \geq \max\{N_\varepsilon, N'_\varepsilon, M_\varepsilon, M'_\varepsilon\}$ .

*This lecture took place on 2018/04/10.*

Then it holds that

$$|c - c'| \leq \underbrace{|c - f(\xi_n)|}_{< \frac{\varepsilon}{3}} + \underbrace{|f(\xi_n) - f(\xi'_n)|}_{< \frac{\varepsilon}{3}} + \underbrace{|f(\xi'_n) - c'|}_{< \frac{\varepsilon}{3}} \quad \forall \varepsilon > 0$$

Hence,  $c = c'$ . We have shown that  $\exists c \in \mathbb{R} : \forall (\xi_n)_{n \in \mathbb{N}}$  with  $\lim_{n \rightarrow \infty} \xi_n = x$  it holds that  $\lim_{n \rightarrow \infty} f(\xi_n) = c$ . So  $\lim_{\xi \rightarrow \infty} f(\xi) = c$  because of Lemma 4.5. QED.

□

**Definition 4.6** (Regulated function). Let  $a < b$ ,  $f : [a, b] \rightarrow \mathbb{R}$ . We call  $f$  a regulated function on  $[a, b]$  if

1.  $\forall x \in (a, b)$ ,  $f$  in  $x$  has a right-sided and a left-sided limit.
2. in  $x = a$ ,  $f$  has a right-sided limit.
3. in  $x = b$ ,  $f$  has a left-sided limit.

$$\mathcal{R}[a, b] = \{ f : [a, b] \rightarrow \mathbb{R} \mid f \text{ is a regulated function} \}$$

**Definition 4.7** (Equivalent definition). 1.  $\forall x \in [a, b]$ ,  $f$  has a right-sided limit in  $x$

2.  $\forall x \in (a, b]$ ,  $f$  has a left-sided limit in  $x$

**Example 4.1.** Let  $f$  be continuous in  $[a, b]$ . Let  $\varphi \in \tau[a, b]$  be a regulated function. Then  $\varphi \in \mathcal{R}[a, b]$ .

*Rationale:*

Let  $x_0 = a < x_1 < \dots < x_n = b$  and  $\varphi|_{(x_{j-1}, x_j)} = c_j$ .

Let  $x \in [a, b]$  be chosen arbitrarily.

**Case 1** Let  $x \in (x_{j-1}, x_j)$  for some  $j \in \{1, \dots, n\}$

$$\implies \lim_{\xi \rightarrow x} \varphi(\xi) = c_j$$

Choose  $\delta$  small enough such that  $(x - \delta, x + \delta) \subseteq (x_{j-1}, x_j)$ .  $\forall \xi$  with  $\xi \in (x - \delta, x + \delta)$  it holds that

$$|\varphi(\xi) - c_j| = 0$$

**Case 2** Let  $x = x_j$  for  $j = 1, \dots, n - 1$ .

$$\implies \lim_{\xi \rightarrow x_j^+} \varphi(\xi) = c_{j+1}$$

$$\lim_{\xi \rightarrow x_j^-} \varphi(\xi) = c_j$$

Compare with Figure 8.

**Case 3** Let  $x = x_0 = a \implies \lim_{\xi \rightarrow a^+} \varphi(\xi) = c_1$ .

$$x = x_n = b \implies \lim_{\xi \rightarrow b^-} \varphi(\xi) = c_n$$



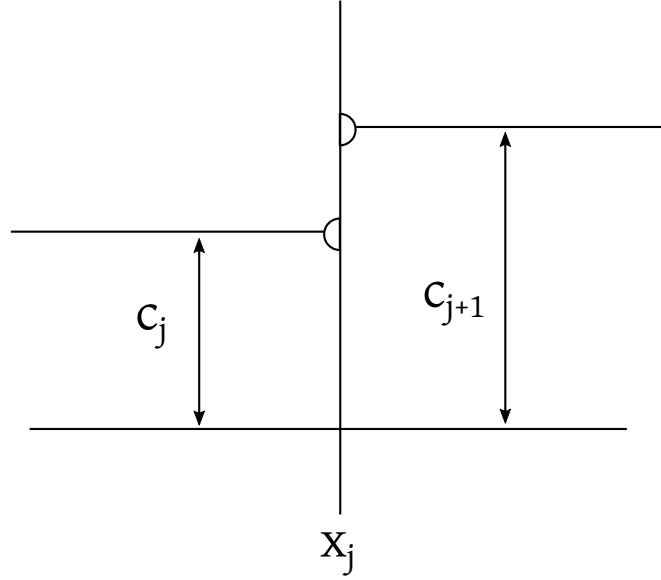


Figure 8: Regulated function

Let  $f : [a, b] \rightarrow \mathbb{R}$  be monotonically increasing or monotonically decreasing. Then  $f \in \mathcal{R}[a, b]$ . The proof will be done in the practicals.

**Definition 4.8** (Boundedness). Let  $X \neq \emptyset$  be a set.  $f : X \rightarrow \mathbb{K}$  with  $\mathbb{K} = \mathbb{R}$  or  $\mathbb{K} = \mathbb{C}$ . We say:  $f$  is bounded on  $X$ , if  $f(X) \subseteq \mathbb{K}$  is a bounded set in  $\mathbb{K}$ . Hence,  $\exists m \geq 0 : |f(x)| \leq m \forall x \in X$ . We let,

$$\mathcal{B}(X) = \{f : X \rightarrow \mathbb{K} \mid f \text{ is bounded}\}$$

$\mathcal{B}(X)$  has vector space structure.  $f, g \in \mathcal{B}(X), \lambda \in \mathbb{K}$ .

$$(f + g)(x) = f(x) + g(x)$$

$$(\lambda \cdot f)(x) = \lambda \cdot f(x)$$

$f + g \in \mathcal{B}(X)$  and  $\lambda f \in \mathcal{B}(X)$ . Let  $|f(x)| \leq m \forall x \in X$  and  $|g(x)| \leq m' \forall x \in X$ . Then it holds that

$$|(f + g)(x)| = |f(x) + g(x)| \leq |f(x)| + |g(x)| \leq m + m'$$

**Remark 4.4.** It is very interesting, that  $X$  does not require any kind of algebraic structure.

We let

$$\|f\|_\infty = \sup \underbrace{\{|f(x)| : x \in X\}}_{\text{bounded in } \mathbb{R}} = \min \{m \geq 0 : |f(x)| \leq m \forall x \in X\}$$

Some work is required to show that  $\|\cdot\|_\infty$  is a norm on  $\mathcal{B}(X)$ .

Hence,  $(\mathcal{B}(X), \|\cdot\|_\infty)$  is a normed vector space. Convergence in  $\mathcal{B}(X)$ : It holds that  $f_n \rightarrow f$  in  $(\mathcal{B}(X), \|\cdot\|_\infty)$  if and only if  $\forall \varepsilon > 0 \exists N \in \mathbb{N} : n \geq N \implies \|f_n - f\|_\infty < \varepsilon$ .

$$\begin{aligned} \|f_n - f\|_\infty < \varepsilon &\iff \sup \{|f_n(x) - f(x)| : x \in X\} < \varepsilon \\ &\iff |f_n(x) - f(x)| \leq \varepsilon \forall x \in X \end{aligned}$$

Hence,  $f_n \rightarrow f$  in  $(\mathcal{B}(X), \|\cdot\|_\infty) \iff \forall \varepsilon > 0 \exists N \in \mathbb{N} : n \geq N \implies |f_n(x) - f(x)| \leq \varepsilon \forall x \in X$ . We say “ $f_n$  converges uniformly to  $f$  on  $X$ ”.

**Theorem 4.1** (Approximation theorem for regulated function). *Let  $f : [a, b] \rightarrow \mathbb{R}$ . Then it holds that  $f \in \mathcal{R}[a, b] \iff \forall \varepsilon > 0$  there exists some step function  $\varphi \in \tau[a, b]$  such that  $|\varphi(x) - f(x)| < \varepsilon \forall x \in [a, b]$  ( $\|\varphi - f\|_\infty < \varepsilon$ ).*

*Epecially  $\varepsilon_n = \frac{1}{n}$  and  $\varphi_n$  as above. Then it holds that  $\|\varphi_n - f\|_\infty < \frac{1}{n}$ , hence  $f = \lim_{n \rightarrow \infty} \varphi_n$  uniformly on  $[a, b]$ .*

*Proof.* Direction  $\implies$ . Let  $f \in \mathcal{R}[a, b]$ .

Proof by contradiction. We negate our hypothesis:

$$\exists \varepsilon > 0 : \forall \varphi \in \tau[a, b] \exists x \in [a, b] : |\varphi(x) - f(x)| \geq \varepsilon \quad (1)$$

Assume (1) holds for  $f \in [a, b]$ . We construct nested intervals  $[a_n, b_n]$  with  $[a_{n+1}, b_{n+1}] \subseteq [a_n, b_n]$  and  $b_{n+1} - a_{n+1} = \frac{1}{2}(b_n - a_n)$  and (1) holds on  $[a_n, b_n] \forall n \in \mathbb{N}$ . Hence  $\forall \varphi \in \tau[a_n, b_n] \exists x \in [a_n, b_n]$  such that  $|\varphi(x) - f(x)| \geq \varepsilon$ . This is what we want to show.

Let  $a_0 = a$  and  $b_0 = b$ . Then (1) holds on  $[a_0, b_0]$  by assumption.  $n \rightarrow n + 1$ : Construction of  $[a_{n+1}, b_{n+1}]$ . Let  $m_n = \frac{1}{2}(a_n + b_n)$ . We need to prove: (1) holds either on  $[a_n, m_n]$  or on  $[m_n, b_n]$ .

Because if the opposite of (1) holds on  $[a_n, m_n]$  as well as  $[m_n, b_n]$ , then there exists  $\varphi_n^1 \in \tau[a_n, m_n]$  with  $|\varphi_n^1(x) - f(x)| < \varepsilon \forall x \in [a_n, m_n]$  and if the opposite of (1) holds on  $[m_n, b_n]$ :

$$\exists \varphi_n^2 \in \tau[m_n, b_n] : |\varphi_n^2(x) - f(x)| < \varepsilon \forall x \in [m_n, b_n]$$

Let

$$\varphi^n(x) = \begin{cases} \varphi_n^1(x) & \text{if } x \in [a_n, m_n] \\ \varphi_n^2(x) & \text{if } x \in (m_n, b_n] \end{cases}$$

Then  $\varphi^n$  is piecewise constant, hence  $\varphi^n \in \tau[a_n, b_n]$  and it holds that

$$|\varphi^n(x) - f(x)| = \begin{cases} \underbrace{|\varphi_1^n(x) - f(x)|}_{< \varepsilon} & \text{for } x \in [a_n, m_n] \\ \underbrace{|\varphi_2^n(x) - f(x)|}_{< \varepsilon} & \text{for } x \in [m_n, b_n] \end{cases} < \varepsilon$$

This contradicts with (1) on  $[a_n, b_n]$ .

Hence: (1) holds on  $[a_n, m_n]$  or on  $[m_n, b_n]$ .

Choose  $[a_{n+1}, b_{n+1}]$  as one of the subintervals in which (1) holds.  $\square$

Let  $X \in \bigcap_{n \in \mathbb{N}} [a_n, b_n]$  (by completeness of  $\mathbb{R}$ ).

1. Let  $x \in (a, b)$ . Let  $\varepsilon$  as above such that (1) holds on every interval  $[a_n, b_n]$ .

Let  $c_+ = \lim_{\xi \rightarrow x^+} f(\xi)$  and  $c_- = \lim_{\xi \rightarrow x^-} f(\xi)$  (possible, because  $f \in \mathcal{R}[a, b]$ ).

Limes property:  $\exists \delta > 0 : |\xi - x| < \delta$  and  $\xi < x$ , then  $|f(\xi) - c_-| < \varepsilon$  and  $|\xi - x| < \delta$  and  $x < \delta$  then  $|f(\xi) - c_+| < \varepsilon$ .

Additionally, choose  $\delta$  sufficiently small enough such that  $(x - \delta, x + \delta) \subseteq [a, b]$ . Let

$$\hat{\varphi}(\xi) = \begin{cases} 0 & \text{for } \xi \in [a, b] \setminus (x - \delta, x + \delta) \\ c_- & \text{for } \xi \in (x - \delta, x) \\ c_+ & \text{for } \xi \in (x, x + \delta) \\ f(x) & \text{for } \xi = x \end{cases}$$

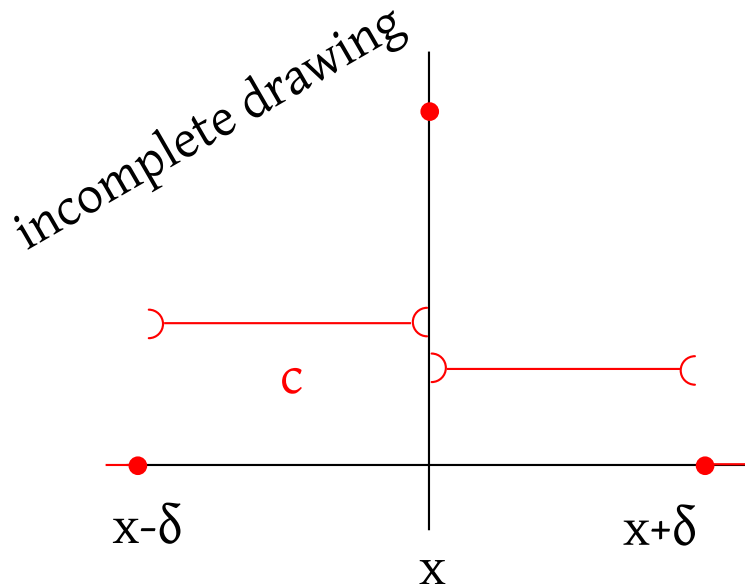
$\hat{\varphi} \in \tau[a, b]$  and it holds that

$$\forall \xi \in (x - \delta, x + \delta) : |\hat{\varphi}(\xi) - f(\xi)| = \begin{cases} \underbrace{|c_- - f(\xi)|}_{< \varepsilon} & \text{for } \xi \in (x - \delta, x) \\ \underbrace{|f(x) - f(x)|}_{=0} & \text{for } \xi = x \\ \underbrace{|c_+ - f(\xi)|}_{< \varepsilon} & \text{for } \xi \in (x, x + \delta) \end{cases} < \varepsilon$$

Now let  $N$  be sufficiently large enough such that  $[a_N, b_N] \subseteq (x - \delta, x + \delta)$  (possible because  $([a_n, b_n])_{n \in \mathbb{N}}$  gives nested intervals tightening on  $x$ ). Then it holds on  $[a_N, b_N]$  that:

$$\hat{\varphi}|_{[a_N, b_N]} \in \tau[a_N, b_N]$$

and  $\forall \xi \in [a_N, b_N] \subseteq (x - \delta, x + \delta)$  it holds that  $|\hat{\varphi}(\xi) - f(\xi)| < \varepsilon$ . This contradicts with (1) on  $[a_N, b_N]$ .



We also need to cover the special cases  $x = a$  and  $x = b$ . But this works analogously with one-sided limits.

Direction  $\Leftarrow$ : Let  $f = \lim_{n \rightarrow \infty} \varphi_n$  uniform on  $[a, b]$ . Show that  $\forall x \in [a, b]$  there exists a right-sided limit of  $f$  in  $x$ .

Let  $\varepsilon > 0$  be arbitrary.  $N \in \mathbb{N}$  sufficiently large such that  $|f(\xi) - \varphi_N(\xi)| < \frac{\varepsilon}{2} \forall \xi \in [a, b]$ .  $\varphi_N$  is piecewise constant. Choose  $\delta > 0$  such that  $\varphi_N|_{(x, x+\delta)} = c$ . Now let  $\xi, \eta \in (x, x + \delta)$  be chosen arbitrarily. Then it holds that

$$\begin{aligned}
 |f(\xi) - f(\eta)| &\leq \left| f(\xi) - \underbrace{c}_{=\varphi_N(\xi)} \right| + \left| \underbrace{c}_{=\varphi_N(\eta)} - f(\eta) \right| \\
 &= \left| \underbrace{f(\xi) - \varphi_N(\xi)}_{< \frac{\varepsilon}{2}} \right| + \left| \underbrace{\varphi_N(\eta) - f(\eta)}_{< \frac{\varepsilon}{2}} \right| < \varepsilon
 \end{aligned}$$

Therefore  $f$  has a right-sided limit in  $x$  by the Cauchy criterion.  $f$  has left-sided limit in every point  $x \in (a, b]$  analogously.

**Corollary.** Every regulated function  $f \in \mathcal{R}[a, b]$  is bounded. Let  $\varphi \in \tau[a, b]$  with  $\|f - \varphi\|_\infty < 1$ .  $\varphi$  is bounded, hence  $\exists m \in [0, \infty)$ :  $|\varphi(x)| \leq m \forall x \in [a, b]$ . Then it holds

that  $|f(x)| \leq |f(x) - \varphi(x)| + |\varphi(x)| < 1 + m \forall x \in [a, b]$ , hence  $f \in \mathcal{B}[a, b]$ .

$$\mathcal{R}[a, b] \subseteq \mathcal{B}[a, b]$$

**Corollary.** Let  $f \in \mathcal{R}[a, b] \iff f = \sum_{j=0}^{\infty} \psi_j$  with  $\psi_j \in \tau[a, b]$  and the series converges uniformly on  $[a, b]$ .

*Proof.* Direction  $\Leftarrow$ .

Let  $f = \sum_{j=0}^{\infty} \psi_j$  with uniform convergence. Let  $\varphi_n = \sum_{j=0}^n \psi_j \in \tau[a, b]$  and  $f = \lim_{n \rightarrow \infty} \varphi_n$  uniform on  $[a, b] \implies f \in \mathcal{R}[a, b]$ .  
Satz 1?!

Direction  $\implies$ .

Let  $f \in \mathcal{R}[a, b]$  and  $f = \lim_{n \rightarrow \infty} \varphi_n$  with  $\varphi_n \in \tau[a, b]$  (by Satz 1?!).

$$\begin{aligned} \psi_0 &= \varphi_0 \\ \psi_j &= \varphi_j - \varphi_{j-1} \quad \text{for } j \geq 1 \\ \sum_{j=0}^n \psi_j &= \varphi_0 + \sum_{j=1}^n (\varphi_j - \varphi_{j-1}) = \varphi_0 + \sum_{j=1}^n \varphi_j - \sum_{j=0}^{n-1} \varphi_j = \varphi_n \end{aligned}$$

converges uniformly to  $f$ . □

## Integration of regulated functions

**Definition 5.1** (Definition with a theorem). Let  $f \in \mathcal{R}[a, b]$  and  $\varphi_n \in \tau[a, b]$  with  $f = \lim_{n \rightarrow \infty} \varphi_n$  is uniform on  $[a, b]$ . We let

$$\int_a^b f \, dx = \lim_{n \rightarrow \infty} \int_a^b \varphi_n \, dx$$

for the integral of  $f$  on  $[a, b]$ .

*Theorem:* This limit (on the right-hand side) always exists and is independent of the particular choice of the approximating sequence.

*Proof.*  $\varphi_n$  is chosen as above.

$$i_n = \int_a^b \varphi_n \, dx$$

Show:  $i_n$  is cauchy sequence in  $\mathbb{R}$ .

This lecture took place on 2018/04/12.

Let  $\varepsilon > 0$  be chosen arbitrary. Choose  $N \in \mathbb{N}$  such that

$$n \geq N \implies \|f - \varphi_n\|_\infty < \frac{\varepsilon}{2(b-a)}$$

For  $n, m \geq N$  it holds for  $x \in [a, b]$  that

$$\begin{aligned} |\varphi_n(x) - \varphi_m(x)| &\leq |\varphi_n(x) - f(x)| + |f(x) - \varphi_m(x)| \\ &\leq \| \varphi_n - f \|_\infty + \| f - \varphi_m \|_\infty < \frac{\varepsilon}{2(b-a)} + \frac{\varepsilon}{2(b-a)} = \frac{\varepsilon}{b-a} \end{aligned}$$

$|\varphi_n - \varphi_m|$  is a step function.

$$|\varphi_n - \varphi_m| \leq \frac{\varepsilon}{b-a} \cdot \underbrace{\chi_{[a,b]}}_{\in \tau[a,b]}$$

Integral for subsequence is monotonous:

$$\begin{aligned} |i_n - i_m| &= \left| \int_a^b \varphi_n dx - \int_a^b \varphi_m dx \right| = \left| \int_a^b (\varphi_n - \varphi_m) dx \right| \leq \int_a^b |\varphi_n - \varphi_m| dx \\ &\underbrace{\leq}_{\text{by monotonicity}} \int_a^b \frac{\varepsilon}{b-a} \cdot \chi_{[a,b]} dx = \frac{\varepsilon}{b-a} \underbrace{\int_a^b \chi_{[a,b]} dx}_{1 \cdot (b-a)} = \varepsilon \end{aligned}$$

So  $(i_n)_{n \in \mathbb{N}}$  is a Cauchy sequence.  $\mathbb{R}$  is complete, hence  $i = \lim_{n \rightarrow \infty} i_n$  exists.

Uniqueness: (dt. mithilfe des Reissverschlussprinzips)

Let  $(\varphi_n)_{n \in \mathbb{N}}, (\Phi_n)_{n \in \mathbb{N}}$  be two sequences of step functions, converging uniformly towards  $f$ .

$$\begin{aligned} i_n &= \int_a^b \varphi_n dx \quad \text{and} \quad j_n = \int_a^b \Phi_n dx \\ i &= \lim_{n \rightarrow \infty} i_n \quad \quad j = \lim_{n \rightarrow \infty} j_n \end{aligned}$$

Show that  $i = j$ .

Now we construct a sequence  $(\mu_n)_{n \in \mathbb{N}}$  of step functions.

$$\underbrace{(\varphi_1, \Phi_1, \varphi_2, \Phi_2, \dots)}_{(\mu_n)_{n \in \mathbb{N}}}$$

$\mu_n$  is a sequence of step functions converging uniformly towards  $f$  (the proof is left as an exercise to the reader).

Because of part 1 of the proof:

$$m_n = \int_a^b \mu_n dx \text{ converges with limit } m$$

$(i_n)_{n \in \mathbb{N}}$  as well as  $(j_n)_{n \in \mathbb{N}}$  are subsequences of  $(m_n)_{n \in \mathbb{N}}$ . Hence it holds that  $i = \lim_{n \rightarrow \infty} i_n = m = \lim_{n \rightarrow \infty} j_n = j$ .  $\square$

**Theorem 5.1** (Elementary properties of an integral). *Let  $f, g \in \mathcal{R}[a, b]$ ,  $\lambda, \mu \in \mathbb{R}$ . Then it holds that*

**Linearity**

$$\lambda f + \mu g \in \mathcal{R}[a, b] \text{ and } \int_a^b (\lambda f + \mu g) dx = \lambda \int_a^b f dx + \mu \int_a^b g dx$$

**Monotonicity** *If  $f(x) \leq g(x) \forall x \in [a, b]$  ( $f \leq g$ ) it holds that*

$$\int_a^b f dx \leq \int_a^b g dx$$

**Boundedness**  $|f| \in \mathcal{R}[a, b]$  and

$$\left| \int_a^b f dx \right| \leq \int_a^b |f| dx$$

*Proof.* We prove linearity.

Let  $x \in [a, b]$  and  $c_+ = \lim_{\xi \rightarrow x_+} f(\xi)$  as well as  $d_+ = \lim_{\xi \rightarrow x_+} g(\xi)$  ( $f, g \in \mathcal{R}[a, b]$ ). Then it holds that

$$\lim_{\xi \rightarrow x^+} (\lambda f(\xi) + \mu g(\xi)) = \lambda \lim_{\xi \rightarrow x^+} f(\xi) + \mu \lim_{\xi \rightarrow x^+} g(\xi) = \lambda c_+ + \mu d_+$$

exists. Analogously for the left side, hence  $\lambda f + \mu g \in \mathcal{R}[a, b]$ .

Let  $\varphi_n, \Phi_n \in \mathcal{C}[a, b]$  with  $\varphi_n \rightarrow f$  and  $\Phi_n \rightarrow g$  is uniform on  $[a, b]$ . Hence  $\lambda \varphi_n + \mu \Phi_n \rightarrow \lambda f + \mu g$  is continuous on  $[a, b]$ .

Proof of this:

Let  $\varepsilon > 0$  be arbitrary,  $N$  such that  $n \geq N \implies \|\varphi_n - f\|_\infty < \frac{\varepsilon}{2(|\lambda|+1)}$  and  $M$  such that  $n \geq M \implies \|\Phi_n - g\|_\infty < \frac{\varepsilon}{2(|\mu|+1)}$ .

Then it holds that

$$\begin{aligned} \|\lambda \varphi_n + \mu \Phi_n - \lambda f - \mu g\|_\infty &\leq |\lambda| \|\varphi_n - f\|_\infty + |\mu| \|\Phi_n - g\|_\infty \\ &< \frac{|\lambda|}{2(|\lambda|+1)} \cdot \varepsilon + \frac{|\mu|}{2(|\mu|+1)} \cdot \varepsilon < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon \end{aligned}$$

We continue:

$$\begin{aligned}
\int_a^b (\lambda f + \mu g) dx &= \lim_{n \rightarrow \infty} \int_a^b (\lambda \varphi_n + \mu \Phi_n) dx = \lim_{n \rightarrow \infty} (\lambda \int_a^b \varphi_n dx + \mu \int_a^b \Phi_n dx) \\
&= \lambda \underbrace{\lim_{n \rightarrow \infty} \int_a^b \varphi_n dx}_{\text{exists}} + \mu \underbrace{\lim_{n \rightarrow \infty} \int_a^b \Phi_n dx}_{\text{exists}} \\
&= \lambda \int_a^b f dx + \mu \int_a^b g dx
\end{aligned}$$

We prove monotonicity.

Show: Let  $h \in \mathcal{R}[a, b]$  with  $h \geq 0$  in  $[a, b]$ . Then it holds that  $\int_a^b h dx \geq 0$ .

We will show that  $(\tilde{\varphi}_n)_{n \in \mathbb{N}}$  exists with  $\tilde{\varphi}_n \rightarrow h$  uniform on  $[a, b]$  and  $\tilde{\varphi}_n \geq 0$ .

Therefore we prove: Let  $(\varphi_n)_{n \in \mathbb{N}}$ ,  $\varphi_n \in \tau[a, b]$  with  $\varphi_n \rightarrow h$  uniform on  $[a, b]$ .

Define  $\tilde{\varphi}_n$  such that

$$\varphi_n = \sum_{j=1}^{m_n} c_j \chi_{(x_{j-1}, x_j)} + \sum_{j=0}^{m_n} d_j \chi_{\{x_j\}}$$

Let

$$\tilde{\varphi}_n = \sum_{j=1}^{m_n} \underbrace{\tilde{c}_j}_{\geq 0} \chi_{(x_{j-1}, x_j)} + \sum_{j=0}^{m_n} \underbrace{h(x_j)}_{\geq 0} \chi_{\{x_j\}}$$

and  $\tilde{c}_j := \max c_j, 0 \geq 0$ . So it holds that  $\tilde{\varphi}_n \geq 0$ .

For  $x = x_l$  ( $l \in \{0, \dots, m_n\}$ ) it holds that

$$\begin{aligned}
|\tilde{\varphi}_n(x_l) - h(x_l)| &= \left| \sum_{j=1}^{m_n} \tilde{c}_j \underbrace{\chi_{(x_{j-1}, x_j)}(x_l)}_{=0 \text{ bc. } x_l \notin (x_{j-1}, x_j)} + \sum_{j=0}^{m_n} h(x_j) \underbrace{\chi_{\{x_j\}}(x_l)}_{=\delta_{j,l}} - h(x_l) \right| \\
&= |h(x_l) - h(x_l)| = 0 \leq |\varphi_n(x_l) - h(x_l)|
\end{aligned}$$

For  $x \in (x_{j-1}, x_j)$  it holds that

$$\begin{aligned}
|\tilde{\varphi}_n(x) - h(x)| &= \left| \sum_{j=1}^{m_n} \tilde{c}_j \underbrace{\chi_{(x_{j-1}, x_j)}(x)}_{\delta_{l,j}} + \sum_{j=0}^{m_n} h(x_j) \cdot \underbrace{\chi_{\{x_j\}}(x)}_{=0 \text{ bc. } x \neq x_j} - h(x) \right| \\
&= |\tilde{c}_l - h(x)| = \begin{cases} |c_l - h(x)| & \text{if } c_l \geq 0 \\ |h(x)| = h(x) & \text{if } c_l < 0 \end{cases}
\end{aligned}$$



$$\begin{aligned}
&\leq \begin{cases} |c_l - h(x)| & \text{if } c_l \geq 0 \\ h(x) - c_l & \text{if } c_l < 0 \end{cases} \\
&= \begin{cases} |\varphi_n(x) - h(x)| & \text{if } c_l = \varphi_n(x) \geq 0 \\ |h(x) - \varphi_n(x)| & \text{if } c_l = \varphi_n(x) < 0 \end{cases} \\
&= |\varphi_n(x) - h(x)|
\end{aligned}$$

hence,  $|\tilde{\varphi}_n(x) - h(x)| \leq |\varphi_n(x) - h(x)|$  for  $x \in (x_{l-1}, x_l)$  as well as  $x = x_l$ , hence

$$\|\tilde{\varphi}_n - h\|_\infty \leq \underbrace{\|\varphi_n - h\|_\infty}_{\rightarrow 0 \text{ for } n \rightarrow \infty}$$

Hence  $\|\tilde{\varphi}_n - h\|_\infty \rightarrow 0$  for  $n \rightarrow \infty$ , hence  $\tilde{\varphi}_n$  converges uniformly to  $h$ . There exists

$$\int_a^b h \, dx = \lim_{n \rightarrow \infty} \underbrace{\int_a^b \tilde{\varphi}_n \, dx}_{\geq 0} \geq 0$$

Monotonicity: Let  $f \leq g$  in  $[a, b]$ , hence  $h = g - f \geq 0$  in  $[a, b]$

$$\begin{aligned}
\Rightarrow 0 &\leq \int_a^b h \, dx = \int_a^b g \, dx - \int_a^b f \, dx \\
&\Rightarrow \int_a^b f \, dx \leq \int_a^b g \, dx
\end{aligned}$$

And finally, boundedness is left.

Consider  $|f| \in \mathcal{R}[a, b]$ . Proving this is left as an exercise.  $f \leq |f|$  in  $[a, b] \Rightarrow \int_a^b f \, dx \leq \int_a^b |f| \, dx$ .

TODO

$$-f \leq |f| \text{ in } [a, b] \Rightarrow \int_a^b (-f) \, dx = - \int_a^b f \, dx \leq \int_a^b |f| \, dx \Rightarrow \left| \int_a^b f \, dx \right| \text{ TODO}$$

□

**Remark 5.1.**  $\mathcal{R}[a, b]$  is a vector space.

1.  $f, g \in \mathcal{R}[a, b] \Rightarrow \lambda f + \mu g \in \mathcal{R}[a, b]$ .  $\|\cdot\|_\infty$  is a norm on  $\mathcal{R}[a, b]$ .  $(\mathcal{R}[a, b], \|\cdot\|_\infty)$  is a normed vector space. Subspace of  $(\mathcal{B}[a, b], \|\cdot\|_\infty)$ . We will show in the practicals that  $(\mathcal{R}[a, b], \|\cdot\|_\infty)$  is complete.

**Theorem 5.2** (Mean value theorem of integral calculus). *Let  $f$  be continuous on  $[a, b]$  and  $p \in \mathcal{R}[a, b]$  and  $p \geq 0$  in  $[a, b]$ . Then  $f \cdot p \in \mathcal{R}[a, b]$  and there exists  $\xi \in [a, b]$  such that*

$$\int_a^b f \cdot p \, dx = f(\xi) \cdot \int_a^b p \, dx$$

*Proof.* Let  $m = \min \{f(z) : z \in [a, b]\}$  (exists because  $f$  is continuous and  $[a, b]$  is compact).

$$M = \max \{f(z) : z \in [a, b]\}$$

$$f([a, b]) = [m, M] \text{ (by the mean value theorem)}$$

It holds that

$$m \cdot \underbrace{p(x)}_{\geq 0} \leq f(x) \cdot p(x) \leq M \cdot p(x)$$

By monotonicity,

$$m \int_a^b p(x) \, dx \leq \int_a^b f p \, dx \leq M \int_a^b p \, dx$$

Therefore, there exists  $\eta \in [m, M]$ .

$$\eta \cdot \int_a^b p(x) \, dx = \int_a^b f p \, dx$$

Mean value theorem: For  $\eta \in [m, M]$  there exists  $\xi \in [a, b]$  such that

$$\eta = f(\xi) \text{ (f is continuous!)}$$

Hence,

$$f(\xi) \int_a^b p \, dx = \int_a^b f \cdot p \, dx$$

$f \cdot p$  is regulated function (over one-sided limits). □

**Lemma 5.1.** *Let  $f \in \mathcal{R}[a, b]$  and  $a \leq \alpha < \beta < \gamma \leq b$ . Then*

$$f|_{[\alpha, \beta]} \in \mathcal{R}[\alpha, \beta], f|_{[\beta, \gamma]} \in \mathcal{R}[\beta, \gamma]$$

$$f|_{[\alpha, \gamma]} \in \mathcal{R}[\alpha, \gamma] \text{ (immediate over onesided limit)}$$

and it holds that

$$\int_{\alpha}^{\gamma} f \, dx = \int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\gamma} f \, dx$$

Compare with Figure 9.

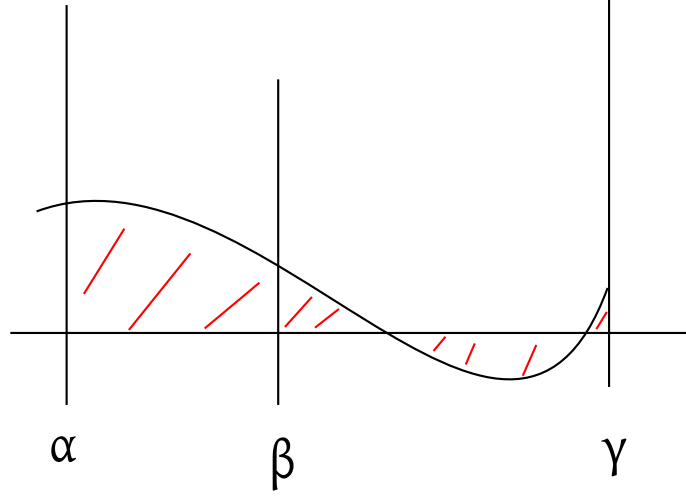


Figure 9: Positive and negative area covered by the integral

*Proof.* Show that this statement holds for  $\varphi \in \tau[a, b]$ . Without loss of generality,  $\alpha = a, \gamma = b$ .

$$\gamma = \sum_{j=1}^m c_j \chi_{(x_{j-1}, x_j)} + \sum_{j=0}^m \underbrace{0}_{\text{it does not matter for the integral}} \cdot \chi_{x_j}$$

**Case 1**  $\beta = x_l$  for some  $l \in \{1, \dots, m-1\}$

$$\int_{\alpha}^{\gamma} \varphi dx = \sum_{j=1}^m c_j (x_j - x_{j-1})$$

$$\int_{\alpha}^{\beta} \varphi dx = \int_{\alpha}^{x_l} \varphi dx = \sum_{j=1}^l c_j (x_j - x_{j-1})$$

$$\int_{\beta}^{\gamma} \varphi dx = \int_{x_l}^{\gamma} \varphi dx = \sum_{j=l+1}^m c_j (x_j - x_{j-1})$$

And now,

$$\sum_{j=l+1}^m c_j (x_j - x_{j-1}) + \sum_{j=1}^l c_j (x_j - x_{j-1}) = \sum_{j=1}^m c_j (x_j - x_{j-1})$$

**Case 2**  $\beta \in (x_{l-1}, x_l)$  for some  $l \in \{1, \dots, m\}$ .

$$\begin{aligned}
\int_{\beta}^{\gamma} \varphi \, dx &= c_l(x_l - \beta) + \sum_{j=l+1}^m c_j(x_j - x_{j-1}) \\
\int_{\alpha}^{\beta} \varphi \, dx + \int_{\beta}^{\gamma} \varphi \, dx &= \sum_{j=1}^{l-1} c_j(x_j - x_{j-1}) \\
&\quad + c_l(\beta - x_{l-1}) + c_l(x_l - \beta) + \sum_{j=l+1}^m c_j(x_j - x_{j-1}) \\
&= \sum_{j=1}^m c_j(x_j - x_{j-1}) = \int_{\alpha}^{\gamma} \varphi \, dx
\end{aligned}$$

TODO verify previous lines Let  $\varphi_n \in \tau[\alpha, \beta]$  with  $\varphi_n \rightarrow f$  uniform on  $[\alpha, \beta] \implies \varphi_n|_{[\alpha, \beta]} \rightarrow f|_{[\alpha, \beta]}$  uniform on  $[\alpha, \beta]$  and also  $\varphi_n|_{[\beta, \gamma]} \rightarrow f|_{[\beta, \gamma]}$  uniform on  $[\beta, \gamma]$ .

$$\begin{aligned}
\int_{\alpha}^{\gamma} f \, dx &= \lim_{n \rightarrow \infty} \int_{\alpha}^{\gamma} \varphi_n \, dx = \lim_{n \rightarrow \infty} \left( \int_{\alpha}^{\beta} \varphi_n \, dx + \int_{\beta}^{\gamma} \varphi_n \, dx \right) \\
&= \underbrace{\lim_{n \rightarrow \infty} \int_{\alpha}^{\beta} \varphi_n \, dx}_{\text{exists because } \varphi_n|_{[\alpha, \beta]} \rightarrow f|_{[\alpha, \beta]} \text{ uniform}} + \lim_{n \rightarrow \infty} \int_{\beta}^{\gamma} \varphi_n \, dx \\
&= \int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\gamma} f \, dx
\end{aligned}$$

□

**Remark 5.2** (Notation). Let  $\alpha < \beta$ ,  $\alpha, \beta \in [a, b]$  and  $f \in \mathcal{R}[a, b]$ . We let

$$\int_{\beta}^{\alpha} f \, dx := - \int_{\alpha}^{\beta} f \, dx$$

By this convention, it holds that

$$\int_{\alpha}^{\alpha} f \, dx = - \int_{\alpha}^{\alpha} f \, dx \implies \int_{\alpha}^{\alpha} f \, dx = 0$$

**Lemma 5.2.** Let  $f \in \mathcal{R}[a, b]$  and  $\alpha, \beta, \gamma \in [a, b]$  (without particular order). Then it holds that

$$\int_{\alpha}^{\gamma} f \, dx = \int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\gamma} f \, dx$$

*Proof.* Special case: 2 points are equal

$$\begin{aligned}\alpha = \gamma &\implies \int_a^\alpha f dx = 0 \\ \int_\alpha^\beta f dx + \int_\beta^\alpha f dx &= \int_\alpha^\beta f dx - \int_\alpha^\beta f dx = 0 \\ \beta = \gamma \quad \beta = \alpha\end{aligned}$$

Case:  $\alpha < \beta < \gamma$  follows immediately

And just as a representative other case:  $\alpha < \gamma < \beta$

$$\begin{aligned}\int_\alpha^\beta f dx &\stackrel{\text{by Lemma 2.1}}{=} \int_\alpha^\gamma f dx + \underbrace{\int_\gamma^\beta f dx}_{-\int_\beta^\gamma f dx} \\ \int_\alpha^\beta f dx + \int_\beta^\gamma f dx &= \int_\alpha^\gamma f dx\end{aligned}$$

□

*This lecture took place on 2018/04/17.*

**Lemma 5.3.** Let  $f \in \mathcal{R}[a, b]$ . Then there exists an at most countable set  $A \subseteq [a, b]$  such that  $f$  is continuous in every point  $x \in [a, b] \setminus A$ .

*Proof.* Let  $f \in \mathcal{R}[a, b]$  and  $(\varphi_n)_{n \in \mathbb{N}}$  with  $\varphi_n \in \tau[a, b]$  and  $\varphi \rightarrow f$  converging uniformly on  $[a, b]$ .

$$\begin{aligned}\varphi_n &= \sum_{j=1}^{m_n} c_j^n \chi_{(X_{j-1}^n, X_j^n)} + \sum_{j=0}^{m_n} d_j^n \chi_{\{x_j^n\}} \\ x_0^n &= a < x_1^n < \dots < x_{m_n}^n = b\end{aligned}$$

are separating points for  $\varphi_n$

$$A = \{X_j^n : n \in \mathbb{N}, j \in \{0, \dots, m_n\}\}$$

$A$  is a countable union of finite sets  $A_n = \{x_0^n, x_{m_n}^n\}$ .  $A$  is countable (as unions of finite sets are).

Now we show:  $f$  is continuous in every point  $x \in [a, b] : x \notin A$ . Let  $\varepsilon > 0$  be arbitrary. Choose  $N \in \mathbb{N}$  sufficiently large such that  $\|\varphi_N - f\|_\infty < \frac{\varepsilon}{2}$ . Because  $x \in A$ , there exists  $j \in \{1, \dots, m_N\}$  such that  $x \in (x_{j-1}^N, x_j^N)$  is open. Choose  $\delta > 0$

such that  $(x - \delta, x + \delta) \subset (x_{j-1}^N, x_j^N)$ , hence  $\forall \xi \in (x - \delta, x + \delta)$  it holds that  $\varphi_N(\xi) = c_j^N$ . Now consider  $\xi \in (x - \delta, x + \delta)$ , hence  $|\xi - x| < \delta$ . Then it holds that

$$\begin{aligned} |f(\xi) - f(x)| &= \left| f(\xi) - \underbrace{\varphi_N(x)}_{c_j^N = \varphi_N(\xi)} + \varphi_N(x) - f(x) \right| \\ &\leq \underbrace{|f(\xi) - \varphi_N(\xi)|}_{\leq \|f - \varphi_N\|_\infty} + \underbrace{|\varphi_N(x) - f(x)|}_{\leq \|\varphi_N - f\|_\infty} < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon \end{aligned}$$

Hence  $f$  is continuous in  $x$ .  $\square$

**Remark 5.3** (Notation). Let  $f \in \mathcal{R}[a, b]$ . For  $x \in [a, b)$ , there exists  $f_+(x) := \lim_{\xi \rightarrow x_+} f(\xi)$ . For  $x \in (a, b]$ , there exists  $f_-(x) := \lim_{\xi \rightarrow x_-} f(\xi)$ . Because of Lemma 5.3, it holds that  $f_+(x) = f_-(x) = f(x)$  for all  $x \in [a, b] \setminus A$  and  $A$  is at most countable.

**Definition 5.2** (One-sided derivatives). Let  $g : [a, b] \rightarrow \mathbb{R}$  and  $x \in [a, b)$ . We say  $g$  has the right-sided derivative  $g'_+(x)$  if

$$\lim_{\xi \rightarrow x_+} \frac{g(\xi) - g(x)}{\xi - x} =: g'_+(x)$$

exists. Analogously we define the left-sided derivative

$$g'_-(x) = \lim_{\xi \rightarrow x_-} \frac{g(\xi) - g(x)}{\xi - x}$$

for  $x \in (a, b]$ . Compare with Figure 10.

**Remark 5.4.** If  $g$  in  $x$  has a one-sided derivative, then it holds that

$$\lim_{\xi \rightarrow x_\pm} (g(\xi) - g(x)) = 0$$

Hence  $g$  is continuous in  $x$ .

**Remark 5.5.**  $g : [a, b] \rightarrow \mathbb{R}$  is differentiable in point  $x \in (a, b)$  with derivative  $g'(x)$   $\iff$   $g$  has a left- and right-sided derivative in  $x$  and it holds that  $g'_-(x) = g'_+(x)$  ( $= g'(x)$ ).

**Theorem 5.3** (Fundamental theorem of differential/integration calculus, variation 1). Isaac Barrow (1630–1677), Isaac Newton (1642–1726), Gottfried Wilhelm von Leibniz (1646–1716).

Let  $f \in \mathcal{R}[a, b]$ ,  $\alpha \in [a, b]$  and we define

$$F(x) = \int_\alpha^x f \, d\xi$$

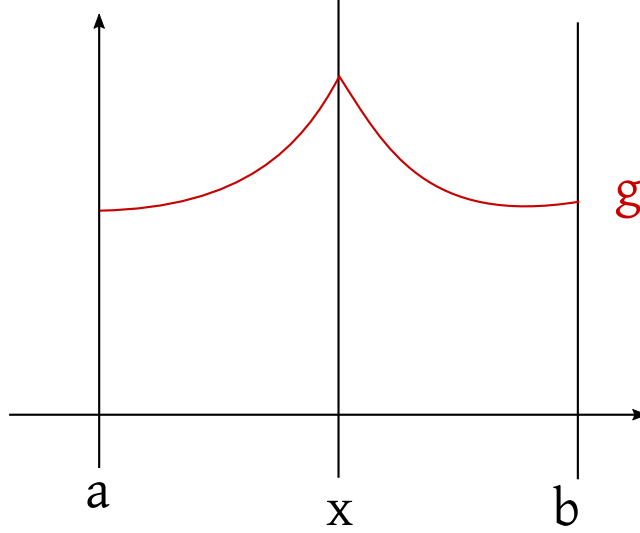


Figure 10: In this example, the left- and right-sided derivatives are not equal.  
 $f'_+(x) \neq f'_-(x)$

Then  $F$  is right-sided differentiable in every point  $x \in [a, b]$  and in every  $x \in (a, b]$  left-sided differentiable. Furthermore it holds that

$$F'_+(x) = f_+(x) \forall x \in [a, b] \quad (2)$$

$$F'_-(x) = f_-(x) \forall x \in (a, b] \quad (3)$$

**Remark 5.6.**

$$\frac{d}{dx} \left( \int_a^x f \, d\xi \right) = f(x)$$

for all  $x$  such that  $f$  is continuous in  $x$ . For those  $x$ ,  $F'(x)$  is differentiable in  $x$  with  $F'(x) = f(x)$ .

**Definition 5.3.** Let  $f \in \mathcal{R}[a, b]$  and  $\varphi : [a, b] \rightarrow \mathbb{R}$  such that  $\varphi$  is one-sided differentiable on  $[a, b]$ . If  $\Phi'_+(x) = f_+(x) \forall x \in [a, b]$  and  $\Phi'_-(x) = f_-(x) \forall x \in (a, b]$  then we call  $\Phi$  an antiderivative of regulated function  $f$ .

*Proof of the Theorem 5.3.* Let  $x_1, x_2 \in [a, b]$  be arbitrary. Let  $F$  be defined as above. Then it holds that

$$|F(x_2) - F(x_1)| = \left| \int_a^{x_2} f \, d\xi - \int_a^{x_1} f \, d\xi \right|$$

$$\begin{aligned}
&= \left| \int_{\alpha}^{x_2} f d\xi + \int_{x_1}^{\alpha} f d\xi \right| = \left| \int_{x_1}^{x_2} f d\xi \right| \\
&\leq \int_{x_1}^{x_2} |f| d\xi \leq \int_{x_1}^{x_2} \underbrace{\|f\|_{\infty}}_{\text{const independent of } \xi} d\xi = \|f\|_{\infty} \cdot |x_2 - x_1|
\end{aligned}$$

Hence  $F$  is Lipschitz continuous with Lipschitz constant  $\|f\|_{\infty}$ . So  $F$  is continuous in  $[a, b]$ .

One-sided derivatives: Let  $x \in [a, b)$  and  $\varepsilon > 0$  be arbitrary. Choose  $\delta > 0$  such that  $\forall \xi \in [x, x + \delta)$  it holds that  $|f(\xi) - f_+(x)| < \varepsilon$ . For  $\xi \in (x, x + \delta)$  it holds that

$$\begin{aligned}
\left| \frac{F(\xi) - F(x)}{\xi - x} - f_+(x) \right| &= \frac{1}{|\xi - x|} \left| \underbrace{\int_x^{\xi} f dy}_{F(\xi) - F(x)} - \underbrace{f_+(x)(\xi - x)}_{\int_x^{\xi} f_+(x) dy} \right| = \frac{1}{|\xi - x|} \left| \int_x^{\xi} (f - f_+(x)) dy \right| \leq \frac{1}{|\xi - x|} \int_x^{\xi} \underbrace{|f(y) - f_+(x)|}_{< \varepsilon} dy \\
&\quad y \in (x, \xi) \subseteq (x, x + \delta) \\
&< \frac{1}{\xi - x} \varepsilon \cdot \underbrace{\int_x^{\xi} 1 dy}_{|\xi - x|} = \varepsilon
\end{aligned}$$

Hence,  $F'_+(x) = f_+(x)$ . Analogously,  $F'_-(x) = f_-(x)$  for  $x \in (a, b]$ .  $\square$

**Theorem 5.4** (Fundamental theorem of differential/integration calculus, variation 2). *Let  $f \in \mathcal{R}[a, b]$  and  $\phi$  is an arbitrary antiderivative of  $f$  according to Definition 5.3. For  $\alpha, \beta \in [a, b]$  arbitrary, it holds that*

$$\int_{\alpha}^{\beta} f dx = \phi(\beta) - \phi(\alpha)$$

**Remark 5.7.** *Let  $f$  be continuous and  $\phi$  be an antiderivative of  $f$ . Hence,  $\Phi'(x) = f(x) \forall x \in [a, b]$ . Then it holds that*

$$\int_{\alpha}^{\beta} \Phi' dx = \Phi(\beta) - \Phi(\alpha)$$

*“Integral of a derivative of  $\Phi$  gives  $\Phi(\beta) - \Phi(\alpha)$ ”.*

**Lemma 5.4.** *Let  $A \subseteq [a, b]$  countable.  $f : [a, b] \rightarrow \mathbb{R}$  is continuous and  $f$  is differentiable in every point  $x \in [a, b] \setminus A$ . Furthermore let  $|f'(x)| \leq L$  ( $L \geq 0$ ) for all  $x \in [a, b] \setminus A$ . Then  $f$  is Lipschitz continuous on  $[a, b]$  with constant  $L$ , hence*

$$|f(x_2) - f(x_1)| \leq L|x_2 - x_1| \forall x_1, x_2 \in [a, b]$$



**Remark 5.8.** Some people call it differentiable almost everywhere, but this expression collides with a different definition pronounced the same way from measure theory.

*Proof.* Let  $x_1, x_2 \in [a, b]$ , wlog.  $x_1 < x_2$ . Let  $\varepsilon > 0$  be arbitrary. We define

$$F_\varepsilon(x) = |f(x) - f(x_1)| - (L + \varepsilon)(x - x_1)$$

for  $x \in [x_1, b]$ .

Let  $\varepsilon > 0$  be arbitrary. We prove:  $F_\varepsilon(x) \leq 0 \forall x \in [x_1, b]$ . In particular:  $F_\varepsilon(x_2) \leq 0$ . Hence,

$$|f(x_2) - f(x_1)| \leq (L + \varepsilon) \underbrace{(x_2 - x_1)}_{|x_2 - x_1|}$$

We prove by contradiction: Assume there exists  $\varepsilon > 0$  and  $x_\varepsilon > x_1$  such that  $F_\varepsilon(x_\varepsilon) > 0$ .

We recognize: Let  $A' = [x_1, b] \cap A$  be countable.

1. hence  $F_\varepsilon(A') \subseteq \mathbb{R}$  is countable
2.  $F_\varepsilon(x_1) = 0, F_\varepsilon(x_\varepsilon) > 0 \implies x_\varepsilon > x_1$
3.  $F_\varepsilon$  is continuous on  $[x_1, b]$ . It holds that  $0 \in F_\varepsilon([x_1, x_\varepsilon])$  and because  $0 = F_\varepsilon(x_1)$  and  $\varepsilon \in F_\varepsilon([x_1, x_\varepsilon])$  because  $\varepsilon = F_\varepsilon(x_\varepsilon)$ .

By the Intermediate Value Theorem, it follows that  $[0, \varepsilon] \subseteq \text{TODO}$  By the Intermediate Value Theorem, it follows that  $\underbrace{[0, \eta]}_{\text{uncountable}} \subseteq F_\varepsilon([x_1, x_\varepsilon])$ .

$F_\varepsilon(A')$  is countable, hence there exists  $\gamma \in (0, \eta]$  such that  $\gamma = F_\varepsilon(y)$  and  $\gamma \notin A'$  ( $\gamma > 0$ )<sup>2</sup>. Hence,  $y \notin A'$ . So  $f$  in  $y$  is differentiable. Let  $B := F_\varepsilon^{-1}(\{\gamma\}) \cap ([x_1, x_\varepsilon] \setminus A')$ . Then  $B \neq \emptyset$ .

$B \subseteq [x_1, x_\varepsilon]$  is therefore bounded,  $B \neq \emptyset$ . Hence,  $B$  has a supremum. Let  $x = \sup B$ . Choose  $(y_n)_{n \in \mathbb{N}}$  with  $y_n \in B$  and  $y_n \rightarrow x$  for  $n \rightarrow \infty$ . Because  $F_\varepsilon$  is continuous, it holds that

$$\lim_{n \rightarrow \infty} \underbrace{F_\varepsilon(y_n)}_{\gamma} = F_\varepsilon(x)$$

hence  $F_\varepsilon(x) = \gamma$ . This implies  $x \notin A$ .

Furthermore it holds for  $w \in (x, x_\varepsilon]$  that  $F_\varepsilon(w) > \gamma$ . Because assume the opposite ( $F_\varepsilon(w) \leq \gamma$  for  $w > x$ ). Furthermore it holds that  $F_\varepsilon(x_\varepsilon) = \eta \geq \gamma$ . Because of the Intermediate Value Theorem,  $\exists y \geq w$  with  $F_\varepsilon(y) = \gamma$ . This contradicts with the supremum property of  $x$ .

---

<sup>2</sup>remember this as reference (\*)

Now let  $y \in (x, x_\varepsilon]$ .

$$\begin{aligned}
\varphi(y) &= \frac{F_\varepsilon(y) - F_\varepsilon(x)}{y - x} \\
&\stackrel{\substack{\text{definition of} \\ F_\varepsilon}}{=} \frac{|f(y) - f(x_1)| - |f(x) - f(x_1)|}{y - x} - \frac{(L + \varepsilon)(y - x_1 - x + x_1)}{y - x} \\
&\stackrel{\substack{\leq \\ \text{inversed triangle ineq.}}}{\leq} \frac{f(y) - f(x)}{y - x} - (L + \varepsilon)
\end{aligned}$$

Because  $F_\varepsilon(y) > \gamma = F_\varepsilon(x)$  it holds that  $\varphi(y) > 0$  for  $y > x$ . So,

$$\frac{|f(y) - f(x)|}{y - x} \geq L + \varepsilon$$

$$|f'(x)| = \lim_{y \rightarrow x_+} \left| \frac{f(y) - f(x)}{y - x} \right| \geq L + \varepsilon$$

This contradicts with the boundedness of the derivative by  $L$  and  $f$  is in  $x \notin A$  differentiable.

So, equations 2 do not hold. Therefore  $\forall x_1, x_2$  with  $x_1 < x_2$  in  $[a, b]$  and  $\forall \varepsilon > 0$ ,

$$\begin{aligned}
|f(x_2) - f(x_1)| &\leq (L + \varepsilon)|x_2 - x_1| \\
\implies |f(x_2) - f(x_1)| &\leq L|x_2 - x_1|
\end{aligned}$$

□

**Corollary** (Corollary to Lemma 5.4). *Let  $f, g : [a, b] \rightarrow \mathbb{R}$  differentiable for all points  $x \in [a, b] \setminus A$  and  $A$  is countable. Furthermore let  $f'(x) = g'(x) \forall x \notin A$ . Then there exists  $K \in \mathbb{R}$  such that  $f(x) = g(x) + K \forall x \in [a, b]$ .*

*Proof.* Let  $h = f - g$ . Then it holds that

$$h'(x) = f'(x) - g'(x) = 0 \forall x \in [a, b] \setminus A$$

By Lemma 5.4 with  $L = 0$ , it follows that

$$\begin{aligned}
|h(x_1) - h(x_2)| &\leq 0 \cdot |x_1 - x_2| = 0 \\
\implies h(x_1) &= h(x_2) \forall x_1, x_2 \in [a, b]
\end{aligned}$$

Hence,  $h(x) = K \in \mathbb{R}$ .

$$\implies f(x) = g(x) + h(x) = g(x) + K$$

□

This lecture took place on 2018/04/19.

By reference (\*),  $\gamma \in [0, \eta]$  (uncountable) and  $\gamma \notin f(A)$  (countable).

$$\implies \forall u \in [x_1, b) \text{ with } F_\varepsilon(u) = \gamma$$

it holds that  $u \notin A$ , hence  $f$  is differentiable in  $u$ .

*Proof of Theorem 5.4.* Let  $f \in \mathcal{R}[a, b]$ ,  $\phi$  is an antiderivative of  $f$ , hence  $\phi'_+ = f_+$ ,  $\phi'_- = f_-$ . Let  $\alpha \in [a, b]$  be arbitrary. By the Theorem variant 1,  $F(x) = \int_\alpha^x f d\xi$  is also an antiderivative of  $f$ . By Lemma ??,  $\exists K \in \mathbb{R} : F(x) = \int_\alpha^x f d\xi = \phi(x) + K$ . Determine  $K$ : Let  $x = \alpha \implies F(\alpha) = \int_\alpha^\alpha f dx = 0 = \phi(\alpha) - K$  hence  $K = \phi(\alpha)$ . Hence,

$$\int_\alpha^x f d\xi = \phi(x) - \phi(\alpha)$$

Let  $x = \beta$ . □

**Remark 5.9** (Remark for the previous corollary).  $F, \phi$  are differentiable on all points  $x$  for which  $f$  is continuous (all of them except for countable many). For those  $x$ , it holds that  $F'(x) = \phi'(x) = f(x)$ .

**Remark 5.10** (Notation). Let  $f \in \mathcal{R}[a, b]$ . Then

$$\int f dx$$

- is some particular antiderivative of  $f$  (usually some arbitrary chosen)
- the set of all antiderivatives of  $f$

$$\int f dx = \{F : F \text{ is antiderivative of } f\}$$

If  $F_0$  is some fixed antiderivative, then

$$\int f dx = \{F_0 + K : K \in \mathbb{R}\}$$

Then  $\int f dx$  is the so-called indefinite integral of  $f$ . Notation:

$$\int x^k dx = \frac{x^{k+1}}{k+1} + c \quad (k \neq -1)$$

$f$	$F$	remark
$x^\alpha$	$\frac{x^{\alpha+1}}{\alpha+1} + c$	$\alpha \in \mathbb{R} \setminus \{-1\}$ ; restrict $x$ such that $x^\alpha$ and $x^{\alpha+1}$ are defined
$x^{-1}$	$\ln x + c \ (x > 0)$	
$\left(\frac{1}{-x}\right) \cdot (-1) = x^{-1}$	$\ln -x + c \ (x < 0)$	
$e^x$	$e^x$	
$\sin x$	$-\cos x$	
$\cos x$	$\sin x$	
$\sinh x$	$\cosh x$	
$\cosh x$	$\sinh x$	
$\frac{1}{1+x^2}$	$\arctan x$	
$\frac{1}{\sqrt{1-x^2}}$	$\arcsin x$	$ x  < 1$
$-\frac{1}{\sqrt{1-x^2}}$	$\arccos x$	

Table 1: Table of antiderivatives

## Integration methods

In this chapter, we discuss how to determine the antiderivative of a function. Usually they are composites of basic functions. Some of these are given in Table 1.

**Remark 5.11.** Let  $F, G : [a, b] \rightarrow \mathbb{R}$  in  $x \in [a, b)$  right-sided differentiable. Then also  $F \cdot G$  in  $x$  is right-sided differentiable and it holds that

$$(F \cdot G)'_+(x) = F'_+(x) \cdot G(x) + F(x) \cdot G'_+(x)$$

hence the product law holds.

Analogously, the same holds for the left-sided derivative.

Look up the proof in the course Analysis 1.

## Partial integration

**Definition 5.4** (Partial integration). Let  $f, g$  be given. Let  $F, G$  be its antiderivatives respectively. Then  $F \cdot G$  is an antiderivative of  $F \cdot g + f \cdot G$ .

This is immediate, because

$$(F \cdot G)'_+ = F'_+ \cdot G + F \cdot G'_+ = f_+ \cdot G + F \cdot g_+ = f_+ G_+ + F_+ \cdot g_+$$

Hence, it holds that

$$\int_a^b (Fg + fG) dx = \underbrace{F(b) \cdot G(b) - F(a)G(a)}_{=: F \cdot G|_a^b}$$

Usually, this is rewritten as

$$\int_a^b F \cdot g \, dx = F \cdot G \Big|_a^b - \int_a^b f G \, dx$$

If  $F = u$  is continuously differentiable and  $G = v$  as well, then  $f = u'$  and  $g = v'$  and the law has the structure

$$\int_a^b uv' \, dx = u \cdot v \Big|_a^b - \int_a^b u'v \, dx$$

**Example 5.1.** Let  $a \neq -1$  and  $x > 0$ .

$$\int \underbrace{x^a}_{v'} \cdot \underbrace{\ln x}_u \, dx = \underbrace{\left| \begin{array}{ll} u = \ln x & u' = \frac{1}{x} \\ v' = x^a & v = \frac{x^{a+1}}{a+1} \end{array} \right|}_{\text{scribble notes}} \frac{x^{a+1}}{a+1} \cdot \ln x - \int \frac{1}{x} \cdot \frac{x^{a+1}}{a+1} \, dx$$

$$= \frac{x^{a+1}}{a+1} \cdot \ln x - \frac{1}{a+1} \int x^a \, dx = \frac{x^{a+1}}{a+1} \cdot \ln x - \frac{1}{(a+1)^2} x^{a+1}$$

**Example 5.2.** Let  $k \in \{2, 3, 4, \dots\}$ .

$$\int \cos^k(x) \, dx = \left| \begin{array}{ll} u = \cos^{k-1}(x) & u' = (k-1) \cdot \cos^{k-2}(x) \cdot (-\sin x) \\ v' = \cos x & v = \sin x \end{array} \right|$$

$$\cos^{k-1}(x) \sin x + (k-1) \int \cos^{k-2}(x) \cdot \underbrace{\sin^2(x)}_{(1-\cos^2 x)} \, dx$$

$$= \cos^{k-1}(x) \cdot \sin(x) + (k-1) \int \cos^{k-2}(x) \, dx - (k-1) \int \cos^k(x) \, dx$$

Then we can use the following identity:

$$k \int \cos^k(x) \, dx = \cos^{k-1}(x) \cdot \sin(x) + (k-1) \int \cos^{k-2}(x) \, dx$$

This gives a recursive formula:

$$\int \cos^k(x) \, dx = \frac{1}{k} \cos^{k-1}(x) \cdot \frac{k-1}{k} \sin(x) + (k-1) \int \cos^{k-2}(x) \, dx$$

Analogously,

$$\int \sin^k(x) \, dx = -\frac{1}{k} \sin^{k-1}(x) \cdot \cos(x) + \frac{k-1}{k} \int \sin^{k-2}(x) \, dx$$

Let  $c_m = \int_0^{\frac{\pi}{2}} \cos^m(x) dx$ . Then the following formula holds:

$$\begin{aligned} c_{2n} &= \frac{2n-1}{2n} \cdot \frac{2n-3}{2n-2} \cdot \frac{2n-5}{2n-4} \cdots \frac{1}{2} \cdot \frac{\pi}{2} \\ &= \prod_{k=1}^n \frac{2k-1}{2k} \cdot \frac{\pi}{2} \\ c_{2n+1} &= \prod_{k=1}^n \frac{2k}{2k+1} \end{aligned}$$

*Proof by induction.* Let  $n = 1$ .

$$\begin{aligned} c_2 &= \int_0^{\frac{\pi}{2}} \cos^2 x dx = \frac{1}{2} \cos x \sin x \Big|_0^{\frac{\pi}{2}} + \frac{1}{2} \int_0^{\frac{\pi}{2}} 1 dx = 0 - 0 + \frac{\pi}{4} \\ &= \underbrace{\prod_{k=1}^1 \frac{2k-1}{2k}}_{\frac{1}{2}} \cdot \frac{\pi}{2} \end{aligned}$$

$$c_1 = \int_0^{\frac{\pi}{2}} \cos x dx = \sin x \Big|_0^{\frac{\pi}{2}} = 1 - 0 = 1$$

$$\underbrace{\prod_{k=1}^0 \frac{2k}{2k+1}}_{\text{empty product}} = 1$$

We make the induction step  $n \rightarrow n+1$ :

$$\begin{aligned} c_{2(n+1)} &= \frac{1}{2n+2} \cdot \underbrace{\cos^{2n+1}(x)}_{=0 \text{ for } x=\frac{\pi}{2}} \cdot \underbrace{\sin(x)}_{=0 \text{ for } x=0} \Big|_0^{\frac{\pi}{2}} + \frac{2n+1}{2n+2} \int_0^{\frac{\pi}{2}} \cos^{2n}(x) dx \\ &= \frac{2n+1}{2n+2} \prod_{k=1}^n \frac{2k-1}{2k} \cdot \frac{\pi}{2} = \prod_{k=1}^{n+1} \frac{2k-1}{2k} \cdot \frac{\pi}{2} \end{aligned}$$

$c_{2(n+1)+1}$  analogously. □

**Theorem 5.5** (Wallis product). *John Wallis (1616–1703), result from 1655*

Let  $w_n = \prod_{k=1}^n \frac{(2k)^2}{(2k-1)(2k+1)} = \frac{2 \cdot 2}{1 \cdot 3} \cdot \frac{4 \cdot 4}{3 \cdot 5} \cdots$ . Then it holds that  $\lim_{n \rightarrow \infty} w_n = \frac{\pi}{2}$ .

*Proof.*

$$\frac{\pi}{2} \cdot \frac{c_{2n+1}}{c_{2n}} = \frac{\pi}{2} \cdot \prod_{k=1}^n \frac{\frac{2k}{2k+1}}{\prod_{k=1}^n \frac{2k-1}{2k} \cdot \frac{\pi}{2}} = \prod_{k=1}^n \frac{(2k)^2}{(2k-1)(2k+1)} = w_n$$

It remains to show that  $\lim_{n \rightarrow \infty} \frac{c_{2n+1}}{c_{2n}} = 1$  in  $[0, \frac{\pi}{2}]$  it holds that  $0 \leq \cos x \leq 1$ .

$$\implies \cos^{2n+2}(x) \leq \cos^{2n+1}(x) \leq \cos^{2n}(x)$$

So,  $c_{2n+2} \leq c_{2n+1} \leq c_{2n}$  for  $n \geq 1$ .

$$\begin{aligned} 1 &\geq \frac{c_{2n+1}}{c_{2n}} \\ \implies 1 &\geq \frac{c_{2n+1}}{c_{2n}} \geq \frac{c_{2n+2}}{c_{2n}} = \frac{\prod_{k=1}^{n+1} \frac{2k-1}{2k} \frac{\pi}{2}}{\prod_{k=1}^n \frac{2k-1}{2k} \frac{\pi}{2}} \\ &= \frac{2n+2-1}{2n+2} \rightarrow 1 \text{ for } n \rightarrow \infty \end{aligned}$$

Because of the sandwich lemma for convergent sequences, the intermediate expression must also converge to 1, hence

$$\lim_{n \rightarrow \infty} \frac{c_{2n+1}}{c_{2n}} = 1 \quad \wedge \quad \frac{\pi}{2} \cdot \lim_{n \rightarrow \infty} \frac{c_{2n+1}}{c_{2n}} = \underbrace{\lim_{n \rightarrow \infty} w_n}_{=1}$$

□

## Integration by substitution

**Definition 5.5** (Integration by substitution). *Let  $f : [a, b] \rightarrow \mathbb{R}$  be continuous. Let  $t : [\alpha, \beta] \rightarrow [a, b]$  be continuously differentiable. Let  $F$  be an antiderivative of  $f$  ( $F$  is therefore continuously differentiable). Then  $F \circ t : [\alpha, \beta] \rightarrow \mathbb{R}$  is also continuously differentiable and the chain rule holds:*

$$(F \circ t)' = (F' \circ t) \cdot t' = (f \circ t) \cdot t'$$

Hence  $F \circ t$  is an antiderivative of  $(f \circ t) \cdot t'$ . We apply it to integration:

$$\int_{\alpha}^{\beta} (f \circ t)(u) \cdot t'(u) du = (F \circ t)(\beta) - (F \circ t)(\alpha) = F(t(\beta)) - F(t(\alpha)) = \int_{t(\alpha)}^{t(\beta)} f(x) dx$$

Then we get the substitution integration method:

$$\int_{t(\alpha)}^{t(\beta)} f(x) dx = \int_{\alpha}^{\beta} f(t(u)) \cdot t'(u) du$$

**Remark 5.12** (Mnemonic). Consider the left-hand side and right-hand side simultaneously. Let  $x = t(u)$  (expressions inside parentheses). Then  $dx = t'(u) \cdot du$  (expressions on the right). Let  $u = \alpha \implies x = t(\alpha)$  and  $u = \beta \implies x = t(\beta)$  (interval boundaries).

**Example 5.3.**

$$\int_0^1 2x \sqrt{1-x^2} dx$$

Usually we have some expression, we want to substitute with  $u$ .

$$1 - x^2 = u \quad x = \sqrt{1-u} = t(u)$$

$$x = 0 = t(1) \quad x = 1 = t(0)$$

$$dx = \frac{1}{2} \cdot \frac{1}{\sqrt{1-u}} \cdot (-1) du$$

$$\int_0^1 2x \sqrt{1-x^2} dx = \int_1^0 2 \cdot \sqrt{1-u} \cdot u \cdot \frac{1}{2}(-1) \frac{1}{\sqrt{1-u}} du = \int_0^1 \sqrt{u} du = \left. \frac{u^{\frac{3}{2}}}{\frac{3}{2}} \right|_0^1 = \frac{2}{3}$$

$$\int_0^1 2x \sqrt{\underbrace{1-x^2}_u} dx = \left| \begin{array}{ll} u = 1 - x^2 & \\ x = 0 & \Leftrightarrow u = 1 \\ x = 1 & \Leftrightarrow u = 0 \\ 1 \cdot du & = -2x dx \end{array} \right| = - \int_1^0 \sqrt{u} du = \int_0^1 \sqrt{u} du$$

In general: we set  $h(u) = g(x)$ , then it holds that  $h'(u) du = g'(x) dx$ .

**Theorem 5.6.** Let  $f, \tilde{f} \in \mathcal{R}[a, b]$  and  $A \subseteq [a, b]$  countable. Furthermore  $f(x) = \tilde{f}(x) \forall x \in [a, b] \setminus A$ . Then it holds that

$$\int_a^b |f - \tilde{f}| dx = 0$$

Then it follows especially that

$$\int_a^b f dx = \int_a^b \tilde{f} dx$$

This lecture took place on 2018/04/24.

*Proof.* Show:  $r \in \mathcal{R}[a, b], r \geq 0$ .  $\int_a^b r dx = 0$  and  $r(x) = 0$  for  $x \in [a, b] \setminus A$ . Then it holds that  $\int_a^b r dx = 0$ . Let  $r$  be as above. First, we show:  $r_+(x) = \lim_{\xi \rightarrow x+} r(\xi) = 0 \forall x \in [a, b)$  and also  $r_-(x) = 0 \forall x \in (a, b]$ .

Proof of that: Let  $x \in [a, b)$  and  $y = r_+(x)$  (exists because  $r \in \mathcal{R}[a, b]$ ). Choose  $\delta_n = \frac{1}{n}$ .  $(x, x + \frac{1}{n}) \cap [a, b)$  is an open interval with uncountable many points, so



there is certainly one point in  $A$ . So there exists  $\xi_n \in ((x, x + \frac{1}{n}) \cap [a, b]) \setminus A$  and  $|\xi_n - x| < \delta_n = \frac{1}{n}$ . Hence,  $\lim_{n \rightarrow \infty} \xi_n = x$  and  $r(\xi_n) = 0$ . Therefore,  $\lim_{n \rightarrow \infty} r(\xi_n) = 0$  where  $r(\xi_n) = y = r_+(x)$ .

Analogously,  $r_-(x) = 0$  on  $(a, b]$ .

Let  $\varepsilon > 0$  be arbitrary. We let  $A_\varepsilon = \{w \in [a, b] \mid r(w) > \varepsilon\}$ . We show:  $A_\varepsilon$  is finite.

Assume  $A_\varepsilon$  would have infinitely many points. Choose a sequence  $(w_n)_{n \in \mathbb{N}}$  with  $w_n \in A_\varepsilon$  and  $w_n \neq w_m$  for  $n \neq m$  (works because  $A_\varepsilon$  is infinite).  $(w_n)_{n \in \mathbb{N}}$  is bounded, hence there exists a convergent subsequence  $(w_{n_k})_{k \in \mathbb{N}}$  with  $x = \lim_{k \rightarrow \infty} w_{n_k} \in [a, b]$  and  $w_{n_k} \in [a, b]$ .

Either  $(w_{n_k})$  contains infinitely many sequence element  $w_{n_k} < x$  (variant (a)) or infinitely many  $w_{n_k} > x$  (variant (b)). Let variant b hold without loss of generality.

Combine all  $w_{n_k} > x$  to one subsequence  $(w_{n_{k_l}})_{l \in \mathbb{N}}$ . This gives  $\lim_{l \rightarrow \infty} w_{n_{k_l}} = x$  and  $w_{n_{k_l}} > x$ , thus  $\lim_{l \rightarrow \infty} \underbrace{r(w_{n_{k_l}})}_{\geq \varepsilon \text{ because } w_{n_{k_l}} \in A_\varepsilon} = r_+(x) = 0$ . This gives a contradiction.

$\geq \varepsilon$  because  $w_{n_{k_l}} \in A_\varepsilon$

$A_\varepsilon$  must be finite.

Consider

$$A_{\frac{1}{n}} = \{w_1^n, \dots, w_{m_n}^n\}$$

finite. Let  $\varphi_n = \sum_{k=1}^{m_n} r(w_k^n) \cdot \chi_{\{w_k^n\}} \in \tau[a, b]$ .

For  $x = w_k^n \in A_{\frac{1}{n}}$  it holds that

$$\varphi_n(w_k^n) = \sum_{k=1}^{m_n} r(w_k^n) \cdot \underbrace{\chi_{\{w_k^n\}}(w_j^n)}_{\delta_{jk}} = r(w_j^n)$$

so  $|\varphi_n(x) - r(x)| = 0 \forall x \in A_{\frac{1}{n}}$ . Let  $x \in [a, b] \setminus A_{\frac{1}{n}}$ . Then it holds  $0 \leq r(x) < \frac{1}{n}$  and for  $x \notin A_{\frac{1}{n}}$  it holds that  $\varphi(x) = 0$ . Therefore,

$$|r(x) - \varphi(x)| = r(x) < \frac{1}{n}$$

hence  $\|r - \varphi_n\|_\infty < \frac{1}{n}$ . This means that  $\varphi_n \rightarrow r$  uniformly on  $[a, b]$ . Therefore

$$\lim_{n \rightarrow \infty} \underbrace{\int_a^b \varphi_n dx}_{=0} = \int_a^b r dx = 0$$

Now we want to finish the proof of our theorem: Let  $r(x) = |f(x) - \tilde{f}(x)| \geq 0$  and  $r(x) = 0$  for  $x \notin A$ . So,  $\int_a^b |f - \tilde{f}| dx = 0$  (first part proven).

$$\left| \int_a^b f dx - \int_a^b \tilde{f} dx \right| = \left| \int_a^b (f - \tilde{f}) dx \right| \leq \int_a^b |f - \tilde{f}| dx = 0$$

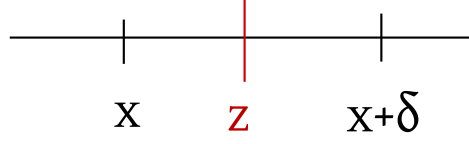


Figure 11:  $x$  and  $z$

$$\Rightarrow \int_a^b f dx = \int_a^b \tilde{f} dx$$

Second part proven. □

**Lemma 5.5.** Let  $f \in \mathcal{R}[a, b]$ . Then it holds that  $f_+ \in \mathcal{R}[a, b]$  and also  $f_- \in \mathcal{R}[a, b]$ .

*Proof.* Only for  $f_+$ : First, we show: Let  $x \in [a, b]$ .

$$f_+(x) = \lim_{\xi \rightarrow x_+} f(\xi) = \lim_{\xi \rightarrow x_+} f_+(\xi)$$

(the plus is important on the right-hand side!).

Proof of this: Let  $\varepsilon > 0$  be arbitrary. Then there exists  $\delta > 0$  such that  $\forall \xi \in (x, x + \delta)$ :  $|f(\xi) - f_+(x)| < \frac{\varepsilon}{2}$ . Now let  $z \in (x, x + \delta)$  be arbitrary chosen. For  $z$  there exists  $\xi \in (z, x + \delta)$ .

$\xi$  sufficiently close enough to  $z$  such that  $|f(\xi) - f_+(z)| \leq \frac{\varepsilon}{2}$  because  $f_+(z)$  exists.

$$|f_+(z) - f_+(x)| \leq |f_+(z) - f(\xi)| + |f(\xi) - f_+(x)| < \frac{\varepsilon}{2} + \frac{\varepsilon}{2}$$

TODO some content missing here

It remains to show:  $f_+$  has left-sided limits. Let  $x \in (a, b]$  be arbitrary and  $f_-(x) = \lim_{\xi \rightarrow x_-} f(\xi)$ . We show:  $f_-(x) = \lim_{\xi \rightarrow x_-} f_+(\xi)$  (again: the plus is important).

Let  $\varepsilon > 0$  be arbitrary. Choose  $\delta > 0$  such that  $\forall z \in (x - \delta, x)$  it holds that  $|f(z) - f_-(x)| < \frac{\varepsilon}{2}$ .

Now let  $\xi \in (x - \delta, x)$  (compare with Figure 12) and choose  $x > z > \xi$  with the property that  $|f(z) - f_+(\xi)| < \frac{\varepsilon}{2}$  (possible because  $f$  in  $\xi$  has a right-sided limit):

$$|f_+(\xi) - f_-(x)| \leq \underbrace{|f_+(\xi) - f(z)|}_{< \frac{\varepsilon}{2}} + \underbrace{|f(z) - f_-(x)|}_{< \frac{\varepsilon}{2}}$$

because of the choice of  $\delta$  and  $z \in (\xi, x) \subseteq (x - \delta, x)$ .

Hence,  $\lim_{\xi \rightarrow x_-} f_+(\xi) = f_-(x)$ . Analogously for  $f_-$  □

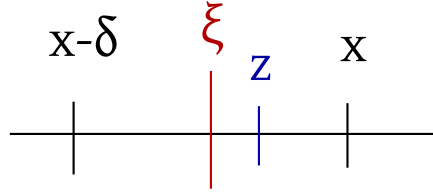


Figure 12:  $\xi$  and  $z$

**Remark 5.13.**

$$\lim_{\xi \rightarrow x_+} f_+(\xi) = f_+(x)$$

$$\lim_{\xi \rightarrow x_-} f_-(\xi) = f_-(x)$$

from the proof. So  $f_+$  is right-sided continuous and  $f_-$  is left-sided continuous.

**Lemma 5.6.** Let  $f \in \mathcal{R}[a, b]$ . Then it holds that

$$\int_a^b f \, dx = \int_a^b f_+ \, dx = \int_a^b f_- \, dx$$

*Proof.* For  $f_+$ :

$$f, f_+ \in \mathcal{R}[a, b]$$

$\forall x \in [a, b]$  with  $f$  is continuous in  $x$  it holds that

$$f(x) = \lim_{\xi \rightarrow x} f(\xi) = \lim_{\xi \rightarrow x_+} f(\xi) = f_+(x)$$

$f$  has at most countable many discontinuity points. By Satz 5.6,

$$\int_a^b |f - f_+| \, dx = 0 \quad \text{or equivalently} \quad \int_a^b f \, dx = \int_a^b f_+ \, dx$$

□

## Improper integrals

Let  $I$  be an interval in  $\mathbb{R}$  with marginal points  $a$  and  $b$  with  $-\infty \leq a < b \leq +\infty$ . Let  $f$  be a regulated function on  $I$ . We define

$$1. \text{ If } I = [a, b), \int_a^b f \, dx = \lim_{\beta \rightarrow b_-} \int_a^\beta f \, dx$$

2. If  $I = (a, b]$ ,  $\int_a^b f dx = \lim_{\alpha \rightarrow a+} \int_{\alpha}^b f dx$
3. If  $I = (a, b)$ ,  $\int_a^b f dx = \lim_{\alpha \rightarrow a+} \int_{\alpha}^c f dx + \lim_{\beta \rightarrow b-} \int_c^{\beta} f dx$

for an arbitrarily chosen  $c \in (a, b)$  under the constraint that the corresponding limits in  $\mathbb{R}$  exist.

Standard examples will follow:

**Example 5.4.** Let  $s > 1$ .

$$\begin{aligned} \int_1^{\infty} x^{-s} dx &= \lim_{\beta \rightarrow \infty} \int_1^{\beta} x^{-s} dx = \lim_{\beta \rightarrow \infty} \left( \frac{1}{-s+1} x^{-s+1} \right) \Big|_1^{\beta} \\ &= \frac{1}{1-s} \cdot \underbrace{\lim_{\beta \rightarrow \infty} \frac{1}{s-1}}_{\substack{\beta > 0 \\ =0}} - \frac{1}{1-s} \cdot 1 = \frac{1}{s-1} \end{aligned}$$

*TODO drawing*

**Example 5.5.** Let  $s < 1$ .

$$\begin{aligned} \int_0^1 x^{-s} dx &= \lim_{\alpha \rightarrow 0+} \int_{\alpha}^1 x^{-s} dx = \lim_{\alpha \rightarrow 0+} \frac{1}{-s+1} x^{-s+1} \Big|_{\alpha}^1 \\ &= \frac{1}{1-s} - \frac{1}{1-s} \cdot \underbrace{\lim_{\alpha \rightarrow 0} \alpha^{\overbrace{1-s}^{>0}}}_{=0} = \frac{1}{1-s} \end{aligned}$$

*TODO drawing*

For  $s = 1$ , neither  $\int_0^1 \frac{1}{x} dx$  nor  $\int_1^{\infty} \frac{1}{x} dx$  exists.

**Example 5.6.** For  $c > 0$ ,

$$\int_0^{\infty} e^{-cx} dx = \lim_{\beta \rightarrow \infty} \int_0^{\beta} e^{-cx} dx = \lim_{\beta \rightarrow \infty} \left( -\frac{1}{c} \right) \cdot e^{-cx} \Big|_0^{\beta} = \frac{1}{c} \cdot \underbrace{\lim_{\beta \rightarrow \infty} e^{-c\beta}}_{=0} + \frac{1}{c} = \frac{1}{c}$$

**Theorem 5.7** (Direct comparison test for improper integrals). In German, “Majorantenkriterium für uneigentliche Integrale”.

Let  $f, g$  be regulated functions on  $I$  and it holds that

$$|f(x)| \leq g(x) \forall x \in I$$

Assume  $\int_a^b g \, dx$  exists as improper integral. Then also the following improper integrals exist:

$$\int_a^b |f| \, dx \text{ and } \int_a^b f \, dx$$

In German,  $g$  is called Majorante of  $f$  (there is no equivalent terminology in English).

*Proof.* Without loss of generality, let  $I = [a, b)$ . Let  $G(\beta) = \int_a^\beta g \, dx$ . We know that  $\lim_{\beta \rightarrow b^-} G(\beta)$  exists. By Lemma 4.6 (Cauchy criterion for existence of limits): Let  $\varepsilon > 0$  be arbitrary, then there exists a right-sided neighborhood  $U$  of  $b$  ( $U = (b - \delta, b)$  if  $b < \infty$  and  $U = (M, \infty)$  if  $b = \infty$ ) with  $u, v \in U$ , then it holds that  $|G(v) - G(u)| < \varepsilon$ .

$$|G(v) - G(u)| = \left| \int_a^v g \, dx - \int_a^u g \, dx \right| = \left| \int_u^v g \, dx \right| = \left| \int_u^v |g| \, dx \right|$$

Let  $F(\beta) = \int_a^\beta |f| \, dx$ . Analogously as for  $G$ , it holds that  $F(v) - F(u) = \int_u^v |f| \, dx$ . Let  $u, v \in U$ . Then it holds that

$$|F(v) - F(u)| = \left| \int_u^v |f| \, dx \right| \leq \left| \int_u^v g \, dx \right| = |G(v) - G(u)| < \varepsilon$$

hence by the Cauchy criterion for  $F$ :  $\lim_{\beta \rightarrow b^-} F(\beta)$  exists, so there exists  $\int_a^b |f| \, dx$  as improper integral. The same applies for the existence of  $\int_a^b f \, dx$ .  $\square$

**Example 5.7.** The cardinal sine function is defined as

$$\text{sinc}(x) = \frac{\sin x}{x}$$

$$\lim_{x \rightarrow 0} \frac{\sin x}{x} = 1 \quad \text{sinc}(0) = 1$$

So  $\text{sinc}(x)$  is continuous on  $\mathbb{R}$ .

$$\int_0^\infty \frac{\sin x}{x} \, dx = \underbrace{\int_0^1 \frac{\sin x}{x} \, dx + \int_1^\infty \frac{\sin x}{x} \, dx}_{\substack{\text{continuous} \\ \text{exists}}}$$

How about  $\int_1^\infty \frac{\sin(x)}{x} \, dx$ ?

$$\begin{aligned} \lim_{\beta \rightarrow \infty} \int_1^\beta \frac{\sin x}{x} \, dx &= \left| \begin{matrix} u = \frac{1}{x} & u' = -\frac{1}{x^2} \\ v' = \sin x & v = -\cos x \end{matrix} \right| = \lim_{\beta \rightarrow \infty} \left[ -\frac{1}{x} \cos x \right]_1^\beta - \int_1^\beta \frac{\cos x}{x^2} \, dx \\ &= \cos(1) - \lim_{\beta \rightarrow \infty} \int_1^\beta \frac{\cos(x)}{x^2} \, dx \end{aligned}$$

$$\left| \frac{\cos(x)}{x^2} \right| \leq \frac{1}{x^2} \text{ on } [1, \beta]$$

and  $\int_1^\infty \frac{1}{x^2} dx$  exists. So  $g(x) = \frac{1}{x^2}$  is a majorant of  $\frac{\cos(x)}{x^2}$  and by Theorem 5.7,  $\lim_{\beta \rightarrow \infty} \int_1^\beta \frac{\cos(x)}{x^2} dx$  exists.

Attention!  $\int_0^\infty \left| \frac{\sin(x)}{x} \right| dx$  does not exist. Is not Lebesgue integrable.

**Definition 5.6.** Let  $x > 0$ . We call  $\Gamma$  Euler's Gamma function.

$$\Gamma(x) := \int_0^\infty t^{x-1} e^{-t} dt$$

**Remark 5.14.** The improper integral in the definition of the  $\Gamma$ -function exists for all  $x > 0$ .

This lecture took place on 2018/04/26.

TODO I missed the first 15 minutes

Proof of this:

Proof.

$$\lim_{t \rightarrow \infty} \underbrace{t^{x-1}}_{\text{polynomially in } t} \cdot \underbrace{e^{-t}}_{\text{exponentially } \rightarrow 0} = 0$$

Also there exists  $L > 1$ , such that  $\forall x > L$  it holds that  $t^{x-1} e^{-t/2} < 1$  on  $[1, L]$  (which is a compact interval) continuous. So there exists  $M > 0$  such that  $t^{x-1} e^{-\frac{t}{2}} \leq M \forall t \in [1, L]$ . Let  $c = \max\{M, 1\}$ . Therefore it holds on  $[1, L]$  and also on  $(L, \infty)$ .

$$t^{x-1} e^{-\frac{t}{2}} \leq c$$

Multiply with  $e^{-\frac{t}{2}} > 0$ , then it holds that  $t^{x-1} \cdot e^{-t} \leq c e^{-\frac{t}{2}} \forall t \in [1, \infty)$ .

$$c \int_1^\infty e^{-\frac{t}{2}} dt$$

exists. By the direct comparison test, we get  $\int_1^\infty t^{x-1} e^{-t} dt$  exists.  $\square$

**Lemma 5.7.** For all  $x > 0$  it holds that

$$\Gamma(x+1) = x \cdot \Gamma(x) \quad (\text{functional equation of the } \Gamma\text{-function})$$

Especially with  $\Gamma(1) = 1$  it holds that  $\Gamma(n+1) = n!$  for all  $n \in \mathbb{N}_0$ .

Proof.

$$\Gamma(x+1) = \int_0^\infty t^{x+1-1} e^{-t} dt = \int_0^\infty t^x e^{-t} dt$$

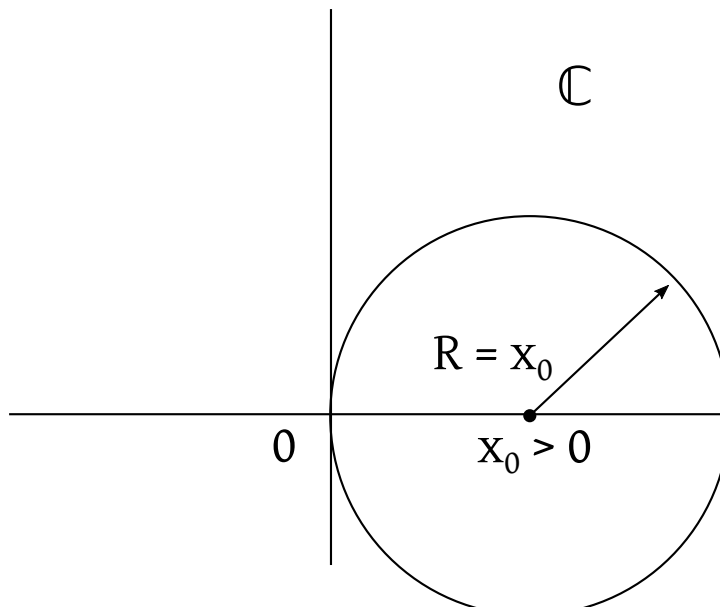


Figure 13:  $\Gamma$  on  $\mathbb{C}$

$$\begin{aligned}
 &= \left| \begin{array}{ll} u = t^x & u' = x \cdot t^{x-1} \\ v' = e^{-t} & v = -e^{-t} \end{array} \right| \\
 &= \underbrace{-t^x \cdot e^{-t} \Big|_0^\infty}_{\substack{=0 \text{ on the upper bound} \\ =0 \text{ on the lower bound}}} + \int_0^\infty x \cdot t^{x-1} \cdot e^{-t} dt = x \int_0^\infty t^{x-1} e^{-t} dt = x\Gamma(x)
 \end{aligned}$$

$$\Gamma(1) = \int_0^\infty \underbrace{t^{1-1}}_{=1} \cdot e^{-t} dt = -e^{-t} \Big|_0^\infty = 1$$

$$\Gamma(n+1) = n \cdot \Gamma(n) = n \cdot (n-1)\Gamma(n-1) = n \cdot (n-1) \cdot \dots \cdot 1 \cdot \underbrace{\Gamma(1)}_{=1} = n!$$

□

**Remark 5.15.** There exists a power series  $\Gamma(x) = \sum_{n=0}^\infty a_n(x-x_0)^n$ .  $\Gamma(z)$  is also defined for  $z \in \mathbb{C}$  with  $\Re z > 0$ . Compare with Figure 13.

## Young's inequality

Some important inequalities in integration theory follow.

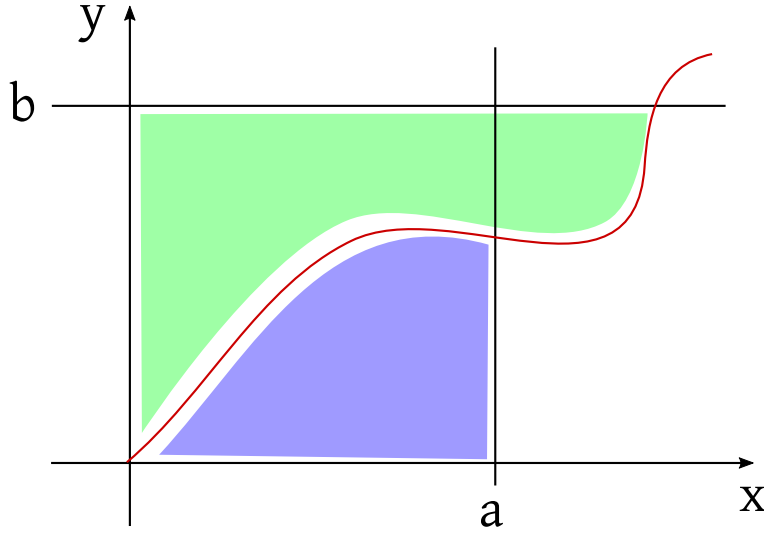


Figure 14: Young's inequality visualized. The blue area denotes  $\int_0^a f(x) dx$  and  $\int_0^b f^{-1}(y) dy$  is the green area.

**Theorem 5.8** (Young's inequality). *Let  $f : [0, \infty) \rightarrow [0, \infty)$  be continuous differentiable, strictly monotonically increasing with  $f(0) = 0$  and  $f$  is unbounded. Then  $f : [0, \infty) \rightarrow [0, \infty)$  bijective and  $f^{-1} : [0, \infty) \rightarrow [0, \infty)$  is strictly monotonically increasing and continuous. Let  $a, b \geq 0$  be given. Then it holds that*

$$ab \leq \int_0^a f(x) dx + \int_0^b f^{-1}(y) dy$$

*Equality is given if and only if,  $b = f(a)$  or  $a = f^{-1}(b)$ . Compare with Figure 14.*

*Proof.* Let  $f : [0, \infty) \rightarrow [0, \infty)$  be as above. Let  $x_1 \neq x_2$ . Without loss of generality  $x_1 < x_2$ . Then it holds that  $f(x_1) < f(x_2) \implies f$  is injective. Surjectivity:  $f(0) = 0$ , hence  $0 \in f([0, \infty))$ . Let  $\eta > 0$  be arbitrary. Because  $f$  is unbounded, there exists  $z \in (0, \infty)$  with  $f(z) > \eta$ .  $f(0) = 0 < \eta < f(z)$ .

By the Intermediate Value Theorem ( $f$  is continuous), there exists  $\xi \in (0, z)$  with  $f(\xi) = \eta$ . So  $f$  is surjective.

$$f^{-1} : [0, \infty) \rightarrow [0, \infty)$$



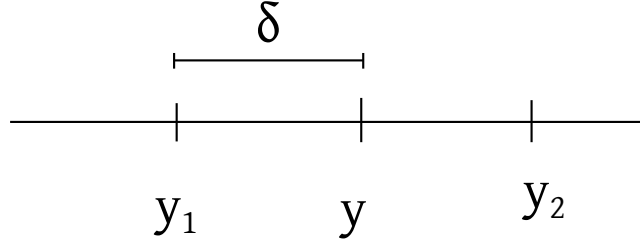


Figure 15:  $\delta$ ,  $y$ ,  $y_1$  and  $y_2$

*Monotonicity:* Let  $y_1 < y_2$ . Then it holds that  $x_1 = f^{-1}(y_1) < x_2 = f^{-1}(y_2)$ . If this would not be true (hence,  $x_2 \leq x_1$ ) then  $y_2 = f(x_2) \leq y_1 = f(x_1)$  gives a contradiction.

*Continuity of  $f^{-1}$ :* Let  $\varepsilon > 0$  be arbitrary. Let  $y \in (0, \infty)$  be chosen arbitrarily. We show  $f^{-1}$  is continuous in  $y$ . Let  $x = f^{-1}(y) > 0$  and choose  $\varepsilon = \min\left\{\frac{x}{2}, \frac{\varepsilon}{2}\right\}$ .

$$x_1 = x - \varepsilon > 0 \quad x_2 = x + \varepsilon > 0$$

Let  $y_1 = f(x_1)$ ,  $y_2 = f(x_2)$ ,  $x_1 = f^{-1}(y_1)$  and  $x_2 = f^{-1}(y_2)$ . By monotonicity of  $f$ :  $x_1 < x < x_2 \implies y_1 < y < y_2$ .

Choose  $\delta = \min\{y - y_1, y_2 - y\} > 0$  (compare with Figure 15). Hence  $(y - \delta, y + \delta) \subseteq (y_1, y_2) \forall \eta \in (y - \delta, y + \delta)$  it holds that

$$f^{-1}(\eta) < f^{-1}(y + \delta) < f^{-1}(y_2) = x_2 = x + \varepsilon$$

$$f^{-1}(\eta) < f^{-1}(y - \delta) < f^{-1}(y_1) = x_1 = x - \varepsilon$$

So  $f^{-1}(\eta) \in (x - \varepsilon, x + \varepsilon)$ , or equivalently

$$|\eta - y| < \delta \implies \left| f^{-1}(\eta) - \underbrace{f^{-1}(y)}_{=x} \right| < c \leq \frac{\varepsilon}{2} < \varepsilon$$

So  $f^{-1}$  is continuous in  $y$  and  $f^{-1}$  is continuous in  $y_0$  analogously.  $\square$

Consider

$$\begin{aligned} \int_0^b f^{-1}(y) dy &= \left| \begin{array}{l} y \\ y=0 \\ y=b \end{array} \right| \begin{array}{l} = f(x) \\ \Rightarrow x = f^{-1}(0) = 0 \\ \Rightarrow x = f^{-1}(b) \end{array} \left| \begin{array}{l} = f'(x) dx \\ = f'(x) dx \\ = f'(x) dx \end{array} \right| = \int_0^{f^{-1}(b)} \underbrace{f^{-1}(f(x))}_{=x} \cdot f'(x) dx = \int_0^{f^{-1}(b)} x \cdot f'(x) dx \\ &= \underbrace{x \cdot f(x) \Big|_0^{f^{-1}(b)}}_{\text{integration by parts}} - 0 \int_0^{f^{-1}(b)} 1 \cdot f(x) dx \\ &= f^{-1}(b) \cdot b - \int_0^{f^{-1}(b)} f(x) dx \end{aligned}$$

So

$$\begin{aligned} I &= \int_0^a f(x) dx + \int_0^b f^{-1}(y) dy = \int_{f^{-1}(b)}^0 f(x) dx + b \cdot f^{-1}(b) \\ &= \int_{f^{-1}(b)}^a f(x) dx + b \cdot f^{-1}(b) \end{aligned}$$

**Case 1**  $a = f^{-1}(b)$

$$\Rightarrow I = \underbrace{\int_a^a f(x) dx}_{=0} + b \cdot a$$

**Case 2**  $b < f(a)$ , or equivalently  $f^{-1}(b) < a$

$$\Rightarrow \int_{f^{-1}(b)}^a \underbrace{f(x)}_{f(f^{-1}(b)) \text{ for } x > f^{-1}(b)} dx > \overbrace{b}^{\text{minimal value}} \cdot \underbrace{(a - f^{-1}(b))}_{\text{length of integration interval}}$$

Therefore  $I > b(a - f^{-1}(b)) + b \cdot f^{-1}(b) = ab$ .

**Case 3**  $b > f(a)$ , or equivalently  $f^{-1}(b) > a$

$$\begin{aligned} \int_{f^{-1}(b)}^a f(x) dx &= \int_a^{f^{-1}(b)} \underbrace{(-f(x))}_{\substack{\text{monotonically decreasing} \\ > -f(f^{-1}(b)) \forall x \in [a, f^{-1}(b)]}} dx > -f(f^{-1}(b)) \cdot (f^{-1}(b) - a) \\ &= -b(f^{-1}(b) - a) \\ I &> -b(f^{-1}(b) - a) + b \cdot f^{-1}(b) = ab \end{aligned}$$

**Remark 5.16.** Young's inequality also holds without requiring differentiability of  $f$  (but the proof is more complex).

**Lemma 5.8** (Special case of Young's inequality). Let  $A, B \geq 0$  and  $p, q > 1$  such that  $\frac{1}{p} + \frac{1}{q} = 1 \iff p + q = p \cdot q$ . Then  $p$  and  $q$  are called conjugate exponents. Then it holds that  $AB \leq \frac{A^p}{p} + \frac{B^q}{q}$ .

*Proof.*

$$f(x) = x^{p-1} \text{ in Young's inequality}$$

$$y = x^{p-1} \iff x = y^{\frac{1}{p-1}}$$

$$\frac{1}{p-1} = q-1 \text{ is immediate, because}$$

$$\frac{1}{p-1} = q-1 \iff 1 = pq - p - q + 1 \iff p + q = pq$$

So  $f^{-1}(y) = y^{\frac{1}{p-1}} = y^{q-1}$ . By Young's inequality:

$$\begin{aligned} AB &\leq \int_0^A x^{p-1} dx + \int_0^B y^{q-1} dy \\ &= \frac{x^p}{p} \Big|_0^A + \frac{y^q}{q} \Big|_0^B = \frac{A^p}{p} + \frac{B^q}{q} \end{aligned}$$

□

**Remark 5.17.**

$$AB = \frac{A^p}{p} + \frac{B^q}{q}$$

Equality holds if and only if  $B = A^{p-1} \iff B^q = \overbrace{A^{pq} - q}^p = A^p$ .

## Hölder's inequality

**Theorem 5.9** (Hölder's inequality). Let  $I$  be an interval with boundary values  $a$  and  $b$ .  $-\infty \leq a < b \leq +\infty$ . Let  $p$  and  $q$  be conjugate exponents. Let  $f_1$  and  $f_2$  be regulated function on  $I$  such that

$$\int_a^b |f_1(x)|^p dx < \infty$$

$$\int_a^b |f_2(x)|^q dx < \infty$$

both exist.

We let  $\|f_1\|_p := \left( \int_a^b |f_1(x)|^p dx \right)^{\frac{1}{p}}$  and  $\|f_2\|_q := \left( \int_a^b |f_2(x)|^q dx \right)^{\frac{1}{q}}$ . They are called  $L^p$ -norm of  $f_1$  and  $L^q$ -norm of  $f_2$ .

Then it holds that

$$\int_a^b |f_1(x) \cdot f_2(x)| dx < \infty$$

exists and

$$\int_a^b |f_1(x) \cdot f_2(x)| dx \leq \|f_1\|_p \cdot \|f_2\|_q$$

*Proof.* Assume that  $\|f_1\|_p > 0$  and  $\|f_2\|_q > 0$ . Let  $A = \frac{|f_1(x)|}{\|f_1\|_p}$  and  $B = \frac{|f_2(x)|}{\|f_2\|_q}$ . By Lemma 5.8,

$$\frac{|f_1(x)|}{\|f_1\|_p} \cdot \frac{|f_2(x)|}{\|f_2\|_q} \leq \frac{1}{q} \cdot \frac{|f_1(x)|^p}{\|f_1\|_p^p} + \frac{1}{q} \cdot \frac{|f_2(x)|^q}{\|f_2\|_q^q}$$

We integrate the inequality,

$$\begin{aligned} & \frac{1}{\|f_1\|_p \cdot \|f_2\|_q} \cdot \int_a^b |f_1(x) \cdot f_2(x)| dx \\ & \leq \frac{1}{p} \cdot \frac{1}{\|f_1\|_p^p} \cdot \underbrace{\int_a^b |f_1(x)|^p dx}_{=\|f_1\|_p^p} + \frac{1}{q} \cdot \frac{1}{\|f_2\|_q^q} \underbrace{\int_a^b |f_2(x)|^q dx}_{=\|f_2\|_q^q} = \frac{1}{p} + \frac{1}{q} = 1 \end{aligned}$$

$$\frac{1}{\|f_1\|_p \cdot \|f_2\|_q} \cdot \int_a^b |f_1(x) \cdot f_2(x)| dx \implies \int_a^b |f_1(x) f_2(x)| dx \leq \|f_1\|_p \cdot \|f_2\|_q$$

Special case: Let  $\|f_1\|_p = 0$

$$\implies \left( \int_a^b |f_1(x)|^p dx \right)^{\frac{1}{p}} = 0 \implies \int_a^b \underbrace{|f_1(x)|^p}_{\geq 0} dx = 0$$

By Theorem 5.6,  $f_1(x) = 0 \forall x \in [a, b] \setminus A$  and  $A$  is at most countable.

$$\implies f_1(x) \cdot f_2(x) = 0 \forall x \in [a, b] \setminus A$$

$$\implies \int_a^b |f_1(x) \cdot f_2(x)| dx = 0$$

$$\implies 0 = 0 \text{ in Hölder's inequality}$$

□

**Remark 5.18** (Special case of Hölder's inequality). Let  $p = q = 2$ ,  $\frac{1}{2} + \frac{1}{2} = 1$ .

$$\int_a^b |f_1(x) \cdot f_2(x)| dx \leq \|f_1\|_2 \|f_2\|_2$$

is called *Cauchy-Schwarz inequality* for  $L^2$  functions.

$$\int_a^b f_1(x)f_2(x) dx = \langle f_1, f_2 \rangle_2 = \langle f_1, f_2 \rangle_{L^2}$$

is an inner product on a proper space of functions.

## Elaboration on differential calculus

We consider a metric space  $X$  and functions  $f : X \rightarrow \mathbb{C}$ . We define a concept of uniform convergence of such sequences:

$$f_n : X \rightarrow \mathbb{C} \quad (n \in \mathbb{N}) \text{ and } f : X \rightarrow \mathbb{C}$$

We say,  $(f_n)_{n \in \mathbb{N}}$  converges uniformly towards  $f$  if  $\forall \varepsilon > 0 \forall N \in \mathbb{N}$  such that  $\forall x \in X$  and  $\forall n \geq N$  it holds that

$$\underbrace{|f_n(x) - f(x)|}_{\text{absolute value in } \mathbb{C}} < \varepsilon$$

$$\iff \sup \{|f_n(x) - f(x)| : x \in X\} < \varepsilon$$

**Remark 6.1.** Do not use  $\|f\|_\infty$  for the definition of uniform convergence, because  $f_n$  and  $f$  must not be necessarily bounded. Hence,

$$\|f\|_\infty = \{ |f(x)| : x \in X \}$$

must not be finite.

**Theorem 6.1.** Let  $X$  be a metric space,  $f_n : X \rightarrow \mathbb{C}$  be a sequence of continuous functions and  $f : X \rightarrow \mathbb{C}$  such that  $f_n \rightarrow f$  uniform on  $X$ . Then  $f$  is also continuous on  $X$ .

*This lecture took place on 2018/05/03.*

*Proof.* Let  $\varepsilon > 0$  be arbitrary. Choose  $x \in X$ . Show:  $f$  is continuous in  $x$ .

Compare with Figure 16.

Because of uniform convergence  $f_n \rightarrow f$ , there exists  $N \in \mathbb{N}$  such that  $|f_N(z) - f(z)| < \frac{\varepsilon}{3} \forall z \in X$ . Let  $N$  be fixed. Because  $f_N$  is continuous in  $x$ , there exists  $\delta > 0$  such that  $d(x, \xi) < \delta \implies |f_N(\xi) - f_N(x)| < \frac{\varepsilon}{3}$ .

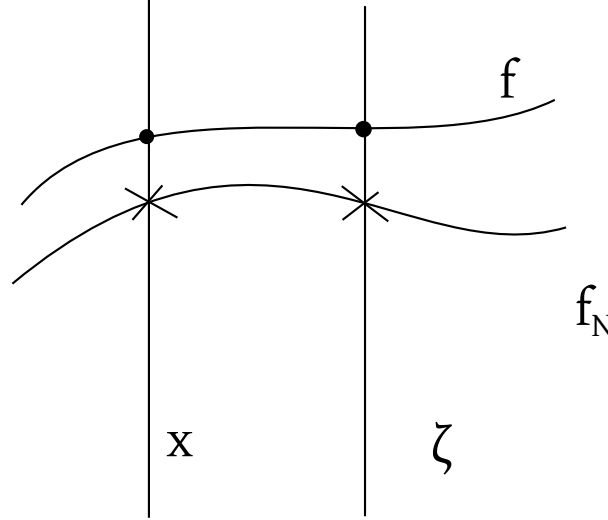


Figure 16: Uniform convergence of  $f_N$  to  $f$

We consider now  $\xi \in X$  with  $d_X(x, \xi) < \delta$ . Then it holds that

$$\begin{aligned}
 |f(x) - f(\xi)| &= |f(x) - f_N(x) + f_N(x) - f_N(\xi) + f_N(\xi) - f(\xi)| \\
 &\leq \underbrace{|f(x) - f_N(x)|}_{< \frac{\varepsilon}{2}} + \underbrace{|f_N(x) - f_N(\xi)|}_{< \frac{\varepsilon}{3}} + \underbrace{|f_N(\xi) - f(\xi)|}_{< \frac{\varepsilon}{3}} \\
 &= \varepsilon
 \end{aligned}$$

by uniform convergence, by continuity and by uniform convergence respectively.

Thus,  $f$  is continuous in  $x$ . □

**Theorem 6.2.** Let  $P(z) = \sum_{k=0}^{\infty} a_k z^k$  be a power series in  $\mathbb{C}$  with convergence radius  $\rho_P > 0$ . Furthermore, let  $0 < r < \rho_P$ . Let  $P_n(z) = \sum_{k=0}^n a_k z^k$  ( $n$ -th partial sum of  $P$ ). Then  $P_n \rightarrow P$  uniformly on  $\overline{K_r(0)}$ .

*Proof.* Approximation theorem for power series. Lettl Analysis 1, lecture notes, section 5, theorem 10.

Let  $0 < r < \rho_P$ . Choose  $\bar{r}$  with  $r < \bar{r} < \rho_P$ . Then it holds for  $z \in \overline{K_r(0)}$  that

$$|P(z) - P_n(z)| < \frac{\bar{r}}{\bar{r} - r} \cdot \left(\frac{r}{\bar{r}}\right)^n$$

Remark 6.2.

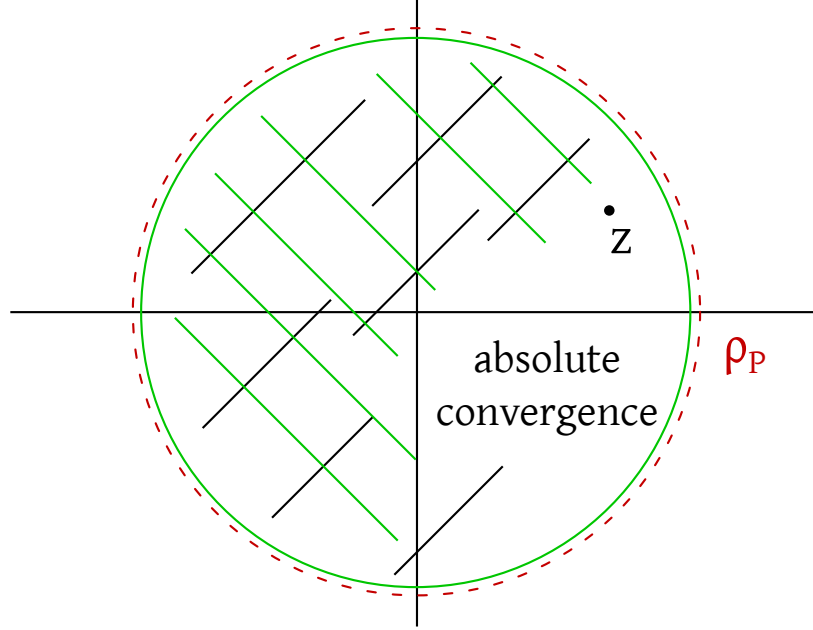


Figure 17: We cannot make a general statement about convergence/divergence. But on every small closed sphere  $P$  converges absolutely for every  $z$

$$\frac{r}{\bar{r}} < 1$$

hence  $\left(\frac{r}{\bar{r}}\right)^n$  is arbitrary small, for every  $n$  sufficiently large.

$$\Rightarrow \sup \left\{ |P(z) - P_n(z) : z \in \overline{K_r(0)} \right\} \leq \underbrace{\frac{\bar{r}}{\bar{r} - r}}_{\text{fixed}} \cdot \underbrace{\left(\frac{r}{\bar{r}}\right)^n}_{\text{arbitrary small for } n \text{ sufficiently large}}$$

Hence,  $P_n \rightarrow P$  uniform on  $\overline{K_r(0)}$ . □

**Corollary.**  $P$  is continuous on  $K_{\rho_P}(0)$ .

**Theorem 6.3.** Let  $I \subseteq \mathbb{R}$  be an interval. Let  $f_n : I \rightarrow \mathbb{R}$  be continuously differentiable on  $I \forall n \in \mathbb{N}$ . It holds that

1.  $\exists g : I \rightarrow \mathbb{R}$  such that  $f'_n \rightarrow g$  uniform on  $I$
2.  $\exists f : I \rightarrow \mathbb{R}$  such that  $\forall x \in I$  it holds that  $f(x) = \lim_{n \rightarrow \infty} f_n(x)$  ("pointwise convergence").

Then it holds that  $f$  is continuously differentiable on  $I$  and  $g = f'$ .

*Proof.*  $g$  is continuous as uniform limit of continuous  $f'_n$  (Theorem 6.1). For  $f_n$ , the Fundamental Theorem of Differential Calculus can be applied ( $f'_n$  is continuous, hence a regulated function). Let  $x_0 \in I$ . Then it holds that

$$f_n(x) = f_n(x_0) + \int_{x_0}^x f'_n(\xi) d\xi$$

Convergence for  $n \rightarrow \infty$ :

$$f_n(x) \rightarrow f(x) \quad f_n(x_0) \rightarrow f(x_0)$$

(Pointwise convergence)

$$\int_{x_0}^x f'_n(\xi) d\xi \rightarrow \int_{x_0}^x g(\xi) d\xi$$

Therefore, for  $n \rightarrow \infty$ ,

$$f(x) = f(x_0) + \int_{x_0}^x g(\xi) d\xi$$

The right-hand side is continuously differentiable by  $x$  according to the Fundamental Theorem, variant 1, with

$$\left( f(x_0) + \int_{x_0}^x g(\xi) d\xi \right)'(x) = g(x)$$

Hence, by  $f(x) = f(x_0) + \int_{x_0}^x g(\xi) d\xi$  it follows that

$$f'(x) = g(x) \quad \forall x \in I$$

□

To finish our proof, we need a result we missed in the section about Integrals.

**Lemma 6.1.** *Let  $(f_n)_{n \in \mathbb{N}}$  be a sequence of regulated functions on  $[a, b]$  and  $f_n \rightarrow f$  uniform on  $[a, b]$ . Then it holds that*

$$\int_a^b |f_n - f| dx \rightarrow 0 \quad \text{for } n \rightarrow \infty \quad \text{especially } \int_a^b f_n dx \rightarrow \int_a^b f dx$$

*Proof.*  $f$  as a uniform limit of regulated functions is a regulated function. The proof has been done in the practicals.

Let  $N \in \mathbb{N}$  large enough such that

$$\forall n \geq N \forall x \in [a, b] : |f_n(x) - f(x)| < \frac{\varepsilon}{b-a}$$

Then it holds that

$$\int_a^b |f_n(x) - f(x)| dx < \int_a^b \frac{\varepsilon}{b-a} dx = \frac{\varepsilon}{b-a} (b-a) = \varepsilon$$



Hence,

$$\lim_{n \rightarrow \infty} \int_a^b |f_n(x) - f(x)| dx = 0$$

$$\underbrace{\left| \int_a^b f_n dx - \int_a^b f dx \right|}_{\Rightarrow \rightarrow 0} \leq \underbrace{\int_a^b |f_n - f| dx}_{\rightarrow 0}$$

So,

$$\int_a^b f dx = \lim_{n \rightarrow \infty} \int_a^b f_n dx$$

□

## Higher derivatives and Taylor's Theorem

**Definition 6.1.** Let  $f : I \rightarrow \mathbb{R}$ ,  $I \subseteq \mathbb{R}$  is an interval. We define inductively:

$$f^{(0)}(x) = f(x)$$

Assume  $f^{(n-1)}$  is defined continuously on  $I$  and differentiable in  $x \in I$ . Then we let

$$f^{(n)}(x) = \left( f^{(n-1)} \right)'(x)$$

$f^{(n)}(x)$  is called  $n$ -th derivative of  $f$  in  $x$ .

Notational remark:

$$f^{(0)} = f \quad f^{(1)} = f' \quad f^{(2)} = f'' \quad f^{(3)} = f''' \quad f^{(4)} = f''''$$

Furthermore, we let

$$C^n(I) := \left\{ f : I \rightarrow \mathbb{R} : f^{(k)}(x) \text{ exists } \forall x \in I \text{ and } x \mapsto f^{(k)}(x) \text{ is continuous } \forall 0 \leq k \leq n \right\}$$

We call  $C$  the space of  $n$ -times continuously differentiable functions on  $I$ .

**Remark 6.3.**  $C^n(I)$  is a vector space. If  $I = [a, b]$  is compact, then

$$\|f\|_{C^n} = \max \left\{ \sup |f^{(k)}(x)| : x \in I : 0 \leq k \leq n \right\}$$

defines a norm on  $C^n(I)$  with  $\sup |f^{(k)}(x)| : x \in I = \|f^{(k)}\|_{\infty}$ .

**Remark 6.4** (New topic). Let  $f \in C^n(I)$  and  $x_0 \in I$ . Find an appropriate polynomial  $T$  which approximated  $f$  in an environment of  $x_0$  in the "best" way.

**Definition 6.2.** Let  $P(x) = \sum_{k=0}^n a_k x^k$  be a polynomial with  $a_n \neq 0$  (hence degree of  $P$  is  $n$ ).

$$P \in \mathbb{R}[x] \dots \text{ set of all polynomials with coefficients in } \mathbb{R}$$

This set of polynomials is a ring.

$x_0 \in \mathbb{R}$  is called  $k$ -times root of  $P$  ( $k \in \mathbb{N}$ ) if  $Q \in \mathbb{R}[x]$  exists such that  $P(x) = (x - x_0)^k Q(x)$  with  $Q(x_0) \neq 0$ .

**Remark 6.5.**  $P(x) = (x - x_0)^k \cdot Q(x)$  means that division of  $P$  by  $(x - x_0)^k$  gives no remainder. Recall that division with remainder means that  $\exists \hat{Q}, \hat{R}$  that are polynomials of degree  $\hat{R} < k$ ,

$$P(x) = (x - x_0)^k \cdot \hat{Q}(x) + \hat{R}(x)$$

$\hat{Q}, \hat{R}$  is unique. If  $P(x) = (x - x_0)^k \cdot Q(x) \implies \hat{R} = 0, \hat{Q} = Q$ .

**Lemma 6.2.** Let  $P(x) = \sum_{l=0}^n a_l x^l$  with  $a_n \neq 0$ . Let  $1 \leq k \leq n$ . Then it holds that  $x_0 \in \mathbb{R}$  is a  $k$ -times root of polynomial  $P \iff P^{(j)}(x_0) = 0$  for  $j = 0, \dots, k-1$  and  $P^{(k)}(x_0) \neq 0$ .

*Proof.* Proof by complete induction.

**Induction begin** Consider  $k = 1$ . Direction  $\implies$ .

Let  $x_0$  be a simple root of  $P$ , then it holds that  $P(x) = (x - x_0) \cdot Q(x)$  and  $Q(x_0) \neq 0$ . Hence,  $P(x_0) = (x_0 - x_0) \cdot Q(x_0) = 0$  and  $P'(x) = Q(x) + (x - x_0) \cdot Q'(x)$ . Thus,  $P'(x_0) = Q(x_0) + (x_0 - x_0) \cdot Q'(x_0) = Q(x_0) \neq 0$ .

Direction  $\impliedby$ .

Let  $P(x_0) = 0$  and  $P'(x_0) \neq 0$ . Division with remainder:  $P(x) = (x - x_0) \cdot Q(x) + R(x)$  with  $\text{degree}(R) \leq \text{degree}(x - x_0) = 1$ . Thus,  $R$  is constant. We insert  $x_0$ . This gives  $P(x_0) = (x_0 - x_0) \cdot Q(x_0) + R$  with  $P(x_0) = 0$  and  $(x_0 - x_0) = 0$ . Hence,  $R = 0$  is the zero polynomial and  $P(x) = (x - x_0) \cdot Q(x)$ . It remains to show that  $Q(x_0) \neq 0$ .  $P'(x) = 1 \cdot Q(x_0) + (x - x_0) \cdot Q'(x_0)$ . We insert  $x = x_0 \implies 0 \neq P'(x_0) = Q(x_0) + (x_0 - x_0) \cdot Q'(x)$ . Thus it holds that  $Q(x_0) = P'(x_0) \neq 0$ .

**Induction step**

**Claim** (Auxiliary claim). Let  $P(x) = (x - x_0) \cdot \tilde{P}(x)$ . Let  $P, \tilde{P}$  be polynomials. Then it holds  $\forall j \in \mathbb{N}$  that

$$P^{(j)}(x) = (x - x_0) \cdot \tilde{P}^{(j)}(x) + j \cdot \tilde{P}^{(j-1)}(x)$$

*Proof.* Proof by complete induction.

Let  $j = 1$ .

$$P'(x) = 1 \cdot \underbrace{\tilde{P}(x)}_{\tilde{P}^{(0)}(x)} + (x - x_0) \cdot \underbrace{\tilde{P}'(x)}_{\tilde{P}^{(1)}(x)}$$

Consider  $j \rightarrow j + 1$ .

$$\begin{aligned} P^{(j+1)}(x) &= \left(P^{(j)}\right)'(x) \\ &= \underbrace{((x - x_0) \cdot \tilde{P}^{(j)}(x))'}_{\text{induction assumption}} \\ &\quad + j \tilde{P}^{(j-1)}(x)'(x - x_0) \tilde{P}^{(j+1)}(x) + \tilde{P}^{(j)}(x) + j \cdot \tilde{P}^{(j)}(x) \\ &= (x - x_0) \tilde{P}^{(j+1)}(x) + (j + 1) \cdot \tilde{P}^{(j)}(x) \end{aligned}$$

□

We continue with the induction step after verifying our auxiliary claim.

Direction  $\implies$ .

Let  $x_0$  be an  $k+1$  times zero of  $P$ . Hence  $P(x) = (x - x_0)^{k+1} \cdot Q(x)$ .  $Q(x_0) \neq 0$ .

Let  $\tilde{P}(x) = (x - x_0)^k \cdot Q(x)$ . We can apply the induction assumption on  $\tilde{P}$ .

Hence

$$\tilde{P}^{(j)} = 0 \quad \text{for } j = 0, \dots, k-1 \quad \text{and} \quad \tilde{P}^{(k)}(x_0) \neq 0$$

$$P(x) = (x - x_0) \cdot \tilde{P}(x)$$

By the auxiliary claim,  $P^{(j)}(x) = (x - x_0) \cdot \tilde{P}^{(j)}(x) + j \cdot \tilde{P}^{(j-1)}(x)$ . Therefore

$$P^{(j)}(x_0) = j \cdot \tilde{P}^{(j-1)}(x_0) = \begin{cases} 0 & \text{for } j = 0, \dots, k \\ (k+1)\tilde{P}^{(k)}(x_0) \neq 0 & \text{for } j = k+1 \end{cases}$$

□