Analysis 2 Lecture notes, University (of Technology) Graz based on the lecture by Wolfgang Ring

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This lecture took place on 2018/03/06.

1 Mathematical Redux and topological fundamentals

1.1 Metric

Definition 1.1. Let $X \neq \emptyset$ be a set. We define a map $d: X \times X \to [0, \infty)$. d should behave like a geometrical distance. We require $\forall x, y, z \in X$:

- d(x, y) = d(y, x) [called symmetry]
- $d(x, y) = 0 \iff x = y$ [called positive definiteness]
- $\forall x, y, z \in X : d(x, z) \le d(x, y) + d(y, z)$ [called triangle inequality]

Then d is called metric or distance function on X. (X, d) is called metric space.

Example 1.1.

•
$$X \subseteq \mathbb{C}$$
, $d(x, y) = |x - y|$. It satisfies $|x - z| \le |x - y| + |y - z|$

•
$$X \subseteq \mathbb{R}^n$$
, $||x - y|| = \langle x - y, x - y \rangle^{\frac{1}{2}}$

Claim.

$$\langle x, y \rangle = \sum_{i=1}^{n} x_i y_i$$

$$||x|| = \langle x, x \rangle^{\frac{1}{2}} = \sqrt{\sum_{i=1}^{n} x_i^2}$$

$$||x|| = \sqrt{x_1^2 + x_2^2}$$

It holds that $||x + y|| \le ||x|| + ||y||$ [triangle inequality].

Proof.

$$||x + y||^{2} = \langle x + y, x + y \rangle$$

$$= \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle$$

$$= ||x||^{2} + 2 \langle x, y \rangle + ||y||^{2}$$

$$\leq ||x||^{2} + 2 ||x|| ||y|| + ||y||^{2}$$
 [see Cauchy-Schwarz inequality]
$$= (||x|| + ||y||)^{2}$$

$$||x - y||^{2} = \langle x - y, x - y \rangle$$

$$= ||x||^{2} - 2 \langle x, y \rangle + ||y||^{2}$$

$$||x + y||^{2} + ||x - y||^{2} = 2 (||x||^{2} + ||y||^{2})$$

1.2 Cauchy-Schwarz inequality

Theorem 1.1 (Cauchy-Schwarz inequality).

$$|\langle x, y \rangle| \le ||x|| ||y||$$

Proof.

$$0 \le \langle x - \lambda y, x - \lambda y \rangle = \|x\|^2 - 2\lambda \langle x, y \rangle + \lambda^2 \|y\|^2 \qquad \forall \lambda \in \mathbb{R}$$

Let $\lambda = \frac{\langle x, y \rangle}{\|y\|^2}$. Then,

$$0 \le ||x||^2 - 2 \frac{\left|\langle x, y \rangle\right|^2}{\|y\|^2} + \frac{\left|\langle x, y \rangle\right|^2}{\|y\|^4} \cdot \|y\|^2$$

$$\implies 0 \le ||x||^2 - \frac{\left|\langle x, y \rangle\right|^2}{\|y\|^2}$$

$$\implies \left|\langle x, y \rangle\right|^2 \le ||x||^2 \cdot \|y\|^2$$

1.3 Euclidean norm

Definition 1.2. $||x|| = \sqrt{\sum_{i=1}^{n} x_i^2}$ is called Euclidean norm (length) of vector $x \in \mathbb{R}^n$. $||x|| = \langle x, x \rangle^{\frac{1}{2}}$ It holds that

- 1. $\|\lambda x\| = |\lambda| \|x\| \, \forall x \in \mathbb{R}^n, \lambda \in \mathbb{R}$
- 2. $||x|| = 0 \iff x = 0 \text{ in } \mathbb{R}^n$
- 3. $||x + y|| \le ||x|| + ||y||$

In general: Let V be a vector space over \mathbb{R} . A map $\|\cdot\|$, which assigns every vector x a non-negative real number satisfying the properties above, is called norm on V. Then $(V, \|\cdot\|)$ is called a normed vector space.

Let $X \subseteq \mathbb{R}^n$ (V is a normed vector space), then d(x, y) = ||x - y|| is a metric on X.

$$||y - x|| = ||(-1)(x - y)|| = |-1| \cdot ||x - y|| = ||x - y||$$

$$d(x, y) = 0 \iff ||x - y|| = 0 \iff x - y = 0 \iff x = y$$

$$d(x, z) = ||z - x|| = ||z - y + y - x|| \le ||z - y|| + ||y - x|| = d(z, y) + d(y, x)$$

1.4 Metric space

Example 1.2 (metric space). *Metric space, distance is not a norm. Consider an area in* \mathbb{R}^3 .

d(x, y) is the shortest path, connecting x and y in X. See Figure 1

Example 1.3 (French railway). All connections between two cities pass through Paris except one city is Paris.

Example 1.4. $X = \mathbb{R}^2$. Let $p \in \mathbb{R}^2$ be fixed.

$$d(x,y) = \begin{cases} |x-y| & \text{if } x, y, p \text{ are on one line} \\ |x-p| + |p-y| & \text{if } x, y, p \text{ are not on one line} \end{cases}$$

1.5 Open sets, convergence and accumulation points

Now we put some terminology into the context of a metric space. (X, d) is a metric space.

Definition 1.3. *Let* $x \in X$, $r \ge 0$.

$$K_r(x) = \{ z \in X \mid d(x, z) < r \}$$

Is an open sphere *with radius r and center x*.

Definition 1.4.

$$\overline{K_r(x)} = \{z \in X \mid d(x,z) \le r\}$$

Closed sphere with center x and radius r.

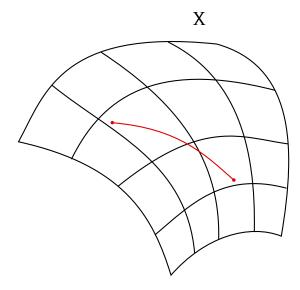


Figure 1: Example in \mathbb{R}^3 . The red line illustrates the shortest path

Definition 1.5 (Sequences in *X*). Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in *X* (hence, $x_n\in X\forall n\in\mathbb{N}$)

1. $(x_n)_{n\in\mathbb{N}}$ is called convergent and limit $x\in X$ if

$$\forall \varepsilon > 0 \exists N \in \mathbb{N} : n \geq N \implies d(x_n, x) < \varepsilon$$

Denoted as $\lim_{n\to\infty} x_n = x$.

2. $(x_n)_{n\in\mathbb{N}}$ is a Cauchy sequence if

$$\forall \varepsilon > 0 \exists N \in \mathbb{N} : n, m \ge N \implies d(x_n, x_m) < \varepsilon$$

Every convergent sequence is also a Cauchy sequence.

Proof. Let $(x_n)_{n\in\mathbb{N}}$ be convergent with limit x. Let $\varepsilon > 0$ be arbitrary. Because $(x_n)_{n\in\mathbb{N}}$ is convergent, there exists $N \in \mathbb{N}$ such that $n \geq N \implies d(x_n, x) < \frac{\varepsilon}{2}$. Now let $n, m \geq N$. Then it holds that

$$d(x_n, x_m) \le \underbrace{d(x_n, x)}_{<\frac{\varepsilon}{2}} + \underbrace{d(x, x_m)}_{<\frac{\varepsilon}{2}} < \varepsilon$$

Definition 1.6. (X, d) is called complete metric space if every Cauchy sequence in X is also convergent (has a limit).

 \mathbb{R} is complete. \mathbb{R}^n is also complete. $\mathbb{Q} \subseteq \mathbb{R}$ is incomplete.

Definition 1.7. Let $(x_n)_{n\in\mathbb{N}}$ be a sequence of X is called "accumulation point" (dt. Häufungspunkt) of the sequence. $\forall \varepsilon > 0$, it holds that $K_{\varepsilon}(x)$ contains infinitely many sequence elements.

This lecture took place on 2018/03/08.

TODO

$$d(x,y) = 0 \iff x = y$$

$$\forall x, y \in X : d(x,y) = d(y,x)$$

$$d(x,z) \le d(x,y) + d(y,z) \forall x, y, z \in X$$

1.6 Norm

Let *V* be a vector space. $\|\cdot\|$ is called *norm on V*.

$$||x|| = 0 \iff x = 0$$

$$\forall \lambda \in \mathbb{R}, \mathbb{C} : \forall x \in V : ||\lambda x|| = |\lambda| ||x||$$

$$\forall x, y, z \in V : ||x + y|| \le ||x|| + ||y||$$

Let $X \subseteq V$ be a subset of normed vector space V. Then X is a metric space with d(x, y) = ||x - y||.

For $V = \mathbb{R}^n$. Then

$$||x|| = \left(\sum_{i=1}^{n} x_i^2\right)^{\frac{1}{2}}$$

is a norm on \mathbb{R}^n . $||x||_2$ is called *Euclidean norm on* \mathbb{R}^n .

Other norms in \mathbb{R}^n :

$$||x||_{\infty} = \max\{|x_i| | i = 1, ..., n\}$$

 $||x||_1 = \sum_{i=1}^n |x_i|$

for $1 \le p < \infty$.

$$||x||_p = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}}$$

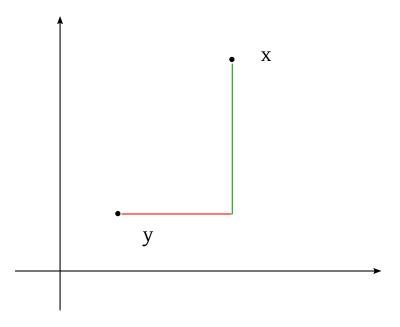


Figure 2: Visualizing $||x||_1$

e.g. $||x||_1$ in \mathbb{R}^2

$$||x - y|| = |x_1 - y_1| + |x_1 - y_2|$$

is the so-called *Manhattan metric*.

The concepts "subsequence", "final element of a sequence", "reordering of a sequence" correspond one-by-one to metric spaces.

Definition 1.8 (Accumulation point). Let $(X_n)_{n\in\mathbb{N}}$ be a sequence in X. $x\in X$ is called accumulation point of sequence X if $\forall \varepsilon > 0$ the sphere $K_{\varepsilon}(x)$ contains infinitely many elements.

Lemma 1.1. $x \in X$ is accumulation point of sequence $(x_n)_{n \in \mathbb{N}}$ if and only iff there exists a subsequence $(x_{n_k})_{k \in \mathbb{N}}$ such that $x = \lim_{k \to \infty} x_{n_k}$.

Proof. See Analysis 1 course

1.7 Contact point

Let $B \subseteq X$, X is a metric space. Then B with d is a metric space itself.

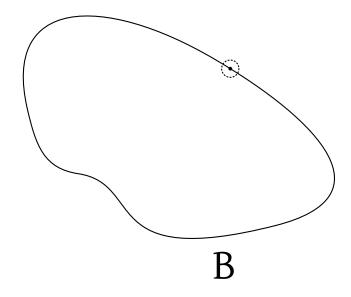


Figure 3: Contact points in set B

Definition 1.9. *Let* $B \subseteq X$ *and* $x \in X$. *We say,* x *is a* contact point of B *if* $\forall \varepsilon > 0 : K_{\varepsilon}(x) \cap B \neq \emptyset$.

[$y \in X$ is not a contact point of $B \iff \exists \varepsilon > 0 : K_{\varepsilon}(y) \cap B = \emptyset$] See Figure 3.

We let $\overline{B} = \{ x \in X \mid x \text{ is contact point of } B \}.$

 \overline{B} is called closed hull of B.

B is called closed if $B = \overline{B}$, hence, every contact point is also element of *B*.

Remark 1.1. Because $\forall x \in B \text{ holds } K_r(x) \cap B \supseteq \{x\} \forall r > 0 \text{ is } x \text{ always contact point of } B. Also <math>B \subseteq \overline{B}$ (always)

Lemma 1.2. x is contact point of $B \iff \exists (x_n)_{n \in \mathbb{N}} \text{ with } x_n \in B \text{ and } \lim_{n \to \infty} x_n = x.$

Proof. Let *x* be a contact point of *B*.

Direction \Rightarrow : Because $K_{\frac{1}{n}}(x) \cap B \neq \emptyset$, choose $X_n \in K_{\frac{1}{n}}(x) \cap B$. The sequence $(x_n)_{n \in \mathbb{N}}$ has property $d(x_n, x) < \frac{1}{n}$. Let $\varepsilon > 0$ be arbitrary. Choose $N \in \mathbb{N}$ sch that $N > \frac{1}{\varepsilon}$ (consider the Archimedean axiom). Then for $n \geq N$, $d(x_n, x) < \frac{1}{n} \leq \frac{1}{N} < \varepsilon$, hence $\lim_{n \to \infty} x_n = x$.

Direction \Leftarrow : Let $x = \lim_{n \to \infty} x_n$ and $x_n \in B$. Let $\varepsilon > 0$ be arbitrary and $N \in \mathbb{N}$ such that $d(x_n, x) < \varepsilon \forall n \ge N$. Then $d(x_n, x) < \varepsilon$, hence

$$x_N \in \underbrace{K_\varepsilon(x) \cap B}_{\neq \emptyset}$$

So *x* is contact point of *B*.

Lemma 1.3. It holds that $\forall B \subseteq X : \overline{B} = \overline{\overline{B}}$, hence \overline{B} itself is closed.

Proof. Show that $x \in \overline{B}$. Let $x \in \overline{\overline{B}}$.

$$\iff \forall \varepsilon > 0 : K_\varepsilon(x) \cap \overline{B} \neq \emptyset$$

Therefore let $\varepsilon > 0$ be arbitrary and $x \in \overline{B}$.

Show that $K_{\varepsilon}(x) \cap B \neq \emptyset$.

Because $x \in \overline{\overline{B}} : \exists y \in \overline{B} : y \in K_{\frac{c}{2}}(x)$. Because $y \in \overline{B} : \exists z \in B : z \in K_{\frac{c}{2}}(y)$. Hence,

$$d(z,x) \le \underbrace{d(z,y)}_{<\frac{\varepsilon}{2}} + \underbrace{d(y,x)}_{<\frac{\varepsilon}{2}} < \varepsilon$$

so $z \in K(x, \varepsilon) \cap B$. So x is contact point of $B \implies x \in \overline{B}$.

Lemma 1.4. *Let X be a metric space.*

- $A_i \subseteq X$ be closed $\forall i \in I$. Then $A = \bigcap_{i \in I} A_i = \{x \in X | x \in A_i \forall i \in I\}$ is closed itself.
- $A_1, ..., A_n \subseteq X$ are closed. Then $\bigcup_{k=1}^n A_k$ is closed in X.
- φ is closed, X is closed.

Proof. See Analysis 1 course.

Definition 1.10. Let $x \in X$ is called accumulation point of set $B \subseteq X$ if $\forall \varepsilon > 0$: $(K_{\varepsilon}(x) \setminus \{x\}) \cap B \neq \emptyset$.

Remark 1.2. Accumulation points only exist in the context of sets. Accumulation values only exist in the context of sequences.

For example (+1, -1, +1, -1, +1, ...) has accumulation values +1 and -1.

Lemma 1.5. Let $x \in X$ is accumulation point on $B \iff$ every sphere $K_{\varepsilon}(x)$ contains infinitely many points of B.

Proof. Direction \Leftarrow is trivial.

Direction \Rightarrow : Choose $x_1 \in (K_1(x) \setminus \{x\}) \cap B$, hence $x_1 \neq x$, $x_1 \in B$ and $d(x_1, x) < 1$. Let $r_1 = 1$.

Inductive: choose $r_n = \min(\frac{1}{n}, d(x_{n-1}, x))$ and $x_n \in (K_{r_n}(x) \setminus \{x\}) \cap B$. Then $d(x_n, x) > 0$ (because $x_n \neq x$) where $d(x_n, x) < r_n < \frac{1}{n}$.

$$0 < d(x_n, x) < \frac{1}{n}$$

Furthermore, $d(x_n, x) < r_n \le d(x_{n-1}, x)$. So $x_n \ne x_{n-1}$.

Inductive: $x_n \neq x_{n-1} \neq x_{n-2} \neq \cdots \neq x_1$. Now consider arbitrary $\varepsilon > 0$ and N large enough such that $\frac{1}{N} < \varepsilon$.

Then it holds that $\forall n \geq N : 0 < d(x_n, x) < \frac{1}{n} \leq \frac{1}{N} < \varepsilon$. So $K_{\varepsilon}(x) \cap B$ contains infinitely many points $x_N, x_{N+1}, x_{N+2}, \dots$

Definition 1.11. Let $U \subseteq X$ and $x \in U$. We say x is an inner point of U if $\exists r > 0 : K_r(x) \subseteq U$. We let $\mathring{U} = \{x \in U \mid x \text{ is inner point of } U\}$ and call it interior of U (offenen Kern von U or das Innere von U). $O \subseteq X$ is called open (open set), if every point $x \in O$ is also an inner point of O. Hence $\mathring{O} = O$.

Example 1.5. Let $K_r(x)$ with r > 0 be an open sphere in X. Then $K_r(x)$ is an open set in X.

Why? Let $y \in K_r(x)$. Show that y is an inner point of the sphere. d(y,x) = s < r. Define r' = r - s > 0. Claim: $K'_r(y) \subseteq K_r(x)$.

TODO drawing

TODO

So it holds that $z \in K_r(x)$ and therefore $K_{r'}(y) \subseteq K_r(x)$.

Lemma 1.6. Let $U \subseteq X$ be arbitrary. Then $\mathring{U} \subseteq X$ be an open set in X.

Proof. Let $x \in \mathring{U}$, hence x is an inner point of U. Show that x is an inner point of \mathring{U} , also $\exists r > 0 : K_r(x) \subseteq \mathring{U}$.

Because $x \in \mathring{U}$, r > 0 exists: $K_r(x) \subseteq U$. Claim: Every point $y \in K_r(x)$ is also an inner point of U. Obvious (previous example), because r' > 0 exists such that $K_{r'}(y) \subseteq K_r(x) \subseteq U$ so $y \in \mathring{U}$ and $K_r(x) \subseteq \mathring{U}$.

Theorem 1.2. *Let X be a metric space.*

$$A \subseteq X$$
 is closed in $X \iff O = X \setminus A = A^C$ is open

Proof. Direction \Leftarrow . Let *A* be closed and *O* + *A*^C. We choose *x* ∈ *O* and show that *x* is in the interior of *O*.

Assume the opoosite.

$$\forall \varepsilon > 0 : \underbrace{\neg \left(K_\varepsilon(x) \subseteq O \right)}_{\Longleftrightarrow K_\varepsilon(x) \cap O^c \neq \emptyset}$$

where $O^C = A$. So x is contact point of A. Because A is closed, it holds that $x \in A$. This contradicts with $x \in O = A^C$.

Direction \Rightarrow . TODO $K_r(x) \cap \underbrace{A}_{=O^c} = \emptyset$. Hence x is not a contact point of A.

So every contact point of *A* is also an element of *A* and *A* is closed.

Theorem 1.3. *Let* X *be a metric space. Then it holds that*

- If $O_i \subseteq X$ is open in $X \forall i \in I$. Then also $O = \bigcup_{i \in I} O_i$ is open in X.
- If O_1, O_2, \ldots, O_n is open in X, then $\bigcap_{k=1}^n O_k$ is open in X.
- *X is open,* Ø *is open.*

Proof. By Lemma 1.4, Theorem 1.2 and De Morgan's Laws:

$$\left(\bigcup_{i\in I} A_i\right)^C = \bigcap_{i \in I} A_i^C$$

1.8 Topology

Definition 1.12. Given a set X. If a subset $T \subseteq \mathcal{P}(X)$ is defined such that the elements $O \in T$ (hence $O \subseteq X$) satisfy the conditions of Theorem 1.3, then T is called topology on X. (X, T) is called topological space.

The sets $O \in T$ are called open sets in terms of T. The complements $A = O^C$ for $O \in T$ are called closed sets.

Definition 1.13. Let $x \in U \subseteq X$. We claim that U is a neighborhood of x, if r > 0 exists such that $x \in K_r(X) \subseteq U$

See Figure 4

Remark 1.3. $O \subseteq X$ is open iff O is neighborhood of every point $x \in O$.

Definition 1.14. Let X and Y be metric spaces and $x_0 \in X$. Let $f: X \to Y$ be given. We say f is continuous in x_0 if

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall x \in X : d_X(x, x_0) < \delta \implies d_Y(f(x), f(x_0)) < \varepsilon$$

Here, d_X is a metric on X and d_Y is a metric on Y.

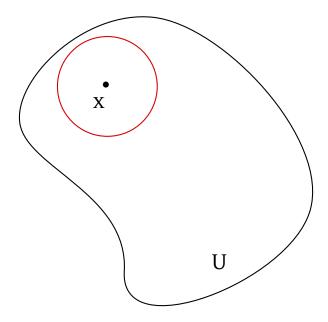


Figure 4: Neighborhood of *x*

This lecture took place on 2018/03/13.

TODO I missed the first twenty minutes (including Satz 3 and 4)

Proof. Direction \Rightarrow .

Let f be continuous in X and let $O \subseteq Y$ be open. Let $U = f^{-1}(O)$ and choose $x_0 \in U$. Then $f(x_0) \in O$, hence O is a neighborhood of $f(x_0)$. By Theorem 5.2 (b), it follows that $U = f^{-1}(O)$ is a neighborhood of x_0 .

Hence, *U* is neighborhood of every of its points, hence open in *X*.

Direction \Leftarrow .

Let the preimages of open sets be open and $x_0 \in X$ and $y_0 = f(x_0)$. Let V be a neighborhood of $y_0 = f(x_0)$, hence $\exists \varepsilon > 0 : K_{\varepsilon}(f(x_0)) \subseteq V$. Because $K_{\varepsilon}(f(x_0))$ is an open set, it holds that $f^{-1}(K_{\varepsilon}(f(x_0))) \in x_0$ is open in X.

Therefore, there exists $\delta > 0$ such that $K_{\delta}(x_0) \subseteq f^{-1}(K_{\varepsilon}(f(x_0))) \subseteq f^{-1}(V)$. Hence, $f^{-1}(V)$ is a neighborhood of x_0 . Then by Theorem 5.2 (b), it follows that f is continuous in x_0 (chosen arbitrarily). Hence f is continuous on X.

2 Variations of continuity notions

Definition 2.1. Let $f: X \to Y$ be given. We call "f uniformly continuous on X" if

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall x, y \in X \land d_X(x, y) < \delta \implies d_Y(f(x), f(y)) < \varepsilon$$

Remark 2.1. *Compare it with the definition of "continuous in X":*

$$\forall x \in X \forall \varepsilon > 0 \exists \delta > 0 : \forall y \in X : d_X(x, y) < \delta \implies d_Y(f(x), f(y)) < \varepsilon$$

The difference is the location of the $\forall x \in X$ quantifier.

Every uniformly continuous map is continuous.

Example: $f:(0,\infty)\to(0,\infty)$ with $f(x)=\frac{1}{x}$ is continuous, but not continuously continuous.

Definition 2.2. $f: X \to Y$ is called Lipschitz continuous with Lipschitz constant $L \ge 0$ if $\forall x, y \in X: d_Y(f(x), f(y)) \le L \cdot d_X(x, y)$.

Rudolf Lipschitz [1832-1903], University of Bonn

Theorem 2.1. Every Lipschitz continuous function is uniformly continuous.

Proof. For $\varepsilon > 0$, choose $\delta = \frac{\varepsilon}{L+1}$. Then it holds that $d_X(x,y) < \delta = \frac{\varepsilon}{L+1} \implies d_Y(f(x),f(y)) \le L \cdot d_X(x,y) < \frac{L}{L+1} \cdot \varepsilon < \varepsilon$.

• Most often $X \subseteq V$, $Y \subseteq W$. V and W are normed vector spaces and d(x,y) = ||x-y||

Definition 2.3. A Lipschitz continuous map $f: X \to X$ with Lipschitz constant L < 1 is called contraction on X. Compare with Figure 5

Theorem 2.2 (Banach fixed-point theorem). Let $f: X \to X$ be a contraction and X be complete. Then there exists a uniquely defined $\hat{x} \in X$ such that $\hat{x} = f(\hat{x})$. \hat{x} is called fixed point on f. Furthermore it holds that $x_0 \in X$ is arbitrary and $x_n = f(x_{n-1})$ for all $n \ge 1$.

$$\lim_{n\to\infty}x_n=\hat{x}$$

TODO drawing Banach's fixed point theorem

Remark 2.2. The following proof is a very common exam question.

Proof. Let $x_0 \in X$ be arbitrary. x_n is constructed inductively by $x_n = f(x_{n-1})$ for all $n \ge 1$.

Claim. $(x_n)_{n\in\mathbb{N}}$ is a Cauchy sequence in X.

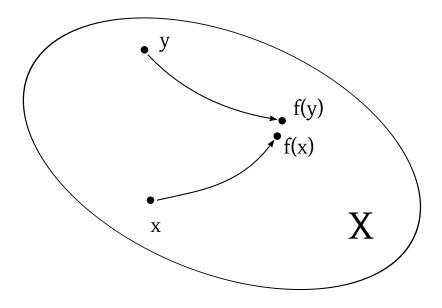


Figure 5: A contraction maps to points closer to each other

$$d(x_n, x_{n+k}) \le d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \dots + d(x_{n+k-1}, x_{n+k})$$

by triangle inequality

$$= d(x_n, x_{n+1}) + d(f(x_n), f(x_{n+1})) + d(f(x_{n+1}), f(x_n + 2)) + \dots + d(f(x_{n+k-2}), f(x_{n+k-1}))$$

$$\leq d(x_n, x_{n+1}) + L(d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \dots + d(x_{n+k-2}, x_{n+k-1}))$$

this inequality is given by contraction

$$= d(x_{n}, x_{n+1})(1 + L) + L \left(d(f(x_{n}), f(x_{n+1})) + \dots + d(f(x_{n+k-3}), f(x_{n+k-2})) \right)$$

$$\leq d(x_{n}, x_{n+1})(1 + L) + L^{2} \left[d(x_{n}, x_{n+1} + \dots + d(x_{n+k-3}, x_{n+k-2})) \right]$$

$$\leq \dots \leq d(x_{n}, x_{n+1})(1 + L + L^{2} + \dots + L^{k-1})$$

$$= d(f(x_{n-1}, f(x_{n})) \left(\sum_{j=0}^{k-1} L^{j} \right) \leq Ld(x_{n-1}, x_{n}) \cdot \left(\sum_{j=0}^{k-1} L^{j} \right)$$

$$\leq L^{n} d(x_{0}, x_{1}) \cdot \left(\sum_{j=1}^{k-1} L^{j} \right)$$

$$\leq \sum_{j=0}^{\infty} L^{j} = \frac{1}{1-L}$$

$$\leq \frac{L^{n}}{1-L} d(x_{0}, x_{1})$$

$$d(x_{n}, x_{n+k}) \leq \frac{L^{n}}{1-L} d(x_{0}, x_{1}) \forall n \in \mathbb{N} \forall k \in \mathbb{N}_{0}$$

with $0 \le L < 1$.

$$\frac{L^{n}}{1-L}d(x_{0},x_{1}) < \varepsilon \iff$$

$$L^{n} < \frac{\varepsilon}{d(x_{0},x_{1})+1}(1-L) \qquad (L>0)$$

$$\iff n \underbrace{\ln L}_{<0} < \ln \frac{\varepsilon}{d(x_{0},x_{1})+1}(1-L)$$

$$\iff n > \frac{1}{\ln L} \ln \frac{\varepsilon}{d(x_{0},x_{1})+1}(1-L)$$

Hence $(x_n)_{n\in\mathbb{N}}$ is a Cauchy sequence in X. X is complete, hence $\exists \hat{x} \in X$: $\hat{x} = \lim_{n\to\infty} x_n$. Because $\hat{x} = \lim_{n\to\infty} x_{n+1} = \lim_{n\to\infty} f(x_n) = f(\hat{x})$ where the last equality is given by continuity of f. Therefore $\hat{x} = f(\hat{x})$ is a fixed point on f.

It remains to prove uniqueness:

Let $\tilde{x} = f(\tilde{x})$. Then it holds that $d(\hat{x}, \tilde{x}) = d(f(\hat{x}), f(\tilde{x})) \le Ld(\hat{x}, \tilde{x})$ with L < 1. If $d(\hat{x}, \tilde{x}) > 0$, then $1 \le L$. This is a contradiction. Hence $d(\hat{x}, \tilde{x}) = 0$ must hold, hence $\hat{x} = \tilde{x}$.

Remark 2.3. • The Fixed Point Theorem provides an algorithm for numeric computation of \hat{x} .

• It can reformulate problems f(x) = 0 (in \mathbb{R}^n) to

$$f(x) + x = g(x) = x$$

 Attention: The conditions of the Fixed Point Theorem cannot be changed to the structure

$$d(f(x), f(y)) < L \cdot d(x, y) \wedge L \leq 1$$

or

$$d(f(x), f(y)) \le L \cdot d(x, y) \land L < 1$$

This will be discussed in the practicals.

Lemma 2.1. Let X be a complete metric space. Let $A \subseteq X$ be closed. Then (A, d) is itself a complete, metric space.

Proof. Let $(x_n)_{n\in\mathbb{N}}$ be a Cauchy sequence in A ($x_n \in A$). Then $(x_n)_{n\in\mathbb{N}}$ is also a Cauchy sequence in X. Because X is complete, there exists $\hat{x} = \lim_{n\to\infty} x_n$. Therefore \hat{x} is a contact point of A. Because A is closed, it holds that $\hat{x} \in A$.

Therefore every Cauchy sequence in A has a limit point in A, hence A is complete.

3 Compactness

Definition 3.1. A metric space (X, d) is called compact if every sequence $(x_n)_{n \in \mathbb{N}}$ has a convergent subsequence.

Specifically, this definition is called sequence compactness. The other definition defines compactness as closed and bounded subset of an Euclidean space. The latter definition only works for a subset of branches in mathematics. Therefore the generalization is recommended to be remembered.

Lemma 3.1. *Let X be a compact, metric space. Then X is complete.*

Proof. Let $(x_n)_{n\in\mathbb{N}}$ be a Cauchy sequence in X. By compactness, it follows that $\exists (x_{n_k})_{k\in\mathbb{N}}$ with $\lim_{k\to\infty} x_{n_k} = \hat{x}$. Choose $\varepsilon > 0$ arbitrary and L large enough such that $k \geq L \implies d(x_{n_k}, \hat{x}) < \frac{\varepsilon}{2}$. Furthermore choose $N \in \mathbb{N}$ large enough such that $n, m \geq N \implies d(x_n, x_m) < \frac{\varepsilon}{2}$ (satisfied, because $(x_n)_{n\in\mathbb{N}}$ is a Cauchy sequence). Choose $K \geq L$ and $n_k \geq N$. Let n_k be fixed this way. Then it holds $\forall n \geq N : d(x_n, \hat{x}) \leq d(x_n, x_{n_k}) + d(x_{n_k}, \hat{x}) < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon$. The first summand $\frac{\varepsilon}{2}$ results from the Cauchy sequence property, the second summand $\frac{\varepsilon}{2}$ results by convergence of (x_{n_k}) . Hence $(x_n)_{n\in\mathbb{N}}$ is convergent with limit \hat{x} .

Definition 3.2. A metric space X is called bounded if there exists $M \ge 0$, such that $d(x, y) \le M \forall x, y \in X$.

It holds for arbitrary $x \in X$ that $\forall y \in X : y \in K_M(x)$. So, $X \subseteq K_M(x)$. On the contrary, let $X \subseteq \overline{K_M(x)}$ and let $y \in X$ and $z \in X$ be arbitrary. Then it holds that $d(y,z) \le d(y,x) + d(x,z) \le M + M = 2M$. Hence, X is bounded.

So, *X* is bounded
$$\iff \exists x \in X \land M \ge 0 : X \subseteq \overline{K_M(x)}$$
.

Lemma 3.2. Every compact, metric space is also bounded.

Proof. Assume *X* is unbounded.

We construct a sequence of points $(x_n)_{n\in\mathbb{N}}$ with $d(x_n,x_m)\geq 1 \forall n,m\in\mathbb{N}$ with $n\neq m$.

We use the following auxiliary result: Let $B = \bigcup_{j=1}^{n} K_1(z_j)$ for arbitrary $n \in \mathbb{N}$ and arbitrary $z_j \in X$. Then B is bounded. This result will be part of the practicals.

We construct $(x_n)_{n\in\mathbb{N}}$ inductively. Choose arbitrary $x_0\in X$. Assume (x_1,\ldots,x_{n-1}) are already found. Then it holds that

$$\underbrace{X}_{\text{unbounded}} \nsubseteq \bigcup_{j=1}^{n-1} K_1(x_j)$$

hence $\exists x_n \in X \setminus \bigcup_{j=1}^{n-1} K_1(x_j)$. Because $x_n \notin K_1(x_j)$ for $j = 0, \ldots, n-1$ it holds that $d(x_n, x_j) \ge 1 \forall j < n$. We get $(x_n)_{n \in \mathbb{N}}$ with $d(x_n, x_m) \ge 1 \forall n \in \mathbb{N} \forall m < n$, hence $m \ne n$. Because $d(x_n, x_m) \ge 1$, i.e. $(x_n)_{n \in \mathbb{N}}$ does not contain any Cauchy sequence as subsequence, $(x_n)_{n \in \mathbb{N}}$ does not have a convergent subsequence. Therefore X is not compact.

This lecture took place on 2018/03/15.

Every compact metric space is bounded. Every compact metric space is complete. In $\mathbb{C}(\mathbb{R}^n)$ it holds that $A \subseteq \mathbb{C}$ is closed. Then A with metric d(x,y) = |x-y| is complete as metric space.

If *A* is additionally bounded, then *A* is compact (see course Analysis 1, Bolzano-Weierstrass).

Attention! Let V be an infinite-dimensional, complete, normed vector space. For example, $V = C([a,b],\mathbb{R}) = \{f:[a,b] \to \mathbb{R} \mid f \text{ is continuous in } [a,b] \}$ with norm $\|f\|_{\infty} = \max \{|f(x)|: x \in [a,b] \}$ and metric $\|f-g\|_{\infty} = \max \{|f(x)-g(x)|: x \in [a,b] \}$. $C([a,b],\mathbb{R})$ is a complete, normed vector space. It holds that $\overline{K_1(0)}$ is not compact in $C([a,b],\mathbb{R})$ (i.e. V, for every infinite-dimensional vector space).

Again: do not remember "compactness" not as closed and bounded, as this only holds in the finite-dimensional case.

In the last proof, we have shown: If a sequence $(x_n)_{n \in \mathbb{N}}$ with $x_n \in X$ and $d(x_n, x_m) \ge 1$ (or $\ge \varepsilon$) $\forall n \ne m \implies X$ is not compact.

Definition 3.3. X is called totally bounded, if for every $\varepsilon > 0$, finitely many points $X_1^{\varepsilon}, X_2^{\varepsilon}, \ldots, X_{N(\varepsilon)}^{\varepsilon}$ such that $X \subseteq \bigcup_{i=1}^{N(\varepsilon)} K_{\varepsilon}(X_i^{\varepsilon})$.

Hence, for every $x \in X$, there exists some X_i^{ε} such that $d(X, X_i^{\varepsilon}) < \varepsilon$.

Remark 3.1 (For the practicals). Let X be totally bounded, then there does not exist some sequence $(x_n)_{n\in\mathbb{N}}$ with $d(x_n,x_m)\geq \varepsilon \forall n\neq m$. It holds, that X is compact if and only if X is totally bounded and complete.

Theorem 3.1. Let $f: X \to Y$ be continuous. Let X be compact. Then image $f(X) \subseteq Y$ is also compact.

Be aware, that this proof is a common exam question and students often begin with the wrong order.

Proof. Let $(y_n)_{n\in\mathbb{N}}$ be an arbitrary sequence in f(X). Show that $(y_n)_{n\in\mathbb{N}}$ has a convergent subsequence. Because $y_n \in f(X)$, there exists at least one x_n with $y_n = f(x_n)$. Then $(x_n)_{n\in\mathbb{N}}$ is a sequence in X, X is compact, hence there exists a subsequence $(x_{n_k})_{k\in\mathbb{N}}$ with $\lim_{k\to\infty} x_{n_k} = \hat{x} \in X$. Because f is continuous, it holds that $\lim_{k\to\infty} f(x_{n_k}) = \lim_{k\to\infty} y_{n_k} = f(\hat{x}) = \hat{y}$. So $(y_n)_{n\in\mathbb{N}}$ has a convergent subsequence. Hence $f(X) \subseteq Y$ is compact.

Theorem 3.2 (Conclusion). Let X be compact, $f: X \to \mathbb{R}$ continuous on X. Then there exists \underline{x} and $\overline{x} \in X$, such that

$$f(\underline{x}) \le f(x) \le f(\overline{x}) \qquad \forall x \in X$$

Hence, f has a maximum and a minimum.

Proof. $f(X) \subseteq \mathbb{R}$ is compact (Theorem 3.1), hence f(X) is bounded and complete, hence closed in \mathbb{R} . There exists $\xi \in \mathbb{R}$ with $\xi = \sup f(X)$, because f(X) is complete and ξ is a contact point of f(X), it holds that $\xi \in f(X)$, hence $\exists \overline{x} \in X : \xi = f(\overline{x})$. Furthermore, ξ is an upper bound of $f(X) \to f(X) \le \xi = f(\overline{x}) \forall X \in X$.

For *x*, it works the same way.

Theorem 3.3. Let $f: X \to Y$ is continuous on X and X is compact. Then f is uniformly continuous on X.

Indirect proof. Assume *X* is compact, $f: X \to Y$ is continuous, but not uniformly continuous. Uniform continuity:

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall x, y \in X : d_X(x, y) < \delta \implies d_Y(f(x), f(y)) < \varepsilon$$

Not uniformly continuous:

$$\exists \varepsilon > 0 \forall \delta_n = \frac{1}{n} (n \in \mathbb{N}) \exists x_n, y_n \in X : d_X(x_n, y_n) < \frac{1}{n} \land d_Y(f(x_n), f(y_n)) \ge \varepsilon$$

Now choose some (x_n) and (y_n) . We will use a specific ε later. Because X is compact, there exists a convergent subsequence of $(x_n)_{n \in \mathbb{N}}$, hence $\lim_{k \to \infty} x_{n_k} = \hat{x}$. The sequence $(y_{n_k})_{k \in \mathbb{N}}$ has a convergent subsequence itself:

$$\lim_{l\to\infty}y_{(n_k)_l}=\hat{y}$$

Because $(x_{n_k})_{n \in \mathbb{N}}$ is convergent, the subsequence $(x_{(n_k)_l})_{l \in \mathbb{N}}$ converges towards the same limit \hat{x} .

$$\tilde{x}_l \coloneqq x_{n_{k_l}} \qquad \tilde{y}_l \coloneqq y_{n_{k_l}}$$

because $l \leq x_{n_l}$ and

$$d_X(\tilde{x}_l, \tilde{y}_l) = d_X(x_{n_{k_l}}, y_{n_{k_l}}) \underbrace{\qquad \qquad}_{\text{by assumption}} \frac{1}{n_{k_l}} \le \frac{1}{l}$$

Claim. For $\hat{x} = \lim_{l \to \infty} \tilde{x}_l$ and $\hat{y} = \lim_{l \to \infty} \tilde{y}_l$, it holds that $\hat{x} = \hat{y}$.

Proof. Let $\varepsilon' > 0$ be arbitrary, l large enough such that

- $\frac{1}{l} < \frac{\varepsilon'}{3}$
- $d_X(\tilde{x}_l, \hat{x}) < \frac{\varepsilon'}{3}$
- $d_X(\tilde{y}_l, \hat{y}) < \frac{\varepsilon'}{3}$

Therefore it holds that

$$d_X(\hat{x},\hat{y}) \leq d_X(\hat{x},\tilde{x}_l) + d_X(\tilde{x}_l,\tilde{y}_l) + d_X(\tilde{y}_l,\hat{y}) < \frac{\varepsilon'}{3} + \frac{1}{l} + \frac{\varepsilon'}{3} < \varepsilon'$$

Therefore it holds that $d_X(\hat{x}, \hat{y}) = 0$, hence $\hat{x} = \hat{y}$.

Because f is continuous and $\tilde{x}_l \to \hat{x}$ and $\tilde{y}_l \to \hat{x}$, there exists $l \in \mathbb{N}$ such that

$$d_Y(f(\tilde{x}_l), f(\hat{x})) < \frac{\varepsilon}{2}$$

and also

$$d_Y(f(\tilde{y}_l),f(\hat{x}))<\frac{\varepsilon}{2}$$

where ε is the epsilon from the very beginning of the proof.

$$\implies d_Y(f(\tilde{x}_l), f(\hat{x})) + d_Y(f(\tilde{y}_l), f(\hat{x})) < \varepsilon$$

This contradicts to

$$d_Y(f(\tilde{x}_l),f(\tilde{y}_l))=d_Y(f(x_{n_{k_l}}),f(y_{n_{k_l}}))\geq \varepsilon$$

Hence, *f* is uniformly continuous.

Subsets of $(\mathbb{R}^n, \|\cdot\|)$ (or $(V, \|\cdot\|)$) as metric spaces.

We consider $\Omega \subseteq V$ where V is a normed vector space. (Ω, d) is d(x, y) = ||x - y|| is a metric space.

$$K_r^{\Omega}(x) = \left\{ y \in \Omega \, \middle| \, \left\| y - x \right\| < r \right\}$$

is a sphere with center x and radius r in Ω .

$$K_r^V(x) = \{ y \in V \mid ||y - x|| < r \}$$

obvious: $K_r^{\Omega}(x) = \Omega \cap K_r^{V}(x)$.

TODO drawing 08

Lemma 3.3. Let $O' \subseteq \Omega \subseteq V$.

Then it holds that O' is open in $\Omega \iff$ there exists $O \subseteq V$ is open in V such that $O' = O \cap \Omega$.

Proof. \Rightarrow Let $O' \subseteq \Omega$ be open in Ω and $x \in O'$ be arbitrary. Then there exists $r(x) > 0 : x \in K^{\Omega}_{r(x)}(x) = K^{V}_{r(x)}(x) \cap \Omega \subseteq O'$. Then it holds that

$$O' = \bigcup_{x \in O'} = \{x\} \subseteq \bigcup_{x \in O'} K_{r(x)}^{\Omega}(x) = \left(\bigcup_{x \in O'} (K_{r(x)}^{V}(x)) \cap \Omega\right) = \left(\bigcup_{x \in O'} K_{r(x)}^{V}(x)\right) \cap \Omega \subseteq O'$$

$$= O \subseteq V \text{ is open in } V$$

So every \subseteq in this inclusion chain is actually an equality. So $O' = O \cap \Omega$.

 \Leftarrow Let $O' = O \cap \Omega$ and $x \in O'$ be chosen arbitrarily. Because $x \in O$ and O is open in V.

$$\exists r > 0 : K_r^V(x) \subseteq O \implies \underbrace{K_r^V(x) \cap \Omega}_{=K^\Omega(x)} \subseteq O \cap \Omega = O'$$

So O' is open in Ω .

Remark 3.2. $A' \subseteq \Omega$ is closed in $\Omega \iff \exists A \subseteq V$ closed in V with $A' = A \cap \Omega$.

Remark 3.3. Let T be an arbitrary topological space with topology τ on T (a system of open sets). Furthermore let $\Omega \subseteq T$.

Then Ω itself is a topological space with $O' \subseteq \Omega$ is open $\iff \exists O \subset T$ open in T with $O' = O \cap \Omega$.

Also called "subspace topology", "trace topology" or "relative topology".

Attention!

$$O' \subseteq \Omega$$
 open in $\Omega \implies O'$ open in V

does *not* hold in general.

Example 3.1.

$$\Omega = [0,1] \cap [0,1)$$

 $K_{\frac{1}{2}}(p) \cap \Omega$ is open in Ω but not open in \mathbb{R}^2 .

Analogously,

$$A' \subseteq \Omega$$
 is closed $\implies A'$ closed in V

does not hold in general.

Remark 3.4. *K* is compact in $\Omega \implies K$ is compact in V

Let $(x_n)_{n\in\mathbb{N}}$ is a sequence in K. Compactness $\implies \exists (x_{n_k})_{k\in\mathbb{N}} : x_{n_k} \to \hat{x} \text{ for } k \to \infty$ and $K \subseteq \Omega \subseteq V$.

Then $(x_n)_{n\in\mathbb{N}}$ also has a convergent subsequence in V.

3.1 Normed vector spaces

Definition 3.4. Let V be a vector space and $\|\cdot\|_1$ and $\|\cdot\|_2$ are normed on V. We say, $\|\cdot\|_1$ is equivalent to norm $\|\cdot\|_2$, if $0 < m \le M$ exist such that

$$m \|v\|_1 \le \|v\|_2 \le M \|v\|_1 \, \forall v \in V$$

Remark 3.5. Equivalence of norms is an equivalence relation.

reflexivity Let m = M = 1. TODO **symmetry**

$$m \|v\|_{1} \leq \|v\|_{2} \implies \|v\|_{1} \leq \frac{1}{m} \|v\|_{2} \wedge \|v\|_{2} \leq M \cdot \|v\|_{1} \implies \frac{1}{M} \|v\|_{2} \leq \|v\|_{1}$$

$$\implies \underbrace{\frac{1}{M}}_{m'} \|v\|_{2} \leq \|v_{1}\| \leq \underbrace{\frac{1}{m}}_{M'} \|v\|_{2}$$

hence the equivalence relations of norms are symmetrical.

transitivity Let $\|\cdot\|_1$ and $\|\cdot\|_2$ be equivalent. Let $\|\cdot\|_2$ and $\|\cdot\|_3$ be equivalent.

$$\begin{split} m \cdot ||v||_1 &\leq ||v||_2 \leq M \, ||v||_1 \, \forall v \in V \\ m' \cdot ||v||_2 &\leq ||v||_3 \leq M' \, ||v||_2 \, \forall v \in V \\ \Longrightarrow m \cdot m' \, ||v||_1 \leq m' \, ||v||_2 \leq ||v||_3 \leq M' \, ||v||_2 \leq M \cdot M' \, ||v||_1 \end{split}$$

This lecture took place on 2018/03/20.

Addendum:

• Let $(x_n)_{n\in\mathbb{N}}$ be in (X, d), then it holds that

$$\underbrace{x = \lim_{n \to \infty} x_n}_{\text{in } X} \iff \underbrace{\lim_{n \to \infty} d(x_n, x) = 0}_{\text{in } \mathbb{R}}$$

 $(\iff \lim_{n\to\infty} ||x_n - x|| = 0 \text{ in normed vector spaces } V)$

• Inversed triangle inequality: Let *V* be a normed vector space. Let $x, y \in V$.

$$||x|| = ||x - y + y|| \le ||x - y|| + ||y||$$

Hence,

$$||x|| - ||y|| \le ||x - y||$$

By exchanging x and y,

$$||y|| - ||x|| \le ||x - y||$$

Hence, it holds that

$$\big|||x|| - \big||y\big||\big| \le \big||x - y\big||$$

• Define the map $n: V \to [0, \infty)$ on $(V, \|\cdot\|)$ with $n(x) = \|x\|$. Then n is continuous on V because

$$|n(x_1) - n(x_2)| = |||x_1|| - ||x_2||| \le ||x_1 - x_2||$$

Hence, *n* is Lipschitz continuous with constant 1.

Regarding the equivalence of norms:

Lemma 3.4. Let $\|\cdot\|_1$ and $\|\cdot\|_2$ be equivalent norms on V. Then it holds that

- 1. $\lim_{n\to\infty} ||x_n x||_1 = 0 \iff \lim_{n\to\infty} ||x_n x||_2 = 0$, hence $(x_n)_{n\in\mathbb{N}}$ is convergent with limit x in regards of $||\cdot||_1 \iff (x_n)_{n\in\mathbb{N}}$ is convergent with limit x in regards of $||\cdot||_2$.
- 2. $O \subseteq V$ is open in regards of $\|\cdot\|_1 \iff O$ is open in regards of $\|\cdot\|_2$, hence $\tau_1 = \tau_2$ (topologies are equivalent).
- 3. $K \subseteq V$ is compact in regards of $\|\cdot\|_1 \iff K$ is compact in regards of $\|\cdot\|_2$.

Proof. Let $\|\cdot\|_1$ and $\|\cdot\|_2$ are equivalent, hence $\exists m, M > 0 : m \|x\|_1 \le \|x\|_2 \le M \|x\|_1 \ \forall x \in V$.

1. Let $\varepsilon > 0$ and $\lim_{n \to \infty} ||x_n - x||_1 = 0$. Choose $N \in \mathbb{N}$ such that $n \ge N \implies ||x_n - x||_1 < \frac{\varepsilon}{M}$. For those n it holds that

$$||x_n - x||_2 \le M ||x_n - x||_1 < \frac{\varepsilon}{M} \cdot M = \varepsilon$$

Hence, $\lim_{n\to\infty} ||x_n - x||_2 = 0$.

2. $K_r^2(x) = \{ y \in V | ||y - x||_2 < r \}$. For $y \in K_r^2(x)$ it holds that

$$m \|y - x\|_1 \le \|y - x\|_2 < r$$

hence,

$$\|y-x\|_1 < \frac{r}{m} \implies y \in K^1_{\frac{r}{m}}(x)$$

hence $K_r^2(x) \subseteq K_{\frac{r}{M}}^1(x)$. Let $y \in K_{\frac{r}{M}}^1(x)$. Then it holds that,

$$||y - x||_2 \le M ||y - x||_1 < M \cdot \frac{r}{M} = r$$

hence $y \in K_r^2(x)$. $\Longrightarrow K_{\frac{r}{M}}^1(x) \subseteq K_r^2(x)$. Now let O be open in regards of $\|\cdot\|_2$, hence

$$\forall x \in O \exists r > 0: K^2_r(x) \subseteq O \implies K^1_{\frac{r}{M}}(x) \subseteq K^2_r(x) \subseteq O$$

so O is open in regards of $\|\cdot\|_1 \implies O$ is open in regards of $\|\cdot\|_2$ analogously.

3. Let K be compact in regards of $\|\cdot\|_1$ and $(x_n)_{n\in\mathbb{N}}$ be a sequence in K. Then there exists a subsequence $(x_{n_k})_{k\in\mathbb{N}}$ with $\|x_{n_k} - x\|_1 \to 0$ for $k \to \infty$ by the first property $\|x_{n_k} - x\|_2 \to 0$. Hence $(x_{n_k})_{k\in\mathbb{N}}$ is also a convergent subsequence in regards of $\|\cdot\|_2$.

Remark 3.6 (Proven in the practicals). Let $(x_n)_{n\in\mathbb{N}}$ be a sequence in \mathbb{R}^k

$$||x||_{\infty} = \max\left\{\left|x^{i}\right| \mid i=1,\ldots,n\right\}$$

$$x = \begin{bmatrix} x^1 \\ x^2 \\ \vdots \\ x^k \end{bmatrix}$$

It holds that $\lim_{n\to\infty} ||x_n - x||_{\infty} = 0 \iff \lim_{n\to\infty} |x_n^i - x^i| = 0$ for all $i \in \{1, \dots, k\}$.

Theorem 3.4 (Bolzano-Weierstrass theorem in \mathbb{R}^k). Let $K \subseteq \mathbb{R}^k$ be closed and bounded. Then K is compact in $(\mathbb{R}^k, \|\cdot\|_{\infty})$.

Proof. Let $||x||_{\infty} \le M \forall x \in K \iff |x^i| \le M \forall x \in K \text{ and } i \in \{1, ..., k\}$. Choose $(x_n)_{n \in \mathbb{N}}$ an arbitrary sequence in $K(x_n^i)_{n \in \mathbb{N}}$ is a bounded sequence in \mathbb{R} . Because $(x_n^1)_{n \in \mathbb{N}}$ is bounded, there exists a convergent subsequence $(x_{n_{i_1}}^1)_{i_1 \in \mathbb{N}}$

$$\lim_{l_1 \to \infty} x_{n_{l_1}}^1 = x^1$$

Consider $(x_{n_{l_1}}^2)_{l_1\in\mathbb{N}}$, a subsequence of a bounded sequence, hence bounded itself. By the Bolzano-Weierstrass theorem in \mathbb{R} , there exists a convergent subsequence $(x_{n_{l_{1}l_2}}^2)_{l_2\in\mathbb{N}}$ with $\lim_{l_2\to\infty}x_{n_{l_{1}l_2}}^2=x^2$. Consider $x_{n_{l_{1}l_2}}^1$ as subsequence of $x_{n_{l_1}}^1$ is already convergent, hence $\lim_{l_2\to\infty}x_{n_{l_{1}l_2}}^1=x^1$. Furthermore, up to index i, it holds that:

$$\lim_{l_k \to \infty} x_{n_{l_{1l_2...l_k}}} = x^i \qquad \text{for } i = 1, ..., k$$

Hence, with $\tilde{x_{l_k}} = x_{n_{l_{1l_2...l_k}}}$ gives a subsequence of x_n , converging by each coordinate. Thus,

$$\lim_{l_k \to \infty} \left\| \tilde{x}_{l_k} - x \right\|_{\infty} = 0$$

Because $\tilde{x}_{l_n} \in K$ and K be closed, it holds that $x \in K$. Hence K is compact.

Theorem 3.5 (Norm equivalence in \mathbb{R}^k). *In* \mathbb{R}^k , *all norms are equivalent.*

Proof. We show: Let $\|\cdot\|$ be an arbitrary norm on \mathbb{R}^n . Then $\|\cdot\|$ is equivalent to $\|\cdot\|_{\infty}$. By transitivity of norm equivalence, two arbitrary norms are equivalent to each other.

1. Let (e_1, e_2, \dots, e_k) be the canonical basis in \mathbb{R}^k .

$$x = \begin{bmatrix} x^1 \\ \vdots \\ x^k \end{bmatrix} = \sum_{j=1}^k x^j e_j$$

Furthermore let $M' = \max\{\|e_j\| : j = 1, ..., k\}$ with $\|e_j\| \neq 0$ and M' > 0. Then it holds that

$$||x|| = \left\| \sum_{j=1}^{k} x^{j} e_{j} \right\| \leq \sum_{j=1}^{k} \left\| x^{j} e_{j} \right\| = \sum_{j=1}^{k} \left| x^{j} \right| \left\| e_{j} \right\| \leq M' \sum_{j=1}^{k} \underbrace{\left| x_{j} \right|}_{\leq ||x||} \leq \underbrace{M' \cdot k}_{M} ||x||_{\infty} = M ||x||_{\infty}$$

2. We consider $\nu : \mathbb{R}^k \to [0, \infty)$. $\nu(x) = ||x||$ as map on $(\mathbb{R}^k, ||\cdot||_{\infty})$.

Claim. v is continuous on $(\mathbb{R}^k, ||\cdot||_{\infty})$.

Proof. Show that,

$$|v(x) - v(y)| = |||x|| - ||y||| \le ||x - y|| \le M ||x - y||$$
inversed triangle ineq. because of (1)

Hence ν is Lipschitz continuous.

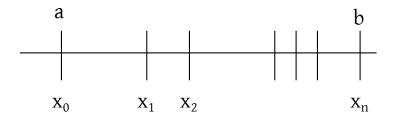


Figure 6: Illustration of a partition

We consider $S_{\infty}^{k-1} = \{x \in \mathbb{R}^k\} ||x||_{\infty} = 1 = \text{boundary}(K_1^{\infty}(0), S_{\infty}^{k-1} \text{ is bounded.})$

Let $(x_n)_{n\in\mathbb{N}}$ is a sequence in S^{k-1}_{∞} with $x=\lim_{n\to\infty}x_n$. Because $n(x)=\|x\|_{\infty}$ is continuous, it holds that

$$\lim_{n \to \infty} ||x_n||_{\infty} = ||x||$$
=1 =1

Hence $x \in S_{\infty}^{k-1}$. Hence, S_{∞}^{k-1} is closed in $(\mathbb{R}^k, \|\cdot\|_{\infty})$. Hence S_{∞}^{k-1} is compact in $(\mathbb{R}^k, \|\cdot\|_{\infty})$, $\nu: S_{\infty}^{k-1} \to [0, \infty)$, with S_{∞}^{k-1} compact, is continuous. Has

a minimum n on S_{∞}^{k-1} . Thus there exists $\overline{x} \in S_{\infty}^{k-1} : \underline{m} = \left\| \underline{\overline{x}} \right\| \le 1$

 $||x|| \forall x \in S_{\infty}^{-1}$. Let $x \in \mathbb{R}^k$ be arbitrary with $x \neq 0$. Then it holds that $\frac{x}{||x||_{\infty}} \in S_{\infty}^{k-1}$ and it holds that

$$m \le \left\| \frac{x}{\|x\|_{\infty}} \right\| = \frac{1}{\|x_{\infty}\|} \|x\| \implies m \|x\|_{\infty} \le \|x\|$$

Inequality also holds true for x = 0.

4 Integration calculus

Definition 4.1. Let a < b with $a, b \in \mathbb{R}$. We consider functions of [a, b]. We call $(x_j)_{j=0}^n$ a partition of [a, b] if $a = x_0 < x_1 < x_2 < \cdots < x_n = b$. x_j decomposes [a, b] in subintervals (x_{j-1}, x_j) . $\varphi : [a, b] \to \mathbb{R}$ is called step function in [a, b] in regards of partition $(x_j)_{j=0}^n$ if $\varphi|_{(x_{j-1}, x_j)} = c_j$, so constant for $j = 1, \ldots, n$.

 φ is called step function in [a, b] if there exists a partition such that φ is a subsequence.

$$\tau[a,b] = \{\varphi : [a,b] \to \mathbb{R} : \varphi \text{ is subsequence}\}$$

• Let $(\xi_i)_{i=0}^m$ be a partition of [a,b] and $(x_j)_{i=0}^n$ is a partition as well. Then we call $(\xi_i)_{i=0}^m$ a refinement of [a,b] and $(x_i)_{i=1}^n$ as well. Then $(\xi_i)_{i=0}^n$ is a refinement of $(x_j)_{i=0}^k \text{ if } \{x_0, x_1, \dots, x_n\} \subseteq \{\xi_0, \xi_1, \dots, \xi_m\}$

TODO drawing

Functions values in boundaries x_{i-1} and x_i do not have any constraints and will be relevant for an integral. A φ can be a step function in terms of many, various partitions.

Lemma 4.1. Let $\varphi \in \tau[a,b]$ be a step function in terms of partition $(x_j)_{j=0}^n$ and let $(x_i)_{i=0}^n$ be a refinement of $(x_j)_{i=0}^n$ in terms of $(x_i)_{i=0}^m$.

Proof. Refinement: For every $j \in \{0, ..., n\}$ there exists $i_j \in \{0, ..., m\}$ such that $X_j = \xi_{i_j}$. $i_0 = 0$, $i_n = m$. $i_{j-1} < i_j$.

Let $i \in \{1, ..., m\}$. Then there exists a uniquely determined $j \in \{1, ..., n\}$ such that $\xi_{i-1} < \xi_i \le \xi_j$

TODO drawing

Then it holds that $(\xi_{i-1}, \xi_i) \subseteq \underbrace{(\xi_{i_{j-1}})}_{=(x_{j-1}, x_j)}$, ξ_{i_j}) and $\varphi|_{(\xi_{i-1}, \xi_j)} = c_j = \text{const.}$ So φ is a subsequence in regards of $(\xi_i)_{i=0}^m$.

Definition 4.2. Let $\varphi \in \tau[a,b]$ in terms of partition $(X_j)_{j=0}^n$ with $\varphi|_{(X_{j-1},X_j)} = c_j$ and $\Delta X_i = X_i - X_{j-1} > 0$ for g = 1, ..., n. Then we define ...

$$\int_{a}^{b} \varphi \, dx = \sum_{j=1}^{n} c_{j} \triangle x_{j}$$

is called integral of φ in terms of partition $(x_i)_{i=0}^n$

This lecture took place on 2018/03/22.

Step function φ . $\varphi|_{x_{i-1},x_i} = c_i$

$$\delta x_j = x_j - x_{j-1}$$

$$\int_a^b \varphi \, dx = \sum_{j=1}^n c_j \cdot \delta x_j$$

Lemma 4.2. Let $(x_i)_{i=0}^n$ be a partition of [a,b] and $(\xi_i)_{i=0}^m$ be a refinement of $(x_j)_{j=0}^n$. Furthermore let φ be a subsequence with respect to $(x_j)_{i=0}^n$ (so also with respect to $(\xi_j)_{i=0}^m$). Then the integrals of φ with respect to $(x_j)_{i=0}^n$ and $(\xi_i)_{i=0}^m$ are equal.

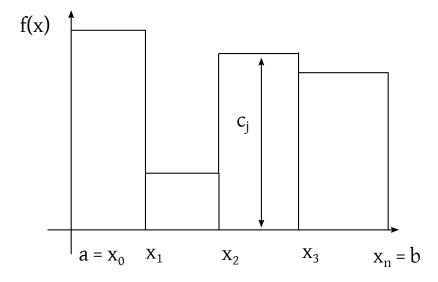


Figure 7: Integral of a step function as sum of areas of rectangles

Proof. There exist indices i_j for j = 0, n such that $x_j = \xi_{ij}$.

$$i_{0} = 0 i_{n} = m i_{j-1} < i_{j}$$

$$\delta x_{j} = x_{j} - x_{j-1} = \xi_{i_{j}} - \xi_{i_{j-1}} = \xi_{i_{j}} - \xi_{i_{j-1}} = \sum_{\substack{i=i_{j-1}+1\\ \text{telescoping sum}}}^{i_{j}} (\xi_{i} - \xi_{i-1}) = \sum_{\substack{i=i_{j-1}+1\\ \text{telescoping sum}}}^{i_{j}} \delta \xi_{i}$$

$$\varphi|_{x_{j-1},x_{j}} = c_{j} \implies \varphi|_{(\xi_{i-1},\xi_{i})} = c_{j} \text{ for } i = i_{j-1} + 1, \dots, i_{j}$$

$$\tilde{c}_{i} = \varphi|_{(\xi_{i-1},\xi_{i})}$$

$$\sum_{\substack{i=1\\ \text{integral of } \varphi \text{ w.r.t } (\xi_{i})_{i=0}^{m}}}^{m} \tilde{c}_{i} \delta \xi_{i} = \sum_{j=1}^{n} c_{j} \delta \xi_{i} = \sum_{j=1}^{n} c_{j} \delta x_{j}$$

$$\lim_{\substack{i=1\\ \text{integral of } \varphi \text{ w.r.t } (\xi_{i})_{i=0}^{m}}}$$

This is the integral of φ with respect to $(x_j)_{j=0}^n$.

Lemma 4.3. Let φ be a step function with respect to $(x_j)_{j=0}^n$ and $(w_i)_{i=0}^L$. Then the integrals of φ with respect to $(x_j)_{j=0}^n$ and with respect to $(w_l)_{l=0}^L$ equal.

Proof. Let $\{\xi_i \mid i=1,\ldots,m\} = \{x_j \mid j=0,\ldots,n\} \cup \{w_l \mid l=0,\ldots,L\}$ with $\xi_0=a$, $\xi_m=x_n=w_L=b$ and $\xi_{i-1}<\xi_i$ for $i=1,\ldots,m$. Then $(\xi_i)_{i=0}^m$ is a refinement of $(x_j)_{j=0}^n$ as well as $(w_l)_{l=0}^L$. By Lemma 4.2, the integral of φ with respect to $(x_j)_{j=0}^n=0$ integral of φ with respect to $(\xi_i)_{i=1}^m=0$ integral of φ with respect to $(w_l)_{l=0}^L$. Here we discard the statement "with respect to $(x_j)_{j=0}^n$ ".

Lemma 4.4. *Let* f, g *be step functions on* [a,b]. f, $g \in \tau[a,b]$.

• for $\alpha, \beta \in \mathbb{R}$, let $\alpha f + \beta g \in \tau[a, b]$ and

$$\int_{a}^{b} (\alpha f + \beta g) dx = \alpha \int_{a}^{b} f dx + \beta \int_{a}^{b} g dx$$

Hence, the integral is linear on [a,b]. $\tau[a,b]$ is a vector space.

- $f \le g$ in [a,b], then $\int_a^b f dx \le \int_a^b g dx$ (monotonicity).
- $\left| \int_a^b f \, dx \right| \le \int_a^b |f| \, dx \, (|f(x)|)$ is also a step function)

Proof. 1. Let $f, g \in \tau[a, b]$. Let $(\xi_i)_{i=0}^m$ be a partition such that $f|_{(\xi_{i-1}, \xi_i)} = c_i$ and $g|_{(\xi_{i-1}, \xi_i)} = d_i$. Then

$$\int_{a}^{b} (\alpha f + \beta g) dx = \sum_{i=1}^{m} (\alpha c_{i} + \beta d_{i}) \delta \xi_{i} = \alpha \sum_{i=1}^{m} c_{i} \delta \xi_{i} + \beta \sum_{i=1}^{m} d_{i} \delta \xi_{i} = \alpha \int_{a}^{b} f dx + \beta \int_{a}^{b} g dx$$

Furthermore,

$$(\alpha f + \beta g)|_{(\xi_{i-1},\xi_i)} = \alpha c_i + \beta d_i = \text{const.}$$

Thus,

$$\alpha f + \beta g \in \tau[a, b]$$

- 2. Let $h \in \tau[a, b]$ with $h(x) \ge 0 \forall x \in [a, b]$ be a step function and $\int_a^b h \, dx = \sum_{i=1}^m \underbrace{h_i}_{\ge 0} \delta \xi_i \ge 0$ TODO Hence, it holds that $0 \le \int_a^b h \, dx = \int_a^b (g f) \, dx = \int_a^b g \, dx \int_a^b f \, dx$.
- 3. $f \le |f|$, hence $\int_a^b f dx \le \int_a^b |f| dx$ and also $-f \le |f|$, so

$$\int_{a}^{b} (-f) dx = -\int_{a}^{b} f dx \le \int_{a}^{b} |f| dx$$

$$\implies \left| \int_{a}^{b} f dx \right| \le \int_{a}^{b} |f| dx$$

It is left to prove: $|f| \in \tau[a, b]$ (i.e. |f| is a step function)

Let $f|_{(\xi_{i-1},\xi_i)} = c_i \implies |f||_{(\xi_{i-1},\xi_i)} = |c_i| = \text{constant. Hence } |f| \in \tau[a,b].$

Definition 4.3. *Let* $a \subseteq \mathbb{R}^k$. *We call* $\chi_A : \mathbb{R}^n \to \mathbb{R}$ *with*

$$\chi_A(x) = \begin{cases} 1 & if \ x \in A \\ 0 & else \end{cases}$$

a characteristic function (*indicator function*) *of set A. Often denoted as* $\chi_A = 1$.

Remark 4.1. TODO drawings

Let A = (a',b') with $a \le a' < b' \le b$. Then $\chi_{(a',b')} \in \tau[a,b]$. Also for $x \in [a,b]$, it holds that $\chi_{\{x\}} = \tau[a,b]$. Therefore every linear combination of characteristic functions of open subintervals (a',b') of [a,b] as characteristic functions of one-point sets $\chi_{\{x\}}, x \in [a,b]$ a step function on [a,b].

$$\sum_{i=1}^n \alpha_j \chi_{(a_j,b_j)} + \sum_{k=1}^m \beta_k \chi_{\{x_k\}} \in \tau[a,b]$$

On the opposite, $f \in \tau[a,b]$, hence

$$f|_{(x_{j-1},x_j)} = c_j \text{ and } f(x_j) = d_j$$

$$f = \sum_{i=1}^{n} c_j \chi_{(x_{j-1}, x_j)} + \sum_{i=0}^{n} d_j \chi_{\{x_j\}} = (*)$$

for $x \in (x_{i-1}, x_i)$ it holds that $\xi_{(x_{i-1}, x_i)}(x) = 1$.

$$\chi_{(x_{l-1},x_l)}(x) = 0$$
 for $l \neq j$

$$\chi_{\{x_l\}}(x) = 0$$
 for $l = 0, ..., n$

i.e. $\sum_{j=1}^{n} c_{l}\chi_{(x_{l-1},x_{l})}(x) + \sum_{l=0}^{n} d_{j}\chi_{\{x_{l}\}}(x) = c_{j} \cdot 1 + 0 = c_{j}$ hence $(*) = c_{j}$ on (x_{j-1},x_{j}) . Therefore $f \in \tau[a,b] \iff f$ is linear combination of characteristic functions of open intervals or one-pointed sets.

4.1 Regulated functions

Definition 4.4. Let X be a metric space $A \subseteq X$ and $x \in X$ is an accumulating point¹ of A. Let $f: A \to \mathbb{R}$. We say, f has limit $c \in \mathbb{R}$ in x ($\lim_{\xi \to x} f(\xi) = c$) if

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall \xi \in A, \xi \neq x \text{ and } d(\xi, x) < \delta : |f(\xi) - c| < \varepsilon$$

¹An accumulation point has 3 equivalent definitions (sequence, intersection, infinitely many elements in sphere).

Remark 4.2. $x \in A$ and $c = f(x) \implies f$ is continuous in x.

We usually consider $A = [a, b] \subseteq \mathbb{R}$, $x \in [a, b]$.

It is possible, that f in x has a limit, $x \in A$ and $c = \lim_{\xi \to x} f(\xi) \neq f(x)$.

TODO drawing

Definition 4.5. Now let $A \subseteq \mathbb{R}$ and x is a accumulation point of A. Let $f: A \to \mathbb{R}$ be given. We say f has a right-sided limit c in x with $c = \lim_{\xi \to x^+} f(\xi) = c$ if $\forall \varepsilon > 0 \exists \delta > 0: \forall \xi \in A, \xi > x$

$$\wedge |\xi - x| = \xi - x < \delta \implies |f(\xi) - c| < \varepsilon$$

The left-sided limit follows analogously.

$$c = \lim_{\xi \to x^{-}} f(\xi)$$

$$c = \lim_{\xi \to x^+} f(\xi) \qquad d = \lim_{\xi \to x^-} f(\xi)$$

TODO drawing

Lemma 4.5 (Sequence criterion for limits of functions). *Let* $f : A \subseteq X \to \mathbb{R}$ *be given.* x *is an accumulation point of* A. *Then it holds that*

$$\lim_{\xi \to x} f(\xi) = c \iff \forall (\xi_n)_{n \in \mathbb{N}} : \xi_n \in A, \xi_n \neq x \ and \ \lim_{n \to \infty} \xi_n = x \ it \ holds \ that \ \lim_{n \to \infty} f(\xi_n) = c$$

For one-sided limits $A \subseteq \mathbb{R}$ it holds that

$$c = \lim_{\xi \to x^+} f(\xi) \iff \forall (\xi_n)_{n \in \mathbb{N}} : \xi \in A \qquad \xi_n > x \text{ with } \lim_{n \to \infty} \xi_n = x \text{ it holds that } \lim_{n \to \infty} f(\xi_n) = c$$

Remark 4.3. Attention! We, therefore, use two different definitions of limits.

Lemma 4.6 (Cauchy criterion of limits of functions). Let $f: A \subseteq X \to \mathbb{R}$. Let x be an accumulation point of A. Let X be a metric space. Then it holds that f has a limit in x if and only if

$$\forall \varepsilon > 0 \exists \delta > 0 : \forall \xi, \eta \in A : \xi \neq x_i : \eta \neq x :$$

with $d(\xi, x) < \delta$ and $d(\eta, x) < \delta$ it holds that $|f(\xi) - f(\eta)| < \varepsilon$. Analogously for one-sided limits with $A \subseteq \mathbb{R}$. Additionally, we need the constraint that $\xi > X$ and $\eta > x$ for $\lim_{\xi \to x^+} f(\xi)$ or equivalently, $\xi < x$ and $\eta < x$ for $\lim_{\xi \to x^-} f(\xi)$.

TODO normalize and visualize equivalent statements for left-sided and right-sided limit (using Ring's notes)

Proof. \Leftarrow Let $c = \lim_{\xi \to x} f(\xi)$ and let $\varepsilon > 0$ be chosen arbitrarily. Then there exists $\delta > 0$ such that $d(\xi, x) < \delta$ and $\xi \neq x$

$$\implies \left| f(\xi) - c \right| < \frac{\varepsilon}{2}$$

For ξ , η : $d(\xi, x) < \delta$ and $d(\eta, x) < \delta$ with ξ , $\eta \neq x$ is therefore

$$\left| f(\xi) - f(\eta) \right| = \left| f(\xi) - c + c - f(\eta) \right| \le \left| f(\xi) - c \right| + \left| f(\eta) - c \right| < \frac{\varepsilon}{2} + \frac{\varepsilon}{=} \varepsilon$$

- ⇒ Assume the Cauchy criterion holds. We show that
 - 1. for every sequence $(\xi_n)_{n\in\mathbb{N}}$, $\xi_n\in A\setminus\{x\}$ with $\lim_{n\to\infty}\xi_n=x$ it holds that $(f(\xi_n))_{n\in\mathbb{N}}$ is a Cauchy sequence in \mathbb{R} and therefore convergent in \mathbb{R}
 - 2. all Cauchy sequences have the *same* limit *c*.

We prove (1.)

Let $(\xi_n)_{n\in\mathbb{N}}$ be as above. Let $\varepsilon > 0$ be arbitrary. and N_{ε} large enough such that $\forall n \in N_{\varepsilon}$ it holds that $d(\xi_n, x) < \delta$ (δ chosen appropriately to ε according to the Cauchy criterion).

By the Cauchy criterion, $|f(\xi_n) - f(\xi_m)| < \varepsilon$ for all $m, n \ge N_{\varepsilon}$. Therefore $(f(\xi_n))_{n \in \mathbb{N}}$ is a Cauchy sequence in \mathbb{R} . If \mathbb{R} is complete, then there exists $c = \lim_{n \to \infty} f(\xi_n)$. QED.

We prove (2.)

Let $\xi_n \to x$ as above and $\xi_n' \to x$ as above and $c = \lim_{n \to \infty} f(\xi_n)$ as well as $c' = \lim_{n \to \infty} f(\xi_n')$. Let $\varepsilon > 0$ be arbitrary, N_{ε} such that $n \ge N_{\varepsilon} \implies \left| f(\xi_n) - c \right| < \frac{\varepsilon}{3}$ and $N_{\varepsilon}' \in \mathbb{N}$ such that $n \ge N_{\varepsilon}' \implies \left| f(\xi_n') - c' \right| < \frac{\varepsilon}{3}$.

Furthermore choose $\delta > 0$ such that

$$d(\xi, x) < \delta \wedge d(\eta, x) < \delta \implies |f(\xi) - f(\eta)| < \frac{\varepsilon}{3}$$

(because of the Cauchy criterion). M_{ε} such that

$$n \ge M_{\varepsilon} \implies d(\xi_n, x) < \delta \land M'_{\varepsilon} : n \ge M'_{\varepsilon} \implies d(\xi'_n, x) < \delta$$

Let $n \ge \max\{N_{\varepsilon}, N'_{\varepsilon}, M_{\varepsilon}, M'_{\varepsilon}\}$.

This lecture took place on 2018/04/10.

Then it holds that

$$|c - c'| \le \underbrace{\left|c - f(\xi_n)\right|}_{<\frac{\varepsilon}{3}} + \underbrace{\left|f(\xi_n) - f(\xi_n')\right|}_{<\frac{\varepsilon}{3}} + \underbrace{\left|f(\xi_n') - c'\right|}_{<\frac{\varepsilon}{3}} \qquad \forall \varepsilon > 0$$

Hence, c = c'. We have shown that $\exists c \in \mathbb{R} : \forall (\xi_n)_{n \in \mathbb{N}}$ with $\lim_{n \to \infty} \xi_n = x$ it holds that $\lim_{n \to \infty} f(\xi_n) = c$. So $\lim_{\xi \to \infty} f(\xi) = c$ because of Lemma 4.5. QED.

Definition 4.6 (Regulated function). *Let* a < b, $f : [a,b] \rightarrow \mathbb{R}$. *We call* f a regulated function on [a,b] *if*

- 1. $\forall x \in (a, b)$, f in x has a right-sided and a left-sided limit.
- 2. in x = a, f has a right-sided limit.
- 3. in x = b, f has a left-sided limit.

$$\mathcal{R}[a,b] = \{ f : [a,b] \to \mathbb{R} \mid f \text{ is a regulated function} \}$$

Definition 4.7 (Equivalent definition). 1. $\forall x \in [a, b)$, f has a right-sided limit in x

2. $\forall x \in (a, b]$, f has a left-sided limit in x

Example 4.1. Let f be continuous in [a,b]. Let $\varphi \in \tau[a,b]$ be a regulated function. Then $\varphi \in \mathcal{R}[a,b]$.

Rationale:

Let $x_0 = a < x_1 < \dots < x_n = b$ and $\varphi|_{(x_{i-1},x_i)} = c_i$.

Let $x \in [a, b]$ be chosen arbitrarily.

Case 1 *Let* $x \in (x_{i-1}, x_i)$ *for some* $j \in \{1, ..., n\}$

$$\implies \lim_{\xi \to x} \varphi(\xi) = c_j$$

Choose δ small enough such that $(x-\delta, x+\delta) \subseteq (x_{j-1}, x_j)$. $\forall \xi$ with $\xi \in (x-\delta, x+\delta)$ it holds that

$$\left|\varphi(\xi)-c_j\right|=0$$

Case 2 *Let* $x = x_j$ *for* j = 1, ..., n - 1.

$$\implies \lim_{\xi \to x_j^+} \varphi(\xi) = c_{j+1}$$

$$\lim_{\xi \to x_j^-} \varphi(\xi) = c_j$$

Compare with Figure 8.

Case 3 Let $x = x_0 = a \implies \lim_{\xi \to a^+} \varphi(\xi) = c_1$.

$$x = x_n = b \implies \lim_{\xi \to b^-} \varphi(\xi) = c_n$$

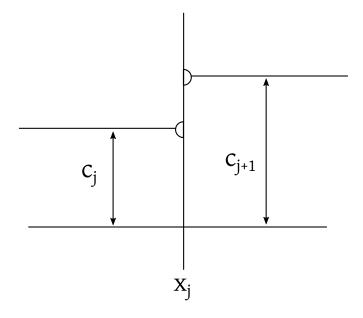


Figure 8: Regulated function

Let $f : [a,b] \to \mathbb{R}$ be monotonically increasing oder monotonically decreasing. Then $f \in \mathcal{R}[a,b]$. The proof will be done in the practicals.

Definition 4.8 (Boundedness). Let $X \neq \emptyset$ be a set. $f: X \to \mathbb{K}$ with $\mathbb{K} = \mathbb{R}$ or $\mathbb{K} = \mathbb{C}$. We say: f is bounded on X, if $f(X) \subseteq \mathbb{K}$ is a bounded set in \mathbb{K} . Hence, $\exists m \geq 0 : |f(x)| \leq m \forall x \in X$. We let,

$$\mathcal{B}(X) = \left\{ f : X \to \mathbb{K} \mid f \text{ is bounded} \right\}$$

 $\mathcal{B}(X)$ has vector space structure. $f, g \in \mathcal{B}(X), \lambda \in \mathbb{K}$.

$$(f+g)(x) = f(x) + g(x)$$

$$(\lambda \cdot f)(x) = \lambda \cdot f(x)$$

 $f+g\in\mathcal{B}(X)$ and $\lambda f\in\mathcal{B}(X)$. Let $\big|f(x)\big|\leq m \forall x\in X$ and $\big|g(x)\big|\leq m' \forall x\in X$. Then it holds that

$$\left| (f+g)(x) \right| = \left| f(x) + g(x) \right| \le \left| f(x) \right| + \left| g(x) \right| \le m + m'$$

Remark 4.4. It is very interesting, that X does not require any kind of algebraic structure.

We let

$$||f||_{\infty} = \sup \left\{ |f(x)| \mid x \in X \right\} = \min \left\{ m \ge 0 \mid |f(x)| \le m \forall x \in X \right\}$$

Some work is required to show that $\|\cdot\|_{\infty}$ is a norm on $\mathcal{B}(X)$.

Hence, $(\mathcal{B}(X), \|\cdot\|_{\infty})$ is a normed vector space. Convergence in $\mathcal{B}(X)$: It holds that $f_n \to f$ in $(\mathcal{B}(X), \|\cdot\|_{\infty})$ if and only if $\forall \varepsilon > 0 \exists N \in \mathbb{N} : n \geq N \implies \|f_n - f\|_{\infty} < \varepsilon$.

$$||f_n - f||_{\infty} < \varepsilon \iff \sup \{|f_n(x) - f(x)| : x \in X\}$$

 $\iff |f_n(x) - f(x)| \le \varepsilon \forall x \in X$

Hence, $f_n \to f$ in $(\mathcal{B}(X), \|\cdot\|_{\infty}) \iff \forall \varepsilon > 0 \exists N \in \mathbb{N} : n \ge N \implies |f_n(x) - f(x)| \le \varepsilon \forall x \in X$. We say " f_n converges uniformly to f on X".

Theorem 4.1 (Approximation theorem for regulated function). Let $f : [a,b] \to \mathbb{R}$. Then it holds that $f \in \mathcal{R}[a,b] \iff \forall \varepsilon > 0$ there exists some step function $\varphi \in \tau[a,b]$ such that $|\varphi(x) - f(x)| < \varepsilon \forall x \in [a,b]$ ($||\varphi - f||_{\infty} < \varepsilon$).

Especially $\varepsilon_n = \frac{1}{n}$ and φ_n as above. Then it holds that $\|\varphi_n - f\|_{\infty} < \frac{1}{n}$, hence $f = \lim_{n \to \infty} \varphi_n$ uniformly on [a, b].

Proof. Direction \Rightarrow . Let $f \in \mathcal{R}[a,b]$.

Proof by contradiction. We negate our hypothesis:

$$\exists \varepsilon > 0 : \forall \varphi \in \tau[a, b] \exists x \in [a, b] : |\varphi(x) - f(x)| \ge \varepsilon \tag{1}$$

Assume (1) holds for $f \in [a,b]$. We construct nested intervals $[a_n,b_n]$ with $[a_{n+1},b_{n+1}] \subseteq [a_n,b_n]$ and $b_{n+1}-a_{n+1}=\frac{1}{2}(b_n-a_n)$ and (1) holds on $[a_n,b_n] \forall n \in \mathbb{N}$. Hence $\forall \varphi \in \tau[a_n,b_n] \exists x \in [a_n,b_n]$ such that $|\varphi(x)-f(x)| \ge \varepsilon$. This is what we want to show.

Let $a_0 = a$ and $b_0 = b$. Then (1) holds on $[a_0, b_0]$ by assumption. $n \to n+1$: Construction of $[a_{n+1}, b_{n+1}]$. Let $m_n = \frac{1}{2}(a_n + b_n)$. We need to prove: (1) holds either on $[a_n, m_n]$ or on $[m_n, b_n]$.

Because if the opposite of (1) holds on $[a_n, m_n]$ as well as $[m_n, b_n]$, then there exists $\varphi_1^n \in \tau[a_n, m_n]$ with $|\varphi_n^1(x) - f(x)| < \varepsilon \forall x \in [a_n, m_n]$ and if the opposite of (1) holds on $[m_n, b_n]$:

$$\exists \varphi_n^2 \in \tau[m_n,b_n]: \left|\varphi_n^2(x) - f(x)\right| < \varepsilon \forall x \in [m_n,b_n]$$

Let

$$\varphi^{n}(x) = \begin{cases} \varphi_{n}^{1}(x) & \text{if } x \in [a_{n}, m_{n}] \\ \varphi_{n}^{2}(x) & \text{if } x \in (m_{n}, b_{n}] \end{cases}$$

Then φ^n is piecewise constant, hence $\varphi^n \in \tau[a_n, b_n]$ and it holds that

$$\left|\varphi^{n}(x) - f(x)\right| = \begin{cases} \frac{\left|\varphi_{1}^{n}(x) - f(x)\right|}{<\varepsilon} & \text{for } x \in [a_{n}, m_{n}]\\ \frac{<\varepsilon}{} & \text{for } x \in [m_{n}, b_{n}] < \varepsilon \end{cases}$$

This contradicts with (1) on $[a_n, b_n]$.

Hence: (1) holds on $[a_n, m_n]$ or on $[m_n, b_n]$.

Choose $[a_{n+1}, b_{n+1}]$ as one of the subintervals in which (1) holds.

Let $X \in \bigcap_{n \in \mathbb{N}} [a_n, b_n]$ (by completeness of \mathbb{R}).

1. Let $x \in (a, b)$. Let ε as above such that (1) holds on every interval $[a_n, b_n]$. Let $c_+ = \lim_{\xi \to x^+} f(\xi)$ and $c_- = \lim_{\xi \to x^-} f(\xi)$ (possible, because $f \in \mathcal{R}[a, b]$). Limes property: $\exists \delta > 0 : |\xi - x| < \delta$ and $\xi < x$, then $|f(\xi) - c_-| < \varepsilon$ and $|\xi - x| < \delta$ and $x < \delta$ then $|f(\xi) - c_+| < \varepsilon$.

Additionally, choose δ sufficiently small enough such that $(x - \delta, x + \delta) \subseteq [a, b]$. Let

$$\hat{\varphi}(\xi) = \begin{cases} 0 & \text{for } \xi \in [a,b] \setminus (x-\delta, x+\delta) \\ c_{-} & \text{for } \xi \in (x-\delta, x) \\ c_{+} & \text{for } \xi \in (x, x+\delta) \\ f(x) & \text{for } \xi = x \end{cases}$$

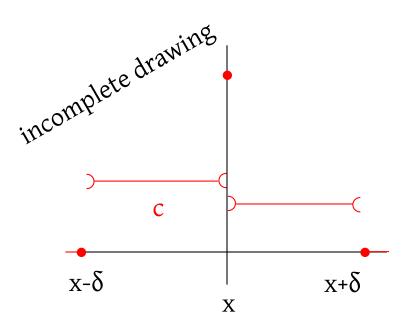
 $\hat{\varphi} \in \tau[a, b]$ and it holds that

$$\forall \xi \in (x - \delta, x + \delta) : \left| \hat{\varphi}(\xi) - f(\xi) \right| = \begin{cases} \underbrace{\left| c_{-} - f(\xi) \right|}_{<\varepsilon} & \text{for } \delta \in (x - \delta, x) \\ \underbrace{\left| f(x) - f(x) \right|}_{=0} & \text{for } \xi = x \\ \underbrace{\left| c_{+} - f(\xi) \right|}_{<\varepsilon} & \text{for } \xi \in (x, x + \delta) \end{cases} < \varepsilon$$

Now let N be sufficiently large enough such that $[a_N, b_N] \subseteq (x - \delta, x + \delta)$ (possible because $([a_n, b_n])_{n \in \mathbb{N}}$ gives nested intervals tightening on x). Then it holds on $[a_N, b_N]$ that:

$$\hat{\varphi}|_{[a_N,b_N]} \in \tau[a_N,b_N]$$

and $\forall \xi \in [a_N, b_N] \subseteq (x - \delta, x + \delta)$ it holds that $|\hat{\varphi}(\xi) - f(\xi)| < \varepsilon$. This contradicts with (1) on $[a_N, b_N]$.



We also need to cover the special cases x = a and x = b. But this works analogously with one-sided limits.

Direction \Leftarrow : Let $f = \lim_{n \to \infty} \varphi_n$ uniform on [a, b]. Show that $\forall x \in [a, b)$ there exists a right-sided limit of f in x.

Let $\varepsilon > 0$ be arbitrary. $N \in \mathbb{N}$ sufficiently large such that $|f(\xi) - \varphi_N(\xi)| < \frac{\varepsilon}{2} \forall \xi \in [a,b]$. φ_N is piecewise constant. Choose $\delta > 0$ such that $\varphi_N|_{(x,x+\delta)} = c$. Now let $\xi, \eta \in (x,x+\delta)$ be chosen arbitrarily. Then it holds that

$$|f(\xi) - f(\eta)| \le \left| f(\xi) - \underbrace{c}_{=\varphi_N(\xi)} \right| + \left| \underbrace{c}_{=\varphi_N(\eta)} - f(\eta) \right|$$

$$= \left| \underbrace{f(\xi) - \varphi_N(\xi)}_{<\frac{\varepsilon}{2}} \right| + \left| \underbrace{\varphi_N(\eta) - f(\eta)}_{<\frac{\varepsilon}{2}} \right| < \varepsilon$$

Therefore f has a right-sided limit in x by the Cauchy criterion. f has left-sided limit in every point $x \in (a, b]$ analogously.

Corollary. Every regulated function $f \in \mathcal{R}[a,b]$ is bounded. Let $\varphi \in \tau[a,b]$ with $||f - \varphi||_{\infty} < 1$. φ is bounded, hence $\exists m \in [0,\infty)$: $|\varphi(x)| \leq m \forall x \in [a,b]$. Then it holds

that $|f(x)| \le |f(x) - \varphi(x)| + |\varphi(x)| < 1 + m \forall x \in [a, b]$, hence $f \in \mathcal{B}[a, b]$.

$$\mathcal{R}[a,b] \subseteq \mathcal{B}[a,b]$$

Corollary. Let $f \in \mathcal{R}[a,b] \iff f = \sum_{j=0}^{\infty} \psi_j$ with $\psi_j \in \tau[a,b]$ and the series converges uniformly on [a,b].

Proof. Direction \Leftarrow .

Let $f = \sum_{j=0}^{\infty} \psi_j$ with uniform convergence. Let $\varphi_n = \sum_{j=0}^{\infty} \psi_j \in \tau[a,b]$ and $f = \lim_{n \to \infty} \phi_n$ uniform on $[a,b] \xrightarrow{} f \in \mathcal{R}[a,b]$.

Satz 12

Direction \Longrightarrow .

Let $f \in \mathcal{R}[a,b]$ and $f = \lim_{n \to \infty} \varphi_n$ with $\varphi_n \in \tau[a,b]$ (by Satz 1?!).

$$\psi_{0} = \varphi_{0}$$

$$\psi_{j} = \varphi_{j} - \varphi_{j-1} \quad \text{for } j \ge 1$$

$$\sum_{j=0}^{n} \psi_{j} = \varphi_{0} + \sum_{j=1}^{n} (\varphi_{j} - \varphi_{j-1}) = \varphi_{0} + \sum_{j=1}^{n} \varphi_{j} - \sum_{j=0}^{n-1} \varphi_{j} = \varphi_{n}$$

converges uniformly to f.

5 Integration of regulated functions

Definition 5.1 (Definition with a theorem). Let $f \in \mathcal{R}[a,b]$ and $\varphi_n \in \tau[a,b]$ with $f = \lim_{n \to \infty} \varphi_n$ is uniform on [a,b]. We let

$$\int_{a}^{b} f \, dx = \lim_{n \to \infty} \int_{a}^{b} \varphi_n \, dx$$

for the integral of f on [a,b].

Theorem: This limit (on the right-hand side) always exists and is independent of the particular choice of the approximating sequence.

Proof. φ_n is chosen as above.

$$i_n = \int_a^b \varphi_n \, dx$$

Show: i_n is cauchy sequence in \mathbb{R} .

This lecture took place on 2018/04/12.

Let $\varepsilon > 0$ be chosen arbitrary. Choose $N \in \mathbb{N}$ such that

$$n \ge N \implies \left\| f - \varphi_n \right\|_{\infty} < \frac{\varepsilon}{2(b-a)}$$

For $n, m \ge N$ it holds for $x \in [a, b]$ that

$$\left| \varphi_n(x) - \varphi_m(x) \right| \le \left| \varphi_n(x) - f(x) \right| + \left| f(x) - \varphi_m(x) \right|$$

$$\le \left\| \varphi_n - f \right\|_{\infty} + \left\| f - \varphi_m \right\|_{\infty} < \frac{\varepsilon}{2(b-a)} + \frac{\varepsilon}{2(b-a)} = \frac{\varepsilon}{b-a}$$

 $|\varphi_n - \varphi_m|$ is a step function.

$$\left|\varphi_n - \varphi_m\right| \le \frac{\varepsilon}{b-a} \cdot \underbrace{\chi_{[a,b]}}_{\in \tau[a,b]}$$

Integral for subsequence is monotonous:

$$|i_{n} - i_{m}| = \left| \int_{a}^{b} \varphi_{n} \, dx - \int_{a}^{b} \varphi_{m} \, dx \right| = \left| \int_{a}^{b} (\varphi_{n} - \varphi_{m}) \, dx \right| \le \int_{a}^{b} \left| \varphi_{n} - \varphi_{m} \right| \, dx$$

$$\leq \int_{a}^{b} \frac{\varepsilon}{b - a} \cdot \chi_{[a,b]} \, dx = \frac{\varepsilon}{b - a} \underbrace{\int_{a}^{b} \chi_{[a,b]} \, dx}_{1,(b-a)} = \varepsilon$$
by monotonicity

So $(i_n)_{n\in\mathbb{N}}$ is a Cauchy sequence. \mathbb{R} is complete, hence $i=\lim_{n\to\infty}i_n$ exists.

Uniqueness: (dt. mithilfe des Reissverschlussprinzips)

Let $(\varphi_n)_{n\in\mathbb{N}}$, $(\Phi_n)_{n\in\mathbb{N}}$ be two sequences of step functions, converging uniformly towards f.

$$i_n = \int_a^b \varphi_n dx$$
 and $j_n = \int_a^b \Phi_n dx$
 $i = \lim_{n \to \infty} i_n$ $j = \lim_{n \to \infty} j_n$

Show that i = j.

Now we construct a sequence $(\mu_n)_{n\in\mathbb{N}}$ of step functions.

$$\underbrace{(\varphi_1,\Phi_1,\varphi_2,\Phi_2,\ldots)}_{(\mu_n)_{n\in\mathbb{N}}}$$

 μ_n is a sequence of step functions converging uniformly towards f (the proof is left as an exercise to the reader).

Because of part 1 of the proof:

$$m_n = \int_a^b \mu_n dx$$
 converges with limit m

 $(i_n)_{n\in\mathbb{N}}$ as well as $(j_n)_{n\in\mathbb{N}}$ are subsequences of $(m_n)_{n\in\mathbb{N}}$. Hence it holds that $i=\lim_{n\to\infty}i_n=m=\lim_{n\to\infty}j_n=j$.

Theorem 5.1 (Elementary properties of an integral). *Let* $f, g \in \mathcal{R}[a, b]$, $\lambda, \mu \in \mathbb{R}$. *Then it holds that*

Linearity

$$\lambda f + \mu g \in \mathcal{R}[a,b]$$
 and $\int_a^b (\lambda f + \mu g) dx = \lambda \int_a^b f dx + \mu \int_a^b g dx$

Monotonicity If $f(x) \le g(x) \forall x \in [a, b]$ ($f \le g$) it holds that

$$\int_{a}^{b} f \, dx \le \int_{a}^{b} g \, dx$$

Boundedness $|f| \in \mathcal{R}[a,b]$ and

$$\left| \int_{a}^{b} f \, dx \right| \leq \int_{a}^{b} \left| f \right| \, dx$$

Proof. We prove linearity.

Let $x \in [a, b)$ and $c_+ = \lim_{\xi \to x_+} f(\xi)$ as well as $d_+ = \lim_{\xi \to x_+} g(\xi)$ ($f, g \in \mathcal{R}[a, b]$). Then it holds that

$$\lim_{\xi \to x^+} (\lambda f(\xi) + \mu g(\xi)) = \lambda \lim_{\xi \to x^+} f(\xi) + \mu \lim_{\xi \to x^+} g(\xi) = \lambda c_+ + \mu d_+$$

exists. Analogously for the left side, hence $\lambda f + \mu g \in \mathcal{R}[a, b]$.

Let $\varphi_n, \Phi_n \in \tau[a,b]$ with $\varphi_n \to f$ and $\Phi_n \to g$ is uniform on [a,b]. Hence $\lambda \varphi_n + \mu \Phi_n \to \lambda f + \mu g$ is continuous on [a,b].

Proof of this:

Let $\varepsilon > 0$ be arbitrary, N such that $n \ge N \implies \|\varphi_n - f\|_{\infty} < \frac{\varepsilon}{2(|\lambda|+1)}$ and M such that $n \ge M \implies \|\Phi_n - g\|_{\infty} < \frac{\varepsilon}{2(|\mu|+1)}$.

Then it holds that

$$\|\lambda \varphi_n + \mu \Phi_n - \lambda f - \mu g\|_{\infty} \le |\lambda| \|\varphi_n - f\|_{\infty} + |\mu| \|\Phi_n - g\|_{\infty}$$

$$< \frac{|\lambda|}{2(|\lambda| + 1)} \cdot \varepsilon + \frac{|\mu|}{2(|\mu| + 1)} \cdot \varepsilon < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon$$

We continue:

$$\int_{a}^{b} (\lambda f + \mu g) dx = \lim_{n \to \infty} \int_{a}^{b} (\lambda \varphi_{n} + \mu \Phi_{n}) dx = \lim_{n \to \infty} (\lambda \int_{a}^{b} \varphi_{n} dx + \mu \int_{a}^{b} \Phi_{n} dx)$$

$$= \lambda \lim_{n \to \infty} \int_{a}^{b} \varphi_{n} dx + \mu \lim_{n \to \infty} \int_{a}^{b} \Phi_{n} dx$$

$$= \lambda \int_{a}^{b} f dx + \mu \int_{a}^{b} g dx$$

We prove monotonicity.

Show: Let $h \in \mathcal{R}[a, b]$ with $h \ge 0$ in [a, b]. Then it holds that $\int_a^b h \, dx \ge 0$.

We will show that $(\tilde{\varphi}_n)_{n\in\mathbb{N}}$ exists with $\tilde{\varphi}_n \to h$ uniform on [a,b] and $\tilde{\varphi}_n \geq 0$.

Therefore we prove: Let $(\varphi_n)_{n\in\mathbb{N}}$, $\varphi_n \in \tau[a,b]$ with $\varphi_n \to h$ uniform on [a,b].

Define $\tilde{\varphi}_n$ such that

$$\varphi_n = \sum_{j=1}^{m_n} c_j \chi_{(x_{j-1}, x_j)} + \sum_{j=0}^{m_n} d_j \chi_{\{x_j\}}$$

Let

$$\tilde{\varphi}_n = \sum_{j=1}^{m_n} \underbrace{\tilde{c}_j}_{>0} \chi_{(x_{j-1}, x_j)} + \sum_{j=0}^{m_n} \underbrace{h(x_j)}_{>0} \chi_{\{x_j\}}$$

and $\tilde{c}_i := \max c_i$, $0 \ge 0$. So it holds that $\tilde{\varphi}_n \ge 0$.

For $x = x_l$ ($l \in \{0, ..., m_n\}$) it holds that

$$\left|\tilde{\varphi}_{n}(x_{l}) - h(x_{l})\right| = \left|\sum_{j=1}^{m_{n}} \tilde{c}_{j} \underbrace{\chi_{(x_{j-1},x_{j})}(x_{l})}_{=0 \text{ bc. } x_{l} \notin (x_{j-1},x_{j})} + \sum_{j=0}^{m_{n}} h(x_{j}) \underbrace{\chi_{\{x_{j}\}}(x_{l})}_{=\delta_{j,l}} - h(x_{l})\right|$$

$$= |h(x_l) - h(x_l)| = 0 \le \left| \varphi_n(x_l) - h(x_l) \right|$$

For $x \in (x_{i-1}, x_i)$ it holds that

$$\begin{aligned} \left| \tilde{\varphi}_{n}(x) - h(x) \right| &= \left| \sum_{j=1}^{m_{n}} \tilde{c}_{j} \underbrace{\chi_{(x_{j-1}, x_{j})}(x)}_{\delta_{l, j}} + \sum_{j=0}^{m_{n}} h(x) \cdot \underbrace{\chi_{\{x_{j}\}}(x)}_{=0 \text{ bc. } x \neq x_{j}} - h(x) \right| \\ &= \left| \tilde{c}_{l} - h(x) \right| = \begin{cases} |c_{l} - h(x)| & \text{if } c_{l} \geq 0 \\ |h(x)| = h(x) & \text{if } c_{l} < 0 \end{cases} \end{aligned}$$

$$\leq \begin{cases} |c_l - h(x)| & \text{if } c_l \geq 0 \\ h(x) - c_l & \text{if } c_l < 0 \end{cases}$$

$$= \begin{cases} \left| \varphi_n(x) - h(x) \right| & \text{if } c_l = \varphi_n(x) \geq 0 \\ \left| h(x) - \varphi_n(x) \right| & \text{if } c_l = \varphi_n(x) < 0 \end{cases}$$

$$= \left| \varphi_n(x) - h(x) \right|$$

hence, $|\tilde{\varphi}_n(x) - h(x)| \le |\varphi_n(x) - h(x)|$ for $x \in (x_{l-1}, x_l)$ as well as $x = x_i$, hence

$$\|\tilde{\varphi}_n - h\|_{\infty} \le \underbrace{\|\varphi_n - h\|_{\infty}}_{\to 0 \text{ for } n \to \infty}$$

Hence $\|\tilde{\varphi}_n - h\|_{\infty} \to 0$ for $n \to \infty$, hence $\tilde{\varphi}_n$ converges uniformly to h. There exists

$$\int_{a}^{b} h \, dx = \lim_{n \to \infty} \int_{a}^{b} \underbrace{\tilde{\varphi}_{n}}_{\geq 0} \, dx \geq 0$$

Monotonicity: Let $f \le g$ in [a,b], hence $h = g - f \ge 0$ in [a,b]

$$\implies 0 \le \int_{a}^{b} h \, dx = \int_{a}^{b} g \, dx - \int_{a}^{b} f \, dx$$

$$\implies \int_{a}^{b} f \, dx \le \int_{a}^{b} g \, dx$$

And finally, boundedness is left.

Consider $|f| \in \mathbb{R}[a,b]$. Proving this is left as an exercise. $f \leq |f|$ in $[a,b] \implies \int_a^b f \, dx \leq \int_a^b |f| \, dx$.

TODO

$$-f \le \left| f \right| \text{ in } [a,b] \implies \int_a^b (-f) \, dx = -\int_a^b f \, dx \le \int_a^b \left| f \right| \, dx \implies \left| \int_a^b f \, dx \right| \text{TODO}$$

Remark 5.1. $\mathcal{R}[a,b]$ *is a vector space.*

1. $f,g \in \mathbb{R}[a,b] \implies \lambda f + \mu g \in \mathcal{R}[a,b]$. $\|\cdot\|_{\infty}$ is a norm on $\mathcal{R}[a,b]$. $(\mathcal{R}[a,b],\|\cdot\|_{\infty})$ is a normed vector space. Subspace of $(\mathcal{B}[a,b],\|\cdot\|_{\infty})$. We will show in the practicals that $(\mathcal{R}[a,b],\|\cdot\|_{\infty})$ is complete.

Theorem 5.2 (Mean value theorem of integration calculus). *Let f be continuous* on [a,b] and $p \in \mathcal{R}[a,b]$ and $p \geq 0$ in [a,b]. Then $f \cdot p \in \mathcal{R}[a,b]$ and there exists $\xi \in [a,b]$ such that

$$\int_{a}^{b} f \cdot p \, dx = f(\xi) \cdot \int_{a}^{b} p \, dx$$

Proof. Let $m = \min\{f(z) : z \in [a, b]\}$ (exists because f is continuous and [a, b] is compact).

$$M = \max\{f(z) : z \in [a, b]\}$$

f([a,b]) = [m,M] (by the mean value theorem)

It holds that

$$m \cdot \underbrace{p(x)}_{\geq 0} \leq f(x) \cdot p(x) \leq M \cdot p(x)$$

By monotonicity,

$$m\int_{a}^{b} p(x) dx \le \int_{a}^{b} f p dx \le M \int_{a}^{b} p dx$$

Therefore, there exists $\eta \in [m, M]$.

$$\eta \cdot \int_a^b p(x) \, dx = \int_a^b f p \, dx$$

Mean value theorem: For $\eta \in [m, M]$ there exists $\xi \in [a, b]$ such that

$$\eta = f(\xi)$$
 (f is continuous!)

Hence,

$$f(\xi) \int_{a}^{b} p \, dx = \int_{a}^{b} f \cdot p \, dx$$

 $f \cdot p$ is regulated function (over one-sided limits).

Lemma 5.1. Let $f \in \mathcal{R}[a, b]$ and $a \le \alpha < \beta < \gamma \le b$. Then

$$f|_{[\alpha,\beta]} \in \mathcal{R}[\alpha,\beta], f|_{\beta,\gamma} \in \mathcal{R}[\beta,\gamma]$$

 $f|_{[\alpha,\gamma]} \in \mathcal{R}[\alpha,\gamma]$ (immediate over onesided limit)

and it holds that

$$\int_{\alpha}^{\gamma} f \, dx = \int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\gamma} f \, dx$$

Compare with Figure 9.

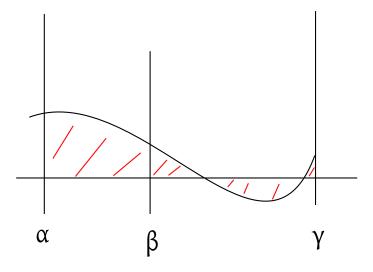


Figure 9: Positive and negative area covered by the integral

Proof. Show that this statement holds for $\varphi \in \tau[a,b]$. Without loss of generality, $\alpha = a, \gamma = b$.

$$\gamma = \sum_{j=1}^{m} c_j \chi_{(x_{j-1}, x_j)} + \sum_{j=0}^{m} \underbrace{0}_{\text{it does not matter for the integral}} \cdot \chi_{x_j}$$

Case 1 $\beta = x_l$ for some $l \in \{1, ..., m - 1\}$

$$\int_{\alpha}^{\gamma} \varphi \, dx = \sum_{j=1}^{m} c_j(x_j - x_{j-1})$$

$$\int_{\alpha}^{\beta} \varphi \, dx = \int_{\alpha}^{x_l} \varphi \, dx = \sum_{j=1}^{l} c_j(x_j - x_{j-1})$$

$$\int_{\beta}^{\gamma} \varphi \, dx = \int_{x_l}^{\gamma} \varphi \, dx = \sum_{i=l+1}^{m} c_j(x_j - x_{j-1})$$

And now,

$$\sum_{j=l+1}^{m} c_j(x_j - x_{j-1}) + \sum_{j=1}^{l} c_j(x_j - x_{j-1}) = \sum_{j=1}^{m} c_j(x_j - x_{j-1})$$

Case 2 $\beta \in (x_{l-1}, x_l)$ for some $l \in \{1, ..., m\}$.

$$\int_{\beta}^{\gamma} \varphi \, dx = c_{l}(x_{l} - \beta) + \sum_{j=l+1}^{m} c_{j}(x_{j} - x_{j-1})$$

$$\int_{\alpha}^{\beta} \varphi \, dx + \int_{\beta}^{\gamma} \varphi \, dx = \sum_{j=1}^{l-1} c_{j}(x_{j} - x_{j-1})$$

$$+c_{l}(\beta - x_{l-1}) + c_{l}(x_{l} - \beta) + \sum_{j=l+1}^{m} c_{j}(x_{j} - x_{j-1})$$

$$= \sum_{j=1}^{m} c_{j}(x_{j} - x_{j-1}) = \int_{\alpha}^{\gamma} \varphi \, dx$$

TODO verify previous lines Let $\varphi_n \in \tau[\alpha, \beta]$ with $\varphi_n \to f$ uniform on $[\alpha, \beta] \implies \varphi_n|_{[\alpha, \beta]} \to f|_{[\alpha, \beta]}$ uniform on $[\alpha, \beta]$ and also $\varphi_n|_{[\beta, \gamma]} \to f|_{[\beta, \gamma]}$ uniform on $[\beta, \gamma]$.

$$\int_{\alpha}^{\gamma} f \, dx = \lim_{n \to \infty} \int_{\alpha}^{\gamma} \varphi_n \, dx = \lim_{n \to \infty} \left(\int_{\alpha}^{\beta} \varphi_n \, dx + \int_{\beta}^{\gamma} \varphi_n \, dx \right)$$

$$= \lim_{n \to \infty} \int_{\alpha}^{\beta} \varphi_n \, dx + \lim_{n \to \infty} \int_{\beta}^{\gamma} \varphi_n \, dx$$
exists because $\varphi_n|_{[\alpha,\beta]} \to f|_{[\alpha,\beta]}$ uniform
$$= \int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\gamma} f \, dx$$

Remark 5.2 (Notation). Let $\alpha < \beta$, α , $\beta \in [a,b]$ and $f \in \mathcal{R}[a,b]$. We let

$$\int_{\beta}^{\alpha} f \, dx \coloneqq -\int_{\alpha}^{\beta} f \, dx$$

By this convention, it holds that

$$\int_{\alpha}^{\alpha} f \, dx = -\int_{\alpha}^{\alpha} f \, dx \implies \int_{\alpha}^{\alpha} f \, dx = 0$$

Lemma 5.2. Let $f \in \mathcal{R}[a,b]$ and $\alpha, \beta, \gamma \in [a,b]$ (without particular order). Then it holds that

$$\int_{\alpha}^{\gamma} f \, dx = \int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\gamma} f \, dx$$

Proof. Special case: 2 points are equal

$$\alpha = \gamma \implies \int_{a}^{\alpha} f \, dx = 0$$

$$\int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\alpha} f \, dx = \int_{\alpha}^{\beta} f \, dx - \int_{\alpha}^{\beta} f \, dx = 0$$

$$\beta = \gamma \qquad \beta = \alpha$$

Case: $\alpha < \beta < \gamma$ follows immediately

And just as a representative other case: $\alpha < \gamma < \beta$

$$\int_{\alpha}^{\beta} f \, dx = \int_{\alpha}^{\gamma} f \, dx + \int_{\gamma}^{\beta} f \, dx$$
by Lemma 2.1
$$-\int_{\beta}^{\gamma} f \, dx$$

$$\int_{\alpha}^{\beta} f \, dx + \int_{\beta}^{\gamma} f \, dx = \int_{\alpha}^{\gamma} f \, dx$$

This lecture took place on 2018/04/17.

Lemma 5.3. Let $f \in \mathcal{R}[a,b]$. Then there exists an at most countable set $A \subseteq [a,b]$ such that f is continuous in every point $x \in [a,b] \setminus A$.

Proof. Let $f \in \mathcal{R}[a,b]$ and $(\varphi_n)_{n \in \mathbb{N}}$ with $\varphi_n \in \tau[a,b]$ and $\varphi \to f$ converging uniformly on [a,b].

$$\varphi_n = \sum_{j=1}^{m_n} c_j^n \chi_{(X_{j-1}^n, X_j^n)} + \sum_{j=0}^{m_n} d_j^n \chi_{\{x_j^n\}}$$

$$x_0^n = a < x_1^n < \ldots < x_{m_n}^n = b$$

are separating points for φ_n

$$A = \{X_j^n : n \in \mathbb{N}, j \in \{0, \dots, m_n\}\}$$

A is a countable union of finite sets $A_n = \{x_0^n, x_{m_n}^n\}$. A is countable (as unions of finite sets are).

Now we show: f is continuous in every point $x \in [a,b]: x \notin A$. Let $\varepsilon > 0$ be arbitrary. Choose $N \in \mathbb{N}$ sufficiently large such that $\|\varphi_N - f\|_{\infty} < \frac{\varepsilon}{2}$. Because $x \in A$, there exists $j \in \{1, \ldots, m_N\}$ such that $x \in (x_{j-1}^N, X_j^N)$ is open. Choose $\delta > 0$

such that $(x - \delta, x + \delta) \subset (x_{j-1}^N, x_j^n)$, hence $\forall \xi \in (x - \delta, x + \delta)$ it holds that $\varphi_N(\xi) = c_j^N$. Now consider $\xi \in (x - \delta, x + \delta)$, hence $|\xi - x| < \delta$. Then it holds that

$$|f(\xi) - f(x)| = \left| f(\xi) - \underbrace{\varphi_N(x)}_{c_j^N = \varphi_N(\xi)} + \varphi_N(x) - f(x) \right|$$

$$\leq \underbrace{\left| f(\xi) - \varphi_N(\xi) \right|}_{\leq \left\| f - \varphi_N \right\|_{\infty}} + \underbrace{\left| \varphi_N(x) - f(x) \right|}_{\leq \left\| \varphi_N - f \right\|_{\infty}} < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon$$

Hence f is continuous in x.

Remark 5.3 (Notation). Let $f \in \mathcal{R}[a,b]$. For $x \in [a,b)$, there exists $f_+(x) := \lim_{\xi \to x_+} f(\xi)$. For $x \in (a,b]$, there exists $f_-(x) := \lim_{\xi \to x_-} f(\xi)$. Because of Lemma 5.3, it holds that $f_+(x) = f_-(x) = f(x)$ for all $x \in [a,b] \setminus A$ and A is at most countable.

Definition 5.2 (One-sided derivatives). *Let* $g : [a, b] \to \mathbb{R}$ *and* $x \in [a, b)$. *We say* g *has the* right-sided derivative $g'_+(x)$ *if*

$$\lim_{\xi \to x_+} \frac{g(\xi) - g(x)}{\xi - x} =: g'_+(x)$$

exists. Analogously we define the left-sided derivative

$$g'_{-}(x) = \lim_{\xi \to x_{-}} \frac{g(\xi) - g(x)}{\xi - x}$$

for $x \in (a, b]$. Compare with Figure 10.

Remark 5.4. If g in x has a one-sided derivative, then it holds that

$$\lim_{\xi \to x_+} (g(\xi) - g(x)) = 0$$

Hence g is continuous in x.

Remark 5.5. $g:[a,b] \to \mathbb{R}$ is differentiable in point $x \in (a,b)$ with derivative $g'(x) \iff g$ has a left- and right-sided derivative in x and it holds that $g'_{-}(x) = g'_{+}(x)$ (=g'(x)).

Theorem 5.3 (Fundamental theorem of differential/integration calculus, variation 1). *Isaac Barrow* (1630–1677), *Isaac Newton* (1642–1726), *Gottfried Wilhelm von Leibniz* (1646–1716).

Let $f \in \mathcal{R}[a,b]$, $\alpha \in [a,b]$ and we define

$$F(x) = \int_{\alpha}^{x} f \, d\xi$$

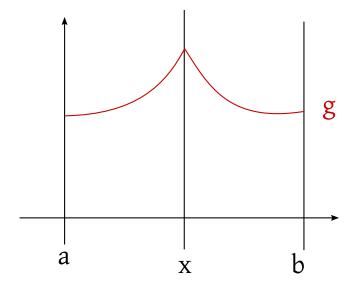


Figure 10: In this example, the left- and right-sided derivatives are not equal. $f'_+(x) \neq f'_-(x)$

Then F is right-sided differentiable in every point $x \in [a,b)$ and in every $x \in (a,b]$ left-sided differentiable. Furthermore it holds that

$$F'_{+}(x) = f_{+}(x) \forall x \in [a, b)$$
(2)

$$F'_{-}(x) = f_{-}(x) \forall x \in (a, b]$$
 (3)

Remark 5.6.

$$\frac{d}{dx}\left(\int_{\alpha}^{x} f \, d\xi\right) = f(x)$$

for all x such that f is continuous in x. For those x, F'(x) is differentiable in x with F'(x) = f(x).

Definition 5.3. Let $f \in \mathcal{R}[a,b]$ and $\varphi : [a,b] \to \mathbb{R}$ such that φ is one-sided differentiable on [a,b]. If $\Phi'_+(x) = f_+(x) \forall x \in [a,b)$ and $\Phi'_-(x) = f_-(x) \forall x \in (a,b]$ then we call Φ an antiderivative of regulated function f.

Proof of the Theorem 5.3. Let $x_1, x_2 \in [a, b]$ be arbitrary. Let F be defined as above. Then it holds that

$$|F(x_2) - F(x_1)| = \left| \int_{\alpha}^{x_2} f \, d\xi - \int_{\alpha}^{x_1} f \, d\xi \right|$$

$$= \left| \int_{\alpha}^{x_2} f \, d\xi + \int_{x_1}^{\alpha} f \, d\xi \right| = \left| \int_{x_1}^{x_2} f \, d\xi \right|$$

$$\leq \int_{x_1}^{x_2} |f| \, d\xi \leq \int_{x_1}^{x_2} \frac{\|f\|_{\infty}}{d\xi} \, d\xi = \|f\|_{\infty} \cdot |x_2 - x_1|$$

Hence *F* is Lipschitz continuous with Lipschitz constant $||f||_{\infty}$. So *F* is continuous in [*a*, *b*].

One-sided derivatives: Let $x \in [a, b)$ and $\varepsilon > 0$ be arbitrary. Choose $\delta > 0$ such that $\forall \xi \in [x, x + \delta)$ it holds that $|f(\xi) - f_+(x)| < \varepsilon$. For $\xi \in (x, x + \delta)$ it holds that

$$\left|\frac{F(\xi) - F(x)}{\xi - x} - f_{+}(x)\right| = \frac{1}{|\xi - x|} \underbrace{\int_{x}^{\xi} f \, dy - \underbrace{f_{+}(x)(\xi - x)}_{\text{const.}}}_{F(\xi) - F(x)} = \frac{1}{|\xi - x|} \left|\int_{x}^{\xi} (f - f_{+}(x)) \, dy\right| \le \frac{1}{|\xi - x|} \int_{x}^{\xi} \underbrace{\left|f(y) - f_{+}(x)\right|}_{<\varepsilon} \, dy$$

$$y \in (x, \xi) \subseteq (x, x + \delta)$$

$$< \frac{1}{\xi - x} \varepsilon \cdot \underbrace{\int_{x}^{\xi} 1 \, dy}_{|\xi - x|} = \varepsilon$$

Hence, $F'_{+}(x) = f_{+}(x)$. Analogously, $F'_{-}(x) = f_{-}(x)$ for $x \in (a, b]$.

Theorem 5.4 (Fundamental theorem of differential/integration calculus, variation 2). Let $f \in \mathcal{R}[a,b]$ and ϕ is an arbitrary antiderviative of f according to Definition 5.3. For $\alpha, \beta \in [a,b]$ arbitrary, it holds that

$$\int_{\alpha}^{\beta} f \, dx = \phi(\beta) - \phi(\alpha)$$

Remark 5.7. Let f be continuous and ϕ be an antiderivative of f. Hence, $\Phi'(x) = f(x) \forall x \in [a,b]$. Then it holds that

$$\int_{\alpha}^{\beta} \Phi' \, dx = \Phi(\beta) - \Phi(\alpha)$$

"Integral of a derivative of Φ gives $\Phi(\beta) - \Phi(\alpha)$ ".

Lemma 5.4. Let $A \subseteq [a,b]$ countable. $f:[a,b] \to \mathbb{R}$ is continuous and f is differentiable in every point $x \in [a,b] \setminus A$. Furthermore let $|f'(x)| \le L$ $(L \ge 0)$ for all $x \in [a,b] \setminus A$. Then f is Lipschitz continuous on [a,b] with constant L, hence

$$|f(x_2) - f(x_1)| \le L|x_2 - x_1| \, \forall x_1, x_2 \in [a, b]$$

Remark 5.8. Some people call it differentiable almost everywhere, but this expression collides with a different definition pronounced the same way from measure theory.

Proof. Let $x_1, x_2 \in [a, b]$, wlog. $x_1 < x_2$. Let $\varepsilon > 0$ be arbitrary. We define

$$F_{\varepsilon}(x) = |f(x) - f(x_1)| - (L + \varepsilon)(x - x_1)$$

for $x \in [x_1, b]$.

Let $\varepsilon > 0$ be arbitrary. We prove: $F_{\varepsilon}(x) \le 0 \forall x \in [x_1, b]$. In particular: $F_{\varepsilon}(x_2) \le 0$. Hence,

$$\left| f(x_2) - f(x_1) \right| \le (L + \varepsilon) \underbrace{(x_2 - x_1)}_{|x_2 - x_1|}$$

We prove by contradiction: Assume there exists $\varepsilon > 0$ and $x_{\varepsilon} > x_1$ such that $F_{\varepsilon}(x_{\varepsilon}) > 0$.

We recognize: Let $A' = [x_1, b] \cap A$ be countable.

- 1. hence $F_{\varepsilon}(A') \subseteq \mathbb{R}$ is countable
- 2. $F_{\varepsilon}(x_1) = 0$, $F_{\varepsilon}(x_{\varepsilon}) > 0 \implies x_{\varepsilon} > x_1$
- 3. F_{ε} is continuous on $[x_1, b]$. It holds that $0 \in F_{\varepsilon}([x_1, x_{\varepsilon}])$ and because $0 = F_{\varepsilon}(x_1)$ and $\varepsilon \in F_{\varepsilon}([x_1, x_{\varepsilon}])$ because $\varepsilon = F_{\varepsilon}(x_{\varepsilon})$.

By the Intermediate Value Theorem, it follows that $[0, \varepsilon] \subseteq \text{TODO}$ By the Intermediate Value Theorem, it follows that $[0, \eta] \subseteq F_{\varepsilon}([x_1, x_{\varepsilon}])$.

ıncountable

 $F_{\varepsilon}(A')$ is countable, hence there exists $\gamma \in (0, \eta]$ such that $\gamma = F_{\varepsilon}(y)$ and $\gamma \notin A'$ $(\gamma > 0)^2$. Hence, $y \notin A'$. So f in y is differentiable. Let $B := F_{\varepsilon}^{-1}(\{\gamma\}) \cap ([x_1, x_{\varepsilon}] \setminus A')$. Then $B \neq \emptyset$.

 $B \subseteq [x_1, x_{\varepsilon}]$ is therefore bounded, $B \ne 0$. Hence, B has a supremum. Let $x = \sup B$. Choose $(y_n)_{n \in \mathbb{N}}$ with $y_n \in B$ and $y_n \to x$ for $n \to \infty$. Because F_{ε} is continuous, it holds that

$$\lim_{n\to\infty} F_{\varepsilon}(y_n) = F_{\varepsilon}(x)$$

hence $F_{\varepsilon}(x) = \gamma$. This implies $x \notin A$.

Furthermore it holds for $w \in (x, x_{\varepsilon}]$ that $F_{\varepsilon}(w) > \gamma$. Because assume the opposite $(F_{\varepsilon}(w) \le \gamma \text{ for } w > x)$. Furthermore it holds that $F_{\varepsilon}(x_{\varepsilon}) = \eta \ge \gamma$. Because of the Intermediate Value Theorem, $\exists y \ge w$ with $F_{\varepsilon}(y) = \gamma$. This contradicts with the supremum property of x.

²remember this as reference (*)

Now let $y \in (x, x_{\varepsilon}]$.

$$\varphi(y) = \frac{F_{\varepsilon}(y) - F_{\varepsilon}(x)}{y - x}$$

$$= \frac{\left| f(y) - f(x_1) \right| - \left| f(x) - f(x_1) \right|}{y - x} - \frac{(L + \varepsilon)(y - x_1 - x + x_1)}{y - x}$$

$$\leq \frac{f(y) - f(x)}{y - x} - (L + \varepsilon)$$
inversed triangle ineq.

Because $F_{\varepsilon}(y) > \gamma = F_{\varepsilon}(x)$ it holds that $\varphi(y) > 0$ for y > x. So,

$$\frac{\left|f(y) - f(x)\right|}{y - x} \ge L + \varepsilon$$

$$|f'(x)| = \lim_{y \to x_+} \left| \frac{f(y) - f(x)}{y - x} \right| \ge L + \varepsilon$$

This contradicts with the boundedness of the derivative by L and f is in $x \notin A$ differentiable.

So, equations 2 do not hold. Therefore $\forall x_1, x_2 \text{ with } x_1 < x_2 \text{ in } [a, b] \text{ and } \forall \varepsilon > 0$,

$$\left| f(x_2) - f(x_1) \right| \le (L + \varepsilon) |x_2 - x_1|$$

$$\implies \left| f(x_2) - f(x_1) \right| \le L |x_2 - x_1|$$

Corollary (Corollary to Lemma 5.4). Let $f,g:[a,b] \to \mathbb{R}$ differentiable for all points $x \in [a,b] \setminus A$ and A is countable. Furthermore let $f'(x) = g'(x) \forall x \notin A$. Then there exists $K \in \mathbb{R}$ such that $f(x) = g(x) + K \forall x \in [a,b]$.

Proof. Let h = f - g. Then it holds that

$$h'(x) = f'(x) - g'(x) = 0 \forall x \in [a, b] \setminus A$$

By Lemma 5.4 with L = 0, it follows that

$$|h(x_1) - f(x_2)| \le 0 \cdot |x_1 - x_2| = 0$$

$$\implies h(x_1) = h(x_2) \forall x_1, x_2 \in [a, b]$$

Hence, $h(x) = K \in \mathbb{R}$.

$$\implies f(x) = g(x) + h(x) = g(x) + K$$

This lecture took place on 2018/04/19.

By reference (*), $\gamma \in [0, \eta)$ (uncountable) and $\gamma \notin f(A)$ (countable).

$$\implies \forall u \in [x_1, b) \text{ with } F_{\varepsilon}(u) = \gamma$$

it holds that $u \notin A$, hence f is differentiable in u.

Proof of Theorem 5.4. Let $f \in \mathcal{R}[a,b]$, ϕ is an antiderivative of f, hence $\phi'_+ = f_+$, $\phi'_- = f_-$. Let $\alpha \in [a,b]$ be arbitrary. By the Theorem variant 1, $F(x) = \int_{\alpha}^{x} f \, d\xi$ is also an antiderivative of f. By Lemma ??, $\exists K \in \mathbb{R} : F(x) = \int_{\alpha}^{x} f \, d\xi = \phi(x) + K$. Determine K: Let $x = \alpha \implies F(\alpha) = \int_{\alpha}^{\alpha} f \, dx = 0 = \phi(\alpha) - K$ hence $K = \phi(\alpha)$. Hence,

$$\int_{\alpha}^{x} f \, d\xi = \phi(x) - \phi(\alpha)$$

Let $x = \beta$.

Remark 5.9 (Remark for the previous corollary). F, ϕ are differentiable on all points x for which f is continuous (all of them except for countable many). For those x, it holds that $F'(x) = \varphi'(x) = f(x)$.

Remark 5.10 (Notation). *Let* $f \in \mathcal{R}[a,b]$. *Then*

$$\int f \, dx$$

- is some particular antiderivative of f (usually some arbitrary chosen)
- the set of all antiderivatives of f

$$\int f \, dx = \{F : F \text{ is antiderivative of } f\}$$

If F_0 *is some fixed antiderivative, then*

$$\int f \, dx = \{ F_0 + K : K \in \mathbb{R} \}$$

Then $\int f dx$ *is the so-called* indefinite integral of f. *Notation:*

$$\int x^k dx = \frac{x^{k+1}}{k+1} + c \qquad (k \neq -1)$$

f	F	remark
χ^{α}	$\frac{x^{\alpha+1}}{\alpha+1}+c$	$\alpha \in \mathbb{R} \setminus \{-1\}$; restrict x such that x^{α} and $x^{\alpha+1}$ are defined
x^{-1}	$\ln x + c (x > 0)$	
$\left(\frac{1}{-x}\right) \cdot (-1) = x^{-1}$ e^x	$ \ln -x + c (x < 0) $	
e^{x}	e^x	
$\sin x$	$-\cos x$	
$\cos x$	$\sin x$	
$\sinh x$	cosh x	
$\cosh x$	sinh x	
$ \begin{array}{c} \frac{1}{1+x^2} \\ 1 \end{array} $	arctan x	
$\frac{1}{\sqrt{1-x^2}}$	arcsin x	x < 1
$-\frac{1}{\sqrt{1-x^2}}$	arccos x	

Table 1: Table of antiderivatives

5.1 Integration methods

In this chapter, we discuss how to determine the antiderivative of a function. Usually they are composites of basic functions. Some of these are given in Table 1.

Remark 5.11. Let $F,G:[a,b] \to \mathbb{R}$ in $x \in [a,b)$ right-sided differentiable. Then also $F \cdot G$ in x is right-sided differentiable and it holds that

$$(F \cdot G)'_{+}(x) = F'_{+}(x) \cdot G(x) + F(x) \cdot G'_{+}(x)$$

hence the product law holds.

Analogously, the same holds for the left-sided derivative.

Look up the proof in the course Analysis 1.

5.1.1 Partial integration

Definition 5.4 (Partial integration). *Let* f, g *be given. Let* F, G *be its antiderivatives respectively. Then* $F \cdot G$ *is an antiderivative of* $F \cdot g + f \cdot G$.

This is immediate, because

$$(F \cdot G)'_{+} = F'_{+} \cdot G + F \cdot G'_{+} = f_{+} \cdot G + F \cdot g_{+} = f_{+}G_{+} + F_{+} \cdot g_{+}$$

Hence, it holds that

$$\int_{a}^{b} (Fg + fG) dx = \underbrace{F(b) \cdot G(b) - F(a)G(a)}_{=:F \cdot G_{a}^{b}}$$

Usually, this is rewritten as

$$\int_{a}^{b} F \cdot g \, dx = F \cdot G|_{a}^{b} - \int_{a}^{b} fG \, dx$$

If F = u is continuously differentiable and G = v as well, then f = u' and g = v' and the law has the structure

$$\int_a^b uv' \, dx = u \cdot v|_a^b - \int_a^b u'v \, dx$$

Example 5.1. Let $a \neq -1$ and x > 0.

$$\int \underbrace{x^{a}}_{v'} \cdot \underbrace{\ln x}_{u} dx = \underbrace{\begin{vmatrix} u = \ln x & u' = \frac{1}{x} \\ v' = x^{\alpha} & v = \frac{x^{\alpha+1}}{\alpha+1} \end{vmatrix}}_{\text{scribble notes}} \underbrace{\frac{x^{\alpha+1}}{\alpha+1} \cdot \ln x - \int \frac{1}{x} \cdot \frac{x^{\alpha+1}}{\alpha+1} dx}_{\text{scribble notes}}$$

$$=\frac{x^{\alpha+1}}{\alpha+1}\cdot \ln x - \frac{1}{\alpha+1}\int x^{\alpha}\,dx = \frac{x^{\alpha+1}}{\alpha+1}\cdot \ln x - \frac{1}{(\alpha+1)^2}x^{\alpha+1}$$

Example 5.2. *Let* $k \in \{2, 3, 4, ...\}$.

$$\int \cos^{k}(x) dx = \begin{vmatrix} u = \cos^{k-1}(x) & u' = (k-1) \cdot \cos^{k-2}(x) \cdot (-\sin x) \\ v' = \cos x & v = \sin x \end{vmatrix}$$
$$\cos^{k-1}(x) \sin x + (k-1) \int \cos^{k-2}(x) \cdot \underbrace{\sin^{2}(x)}_{(1-\cos^{2}x)} dx$$
$$= \cos^{k-1}(x) \cdot \sin(x) + (k-1) \int \cos^{k-2}(x) dx - (k-1) \int \cos^{k}(x) dx$$

Then we can use the following identity:

$$k \int \cos^{k}(x) \, dx = \cos^{k-1}(x) \cdot \sin(x) + (k-1) \int \cos^{k-2}(x) \, dx$$

This gives a recursive formula:

$$\int \cos^k(x) \, dx = \frac{1}{k} \cos^{k-1}(x) \cdot \frac{k-1}{k} \sin(x) + (k-1) \int \cos^{k-2}(x) \, dx$$

Analogously,

$$\int \sin^k(x) \, dx = -\frac{1}{k} \sin^{k-1}(x) \cdot \cos(x) + \frac{k-1}{k} \int \sin^{k-2}(x) \, dx$$

Let $c_m = \int_0^{\frac{\pi}{2}} \cos^m(x) dx$. Then the following formula holds:

$$c_{2n} = \frac{2n-1}{2n} \cdot \frac{2n-3}{2n-2} \cdot \frac{2n-5}{2n-4} \dots \frac{1}{2} \cdot \frac{\pi}{2}$$
$$= \prod_{k=1}^{n} \frac{2k-1}{2k} \cdot \frac{\pi}{2}$$
$$c_{2n+1} = \prod_{k=1}^{n} \frac{2k}{2k+1}$$

Proof by induction. Let n = 1.

$$c_{2} = \int_{0}^{\frac{\pi}{2}} \cos^{2} x \, dx = \frac{1}{2} \cos x \sin x \Big|_{0}^{\frac{\pi}{2}} + \frac{1}{2} \int_{0}^{\frac{\pi}{2}} 1 \, dx = 0 - 0 + \frac{\pi}{4}$$

$$= \prod_{k=1}^{1} \frac{2k-1}{2k} \cdot \frac{\pi}{2}$$

$$c_{1} = \int_{0}^{\frac{\pi}{2}} \cos x \, dx = \sin x \Big|_{0}^{\frac{\pi}{2}} = 1 - 0 = 1$$

$$\prod_{k=1}^{0} \frac{2k}{2k+1} = 1$$
empty product

We make the induction step $n \rightarrow n + 1$:

$$c_{2(n+1)} = \frac{1}{2n+2} \cdot \underbrace{\cos^{2n+1}(x)}_{=0 \text{ for } x = \frac{\pi}{2}} \cdot \underbrace{\sin(x)}_{=0 \text{ for } x = 0} \Big|_{0}^{\frac{\pi}{2}} + \frac{2n+1}{2n+2} \int_{0}^{\frac{\pi}{2}} \cos^{2n}(x) dx$$
$$= \frac{2n+1}{2n+2} \prod_{k=1}^{n} \frac{2k-1}{2k} \cdot \frac{\pi}{2} = \prod_{k=1}^{n+1} \frac{2k-1}{2k} \cdot \frac{\pi}{2}$$

 $c_{2(n+1)+1}$ analogously.

Theorem 5.5 (Wallis product). *John Wallis* (1616–1703), result from 1655 Let $w_n = \prod_{k=1}^n \frac{(2k)^2}{(2k-1)(2k+1)} = \frac{2\cdot 2}{1\cdot 3} \cdot \frac{4\cdot 4}{3\cdot 5} \dots$ Then it holds that $\lim_{n\to\infty} w_n = \frac{\pi}{2}$.

Proof.

$$\frac{\pi}{2} \cdot \frac{c_{2n+1}}{c_{2n}} = \frac{\pi}{2} \cdot \prod_{k=1}^{n} \frac{\frac{2k}{2k+1}}{\prod_{k=1}^{n} \frac{2k-1}{2k} \cdot \frac{\pi}{2}} = \prod_{k=1}^{n} \frac{(2k)^{2}}{(2k-1)(2k+1)} = w_{n}$$

It remains to show that $\lim_{n\to\infty} \frac{c_{2n+1}}{c_{2n}} = 1$ in $[0, \frac{\pi}{2}]$ it holds that $0 \le \cos x \le 1$.

$$\implies \cos^{2n+2}(x) \le \cos^{2n+1}(x) \le \cos^{2n}(x)$$

So, $c_{2n+2} \le c_{2n+1} \le c_{2n}$ for $n \ge 1$.

$$1 \ge \frac{c_{2n+1}}{c_{2n}}$$

$$\implies 1 \ge \frac{c_{2n+1}}{c_{2n}} \ge \frac{c_{2n+2}}{c_{2n}} = \frac{\prod_{k=1}^{n+1} \frac{2k-1}{2k} \frac{\pi}{2}}{\prod_{k=1}^{n} \frac{2k-1}{2k} \frac{\pi}{2}}$$

$$= \frac{2n+2-1}{2n+2} \to 1 \text{ for } n \to \infty$$

Because of the sandwich lemma for convergent sequences, the intermediate expression must also converge to 1, hence

$$\lim_{n \to \infty} \frac{c_{2n+1}}{c_{2n}} = 1 \qquad \wedge \qquad \frac{\pi}{2} \cdot \lim_{n \to \infty} \frac{c_{2n+1}}{c_{2n}} = \lim_{n \to \infty} w_n$$

5.1.2 Integration by substitution

Definition 5.5 (Integration by substitution). Let $f:[a,b] \to \mathbb{R}$ be continuous. Let $t:[\alpha,\beta] \to [a,b]$ be continuously differentiable. Let F be an antiderivative of f (F is therefore continuously differentiable). Then $F \circ t: [\alpha,\beta] \to \mathbb{R}$ is also continuously differentiable and the chain rule holds:

$$(F \circ t)' = (F' \circ t) \cdot t' = (f \circ t) \cdot t'$$

Hence $F \circ t$ is an antiderivative of $(f \circ t) \cdot t'$. We apply it to integration:

$$\int_{\alpha}^{\beta} (f \circ t)(u) \cdot t'(u) \, du = (F \circ t)(\beta) - (F \circ t)(\alpha) = F(t(\beta)) - F(t(\alpha)) = \int_{t(\alpha)}^{t(\beta)} f(x) \, dx$$

Then we get the substitution integration method:

$$\int_{t(\alpha)}^{t(\beta)} f(x) \, dx = \int_{\alpha}^{\beta} f(t(u)) \cdot t'(u) \, du$$

Remark 5.12 (Mnemonic). Consider the left-hand side and right-hand side simultaneously. Let x = t(u) (expressions inside parentheses). Then $dx = t'(u) \cdot du$ (expressions on the right). Let $u = \alpha \implies x = t(\alpha)$ and $u = \beta \implies x = t(\beta)$ (interval boundaries).

Example 5.3.

$$\int_0^1 2x \sqrt{1-x^2} \, dx$$

Usually we have some expression, we want to substitute with u.

$$1 - x^{2} = u \qquad x = \sqrt{1 - u} = t(u)$$

$$x = 0 = t(1) \qquad x = 1 = t(0)$$

$$dx = \frac{1}{2} \cdot \frac{1}{\sqrt{1 - u}} \cdot (-1) du$$

$$\int_{0}^{1} 2x \sqrt{1 - x^{2}} dx = \int_{1}^{0} 2 \cdot \sqrt{1 - u} \cdot u \cdot \frac{1}{2} (-1) \frac{1}{\sqrt{1 - u}} du = \int_{0}^{1} \sqrt{u} du = \frac{u^{\frac{3}{2}}}{\frac{3}{2}} \Big|_{0}^{1} = \frac{2}{3}$$

$$\int_{0}^{1} 2x \sqrt{\frac{1-x^{2}}{u}} dx = \begin{vmatrix} u = 1 - x^{2} \\ x = 0 & \Leftrightarrow u = 1 \\ x = 1 & \Leftrightarrow xu = 0 \\ 1 \cdot du & = -2x dx \end{vmatrix} = -\int_{1}^{0} \sqrt{u} \, du = \int_{0}^{1} \sqrt{u} \, du$$

In general: we set h(u) = g(x), then it holds that h'(u) du = g'(x) dx.

Theorem 5.6. Let $f, \tilde{f} \in \mathcal{R}[a,b]$ and $A \subseteq [a,b]$ countable. Furthermore $f(x) = \tilde{f}(x) \forall x \in [a,b] \setminus A$. Then it holds that

$$\int_{a}^{b} \left| f - \tilde{f} \right| \, dx = 0$$

Then it follows especially that

$$\int_{a}^{b} f \, dx = \int_{a}^{b} \tilde{f} \, dx$$

This lecture took place on 2018/04/24.

Proof. Show: $r \in \mathcal{R}[a,b], r \ge 0$. $\int_a^b r \, dx = 0$ and r(x) = 0 for $x \in [a,b] \setminus A$. Then it holds that $\int_a^b r \, dx = 0$. Let r be as above. First, we show: $r_+(x) = \lim_{\xi \to x_+} r(\xi) = 0 \forall x \in [a,b)$ and also $r_-(x) = 0 \forall x \in [a,b]$.

Proof of that: Let $x \in [a,b)$ and $y = r_+(x)$ (exists because $r \in \mathcal{R}[a,b]$). Choose $\delta_n = \frac{1}{n}$. $(x, x + \frac{1}{n}) \cap [a,b)$ is an open interval with uncountable many points, so

there is certainly one point in A. So there exists $\xi_n \in ((x, x + \frac{1}{n}) \cap [a, b)) \setminus A$ and $|\xi_n - x| < \delta_n = \frac{1}{n}$. Hence, $\lim_{n \to \infty} \xi_n = x$ and $r(\xi_n) = 0$. Therefore, $\lim_{n \to \infty} r(\xi_n) = 0$ where $r(\xi_n) = y = r_+(x)$.

Analogously, $r_{-}(x) = 0$ on (a, b].

Let $\varepsilon > 0$ be arbitrary. We let $A_{\varepsilon} = \{ w \in [a,b] | r(w) > \varepsilon \}$. We show: A_{ε} is finite.

Assume A_{ε} would have infinitely many points. Choose a sequence $(w_n)_{n\in\mathbb{N}}$ with $w_n \in A_{\varepsilon}$ and $w_n \neq w_m$ for $n \neq m$ (works because A_{ε} is infinite). $(w_n)_{n\in\mathbb{N}}$ is bounded, hence there exists a convergent subsequence $(w_{n_k})_{k\in\mathbb{N}}$ with $x = \lim_{k\to\infty} w_{n_k} \in [a,b]$ and $w_{n_k} \in [a,b]$.

Either (w_{n_k}) contains infinitely many sequence element $w_{n_k} < x$ (variant (a)) or infinitely many $w_{n_k} > x$ (variant (b)). Let variant b hold without loss of generality.

Combine all $w_{n_k} > x$ to one subsequence $(w_{n_{k_l}})_{l \in \mathbb{N}}$. This gives $\lim_{l \to \infty} w_{n_{k_l}} = x$ and $w_{n_{k_l}} > x$, thus $\lim_{l \to \infty} \underbrace{r(w_{n_{k_l}})}_{} = r_+(x) = 0$. This gives a contradiction.

$$\geq \varepsilon$$
 because $w_{n_{k_l}} \in A_{\varepsilon}$

 A_{ε} must be finite.

Consider

$$A_{\frac{1}{n}} = \left\{ w_1^n, \dots, w_{m_n}^n \right\}$$

finite. Let $\varphi_n = \sum_{k=1}^{m_n} r(w_k^n) \cdot \chi_{\{w_k^n\}} \in \tau[a, b]$.

For $x = w_k^n \in A_{\frac{1}{n}}$ it holds that

$$\varphi_n(w_k^n) = \sum_{k=1}^{m_n} r(w_k^n) \cdot \underbrace{\chi_{\{w_k^n\}}(w_j^n)}_{\delta_{ik}} = r(w_j^n)$$

so $|\varphi_n(x) - r(x)| = 0 \forall x \in A_{\frac{1}{n}}$. Let $x \in [a,b] \setminus A_{\frac{1}{n}}$. Then it holds $0 \le r(x) < \frac{1}{n}$ and for $x \notin A_{\frac{1}{n}}$ it holds that $\varphi(x) = 0$. Therefore,

$$\left| r(x) - \varphi(x) \right| = r(x) < \frac{1}{n}$$

hence $||r - \varphi_n||_{\infty} < \frac{1}{n}$. This means that $\varphi_n \to r$ uniformly on [a, b]. Therefore

$$\lim_{n \to \infty} \underbrace{\int_a^b \varphi_n \, dx}_{=0} = \int_a^b r \, dx = 0$$

Now we want to finish the proof of our theorem: Let $r(x) = |f(x) - \tilde{f}(x)| \ge 0$ and r(x) = 0 for $x \notin A$. So, $\int_a^b |f - \tilde{f}| dx = 0$ (first part proven).

$$\left| \int_{a}^{b} f \, dx - \int_{a}^{b} \tilde{f} \, dx \right| = \left| \int_{a}^{b} (f - \tilde{f}) \, dx \right| \le \int_{a}^{b} \left| f - \tilde{f} \right| \, dx = 0$$



Figure 11: x and z

$$\implies \int_a^b f \, dx = \int_a^b \tilde{f} \, dx$$

Second part proven.

Lemma 5.5. Let $f \in \mathcal{R}[a,b]$. Then it holds that $f_+ \in \mathcal{R}[a,b]$ and also $f_- \in \mathcal{R}[a,b]$.

Proof. Only for f_+ : First, we show: Let $x \in [a, b)$.

$$f_{+}(x) = \lim_{\xi \to x_{+}} f(\xi) = \lim_{\xi \to x_{+}} f_{+}(x)$$

(the plus is important on the right-hand side!).

Proof of this: Let $\varepsilon > 0$ be arbitrary. Then there exists $\delta > 0$ such that $\forall \xi \in (x, x + \delta)$: $\left| f(\xi) - f_+(x) \right| < \frac{\varepsilon}{2}$. Now let $z \in (x, x + \delta)$ be arbitrary chosen. For z there exists $\xi \in (z, x + \delta)$.

 ξ sufficiently close enough to z such that $|f(\xi) - f_+(z)| \le \frac{\varepsilon}{2}$ because $f_+(z)$ exists.

$$\left| f_{+}(z) - f_{+}(x) \right| \le \left| f_{+}(z) - f(\xi) \right| + \left| f(\xi) - f_{+}(x) \right| < \frac{\varepsilon}{2} + \frac{\varepsilon}{2}$$

TODO some content missing here

It remains to show: f_+ has left-sided limits. Let $x \in (a, b]$ be arbitrary and $f_-(x) = \lim_{\xi \to x_-} f(\xi)$. We show: $f_-(x) = \lim_{\xi \to x_-} f_+(x)$ (again: the plus is important).

Let $\varepsilon > 0$ be arbitrary. Choose $\delta > 0$ such that $\forall z \in (x - \delta, x)$ it holds that $|f(z) - f_{-}(x)| < \frac{\varepsilon}{2}$.

Now let $\xi \in (x - \delta, x)$ (compare with Figure 12) and choose $x > z > \xi$ with the property that $|f(z) - f_+(\xi)| < \frac{\varepsilon}{2}$ (possible because f in ξ has a right-sided limit):

$$\left| f_{+}(\xi) - f_{-}(x) \right| \leq \underbrace{\left| f_{+}(\xi) - f(z) \right|}_{< \frac{\varepsilon}{2}} + \underbrace{\left| f(z) - f_{-}(x) \right|}_{< \frac{\varepsilon}{2}}$$

because of the choice of δ and $z \in (\xi, x) \subseteq (x - \delta, x)$.

Hence, $\lim_{\xi \to x_{-}} f_{+}(\xi) = f_{-}(x)$. Analogously for f_{-}

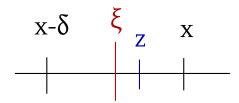


Figure 12: ξ and z

Remark 5.13.

$$\lim_{\xi \to x_+} f_+(\xi) = f_+(x)$$

$$\lim_{\xi \to x_{-}} f_{-}(\xi) = f_{-}(x)$$

from the proof. So f_+ is right-sided continuous and f_- is left-sided continuous.

Lemma 5.6. Let $f \in \mathcal{R}[a, b]$. Then it holds that

$$\int_{a}^{b} f \, dx = \int_{a}^{b} f_{+} \, dx = \int_{a}^{b} f_{-} \, dx$$

Proof. For f_+ :

$$f, f_+ \in \mathcal{R}[a, b]$$

 $\forall x \in [a, b]$ with f is continuous in x it holds that

$$f(x) = \lim_{\xi \to x} f(\xi) = \lim_{\xi \to x_{+}} f(\xi) = f_{+}(x)$$

f has at most countable many discontinuity points. By Satz 5.6,

$$\int_{a}^{b} |f - f_{+}| dx = 0 \quad \text{or equivalently} \quad \int_{a}^{b} f dx = \int_{a}^{b} f_{+} dx$$

5.2 Improper integrals

Let *I* be an interval in $\mathbb R$ with marginal points *a* and *b* with $-\infty \le a < b \le +\infty$. Let *f* be a regulated function on *I*. We define

1. If
$$I = [a, b)$$
, $\int_{a}^{b} f dx = \lim_{\beta \to b_{-}} \int_{a}^{\beta} f dx$

2. If
$$I = (a, b]$$
, $\int_a^b f dx = \lim_{\alpha \to a_+} \int_\alpha^b f dx$

3. If
$$I = (a, b)$$
, $\int_a^b f \, dx = \lim_{\alpha \to a_+} \int_{\alpha}^c f \, dx + \lim_{\beta \to b_-} \int_{c}^{\beta} f \, dx$

for an arbitrarily chosen $c \in (a, b)$ under the constraint that the corresponding limits in \mathbb{R} exist.

Standard examples will follow:

Example 5.4. *Let* s > 1.

$$\int_{1}^{\infty} x^{-s} dx = \lim_{\beta \to \infty} \int_{1}^{\beta} x^{-s} dx = \lim_{\beta \to \infty} \left(\frac{1}{-s+1} x^{-s+1} \right) \Big|_{1}^{\beta}$$

$$= \frac{1}{1-s} \cdot \lim_{\beta \to \infty} \frac{1}{\frac{s-1}{s-1}} - \frac{1}{1-s} \cdot 1 = \frac{1}{s-1}$$

TODO drawing

Example 5.5. *Let* s < 1.

$$\int_{0}^{1} x^{-s} dx = \lim_{\alpha \to 0_{+}} \int_{\alpha}^{1} x^{-s} ds = \lim_{\alpha \to 0_{+}} \frac{1}{-s+1} x^{-s+1} \Big|_{\alpha}^{1}$$

$$= \frac{1}{1-s} - \frac{1}{1-s} \cdot \lim_{\alpha \to 0} \alpha \underbrace{1-s}_{=0}^{>0} = \frac{1}{1-s}$$

TODO drawing

For s = 1, neither $\int_0^1 \frac{1}{x} dx$ nor $\int_1^\infty \frac{1}{x} dx$ exists.

Example 5.6. *For* c > 0,

$$\int_0^\infty e^{-cx} dx = \lim_{\beta \to \infty} \int_0^\beta e^{-cx} dx = \lim_{\beta \to \infty} \left(-\frac{1}{c} \right) \cdot e^{-cx} \Big|_0^\beta - \frac{1}{c} \cdot \underbrace{\lim_{\beta \to \infty} e^{-c\beta}}_{=0} + \frac{1}{c} = \frac{1}{c}$$

Theorem 5.7 (Direct comparison test for improper integrals). *In German, "Majorantenkriterium für uneigentliche Intergale"*.

Let f, g be regulated functions on I and it holds that

$$|f(x)| \le g(x) \forall x \in I$$

Assume $\int_a^b g \, dx$ exists as improper integral. Then also the following improper integrals exist:

$$\int_a^b |f| \ dx \ and \ \int_a^b f \ dx$$

In German, g is called Majorante of f (there is no equivalent terminology in English).

Proof. Without loss of generality, let I = [a,b). Let $G(\beta) = \int_a^\beta g \, dx$. We know that $\lim_{\beta \to b_-} G(\beta)$ exists. By Lemma 4.6 (Cauchy criterion for existence of limits): Let $\varepsilon > 0$ be arbitrary, then there exists a right-sided neighborhood U of v (v if v if

$$|G(v) - G(u)| = \left| \int_a^v g \, dx - \int_a^u g \, dx \right| = \left| \int_u^a g \, dx + \int_a^v g \, dx \right| = \left| \int_u^v g \, dx \right|$$

Let $F(\beta) = \int_a^\beta |f| dx$. Analogously as for G, it holds that $F(v) - F(u) = \int_u^v |f| dx$. Let $u, v \in U$. Then it holds that

$$|F(v) - F(u)| = \left| \int_{u}^{v} |f| \, dx \right| \le \left| \int_{u}^{v} g \, dx \right| = |G(v) - G(u)| < \varepsilon$$

hence by the Cauchy criterion for F: $\lim_{\beta \to b_{-}} F(\beta)$ exists, so there exists $\int_{a}^{b} \left| f \right| dx$ as improper integral. The same applies for the existence of $\int_{a}^{b} f dx$.

Example 5.7. *The cardinal sine function is defined as*

$$\operatorname{sinc}(x) = \frac{\sin x}{x}$$

$$\lim_{x \to 0} \frac{\sin x}{x} = 1 \qquad \operatorname{sinc}(0) = 1$$

So sinc(x) is continuous on \mathbb{R} .

$$\int_{0}^{\infty} \frac{\sin x}{x} dx = \int_{0}^{1} \underbrace{\frac{\sin x}{x}}_{continuous} dx + \int_{1}^{\infty} \frac{\sin x}{x} dx$$

How about $\int_1^\infty \frac{\sin(x)}{x} dx$?

$$\lim_{\beta \to \infty} \int_{1}^{\beta} \frac{\sin x}{x} \, dx = \begin{vmatrix} u = \frac{1}{x} & u' = -\frac{1}{x^{2}} \\ v' = \sin x & v = -\cos x \end{vmatrix} = \lim_{\beta \to \infty} \left[-\frac{1}{x} \cos x \right]_{1}^{\beta} - \int_{1}^{\beta} \frac{\cos x}{x^{2}} \, dx$$

$$= \cos(1) - \lim_{\beta \to \infty} \int_{1}^{\beta} \frac{\cos(x)}{x^{2}} \, dx$$

$$\left| \frac{\cos(x)}{x^2} \right| \le \frac{1}{x^2} \ on \ [1, \beta]$$

and $\int_1^\infty \frac{1}{x^2} dx$ exists. So $g(x) = \frac{1}{x^2}$ is a majorant of $\frac{\cos(x)}{x^2}$ and by Theorem 5.7, $\lim_{\beta \to \infty} \int_1^\beta \frac{\cos(x)}{x^2} dx$ eixsts.

Attention! $\int_0^\infty \left| \frac{\sin(x)}{x} \right| dx$ does not exist. Is not Lebesgue integrable.

Definition 5.6. *Let* x > 0. *We call* Γ Euler's Gamma function.

$$\Gamma(x) := \int_0^\infty t^{x-1} e^{-t} \, dx$$

Remark 5.14. The improper integral in the definition of the Γ -function exists for all x > 0.

This lecture took place on 2018/04/26.

TODO I missed the first 15 minutes

Proof of this:

Proof.

$$\lim_{t \to \infty} \underbrace{t^{x-1}}_{\text{polynomially in } t} \cdot \underbrace{e^{-t}}_{\text{exponentially } \to 0} = 0$$

Also there exists L > 1, such that $\forall x > L$ it holds that $t^{x-1}e^{-t/2} < 1$ on [1,L] (which is a compact interval) continuous. So there exists M > 0 such that $t^{x-1}e^{-\frac{t}{2}} \leq M \forall t \in [1,L]$. Let $c = \max\{M,1\}$. Therefore it holds on [1,L] and also on (L,∞) .

$$t^{x-1}e^{-\frac{t}{2}} < c$$

Multiply with $e^{-\frac{t}{2}} > 0$, then it holds that $t^{x-1} \cdot e^{-t} \le ce^{-\frac{t}{2}} \forall t \in [1, \infty)$.

$$c \int_{1}^{\infty} e^{-\frac{t}{2}} dt$$

exists. By the direct comparison test, we get $\int_1^\infty t^{x-1}e^{-t} dt$ exists.

Lemma 5.7. *For all* x > 0 *it holds that*

$$\Gamma(x+1) = x \cdot \Gamma(x)$$
 (functional equation of the Γ -function)

Especially with $\Gamma(1) = 1$ it holds that $\Gamma(n+1) = n!$ for all $n \in \mathbb{N}_0$.

Proof.

$$\Gamma(x+1) = \int_0^\infty t^{x+1-1} e^{-t} \, dt = \int_0^\infty t^x e^{-t} \, dt$$

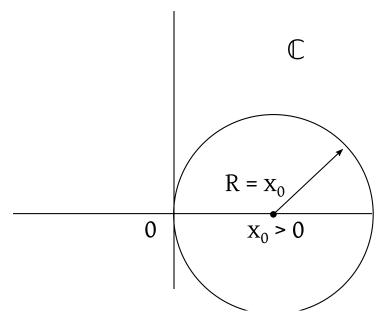


Figure 13: Γ on \mathbb{C}

$$= \begin{vmatrix} u = t^{x} & u' = x \cdot t^{x-1} \\ v' = e^{-t} & v = -e^{-t} \end{vmatrix}$$

$$= \underbrace{-t^{x} \cdot e^{-t} \Big|_{0}^{\infty}}_{0} + \int_{0}^{\infty} x \cdot t^{x-1} \cdot e^{-t} dt = x \int_{0}^{\infty} t^{x-1} e^{-t} dt = x \Gamma(x)$$

$$= 0 \text{ on the upper bound}$$

$$= 0 \text{ on the lower bound}$$

$$\Gamma(1) = \int_{0}^{\infty} \underbrace{t^{1-1} \cdot e^{-t} dt}_{=1} \cdot e^{-t} \Big|_{0}^{\infty} = 1$$

$$\Gamma(n+1) = n \cdot \Gamma(n) = n \cdot (n-1)\Gamma(n-1) = n \cdot (n-1) \cdot \ldots \cdot 1 \cdot \underbrace{\Gamma(1)}_{=1} = n!$$

Remark 5.15. There exists a power series $\Gamma(x) = \sum_{n=0}^{\infty} a_n (x - x_0)^n$. $\Gamma(z)$ is also defined for $z \in \mathbb{C}$ with $\Re z > 0$. Compare with Figure 13.

5.3 Young's inequality

Some important inequalities in integration theory follow.

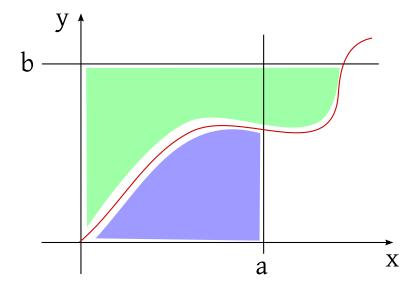


Figure 14: Young's inequality visualized. The blue area denotes $\int_0^\alpha f \, dx$ and $\int_0^b f^{-1}(y) \, dy$ is the green area.

Theorem 5.8 (Young's inequality). Let $f:[0,\infty) \to [0,\infty)$ be continuous differentiable, strictly monotonically increasing with f(0) = 0 and f is unbounded. Then $f:[0,\infty) \to [0,\infty)$ bijective and $f^{-1}:[0,\infty) \to [0,\infty)$ is strictly monotonically increasing and continuous. Let $a,b \ge 0$ be given. Then it holds that

$$ab \le \int_0^{\alpha} f(x) \, dx + \int_0^b f^{-1}(y) \, dy$$

Equality is given if and only if, b = f(a) or $a = f^{-1}(b)$. Compare with Figure 14.

Proof. Let $f:[0,\infty) \to [0,\infty)$ be as above. Let $x_1 \neq x_2$. Without loss of generality $x_1 < x_2$. Then it holds that $f(x_1) < f(x_2) \implies f$ is injective. Surjectivity: f(0) = 0, hence $0 \in f([0,\infty])$. Let $\eta > 0$ be arbitrary. Because f is unbounded, there exists $z \in (0,\infty)$ with $f(z) > \eta$. $f(0) = 0 < \eta < f(z)$.

By the Intermediate Value Theorem (f is continuous), there exists $\xi \in (0, z)$ with $f(\xi) = \eta$. So f is surjective.

$$f^{-1}:[0,\infty)\to[0,\infty)$$

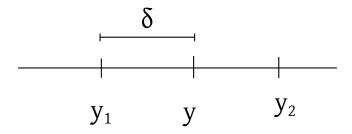


Figure 15: δ , y, y_1 and y_2

Monotonicity: Let $y_1 < y_2$. Then it holds that $x_1 = f^{-1}(y_1) < x_2 = f^{-1}(y_2)$. If this would not be true (hence, $x_2 \le x_1$) then $y_2 = f(x_2) \le y_1 = f(x_1)$ gives a contradiction.

Continuity of f^{-1} : Let $\varepsilon > 0$ be arbitrary. Let $y \in (0, \infty)$ be chosen arbitrarily. We show f^{-1} is continuous in y. Let $x = f^{-1}(y) > 0$ and choose $\hat{\varepsilon} = \min\left\{\frac{x}{2}, \frac{\varepsilon}{2}\right\}$.

$$x_1 = x - \hat{\varepsilon} > 0$$
 $x_2 = x + \hat{\varepsilon} > 0$

Let $y_1 = f(x_1)$, $y_2 = f(x_2)$, $x_1 = f^{-1}(y_1)$ and $x_2 = f^{-1}(y_2)$. By monotonicity of f: $x_1 < x < x_2 \implies y_1 < y < y_2$.

Choose $\delta = \min\{y - y_1, y_2 - y\} > 0$ (compare with Figure 15). Hence $(y - \delta, y + \delta) \subseteq (y_1, y_2) \forall \eta \in (y - \delta, y + \delta)$ it holds that

$$f^{-1}(\eta) < f^{-1}(y+\delta) < f^{-1}(y_2) = x_2 = x + \hat{\varepsilon}$$

$$f^{-1}(\eta) < f^{-1}(y - \delta) < f^{-1}(y_1) = x_1 = x - \hat{\varepsilon}$$

So $f^{-1}(\eta) \in (x - \hat{\varepsilon}, x + \hat{\varepsilon})$, or equivalently

$$\left|\eta - y\right| < \delta \implies \left|f^{-1}(\eta) - \underbrace{f^{-1}(y)}_{-x}\right| < c \le \frac{\varepsilon}{2} < \varepsilon$$

So f^{-1} is continuous in y and f^{-1} is continuous in y_0 analogously.

Consider

$$\int_{0}^{b} f^{-1}(y) \, dy = \begin{vmatrix} y & = f(x) \\ dy & = f'(x) \, dx \\ y = 0 & \Longrightarrow x = f^{-1}(0) = 0 \\ y = b & \Longrightarrow x = f^{-1}(b) \end{vmatrix} = \int_{0}^{f^{-1}(b)} \underbrace{f^{-1}(f(x)) \cdot f'(x)}_{=x} \, dx = \int_{0}^{f^{-1}(b)} x \cdot f'(x) \, dx$$

$$= \underbrace{x \cdot f(x) \Big|_{0}^{f^{-1}(b)} - 0 \int_{0}^{f^{-1}(b)} 1 \cdot f(x) \, dx}_{\text{integration by parts}}$$

$$= f^{-1}(b) \cdot b - \int_0^{f^{-1}(b)} f(x) \, dx$$

So

$$I = \int_0^a f(x) dx + \int_0^b f^{-1}(y) dy = \int_{f^{-1}(b)}^0 f(x) dx + b \cdot f^{-1}(b)$$
$$= \int_{f^{-1}(b)}^a f(x) dx + b \cdot f^{-1}(b)$$

Case 1 $a = f^{-1}(b)$

$$\implies I = \underbrace{\int_{a}^{a} f(x) \, dx + b \cdot a}_{=0}$$

Case 2 b < f(a), or equivalently $f^{-1}(b) < a$

$$\implies \int_{f^{-1}(b)}^{a} \underbrace{f(x)}_{f(f^{-1}(b)) \text{ for } x > f^{-1}(b)} dx > \underbrace{b} \cdot \underbrace{(a - f^{-1}(b))}_{\text{length of integration interval}}$$

Therefore $I > b(a - f^{-1}(b)) + b \cdot f^{-1}(b) = ab$.

Case 3 b > f(a), or equivalently $f^{-1}(b) > a$

$$\int_{f^{-1}(b)}^{a} f(x) dx = \int_{a}^{f^{-1}(b)} \underbrace{(-f(x))}_{\text{monotonically decreasing}} dx > -f(f^{-1}(b)) \cdot (f^{-1}(b) - a)$$

$$= -b(f^{-1}(b) - a)$$

$$I > -b(f^{-1}(b) - a) + b \cdot f^{-1}(b) = ab$$

Remark 5.16. Young's inequality also holds without requiring differentiability of f (but the proof is more complex).

Lemma 5.8 (Special case of Young's inequality). Let $A, B \ge 0$ and p, q > 1 such that $\frac{1}{p} + \frac{1}{q} = 1 \iff p + q = p \cdot q$. Then p and q are called conjugate exponents. Then it holds that $AB \le \frac{A^p}{p} + \frac{B^q}{q}$.

Proof.

$$f(x) = x^{p-1}$$
 in Young's inequality
$$y = x^{p-1} \iff x = y^{\frac{1}{p-1}}$$

$$\frac{1}{p-1} = q-1 \text{ is immediate, because}$$

$$\frac{1}{p-1} = q-1 \iff 1 = pq-p-q+1 \iff p+q=pq$$

So $f^{-1}(y) = y^{\frac{1}{p-1}} = y^{q-1}$. By Young's inequality:

$$AB \le \int_0^A x^{p-1} dx + \int_0^B y^{q-1} dy$$
$$= \frac{x^p}{p} \Big|_0^A + \frac{y^q}{q} \Big|_0^B = \frac{A^p}{p} + \frac{B^q}{q}$$

Remark 5.17.

$$AB = \frac{A^p}{p} + \frac{B^q}{q}$$

Equality holds if and only if $B = A^{p-1} \iff B^q = A^{pq-q} = A^p$.

5.4 Hölder's ineqaulity

Theorem 5.9 (Hölder's inequality). Let I be an interval with boundary values a and $b. -\infty \le a < b \le +\infty$. Let p and q be conjugate exponents. Let f_1 and f_2 be regulated function on I such that

$$\int_{a}^{b} |f_{1}(x)|^{p} dx < \infty$$

$$\int_{a}^{b} |f_{2}(x)|^{q} dx < \infty$$

both exist.

We let $||f_1||_p := \left(\int_a^b |f_1(x)|^p dx\right)^{\frac{1}{p}}$ and $||f_2||_q := \left(\int_a^b |f_2(x)|^q dx\right)^{\frac{1}{q}}$. They are called L^p -norm of f_1 and L^q -norm of f_2 .

Then it holds that

$$\int_{a}^{b} \left| f_1(x) \cdot f_2(x) \right| \, dx < \infty$$

exists and

$$\int_{a}^{b} |f_{1}(x) \cdot f_{2}(x)| dx \le ||f_{1}||_{p} \cdot ||f_{2}||_{q}$$

Proof. Assume that $||f_1||_p > 0$ and $||f_2||_q > 0$. Let $A = \frac{|f_1(x)|}{||f_1||_p}$ and $B = \frac{|f_2(x)|}{||f_2||_q}$. By Lemma 5.8,

$$\frac{\left|f_{1}(x)\right|}{\left\|f_{1}\right\|_{p}} \cdot \frac{\left|f_{2}(x)\right|}{\left\|f_{2}\right\|_{q}} \leq \frac{1}{q} \cdot \frac{\left|f_{1}(x)\right|^{p}}{\left\|f_{1}\right\|_{p}^{p}} + \frac{1}{q} \cdot \frac{\left|f_{2}(x)\right|^{q}}{\left\|f_{2}\right\|_{q}^{q}}$$

We integrate the inequality,

$$\frac{1}{\|f_1\|_p \cdot \|f_2\|_q} \cdot \int_a^b |f_1(x) \cdot f_2(x)| dx$$

$$\leq \frac{1}{p} \cdot \frac{1}{\|f_1\|_p^p} \cdot \underbrace{\int_a^b |f_1(x)|^p |dx}_{=\|f_1\|_1^p} + \frac{1}{q} \cdot \frac{1}{\|f_2\|_q^q} \underbrace{\int_a^b |f_2(x)|^q dx}_{=\|f_2\|_q^q} = \frac{1}{p} + \frac{1}{q} = 1$$

$$\frac{1}{\|f_1\|_p \cdot \|f_2\|_q} \cdot \int_a^b |f_1(x) \cdot f_2(x)| \ dx \implies \int_a^b |f_1(x) f_2(x)| \ dx \le \|f_1\|_p \cdot \|f_2\|_q$$

Special case: Let $||f_1||_p = 0$

$$\Longrightarrow \left(\int_a^b \left| f_1(x) \right|^p dx \right)^{\frac{1}{p}} = 0 \implies \int_a^b \underbrace{\left| f_1(x) \right|^p}_{>0} dx = 0$$

By Theorem 5.6, $f_1(x) = 0 \forall x \in [a, b] \setminus A$ and A is at most countable.

$$\implies f_1(x) \cdot f_2(x) = 0 \forall x \in [a, b] \setminus A$$

$$\implies \int_a^b \left| f_1(x) \cdot f_2(x) \right| \, dx = 0$$

 \implies 0 = 0 in Hölder's inequality

Remark 5.18 (Special case of Hölder's inequality). Let p = q = 2, $\frac{1}{2} + \frac{1}{2} = 1$.

$$\int_{a}^{b} |f_{1}(x) \cdot f_{2}(x)| dx \le ||f_{1}||_{2} ||f_{2}||_{2}$$

is called Cauchy-Schwarz inequality for L^2 functions.

$$\int_{a}^{b} f_{1}(x) f_{2}(x) dx = \langle f_{1}, f_{2} \rangle_{2} = \langle f_{1}, f_{2} \rangle_{L^{2}}$$

is an inner product on a proper space of functions.

6 Elaboration on differential calculus

We consider a metric space X and functions $f: X \to \mathbb{C}$. We define a concept of uniform convergence of such sequences:

$$f_n: X \to \mathbb{C} \quad (n \in \mathbb{N}) \text{ and } f: X \to \mathbb{C}$$

We say, $(f_n)_{n\in\mathbb{N}}$ converges uniformly towards f if $\forall \varepsilon > 0 \forall N \in \mathbb{N}$ such that $\forall x \in X$ and $\forall n \geq N$ it holds that

$$\underbrace{\left|f_n(x) - f(x)\right|}_{\text{absolute value in }\mathbb{C}} < \varepsilon$$

$$\iff \sup\{|f_n(x) - f(x)| : x \in X\} < \varepsilon$$

Remark 6.1. Do not use $||f||_{\infty}$ for the definition of uniform convergence, because f_n and f must not be necessarily bounded. Hence,

$$||f||_{\infty} = \{|f(x)| : x \in X\}$$

must not be finite.

Theorem 6.1. Let X be a metric space, $f_n: X \to \mathbb{C}$ be a sequence of continuous functions and $f: X \to \mathbb{C}$ such that $f_n \to f$ uniform on X. Then f is also continuous on X.

This lecture took place on 2018/05/03.

Proof. Let $\varepsilon > 0$ be arbitrary. Choose $x \in X$. Show: f is continuous in x.

Compare with Figure 16.

Because of uniform convergence $f_n \to f$, there exists $N \in \mathbb{N}$ such that $\left| f_N(z) - f(z) \right| < \frac{\varepsilon}{3} \forall z \in X$. Let N be fixed. Because f_N is continuous in x, there exists $\delta > 0$ such that $d(x, \xi) < \delta \implies \left| f_N(\xi) - f_N(x) \right| < \frac{\varepsilon}{3}$.

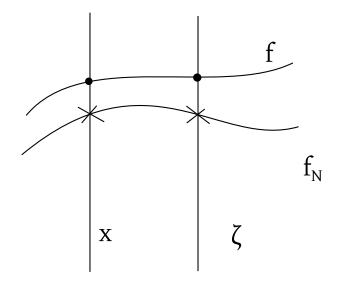


Figure 16: Uniform convergence of f_N to f

We consider now $\xi \in X$ with $d_X(x, \xi) < \delta$. Then it holds that

$$|f(x) - f(\xi)| = |f(x) - f_N(x) + f_N(x) - f_N(\xi) + f_N(\xi) - f(\xi)|$$

$$\leq |f(n) - f_N(x)| + |f_N(x) - f_N(\xi)| + |f_N(\xi) - f(\xi)|$$

$$< \frac{\varepsilon}{2}$$

$$< \frac{\varepsilon}{3}$$

$$< \frac{\varepsilon}{3}$$

by uniform convergence, by continuity and by uniform convergence respectively.

Thus, f is continuous in x.

Theorem 6.2. Let $P(z) = \sum_{k=0}^{\infty} a_k z^k$ be a power series in \mathbb{C} with convergence radius $\rho_P > 0$. Furthermore, let $0 < r < \rho_P$. Let $P_n(z) = \sum_{k=0}^n a_k z^k$ (n-th partial sum of P). Then $P_n \to P$ uniformly on $\overline{K_r(0)}$.

Proof. Approximation theorem for power series. Lettl Analysis 1, lecture notes, section 5, theorem 10.

Let $0 < r < \rho_P$. Choose \bar{r} with $r < \bar{r} < \rho_P$. Then it holds for $z \in \overline{K_r(0)}$ that

$$|P(z) - P_n(z)| < \frac{\overline{r}}{\overline{r} - r} \cdot \left(\frac{r}{\overline{r}}\right)^n$$

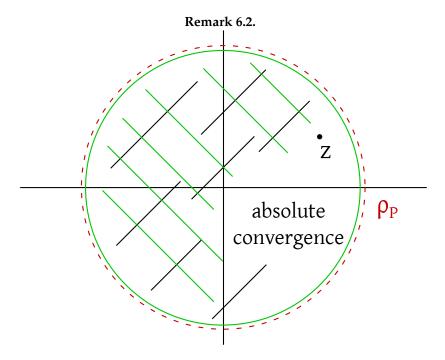


Figure 17: We cannot make a general statement about convergence/divergence. But on every small closed sphere P converges absolutely for every z

$$\frac{r}{\bar{r}} < 1$$

hence $\left(\frac{r}{\bar{r}}\right)^n$ is arbitrary small, for every n sufficiently large.

$$\implies \sup\left\{\left|P(z) - P_n(z) : z \in \overline{K_r(0)}\right|\right\} \le \underbrace{\frac{\overline{r}}{\overline{r} - r}}_{\text{fixed}} \cdot \underbrace{\left(\frac{r}{\overline{r}}\right)^n}_{\text{sufficiently large}}$$

Hence, $P_n \to P$ uniform on $\overline{K_r(0)}$.

Corollary. *P* is continuous on $K_{\rho_P}(0)$.

Theorem 6.3. Let $I \subseteq \mathbb{R}$ be an interval. Let $f_n : I \to \mathbb{R}$ be continuously differentiable on $I \forall n \in \mathbb{N}$. It holds that

- 1. $\exists g: I \to \mathbb{R}$ such that $f'_n \to g$ uniform on I
- 2. $\exists f: I \to \mathbb{R}$ such that $\forall x \in I$ it holds that $f(x) = \lim_{n \to \infty} f_n(x)$ ("pointwise convergence").

Then it holds that f is continuously differentiable on I and g = f'.

Proof. g is continuous as uniform limit of continuous f'_n (Theorem 6.1). For f_n , the Fundamental Theorem of Differential Calculus can be applied (f'_n is continuous, hence a regulated function). Let $x_0 \in I$. Then it holds that

$$f_n(x) = f_n(x_0) + \int_{x_0}^x f'_n(\xi) d\xi$$

Convergence for $n \to \infty$:

$$f_n(x) \to f(x)$$
 $f_n(x_0) \to f(x_0)$

(Pointwise convergence)

$$\int_{x_0}^x f_n'(\xi) d\xi \to \int_{x_0}^x g(\xi) d\xi$$

Therefore, for $n \to \infty$,

$$f(x) = f(x_0) + \int_{x_0}^{x} g(\xi) d\xi$$

The right-hand side is continuously differentiable by *x* according to the Fundamental Theorem, variant 1, with

$$\left(f(x_0) + \int_{x_0}^x g(\xi) d\xi\right)'(x) = g(x)$$

Hence, by $f(x) = f(x_0) + \int_{x_0}^x g(\xi) d\xi$ it follows that

$$f'(x) = g(x) \quad \forall x \in I$$

To finish our proof, we need a result we missed in the section about Integrals.

Lemma 6.1. Let $(f_n)_{n\in\mathbb{N}}$ be a sequence of regulated functions on [a,b] and $f_n\to f$ uniform on [a,b]. Then it holds that

$$\int_{a}^{b} |f_{n} - f| dx \to 0 \quad \text{for } n \to \infty \quad \text{especially } \int_{a}^{b} f_{n} dx \to \int_{a}^{b} f dx$$

Proof. f as a uniform limit of regulated functions is a regulated function. The proof has been done in the practicals.

Let $N \in \mathbb{N}$ large enough such that

$$\forall n \ge N \forall x \in [a, b] : \left| f_n(x) - f(x) \right| < \frac{\varepsilon}{h - a}$$

Then it holds that

$$\int_{a}^{b} \left| f_{n}(x) - f(x) \right| \, dx < \int_{a}^{b} \frac{\varepsilon}{b - a} \, dx = \frac{\varepsilon}{b - a} (b - a) = \varepsilon$$

Hence,

$$\lim_{n \to \infty} \int_{a}^{b} |f_{n}(x) - f(x)| dx = 0$$

$$\underbrace{\left| \int_{a}^{b} f_{n} dx - \int_{a}^{b} f dx \right|}_{\Rightarrow \to 0} \le \underbrace{\int_{a}^{b} |f_{n} - f| dx}_{\to 0}$$

So,

$$\int_{a}^{b} f \, dx = \lim_{n \to \infty} \int_{a}^{b} f_n \, dx$$

6.1 Higher derivatives and Taylor's Theorem

Definition 6.1. Let $f: I \to \mathbb{R}$, $I \subseteq \mathbb{R}$ is an interval. We define inductively:

$$f^{(0)}(x) = f(x)$$

Assume $f^{(n-1)}$ is defined continuously on I and differentiable in $x \in I$. Then we let

$$f^{(n)}(x) = \left(f^{(n-1)}\right)'(x)$$

 $f^{(n)}(x)$ is called n-th derivative of f in x.

Notational remark:

$$f^{(0)} = f$$
 $f^{(1)} = f'$ $f^{(2)} = f''$ $f^{(3)} = f'''$ $f^{(4)} = f''''$

Furthermore, we let

 $C^n(I) := \{ f : I \to \mathbb{R} : f^{(k)}(x) \text{ exists } \forall x \in I \text{ and } x \mapsto f^{(k)}(x) \text{ is continuous } \forall 0 \le k \le n \}$

We call C the space of n-times continuously differentiable functions on I.

Remark 6.3. $C^n(I)$ is a vector space. If I = [a, b] is compact, then

$$||f||_{C^n} = \max \{ \sup |f^{(k)}(x)| : x \in I : 0 \le k \le n \}$$

defines a norm on $C^n(I)$ with $\sup |f^{(k)}(x)| : x \in I = ||f^{(k)}||_{\infty}$.

Remark 6.4 (New topic). Let $f \in C^n(I)$ and $x_0 \in I$. Find an appropriate polynomial T which approximated f in an environment of x_0 in the "best" way.

Definition 6.2. Let $P(x) = \sum_{k=0}^{n} a_k x^k$ be a polynomial with $a_n \neq 0$ (hence degree of P is n).

 $P \in \mathbb{R}[x] \dots$ set of all polynomials with coefficients in \mathbb{R}

This set of polynomials is a ring.

 $x_0 \in \mathbb{R}$ is called k-times root of $P(k \in \mathbb{N})$ if $Q \in \mathbb{R}[x]$ exists such that $P(x) = (x - x_0)^k Q(x)$ with $Q(x_0) \neq 0$.

Remark 6.5. $P(x) = (x - x_0)^k \cdot Q(x)$ means that division of P by $(x - x_0)^k$ gives no remainder. Recall that division with remainder means that $\exists \hat{Q}$, \hat{R} that are polynomials of degree $\hat{R} < k$,

$$P(x) = (x - x_0)^k \cdot \hat{Q}(x) + \hat{R}(x)$$

 \hat{Q} , \hat{R} is unique. If $P(x) = (x - x_0)^k \cdot Q(x) \implies \hat{R} = 0$, $\hat{Q} = Q$.

Lemma 6.2. Let $P(x) = \sum_{l=0}^{n} a_l x^l$ with $a_n \neq 0$. Let $1 \leq k \leq n$. Then it holds that $x_0 \in \mathbb{R}$ is a k-times root of polynomial $P \iff P^{(j)}(x_0) = 0$ for j = 0, ..., k-1 and $P^{(k)}(x_0) \neq 0$.

Proof. Proof by complete induction.

Induction begin Consider k = 1. Direction \Longrightarrow .

Let x_0 be a simple root of P, then it holds that $P(x) = (x - x_0) \cdot Q(x)$ and $Q(x_0) \neq 0$. Hence, $P(x_0) = (x_0 - x_0) \cdot Q(x_0) = 0$ and $P'(x) = Q(x) + (x - x_0) \cdot Q'(x)$. Thus, $P'(x_0) = Q(x_0) + (x_0 - x_0) \cdot Q'(x_0) = Q(x_0) \neq 0$.

Direction \Leftarrow .

Let $P(x_0) = 0$ and $P'(x_0) \neq 0$. Division with remainder: $P(x) = (x - x_0) \cdot Q(x) + R(x)$ with degree(R) \leq degree($x - x_0$) = 1. Thus, R is constant. We insert x_0 . This gives $P(x_0) = (x_0 - x_0) \cdot Q(x_0) + R$ with $P(x_0) = 0$ and $(x_0 - x_0) = 0$. Hence, R = 0 is the zero polynomial and $P(x) = (x - x_0) \cdot Q(x)$. It remains to show that $Q(x_0) \neq 0$. $P'(x) = 1 \cdot Q(x_0) + (x - x_0) \cdot Q'(x_0)$. We insert $x = x_0 \implies 0 \neq P'(x_0) = Q(x_0) + (x_0 - x_0) \cdot Q'(x)$. Thus is holds that $Q(x_0) = P'(x_0) \neq 0$.

Induction step

Claim (Auxiliary claim). Let $P(x) = (x - x_0) \cdot \tilde{P}(x)$. Let P, \tilde{P} be polynomials. Then it holds $\forall j \in \mathbb{N}$ that

$$P^{(j)}(x) = (x - x_0) \cdot \tilde{P}^{(j)}(x) + j \cdot \tilde{P}^{(j-1)}(x)$$

Proof. Proof by complete induction.

Let j = 1.

$$P'(x) = 1 \cdot \underbrace{\tilde{P}(x)}_{\tilde{P}^{(0)}(x)} + (x - x_0) \cdot \underbrace{\tilde{P}'(x)}_{\tilde{P}^{(1)}(x)}$$

Consider $j \rightarrow j + 1$.

$$P^{(j+1)}(x) = (P^{(j)})'(x)$$

$$= ((x - x_0) \cdot \tilde{P}^{(j)}(x)$$
induction
assumption
$$+ j\tilde{P}^{(j-1)}(x))'(x - x_0)\tilde{P}^{(j+1)}(x) + \tilde{P}^{(j)}(x) + j \cdot \tilde{P}^{(j)}(x)$$

$$= (x - x_0)\tilde{P}^{(j+1)}(x) + (j+1) \cdot \tilde{P}^{j}(x)$$

We continue with the induction step after verifying our auxiliary claim. Direction \implies .

Let x_0 be an k+1 times zero of P. Hence $P(x) = (x-x_0)^{k+1} \cdot Q(x)$. $Q(x_0) \neq 0$. Let $\tilde{P}(x) = (x-x_0)^k \cdot Q(x)$. We can apply the induction assumption on \tilde{P} . Hence

$$\tilde{P}^{(j)} = 0$$
 for $j = 0, \dots, k-1$ and $\tilde{P}^{(k)}(x_0) \neq 0$

$$P(x) = (x - x_0) \cdot \tilde{P}(x)$$

By the auxiliary claim, $P^{(j)}(x) = (x - x_0) \cdot \tilde{P}^{(j)}(x) + j \cdot \tilde{P}^{(j-1)}(x)$. Therefore

$$P^{(j)}(x_0) = j \cdot \tilde{P}^{(j-1)}(x) = \begin{cases} 0 & \text{for } j = 0, \dots, k \\ (k+1)\tilde{P}^{(k)}(x_0) \neq 0 & \text{for } j = k+1 \end{cases}$$

Hence, our claim about the derivatives is true (all derivatives are zero). Direction \iff .

Let $P^{(j)}(x_0) = 0$ for j = 0, ..., k and $P^{(k+1)}(x_0) \neq 0$ and induction assumption holds for k. Division with remainder and $P^{(0)}(x_0) = 0 \implies P(x) = (x - x_0) \cdot \tilde{P}(x)$. By our auxiliary claim, we get

$$P^{(j)}(x) = (x - x_0) \cdot \tilde{P}^{(j)}(x) + j\tilde{P}^{(j-1)}(x)$$

we insert $x = x_0$ and use $P^{(j)}(x_0) = 0$ for j = 0, ..., k

$$\implies \tilde{P}^{(j)}(x_0) = 0$$
 for $j = 0, \dots, k-1$

By the induction assumption, $\tilde{P}(x) = (x - x_0)^k Q(x)$ with $Q(x_0) \neq 0$

$$\implies P(x) = (x - x_0) \cdot \tilde{P}(x) = (x - x_0)^{k+1} Q(x)$$

This lecture took place on 2018/05/08.

TODO I missed the first 15 minutes

Definition 6.3. Let I be an interval, $f \in C^n(I)$. We let

$$T_f^n(x_0) \sum_{k=0}^n \frac{1}{k!} f^{(k)}(x_0) (x - x_0)^k$$

 $T_f^n(x; x_0)$ is a polynomial in x with degree $T_f^n \le n$. $T_f^n(x; x_0)$ is called Taylor polynomial of f of order n in x_0 .

Brook Taylor (1685-1731)

Lemma 6.3. The premise is the same like in Definition 6.3 The Taylor polynomial of $T_t^n(x; x_0)$ is the only polynomial of degree $\neq n$ which satisfies

$$(T_f^n)^{(k)}(x_0) = f^{(k)}(x_0)$$
 for $k = 0, ..., n$

Proof. Claim:

$$(T_f^n)^{(k)}(x;x_0) = \sum_{l=k}^n \frac{f^{(l)}(x_0)}{(l-k)!} (x-x_0)^{l-k} \qquad \text{for } 0 \le k \le n$$

Proof of the claim by complete induction:

Induction base n = 0

$$(T_f^n)^{(0)}(x;x_0) = \sum_{l=0}^n \frac{f^{(l)}(x_0)}{l!} (x - x_0)^l$$

Induction step $k \to k + 1$ Let $(T_f^n)^{(k)}(x; x_0)$

$$= \sum_{l=k}^{n} \frac{f^{(l)}(x_0)}{(l-k)!} (x-x_0)^{(l-k)}$$

by induction hypothesis. Then,

$$= \sum_{l=k+1}^{n} \frac{f^{(l)}(x_0)}{(l-k)!} (l-k) \cdot (x-x_0)^{l-k-1}$$
$$= \sum_{l=k+1}^{n} \frac{f^{(l)}(x_0)}{(l-(k+1))!} (x-x_0)^{l-(k+1)}$$

We apply insertion: $x = x_0$ into $(T_f^n)^{(k)}(x; x_0)$

$$(T_f^n)^{(k)}(x;x_0) = \sum_{l=k}^n \frac{f^{(l)}(x_0)}{(l-k)!} (x-x_0)^{l-k} = \frac{f^{(k)}(x_0)}{0!} = f^{(k)}(x_0)$$

We need to prove uniqueness: Let T, \tilde{T} be polynomials with $T^{(k)}(x_0) = \tilde{T}^{(k)}(x_0) = f^{(k)}(x_0)$ for k = 0, ..., n. Assume $T \neq \tilde{T}$, hence $T - \tilde{T} \neq 0$ (where 0 is the zero polynomial). For $P = T - \tilde{T}$ it holds that

$$P^{(k)}(x_0) = T^{(k)}(x_0) - \tilde{T}^{(k)}(x_0) = 0 \qquad \text{(for } 0 \le k \le n)$$

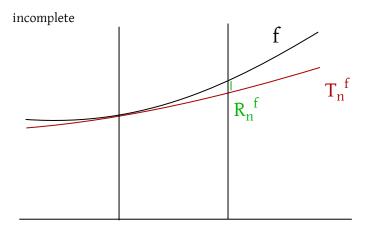


Figure 18: Visualization of the remainder term of a Taylor polynomial

By Lemma ?? it holds that x_0 is an n+1-times root of P. Thus, there exists a polynomial $Q \neq 0$ with $Q(x_0) \neq 0$ such that

$$\underbrace{P(x)}_{\text{degree } \le n} = \underbrace{(x - x_0)^{(n+1)} \cdot Q(x)}_{\text{degree } \ge n+1}$$

This is a contradiction. Hence it holds that $T - \tilde{T} = 0$.

Definition 6.4. Let $f \in C^n(I)$, $x_0 \in I$. Furthermore let $T^n_f(x;x_0)$ be the Taylor polynomial of n-th degree of f in x_0 . We let $R^n_f(x;x_0) = f(x) - T^n_f(x;x_0)$. We call $R^{n+1}_f(x;x_0)$ the approximation error of the Taylor polynomial. Also called remainder term of n+1-th order. Compare with Figure 18.

Theorem 6.4. Let $f^{(n+1)}(I)$, $x \in I$, $x_0 \in I$. Then it holds that

$$R_f^{n+1}(x;x_0) = \frac{1}{n!} \int_{x_0}^x (x-t)^n f^{(n+1)}(t) dt$$

We call it the integral form of the remainder term.

Proof. Complete induction over n.

Induction base n = 0

$$T_f^0(x; x_0) = f(x_0)$$

$$R_f^1(x; x_0) = \underbrace{f(x) - f(x_0)}_{f \in C^1}$$

$$= \int_{x_0}^x f'(t) dt$$

$$= \frac{1}{0!} \int_{x_0}^x (x - t)^0 f^{(1)}(t) dt$$

Induction step $n - 1 \rightarrow n$

$$R_f^n(x;x_0) = f(x) - T_f^{n-1}(x;x_0)$$

$$= \frac{1}{(n-1)!} \int_{x_0}^x (x-t)^{n-1} f^{(n)}(t) dt$$
ind. hypothesis
$$= \begin{vmatrix} u' = (x-t)^{n-1} & v = f^{(n)}(t) \\ u = -\frac{1}{n}(x-t)^n & v' = f^{(n+1)}(t) \end{vmatrix}$$

$$= \frac{1}{(n-1)!} \underbrace{\left[-\frac{1}{n}(x-t)^n \cdot f^{(n)}(t) \right]}_{=\frac{1}{n!}(x-x_0)^n \cdot f^{(n)}(x_0)} \Big|_{t=x_0}^x + \underbrace{\frac{1}{(n-1)!} \int_{x_0}^x (x-t)^n \cdot f^{(n+1)}(t) dt}_{=\frac{1}{n!} \int_{x_0}^x (x-t)^n \cdot f^{(n+1)}(t) dt}$$

So,

$$f(x) - T_f^{n-1}(x; x_0) - \frac{1}{n!} f^{(n)}(x_0)(x - x_0)^n$$

$$= \frac{1}{n!} \int_{x_0}^x (x - t)^n \cdot f^{(n+1)}(t) dt$$

Therefore,

$$R_f^{(n+1)}(x;x_0) = \frac{1}{n!} \int_{x_0}^x (x-t)^n f^{(n+1)}(t) \, dt$$

Theorem 6.5 (Lagrange form of the remainder term). Let $f \in C^{n+1}(I)$, $n \in \mathbb{N}_0$, $x, x_0 \in I$, $x \neq x_0$. Then there exists some ξ between x_0 and x (hence, $\xi \in (x_0, x)$ if $x > x_0$ or $\xi \in (x, x_0)$ if $x < x_0$) such that

$$R_f^{(n+1)}(x;x_0) = \frac{1}{(n+1)!} f^{(n+1)}(\xi) (x - x_0)^{n+1}$$

Proof. Idea: we apply the Mean Value Theorem for definite integrals on the Taylor remainder.

Case 1 Let $x_0 < x$.

$$R_f^{n+1}(x; x_0) = \frac{1}{n!} \int_{x_0}^{x} \underbrace{(x-t)^n}_{\text{regulated function}} \underbrace{f^{(n+1)}(t)}_{\text{continuous in } t} dt$$

$$= \frac{1}{n!} f^{(n+1)}(\xi) \cdot \int_{x_0}^{x} (x-t)^n dt$$

$$= \frac{1}{n!} f^{(n+1)}(\xi) \left[-\frac{1}{n+1} (x-t)^{n+1} \right]_{t=x_0}^{x}$$

$$= \frac{1}{(n+1)!} f^{(n+1)}(\xi) (x-x_0)^{n+1}$$

where MVT is the Mean Value Theorem for definite integrals (Theorem 5.2).

Case 2 Let $x < x_0$ and n odd.

$$R_f^{n+1}(x; x_0) = -\frac{1}{n!} \int_x^{x_0} \underbrace{(x-t)^n \cdot f^{(n+1)}(t) \, dt}_{=(-1)^n (t-x)^n}$$

$$= \frac{1}{n!} \int_x^{x_0} \underbrace{(t-x)^n \cdot f^{(n+1)}(t)}_{\text{continuous}} \, dt$$

$$= \frac{f^{(n+1)}(\xi)}{n!} \int_x^{x_0} (t-x)^n \, dt$$

$$= \frac{f^{(n+1)}(\xi)}{n!} \left[\frac{1}{n+1} (t-x)^{n+1} \right]_x^{x_0}$$

$$= \frac{1}{(n+1)!} f^{(n+1)}(\xi) (x_0 - x)^{n+1}$$

n+1 is even

$$= \frac{1}{(n+1)!} f^{(n+1)}(\xi) (x - x_0)^{n+1}$$

Case 3 Let $x < x_0$ and n even.

$$R_f^{n+1}(x;x) = -\frac{1}{n!} \int_x^{x_0} \underbrace{(x-t)^n \cdot f^{(n+1)}(t)}_{\geq 0} dt$$

$$= -\frac{1}{n!} f^{(n+1)}(\xi) \cdot \int_x^{x_0} (x-t)^n dt$$

$$= -\frac{1}{n!} f^{(n+1)}(\xi) \cdot \left[-\frac{1}{n+1} (x-t)^{n+1} \right]_x^{x_0}$$

$$= \frac{1}{(n+1)!} f^{(n+1)}(\xi) (x-x_0)^{n+1}$$

Any extreme value satisfies its derivative is zero. But not every point with derivative zero is an extreme value. We now consider conditions to select extreme values from all value satisfying derivative zero.

Corollary (Sufficient conditions for existence of extreme values). *Let I be an open interval. Let* $x_0 \in I$ *and* $f \in C^{n+1}(I)$. *Assume*

$$f^{(1)}(x_0) = f^{(2)}(x_0) = \dots = f^{(n)}(x_0) = 0$$

and $f^{(n+1)}(x_0) \neq 0$. Then f in x_0 has

- 1. a strict local maximum if n is even and $f^{(n+1)}(x_0) < 0$
- 2. a strict local minimum if n is odd and $f^{(n+1)}(x_0) > 0$
- 3. no extreme value in x_0 if n is even.

Proof. **Case a** Let $f^{(n+1)}(x_0) < 0$ and $f^{(n+1)}$ is continuous, then $\exists \varepsilon > 0$ such that $(x_0 - \varepsilon, x_0 + \varepsilon) \subseteq I$ (I is open) and $f^{(n+1)}(\xi) < 0 \forall \xi \in (x_0 - \varepsilon, x_0 + \varepsilon)$. Now let $x \in (x_0 - \varepsilon, x_0 + \varepsilon)$. Then by Theorem 6.5,

$$\frac{f^{(n+1)}(\xi)}{(n+1)!}(x-x_0)^{n+1} = R_f^{n+1}(x;x_0) = f(x) - \sum_{k=0}^n \frac{1}{k!} f^{(k)}(x_0)(x-x_0)^k = f(x) - f(x_0)$$

for k = 1, ..., n. So,

$$f(x) - f(x_0) = \underbrace{\frac{\int_{-\infty}^{(n+1)}(\xi)}{(n+1)!}}_{>0 \text{ for } x \neq x_0} \underbrace{(x - x_0)^{n+1}}_{>0 \text{ for } x \neq x_0}$$

hence $f(x) - f(x_0) < 0$, or equivalently

$$f(x) < f(x_0)$$
 $\forall x \in (x_0 - \varepsilon, x_0 + \varepsilon), x \neq x_0$

So *f* is a strict local maximum.

Case b Analogously.

Case c We apply the same idea as in Case a up to the point, where we consider $f(x) - f(x_0)$.

$$f(x) - f(x_0) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0)^{n+1}$$

 $f^{(n+1)}(\xi)$ has the same sign as $\underbrace{f^{(n+1)}(x_0)}$ $\forall \xi \in (x_0 - \varepsilon, x_0 + \varepsilon)$. This is

possible due to continuity of $f^{(n+1)}$ for sufficiently small ε .

$$f(x) - f(x_0) = \underbrace{\frac{f^{(n+1)}(\xi)}{(n+1)}}_{\text{has constant sign indep. of } x} \cdot \underbrace{(x - x_0)}_{\text{changes its sign}} \cdot \underbrace{(x - x_0)}_{\text{odd}}$$

Therefore $f(x) - f(x_0)$ changes its sign for $x = x_0$. Hence f has no extreme value in $x = x_0$.

Theorem 6.6 (Qualitative Taylor equation). Let $f \in C^n(I)$, $x, x_0 \in I$. Then there exists some function $r \in C(I)$ with $r(x_0) = 0$ such that

$$f(x) = T_f^n(x; x_0) + (x - x_0)^n \cdot r(x)$$

or equivalently,

$$R_f^{n+1}(x; x_0) = (x - x_0)^n \cdot r(x)$$

Remark 6.6. For some function r with $\lim_{x\to x_0} r(x) = 0$, we also denote $o(x-x_0)$ instead of r(x). This general notation is called Landau's Big-Oh notation.

$$f(x) = T_f^n(x; x_0) + (x - x_0)^n \cdot o(x - x_0)$$

Proof. Let $r(x) = \frac{f(x) - T_f^n(x;x_0)}{(x - x_0)^n}$ for $x \neq x_0$ and $r(x_0) \coloneqq 0$. Then f is continuous and T_f^n is continuous in every point $x \neq x_0$. It remains to show that r is continuous in $x = x_0$.

$$r(x) = \frac{1}{(x - x_0)^n} \underbrace{\left(f(x) - T_f^{n-1}(x; x_0) - \frac{1}{n!} f^{(n)}(x_0)(x - x_0)^n \right)}_{R_f^n(x; x_0)}$$

$$= \underbrace{\frac{1}{(x - x_0)} \left[\frac{1}{n!} (x - x_0)^n \cdot f^{(n-1)}(\xi) - \frac{1}{n!} f^{(n)}(x_0)(x - x_0)^n \right]}_{\text{Lagrange}}$$

$$\xi \in (x_0, x)$$

$$= \frac{1}{n!} \left[f^{(n)}(\xi) - f^{(n)}(x_0) \right] \to 0 \text{ for } x \to x_0 \text{ because } f^{(n)} \text{ is continuous}$$

as $x_0 < x < x$, hence $\xi \to x_0$ for $x \to x_0$

So
$$\lim_{x\to x_0} r(x) = 0 = r(x_0)$$
, so r in x_0 is continuous.

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