

Linear Algebra 2 – Lecture Notes

Lukas Prokop

summer term 2016

Contents

1 Linear maps (cont.)	3
1.1 Addition to chapter 5.2.4	3
1.2 Example	3
1.3 More general	3
1.4 Remark and a definition for bilinearity	5
1.5 Example	5
1.6 Example	5
2 Determinants	7
2.1 Properties of determinants	9
2.2 Geometric interpretation of the determinant	11

This lecture took place on 29th of Feb 2016 (Prof. Franz Lehner).

Exam: written and orally

Tutorial session:

- Every Monday, 18:30-20:00, SR 11.34
- Contact: gernot.holler@edu.uni-graz.at

Konversatorium:

- Every Monday, 10:00–10:45, SR 11.33

Topics, wie already discussed:

- Vector spaces
- Linear maps and their equivalence with matrices
- We introduced equivalence of matrices ($PAQ = B$)
- We defined the following techniques:
 - Rank
 - Linear equation system
 - Inverse matrices
 - Basis transformation

In this semester, we will discuss:

- PAP^{-1} , which is related to eigenvalues and diagonalization, hence $\bigvee_P PAP^{-1} = D$.

1 Linear maps (cont.)

1.1 Addition to chapter 5.2.4

$\text{Hom}(V, W)$ in special case $W = \mathbb{K}$. We define,

$$V^* := \text{Hom}(V, \mathbb{K})$$

also denoted V' is called *dual space* of vector space V . The elements $v^* \in V^*$ are called *linear forms* or *linear functionals*.

We denote,

$$v^*(v) =: \langle v^*, v \rangle$$

1.2 Example

$$V = \mathbb{K}^n$$

$v^* : V \rightarrow \mathbb{K}$ is uniquely defined with values $v^*(e_i) =: a_i$.

$$\begin{aligned} \langle v^*, v \rangle &= \left\langle v^*, \sum_{i=1}^n v_i e_i \right\rangle = \sum_{i=1}^n v_i \langle v^*, e_i \rangle \\ \left(v^* \left(\sum_{i=1}^n v_i e_i \right) \right) &= \sum_{i=1}^n v_i v^*(e_i) = \sum_{i=1}^n a_i v_i \end{aligned}$$

1.3 More general

We know, $\dim \text{Hom}(V, W) = \dim V \cdot \dim W$.

Theorem 1. *Let V be a vector space over \mathbb{K} .*

- $\dim V =: n < \infty \Rightarrow \dim V^* = n$
More precisely: Let (b_1, \dots, b_n) be a basis of V . Then

$$b_k^* : b_i \mapsto \delta_{ik} = \begin{cases} 1 & i = k \\ 0 & \text{else} \end{cases}$$

is a basis of V^* and is called dual basis.

- For $v^* \in V^*$ it holds that $v^* = \sum_{k=1}^n \langle v^*, b_k \rangle \cdot b_k^*$.
- If $\dim V = \infty, (b_i)_{i \in I}$ basis, then it holds that

$$(b_k^*)_{k \in I}, \langle b_k^*, b_i \rangle = \delta_{ik}$$

is not a basis of V^* .

Proof. • Special case of 5.18

(b_k^*) is linear independent, hence in $\sum_{i=1}^n \lambda_i b_i^* = 0$ all $\lambda_i = 0$.

$$0 = \left\langle \sum_{i=1}^n \lambda_i b_i^*, b_k \right\rangle = \sum_{i=1}^n \lambda_i \underbrace{\langle b_i^*, b_k \rangle}_{\delta_{ik}} = \lambda_k \forall k$$

- Let $v \in V$ with $v = \sum_{i=1}^n v_i b_i$. We need to show

$$\begin{aligned} \langle v^*, v \rangle &\stackrel{!}{=} \left\langle \sum_{k=1}^n \langle v^*, b_k \rangle b_k^*, v \right\rangle \\ \left\langle \sum_{k=1}^n \langle v^*, b_k \rangle b_k^*, v \right\rangle &= \sum_{k=1}^n \langle v^*, b_k \rangle \langle b_k^*, v \rangle \\ &= \sum_{k=1}^n \langle v^*, b_k \rangle \left\langle b_k^*, \sum_{i=1}^n v_i b_i \right\rangle \\ &= \sum_{k=1}^n \sum_{i=1}^n \langle v^*, b_k \rangle \underbrace{\langle b_k^*, b_i \rangle}_{\delta_{ki}} \cdot v_i \\ &= \sum_{k=1}^n \langle v^*, b_k \rangle \langle v^*, b_k \rangle \cdot v_k \\ &= \left\langle v^*, \sum_{k=1}^n v_k b_k \right\rangle \\ &= \langle v^*, v \rangle \end{aligned}$$

- (To be done in the practicals) Consider the functional

$$\langle v^*, b_i \rangle = 1 \Rightarrow v^* \notin L((v_i^*)_{i \in I})$$

□

1.4 Remark and a definition for bilinearity

The mapping $V^* \times V \rightarrow \mathbb{K}$ is linear in v (with fixed v^*) with $(v^*, v) \mapsto \langle v^*, v \rangle$ is linear in v^* (with fixed v). Such a mapping is called *bilinear*.

A mapping $F : V_1 \times \dots \times V_n \rightarrow W$ is called *multilinear* (n -linear) if it is linear in every component. Formally:

$$\begin{aligned} & F(v_1, \dots, v_{k-1}, \lambda v'_k + \mu v''_k, v_{k+1}, \dots, v_n) \\ &= \lambda F(v_1, \dots, v_{k-1}, v'_k, v_{k+1}, \dots, v_n) + \mu F(v_1, \dots, v_{k-1}, v''_k, v_{k+1}, \dots, v_n) \end{aligned}$$

1.5 Example

$V = \mathbb{K}[x]$ polynomials

Basis: $\{x^k \mid k \in \mathbb{N}_0\}$ and $\dim V = \aleph_0$

Every $v^* \in V^*$ is uniquely defined by $a_k := \langle v^*, x^k \rangle$

$$(a_k)_{k \in \mathbb{N}_0}$$

$V^* \cong \mathbb{K}[[t]]$ are the formal power series

$$= \left\{ \sum_{k=0}^{\infty} a_k t^k \mid a_k \in \mathbb{K} \right\}$$

$$\lambda \sum_{k=0}^{\infty} a_k t^k + \mu \sum_{k=0}^{\infty} b_k t^k = \sum_{k=0}^{\infty} (\lambda a_k + \mu b_k) t^k$$

(Compare with Taylor series $f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n$)

$$\left\langle \sum_{k=0}^{\infty} a_k t^k, \sum_{k=0}^n b_k x^k \right\rangle =: \sum_{k=0}^n a_k b_k \text{ is well-defined}$$

$$\rightarrow \mathbb{K}[x]^* \cong \mathbb{K}[[t]]$$

1.6 Example

$C[0, 1]$ continuous functions

Example:

Example 1.

$$x \in [0, 1] \quad \delta_x : C[0, 1] \rightarrow \mathbb{R}$$

$$f \mapsto f(x)$$

$$\langle \delta_x, f \rangle = f(x)$$

$$\langle \delta_x, f \rangle = f(x)$$

$$I(f) = \int_0^1 f(x) dx \text{ is linear}$$

$$\langle I_g, f \rangle = \int_0^1 f(x) g(x) dx$$

$g \in C[0, 1]$ is fixed

$$\Rightarrow I_g \in C[0, 1]$$

$$\langle I_g, \lambda f_1 + \mu f_2 \rangle' = \int_0^1 (\lambda f_1(x) + \mu f_2(x)) g(x) dx$$

$$= \lambda \int_0^1 f_1(x) g(x) dx + \mu \int_0^1 f_2(x) g(x) dx$$

This also works with non-continuous g (it suffices to have g integrable). (Compare with measure theory and Riesz' theorem)

Does there exist some g such that $f(x) = \langle \delta_x, f \rangle = \int_0^1 f(t) g(t) dt$. (Compare with Dirac's δ function and Schwartz/Sobder theory)

$$V^{**} = (V^*)^* \cong V \text{ if } \dim V < \infty$$

Lemma 1. Let V be a vector space over \mathbb{K} . It requires that $\dim V < \infty$ and the Axiom of Choice holds.

$$\bullet v \in V \setminus \{0\} \Leftrightarrow \bigvee_{v^* \in V^*} \langle v^*, v \rangle \neq 0$$

- $\bigwedge_{v \in V} v = 0 \Leftrightarrow \bigwedge_{v^* \in V^*} \langle v^*, v \rangle = 0$

Proof. Addition v to a basis B of V : Define $v^* \in V^*$ by

$$\langle v^*, b \rangle = \begin{cases} 1 & b = v \\ 0 & b \neq v \end{cases} \text{ for } b \in B$$

Theorem 2. Let V be a vector space over \mathbb{K} .

- The map $\iota : V \rightarrow V^{**} := (V^*)^*$ is called *bidual space*.

$$\langle \iota(v), v^* \rangle := \langle v^*, v \rangle$$

is linear and injective.

- if $\dim V < \infty$, then isomorphism.

Proof. • Linearity

$$\iota(\lambda v + \mu w) \stackrel{!}{=} \lambda \iota(v) + \mu \iota(w)$$

must hold in every point $v^* \in V^*$:

$$\begin{aligned} \langle \iota(\lambda v + \mu w), v^* \rangle &= \langle v^*, \lambda v + \mu w \rangle \\ &= \lambda \langle v^*, v \rangle + \mu \langle v^*, w \rangle \\ &= \lambda \langle \iota(v), v^* \rangle + \mu \langle \iota(w), v^* \rangle \\ &= \langle \lambda \iota(v) + \mu \iota(w), v^* \rangle \end{aligned}$$

Is it injective? Let $v \in \ker \iota$.

$$\langle \iota(v), v^* \rangle = 0 \quad \forall v^* \in V^*$$

$$\Rightarrow \langle v^*, v \rangle = 0 \quad \forall v^* \in V^*$$

$$\xrightarrow{\text{Lemma 1}} v = 0$$

- Follows immediately, because the dimension is equal.

Definition 1. Let V, W be vector spaces over \mathbb{K} . $f \in \text{Hom}(V, W)$. We define $f^T \in \text{Hom}(W^*, V^*)$ using $f^T(w^*) \in V^*$ via

$$\langle f^T(w^*), v \rangle = \langle w^*, f(v) \rangle = w^*(f(v)) = w^* \circ f(v)$$

$$f^T(w^*) = w^* \circ f \text{ is linear} \Rightarrow f^T(w^*) \in V^*$$

V to W (with f) and W to \mathbb{K} (with w^*).

□ f^T is called *transposed map*.

Example 2. (See practicals) Let $\dim V = n$ and $\dim W = m$ with $B \subseteq V$ and $C \subseteq W$ as bases and dual bases $B^* \subseteq V^*$ and $C^* \subseteq W^*$

$$\Phi_{B^*}^{C^*}(f^T) = \Phi_C^B(f)^T \quad \text{transposition of matrices}$$

This lecture took place on 2nd of March 2016 (Franz Lehner).

2 Determinants

Leibnitz 1693 (3×3 matrices)

Seki Takukazu 1685 (most general version)

Gauß 1801 (“determinant”)

Cayley 1845 (on matrices)

$$n = 2$$

$$ax + by = e$$

$$cx + dy = f$$

$$\begin{array}{cc|c} a & b & e \\ c & d & f \end{array}$$

1. Case 1: $a \neq 0$ (multiply first row $-\frac{a}{b}$ times second row)

$$\begin{array}{cc|c} a & b & \\ c & d & \\ \hline a & b & \\ 0 & d - \frac{bc}{a} & \end{array}$$

□

Unique solution:

$$d - \frac{bc}{a} \neq 0$$

2. Case 2: $c \neq 0$ (multiple second row $-\frac{a}{c}$ times first row)

$$\begin{array}{cc} a & b \\ c & d \\ 0 & b - \frac{ad}{c} \\ c & d \end{array}$$

Unique solution:

$$b - \frac{ad}{c} \neq 0$$

This gives us

$$ad - bc \neq 0$$

Definition 2.

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc = \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

is called determinant of $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$.

2.1 Properties of determinants

- The determinant is bilinear in the columns and rows.

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} = (v, w)$$

where v and w are column vectors of A .

$$\det(\lambda v_1 + \mu v_2, w) = \lambda \det(v_1, w) + \mu \det(v_2, w)$$

$$\det(v, \lambda w + \mu w_2) = \lambda \det(v, w_1) + \mu \det(v, w_2)$$

$$\det(\lambda v_1 + \mu v_2, w) = \begin{vmatrix} \lambda a_1 + \mu a_2 & b \\ \lambda c_1 + \mu c_2 & d \end{vmatrix}$$

$$= (\lambda a_1 + \mu a_2)d - (\lambda c_1 + \mu c_2)b$$

$$= \lambda(a_1d - c_1b) + \mu(a_2d - c_2b)$$

$$= \lambda \begin{vmatrix} a_1 & b \\ c_1 & d \end{vmatrix} + \mu \begin{vmatrix} a_2 & b \\ c_2 & d \end{vmatrix}$$

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & c \\ b & d \end{vmatrix}$$

- $\det(v, v) = 0$.

$$\begin{vmatrix} a & a \\ c & c \end{vmatrix} = ac - ac = 0$$

-

$$\det \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \det(e_1, e_2) = 1$$

Theorem 3. The properties 1–3 of determinants (see above) characterize the determinant.

Let $\varphi : \mathbb{K}^2 \times \mathbb{K}^2 \rightarrow \mathbb{K}$

- bilinear
- $\bigwedge_{v \in \mathbb{K}^2} \varphi(v, v) = 0$
- $\varphi(e_1, e_2) = 1$. Then it holds that $\varphi = \det$.

Proof. To show: $\varphi(v, w) = \det(v, w) \forall v, w \in \mathbb{K}^2$

$$v = \underbrace{ae_1 + ce_2}_{\begin{pmatrix} a \\ c \end{pmatrix}} \quad w = \underbrace{be_1 + de_2}_{\begin{pmatrix} b \\ d \end{pmatrix}}$$

$$\varphi(v, w) = \varphi(ae_1 + ce_2, be_1 + de_2)$$

$$= a\varphi(e_1, be_1 + de_2) + c \cdot \varphi(e_2, be_1 + de_2)$$

$$= ad \underbrace{\varphi(e_1, e_2)}_{=1} + \underbrace{ab\varphi(e_1, e_1)}_{=0} + cb\varphi(e_2, e_1) + cd \underbrace{\varphi(e_2, e_2)}_{=0}$$

□

Lemma 2. From (i) bilinearity and (ii) $\bigwedge_{v \in \mathbb{K}^2} \varphi(v, v) = 0$ it follows that

$$\bigwedge_{v, w \in \mathbb{K}^2} \varphi(v, w) = -\varphi(w, v)$$

$$\begin{aligned} 0 &\stackrel{(ii)}{=} \varphi(v+w, v+w) \stackrel{(i)}{=} \varphi(v, v) + \varphi(v, w) + \varphi(w, v) + \varphi(w, w) \\ &\stackrel{(ii)}{=} \varphi(v, w) + \varphi(w, v) \end{aligned}$$

2.2 Geometric interpretation of the determinant

Consider an area with w defining its breath and v its depth (hence the area spanning vectors). Let e_1 and e_2 be the spanning vectors of a rectangle corresponding to the parallelogram. $\det(v, w)$ is the surface of the spanned parallelogram. The sign defines the orientation of the pair (v, w) .

$$\det(e_1, e_2) = 1 \quad \det(e_2, e_1) = -1$$

There are surfaces where the surface is infinite if you follow a vector in some direction:

- Möbius strip
- Klein's bottle (named after Felix Klein)

$$A = |v| \cdot h$$

Consider Figure 1. h is the length of the projection of w to v^\perp .

$$\begin{aligned} v = \begin{pmatrix} a \\ b \end{pmatrix} &\rightarrow \vec{n} = \begin{pmatrix} -b \\ a \end{pmatrix} \\ \left\langle \begin{pmatrix} c \\ d \end{pmatrix}, \begin{pmatrix} -b \\ a \end{pmatrix} \right\rangle &= ad - bc \end{aligned}$$

Second proof. $A(v, w)$ satisfies properties (i)–(iii).

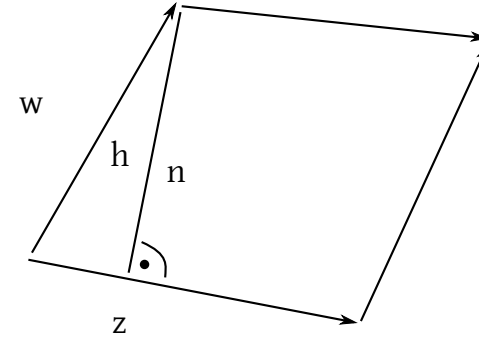


Figure 1: Parallelogram

- Property (iii) follows immediately (the area of unit vectors in two dimensions is 1).
- Property (ii) follows immediately (the area of two vectors in the same direction is 0).

Property (i) defines the linearity in v

1. If v, w are linear dependent, then $A(v, w) = 0$ (one is a multiple of the other)
2. $n \in \mathbb{N}$ with $A(nv, w) = nA(v, w)$

3. For $\tilde{v} = n \cdot v$:

$$A(\tilde{v}, w) = n \cdot A\left(\frac{\tilde{v}}{n}, w\right)$$

$$\Rightarrow A\left(\frac{\tilde{v}}{n}, w\right) = \frac{1}{n} A(\tilde{v}, w)$$

$$A(nv, w) = nA(v, w)$$

$$A\left(\frac{1}{n}v, w\right) = \frac{1}{n}A(v, w)$$

$$A\left(\frac{m}{n}v, w\right) = \frac{m}{n}A(v, w)$$

$$A(-v, w) = -A(v, w)$$

From continuity it follows that $A(\lambda v, w) = \lambda A(v, w)$ for $\lambda \in \mathbb{R}$. Analogously $A(v, \lambda w) = \lambda A(v, w)$.

4. The sum is given with

$$A(v + w, w) = A(v, w)$$

Compare with Figure 2, where $\text{area}(2) + \text{area}(3) = \text{area}(2) + \text{area}(1)$.

$$\begin{aligned} A(\lambda v + \mu w, w) &= A\left(\lambda v + \mu w, \frac{1}{\mu} \mu w\right) \\ &= \frac{1}{\mu} A(\lambda v + \mu w, \mu w) \\ &= \frac{1}{\mu} A(\lambda v, \mu w) \\ &= A(\lambda v, w) \end{aligned}$$

General case: v, w are linear independent and therefore basis of \mathbb{R}^2 . Besides that, v_1 and v_2 are arbitrary.

$$v_1 = \lambda_1 v + \mu_1 w$$

$$v_2 = \lambda_2 v + \mu_2 w$$

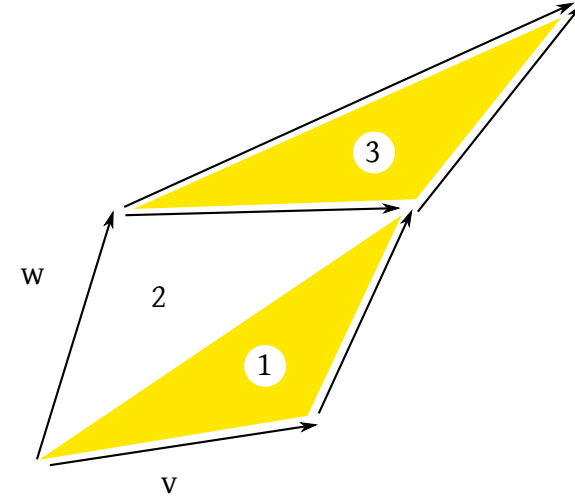


Figure 2: Translation of area 1 to area 3.

$$\begin{aligned} A(v_1 + v_2, w) &= A(\lambda_1 v + \mu_1 w + \lambda_2 v + \mu_2 w, w) \\ &= A((\lambda_1 + \lambda_2)v + (\mu_1 + \mu_2)w, w) \\ &= A((\lambda_1 + \lambda_2)v, w) \\ &= (\lambda_1 + \lambda_2)A(v, w) \\ &= A(\lambda_1 v, w) + A(\lambda_2 v, w) \end{aligned}$$

$$A(\lambda_1 v + \mu_1 w, w) + A(\lambda_2 v + \mu_2 w, w) = A(v_1, w) + A(v_2, w)$$

Additivity follows.

□

Definition 3. Let $\dim V = n$. A determinant form is a map

$$\Delta : V^n \rightarrow \mathbb{K}$$

with properties:

1.

$$\bigwedge_{\lambda} \bigwedge_k \bigwedge_{a_1, \dots, a_n \in V} \Delta(a_1, \dots, a_{k-1}, \lambda a_k, a_{k+1}, \dots, a_n) = \lambda \Delta(a_1, \dots, a_k, \dots, a_n)$$

2.

$$\begin{aligned} \bigwedge_k \bigwedge_{\substack{a_1, \dots, a_n \\ a'_k, a''_k}} \Delta(a_1, \dots, a_{k-1}, a'_k + a''_k, a_{k+1}, \dots, a_n) \\ := \Delta(a_1, \dots, a_{k-1}, a'_k + a''_k, a_{k+1}, \dots, a_n) \end{aligned}$$

3.

$$\Delta(a_1, \dots, a_n) = 0$$

if $\bigvee_{k \neq l} a_k = e_l$ if $\Delta \neq 0$, i.e. Δ is non-trivial.

Multilinearity is defined by the first two properties. Multilinearity means linearity in a_k if $a_1, \dots, a_{k-1}, a_{k+1}, \dots, a_n$ get fixed.

Theorem 4.

$$\dim V = n$$

$$\Delta : V^n \rightarrow \mathbb{K} \text{ is determinant form}$$

Then,

4.

$$\bigwedge_{\lambda \in \mathbb{K}} \bigwedge_{i \neq j} \Delta(a_1, \dots, a_{i-1}, a_i + \lambda a_j, a_{i+1}, \dots, a_n) = \Delta(a_1, \dots, a_i, \dots, a_n)$$

“Addition of λa_j to a_i does not change Δ ”

5.

$$\begin{aligned} \bigwedge_{i > j} \Delta(a_1, \dots, a_{j-1}, a_i, a_{j+1}, \dots, a_{i-1}, a_j, a_{i+1}, \dots, a_n) \\ = -\Delta(a_1, \dots, a_j, \dots, a_i, \dots, a_n) \end{aligned}$$

“Exchanging a_i with a_j inverts the sign”

Proof. 4.

$$\Delta(a_1, \dots, a_i + \lambda a_j, \dots, a_n)$$

Without loss of generality: $i < j$. From properties 1 and 2 it follows that:

$$= \Delta(a_1, \dots, a_i, a_j, a_n) + \lambda \Delta(a_1, \dots, a_j, a_j, \dots, a_k)$$

Oh, a_j occurs twice! Once at index i and once at index j .

$$= 0$$

due to property 3.

5.

$$\begin{aligned} 0 &\stackrel{\text{property 3}}{=} \Delta(a_1, \dots, a_{i-1}, a_i + a_j, \dots, a_{j-1}, a_i + a_j, \dots, a_n) \\ &= \Delta(a_1, \dots, a_{i-1}, \mathbf{a}_i, \dots, a_{j-1}, \mathbf{a}_i, \dots, a_n) = \mathbf{0} \\ &+ \Delta(a_1, \dots, a_{i-1}, \mathbf{a}_i, \dots, a_{j-1}, \mathbf{a}_j, \dots, a_n) \\ &+ \Delta(a_1, \dots, a_{i-1}, \mathbf{a}_j, \dots, a_{j-1}, \mathbf{a}_i, \dots, a_n) \\ &+ \Delta(a_1, \dots, a_{i-1}, \mathbf{a}_j, \dots, a_{j-1}, \mathbf{a}_j, \dots, a_n) = \mathbf{0} \\ &\Rightarrow \delta \end{aligned}$$

□

Definition 4. A permutation of order n is a bijective mapping $\pi : \{1, \dots, n\} \rightarrow \{1, \dots, n\}$.

$\sigma_n =$ set of all permutations

Remark 1. Notation: We write the elements in the first row and their images in the second row.

Definition 5. σ_n constitutes (in terms of composition) a group with neutral element id , the so-called symmetric group.

In the previous course (Theorem 1.40) we have proven: Compositions of bijective functions are bijective. 1.

Remark 2. For $n \geq 3$, σ_n is non-commutative

Theorem 5.

$$|\sigma_n| = n!$$

Remark 3. These are “a lot”!

Example 3.

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 4 & 1 & 3 & 2 \end{pmatrix} \circ \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 3 & 4 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 4 & 3 & 2 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 4 & 1 & 3 & 2 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 3 & 1 \end{pmatrix}$$

Definition 6. A transposition is a permutation of the structure

$$\tau = \tau_{ij} : \begin{array}{l} i \mapsto j \\ j \mapsto i \text{ if } k \notin \{i, j\} \\ k \mapsto k \end{array}$$

Then $\tau_{ij}^{-1} = \tau_{ij}$, hence $\tau_{ij}^2 = \text{id}$.

Theorem 6. σ_n is generated by transpositions. With other words, every permutation π can be represented as composition of transpositions

$$\pi = \tau_1 \circ \dots \circ \tau_k$$

Proof.

$$\pi = \begin{pmatrix} 1 & 2 & \dots & n \\ \pi(1) & \pi(2) & \dots & \pi(n) \end{pmatrix}$$

If $\pi = \text{id}$,

$$\pi = \pi \circ \tau := \text{id}$$

If $\pi \neq \text{id}$,

$$k_1 = \min \{k \mid k \neq \pi(k)\}$$

$$\tau_1 = \tau_{k_1 \pi(k_1)}$$

$$\pi_1 = \tau_1 \circ \pi = \begin{pmatrix} 1 & \dots & k-1 & k_1 & \dots \\ 1 & \dots & k-1 & k_1 & \dots \end{pmatrix}$$

Example: Consider $\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 1 & 3 & 5 & 4 & 7 & 6 & 2 \end{pmatrix}$.

$$k_1 = 2$$

$$\tau_1 = \tau_{23}$$

$$\pi_1 = \tau_1 \circ \pi = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 1 & 2 & 5 & 4 & 7 & 6 & 3 \end{pmatrix}$$

2.

$$k_2 = \min \{k \mid k \neq \pi_1(k)\} > k_1$$

$$\tau_2 = \tau_{k_2, \pi(k_2)}$$

And so on and so forth. $k_j > k_{j-1}$ ends after $\leq n$ steps.

$$\tau_k \circ \tau_{k-1} \circ \dots \circ \tau_1 \circ \pi = \text{id}$$

$$\Rightarrow \pi = \tau_1 \circ \tau_2 \circ \dots \circ \tau_k$$

Regarding the example:

$$k_2 = 3$$

$$\tau_2 = \tau_{35}$$

$$\pi_2 = \tau_2 \circ \pi_1 = \tau_2 \circ \tau_1 \circ \pi = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 1 & 2 & 3 & 4 & 7 & 6 & 5 \end{pmatrix}$$

$$k_3 = 5 \quad \tau_3 = \tau_{57}$$

$$\Rightarrow \pi = \tau_{23} \circ \tau_{35} \circ \tau_{57}$$

□

Definition 7. A malposition of π is a pair (i, j) such that $i < j$ with $\pi(i) > \pi(j)$. Let F_π be the set of malpositions of π .

$$f_\pi := |F_\pi|$$

$$\text{sign}(\pi) := (-1)^{f_\pi} =: (-1)^\pi$$

Example 4.

$$\pi = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 1 & 3 & 5 & 4 & 7 & 6 & 2 \end{pmatrix}$$

$$F_\pi = \{(2, 7), (3, 4), (3, 7), (4, 7), (5, 6), (5, 7), (6, 7)\}$$

$$f_\pi = 7 \quad \text{sign}(\pi) = -1$$

This lecture took place on 7th of March 2016 (Franz Lehner).

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

Recall: Determinant form:

1. $\Delta(a_1, \dots, \lambda a_k, \dots, a_n) = \lambda \Delta(a_1, \dots, a_n)$
2. $\Delta(a_1, \dots, a'_k + a''_k, \dots, a_n) = \Delta(a_1, \dots, a'_k, \dots, a_n) + \Delta(a_1, \dots, a''_k, \dots, a_n)$
3. $\Delta(a_1, \dots, a_k, \dots, a_l, \dots, a_n) = 0$ if $a_k = a_l$

Conclusions:

4. $\Delta(a_1, \dots, a_k + \lambda a_l, \dots, a_n) = \Delta(a_1, \dots, a_n)$ if $k \neq l$
5. $\Delta(a_1, \dots, a_k, \dots, a_l, \dots, a_n) = -\Delta(a_1, \dots, a_l, \dots, a_k, \dots, a_n)$

$$\Delta(a_{\pi(1)}, \dots, a_{\pi(n)}) = (-1)^k \Delta(a_1, \dots, a_n)$$

Decompose $\pi = \tau_1 \circ \dots \circ \tau_k \circ \tau_{12} \circ \tau_{12}$. This decomposition is not distinct (k is distinct mod 2)

$$\pi \in \sigma_n \quad \text{permutation}$$

$$F_\pi = \{(i, j) \mid i < j, \pi(i) > \pi(j), \text{ malpositions} \}$$

$$f_\pi = |F_\pi|$$

$$\text{sign}(\pi) := (-1)^{f_\pi} =: (-1)^\pi$$

Theorem 7. • $\bigwedge_{\pi \in \sigma_n} \text{sign}(\pi) = \prod_{1 \leq i < j \leq n} \frac{\pi(j) - \pi(i)}{j - i}$

• For transposition τ it holds that $\text{sign}(\tau) = -1$

Proof. • Every pair $\{i, j\}$ occurs in the enumerator exactly once.

$$\frac{\prod_{i < j} \pi(j) - \pi(i)}{\prod_{i < j} (j - i)}$$

Denominator: $j > i$, positive. Enumerator: positive if $\pi(j) > \pi(i)$, negative if $\pi(i) > \pi(j)$.

•

$$\tau = \begin{pmatrix} 1 & \dots & k & \dots & l & \dots & n \\ 1 & \dots & l & \dots & k & \dots & n \end{pmatrix}$$

$$F_\tau(\underbrace{((k, k+1), (k, k+2), \dots, (k, l-1), (k, l))}_{\text{malpositions with } k, l-k \text{ times}}, \underbrace{((k+1, l), \dots, (l-1, l))}_{l-k-1 \text{ times}})$$

Example:

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 \\ 1 & 2 & 3 & 8 & 5 & 6 & 7 & 4 & 9 & 10 \end{pmatrix}$$

Yields 7 malpositions (8 needs to be repositioned with 3 transpositions, 4 needs to be repositions with 4 transpositions).

□

$$\text{sign}(\pi) = \prod_{i < j} \frac{\pi(j) - \pi(i)}{j - i} \quad \binom{n}{2} \text{ factors}$$

$$\text{sign}(\tau) = -1$$

Theorem 8. 1. $\text{sign}(id) = 1$

2. $\text{sign}(\pi \circ \sigma) = \text{sign}(\pi) \cdot \text{sign}(\sigma)$, hence

$$\text{sign } \sigma_n \rightarrow (\{+1, -1\}, \cdot)$$

is a group homomorphism. (In general: A group homomorphism $h : G \rightarrow (\mathcal{T}, \cdot)$ is called character)

3. $\text{sign}(\pi^{-1}) = \text{sign}(\pi)$

Remark 4.

$$\mathcal{T} = \{z \in \mathbb{C} \mid |z| = 1\}$$

Torus with multiplication is a group.

$$|z_1 \cdot z_2| = |z_1| \cdot |z_2| = 1$$

Proof. 1. trivial

2.

$$\begin{aligned} \text{sign}(\pi \cdot \sigma) &= \prod_{i < j} \frac{\pi \circ \sigma(j) - \pi \circ \sigma(i)}{j - i} \\ &= \underbrace{\prod_{i < j} \frac{\pi(\sigma(j)) - \pi(\sigma(i))}{\sigma(j) - \sigma(i)}}_{=\text{sign}(\pi)} \cdot \underbrace{\prod_{i < j} \frac{\sigma(j) - \sigma(i)}{j - i}}_{=\text{sign}(\sigma)} \end{aligned}$$

3. Group homomorphism!

Corollary 1. • If $\pi = \tau_1 \circ \tau_2 \circ \dots \circ \tau_k$, product of transpositions

$$\Rightarrow \text{sign}(\pi) = (-1)^k$$

• $\mathfrak{a}_n := \ker(\text{sign}) = \{\pi \in \sigma_n \mid \text{sign}(\pi) = 1\}$

“even permutations”, “alternating group”

$$|\mathfrak{a}_n| = \frac{n!}{2}$$

Corollary 2.

$$\Delta : V^k \rightarrow \mathbb{K} \text{ determinant form}$$

then it holds that

$$\bigwedge_{\pi \in \sigma_n} \bigwedge_{a_1, \dots, a_n \in V} \Delta(a_{\pi(1)}, \dots, a_{\pi(n)}) = \text{sign}(\pi) \cdot \Delta(a_1, \dots, a_n)$$

Proof. • If $\pi = \tau_{kl}$ transposition $\xrightarrow{\text{Theorem 4}} \Delta(a_{\tau(1)}, \dots, a_{\tau(n)}) = -\Delta(a_1, \dots, a_n) = \text{sign}(\tau_{kl}) \cdot \Delta(a_1, \dots, a_n)$

• If $\pi = \tau_1 \circ \dots \circ \tau_k = \tau_1 \circ \tilde{\pi}, \tilde{\pi} = \tau_2 \circ \dots \circ \tau_k$

$$\Delta(a_{\tau_1 \circ \tilde{\pi}(1)}, \dots, a_{\tau_1 \circ \tilde{\pi}(n)}) = -\Delta(a_{\tilde{\pi}(1)}, \dots, a_{\tilde{\pi}(n)}) = (-1)^2 \cdot \Delta(a_{\tilde{\pi}(1)}, a_{\tilde{\pi}(n)}) \rightarrow (-1)^k \cdot \Delta(a_1, \dots, a_n)$$

□

Theorem 9 (Leibnitz’ definition of $\det(A)$). Let $B = (b_1, \dots, b_n)$ be the basis of V . $a_1, \dots, a_n \in V$ with coordinates

$$\Phi_B(a_j) = \begin{bmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{nj} \end{bmatrix}$$

$$A := [a_{ij}]_{i,j=1,\dots,n} = [\Phi_B(a_1), \Phi_B(a_2), \dots, \Phi_B(a_n)]$$

Then it holds that for every determinant form $\Delta : V^k \rightarrow \mathbb{K}$:

$$\Delta(a_1, \dots, a_n) = \det(A) \cdot \Delta(b_1, \dots, b_n)$$

where

$$\det(A) := \sum_{\pi \in \sigma_n} \text{sign}_{\mathbb{K}} \pi a_{\pi(1),1} a_{\pi(2),2} \dots a_{\pi(n),n}$$

is the determinant of A

Example 5. Example ($n = 2$):

$$\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11} \cdot a_{22} - a_{12} \cdot a_{21}$$

$$\text{sign} \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix} = 1$$

$$\text{sign} \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = -1$$

Proof.

$$a_j = \sum_{i=1}^n a_{ij} b_i$$

$$\begin{aligned} \Delta(a_1, \dots, a_n) &= \Delta \left(\sum_{i=1}^n a_{i,1} b_i, \sum_{i=2}^n a_{i,2} b_i, \dots, \sum_{i=n}^n a_{i,n} b_i \right) \\ &= \sum_{i_1=1}^n a_{i_1,1} \sum_{i_2=1}^n a_{i_2,2} \dots \sum_{i_n=1}^n a_{i_n,n} \underbrace{\Delta(b_{i_1}, b_{i_2}, \dots, b_{i_n})}_{=0 \text{ if some } i_k = i_l} \end{aligned}$$

So summands with equal indices disappear. It holds that \sum_{i_1, \dots, i_n} such that i_1, \dots, i_n are different. Hence every value from $\{1, \dots, n\}$ occurs exactly once. This is the set of all permutations π ($i_j = \pi(j)$)

$$= \sum_{\pi \in \sigma_n} a_{\pi(1),1} a_{\pi(2),2} \dots a_{\pi(n),n} \underbrace{\Delta(b_{\pi(1)}, \dots, b_{\pi(n)})}_{\text{sign}(\pi) \cdot \Delta(b_1, \dots, b_n)}$$

□

Corollary 3. A determinant form is uniquely defined on a basis (b_1, \dots, b_n) by the value $\Delta(b_1, \dots, b_n)$. Especially Δ is nontrivial,

$$\Leftrightarrow \Delta(b_1, \dots, b_n) \neq 0 \text{ on some basis.}$$

$$\Leftrightarrow \Delta(b_1, \dots, b_n) \neq 0 \text{ in every basis } b_1, \dots, b_n.$$

Let $\Delta(b'_1, \dots, b'_n) = 0$ for some other basis, represent b_1, \dots, b_n in basis b'_1, \dots, b'_n

$$b_j = \sum a_{ij} b'_i \Rightarrow \Delta(b_1, \dots, b_n) = \det(A) \cdot \Delta(b'_1, \dots, b'_n) = 0$$

$$\Delta(a_1, \dots, a_n) = \det(A) \cdot \Delta(b_1, \dots, b_n)$$

Theorem 10. Let $B = (b_1, \dots, b_n)$ be a basis of V over \mathbb{K} . $c \in \mathbb{K}$. For $a_1, \dots, a_n \in V$, let $A = [\Phi_B(a_1), \dots, \Phi_B(a_n)]$. Then

$$\Delta(a_1, \dots, a_n) = c \cdot \det(A)$$

defines a determinant form, specifically the unique determinant form with value

$$\Delta(b_1, \dots, b_n) = c$$

Proof. The 3 properties of a determinant form:

1.

$$\begin{aligned} \Delta(a_1, \dots, \lambda a_k, \dots, a_n) &= c \cdot \det[\Phi_B(a_1), \dots, \lambda \cdot \Phi_B(a_k), \dots, \Phi_B(a_n)] \\ &= c \cdot \sum_{\pi \in \sigma_n} \text{sign } \pi \cdot a_{\pi(1),1} a_{\pi(2),2} \dots - \lambda a_{\pi(k),k} \dots a_{\pi(n),n} \\ &= \lambda \cdot c \cdot \sum_{\pi \in \sigma_n} \text{sign } \pi \cdot a_{\pi(1),1} a_{\pi(2),2} \dots a_{\pi(n),n} \\ &= \lambda \cdot \Delta(a_1, \dots, a_n) \end{aligned}$$

2.

$$\begin{aligned} &= \Delta(a_1, \dots, a'_k + a''_k, \dots, a_n) \\ &= c \cdot \det[\Phi_B(a_1), \dots, \Phi_B(a'_k) + \Phi_B(a''_k), \dots, \Phi_B(a_n)] \\ &= c \cdot \sum_{\pi \in \sigma_n} \text{sign } \pi \cdot a_{\pi(1),1} \cdot a_{\pi(2),2} \dots (a'_{\pi(k),k} + a''_{\pi(k),k}) \dots a_{\pi(n),n} \\ &= c \cdot \sum_{\pi \in \sigma_n} \text{sign } \pi \cdot a_{\pi(1),1} \cdot a'_{\pi(k),k} \dots a_{\pi(n),n} + c \cdot \sum_{\pi \in \sigma_n} \text{sign}(\pi) a_{\pi(1),1} \dots a''_{\pi(k),k} \dots a_{\pi(n),n} \\ &= \Delta(a_1, \dots, a'_k, \dots, a_n) + \Delta(a_1, \dots, a''_k, \dots, a_n) \end{aligned}$$

3. Let $a_k = a_l$ for $k < l$. Show that $\Delta(a_1, \dots, a_n) = 0$

τ_{kl} = transposition exchanging k and l

$$\sigma_n = \mathbf{a}_n \dot{\cup} (\mathbf{a}_n \cdot \tau_{kl})$$

$$\text{Claim: } \{\pi \mid \text{sign } \pi = -1\} = \{\pi \circ \tau_{kl} \mid \text{sign } \pi = +1\}$$

$$\supseteq \text{ If } \text{sign } \pi = +1 \Rightarrow \text{sign}(\pi \circ \tau_{kl}) = \underbrace{\text{sign } \pi}_{+1} \cdot \underbrace{\text{sign } \tau_{kl}}_{-1} = -1$$

$$\subseteq \text{ If } \text{sign } \pi = -1 \Rightarrow \text{sign}(\pi \circ \tau_{kl}) = +1 \Rightarrow \pi = \underbrace{(\pi \circ \tau_{kl}) \circ \tau_{kl}}_{\in \mathfrak{a}_n} \in \mathfrak{a}_n \cdot \tau_{kl}$$

$$\begin{aligned} \Delta(a_1, \dots, a_n) &= c \cdot \sum_{\pi \in \sigma_n = \mathfrak{a}_n \cup \mathfrak{a}_n \cdot \tau_{kl}} \text{sign}(\pi) a_{\pi(1),1} \dots a_{\pi(n),n} \\ &= c \cdot \sum_{\pi \in \mathfrak{a}_n} a_{\pi(1),1} \dots a_{\pi(n),n} \\ &\quad - \sum_{\pi \in \mathfrak{a}_n} a_{\pi \circ \tau_{kl}(1),1} \dots a_{\pi \circ \tau_{kl}(k),k} \dots a_{\pi \circ \tau_{kl}(l),l} \dots a_{\pi \circ \tau_{kl}(n),n} \\ &= c \cdot \sum_{\pi \in \mathfrak{a}_n} a_{\pi(1),1} \dots a_{\pi(n),n} \end{aligned}$$

What we did:

- (a) $a_{\pi(l),k} = a_{\pi(l),l}$ and $a_{\pi(k),l} = a_{\pi(k),k}$ because $a_k = a_l$
- (b) exchange factors

$$\begin{aligned} &= c \sum_{\pi \in \mathfrak{a}_n} a_{\pi(1),1} \dots a_{\pi(k),k} \dots a_{\pi(l),l} \dots a_{\pi(n),n} \\ &\quad - c \sum_{\pi \in \mathfrak{a}_n} a_{\pi(1),1} \dots a_{\pi(k),k} \dots a_{\pi(l),l} \dots a_{\pi(n),n} \\ &= 0 \end{aligned}$$

Value for (b_1, \dots, b_n)

$$a_{ij} = \delta_{ij} \Rightarrow A = I$$

$$\det(I) = \sum_{\pi \in \sigma_n} \text{sign } \pi \cdot \delta_{\pi(1),1} \dots \delta_{\pi(n),n} = +1$$

for all $\pi(j) = j$ otherwise 0.

$\Rightarrow \pi = \text{id}$ is the only summand

$$\Delta(b_1, \dots, b_n) = \det(I) \cdot c = c$$

Remark 5. “ \mathfrak{a}_n is the subgroup of index 2” $[\sigma_n : \mathfrak{a}_n] = 2$

You might be familiar with:

$$\mathbb{Z}_n = \mathbb{Z}/n\mathbb{Z}$$

$$[\mathbb{Z} : n\mathbb{Z}] = n$$

Theorem 11 (Summary). • The set of determinant forms $\Delta : V^n \rightarrow \mathbb{K}$ constructs a one-dimensional vector space, $\Lambda^n V$

- There exists a non-trivial determinant form with $\Delta(b_1, \dots, b_n) = 1$

This lecture took place on 9th of March 2016 (Franz Lehner).
Revision: $-\sum_{\pi \in \mathfrak{a}_n} a_{\pi(1),1} \dots a_{\pi(l),k} \dots a_{\pi(k),l} \dots a_{\pi(n),n}$

$$\Delta : V^n \rightarrow \mathbb{K}$$

$$\Delta(a_1, \dots, a_n) = \det A \cdot \Delta(b_1, \dots, b_n)$$

$$\phi_B(a_j) = \begin{pmatrix} a_{1j} \\ \vdots \\ a_{nj} \end{pmatrix}$$

$$\det A = \sum_{\pi \in \sigma_n} \text{sign } \pi \cdot a_{\pi(1),1} \dots a_{\pi(n),n}$$

$$\Delta(v_1, \dots, v_n) \neq 0 \Leftrightarrow v_1, \dots, v_n \text{ linear independent } (\Leftrightarrow \text{basis})$$

Theorem 12.

$$\det(A \cdot B) = \det(A) \cdot \det(B)$$

Lemma 3. Let V, W be vector spaces over \mathbb{K} with $\dim V = \dim W = n$.

$$\Delta : W^n \rightarrow \mathbb{K}$$

$$f : V \rightarrow W$$

$$\begin{aligned} \Rightarrow f^n : V^n &\rightarrow W^n \xrightarrow{\Delta} \mathbb{K} \\ (v_1, \dots, v_n) &\mapsto (f(v_1), \dots, f(v_n)) \end{aligned}$$

Then $\Delta^f : V^n \rightarrow \mathbb{K}$

$$\Delta^f(v_1, \dots, v_n) = \Delta(f(v_1), \dots, f(v_n))$$

is a determinant form in V .

Proof. 1.

$$\begin{aligned} \Delta f(v_1, \dots, \lambda v_k, \dots, v_n) &= \Delta(f(v_1), \dots, f(\lambda v_k), \dots, f(v_n)) \\ &= \lambda \Delta(f(v_1), \dots, f(v_n)) \\ &= \lambda \cdot \Delta^f(v_1, \dots, v_n) \end{aligned}$$

2.

$$\begin{aligned} &= \Delta^f(v_1, \dots, v'_k + v''_k, \dots, v_n) \\ &= \Delta(f(v_1), \dots, f(v'_k + v''_k), \dots, f(v_n)) \\ &= \Delta(f(v_1), \dots, f(v'_k) + f(v''_k), \dots, f(v_n)) \\ &= \Delta(f(v_1), \dots, f(v'_k), \dots, f(v_n)) + \Delta(f(v_1), \dots, f(v''_k), \dots, f(v_n)) \\ &= \Delta^f(v_1, \dots, v'_k, \dots, v_n) + \Delta^f(v_1, \dots, v''_k, \dots, v_n) \end{aligned}$$

3.

$$\begin{aligned} \Delta^f(v_1, \dots, v_k, \dots, v_l, \dots, v_n) \quad v_k = v_l &\Rightarrow f(v_k) = f(v_l) \\ &= \Delta(f(v_1), \dots, f(v_k), \dots, f(v_l), \dots, f(v_n)) \\ &= 0 \end{aligned}$$

□

Corollary 4 (Conclusions for $V = W$).

$$\Delta : V^n \rightarrow \mathbb{K}$$

non-trivial determinant form

$$f : V \rightarrow V$$

$\Rightarrow \Delta^f$ is a determinant form

$$\dim \bigwedge^n V = 1 \Rightarrow \bigvee_{c_f \in \mathbb{K}} \Delta^k = c_f \cdot \Delta$$

$c_f =: \det f$ is called determinant of f

Corollary 5. Let V , Δ and f be like above.

1. For every basis $B = (b_1, \dots, b_n)$ it holds that

$$\Delta^f(b_1, \dots, b_n) = \Delta(f(b_1), \dots, f(b_n)) = \det(f) \cdot \Delta(b_1, \dots, b_n)$$

$$\det(f) = \frac{\Delta(f(b_1), \dots, f(b_n))}{\Delta(b_1, \dots, b_n)}$$

2. with $a_j = f(b_j)$ it holds that

$$\det \Phi_B^B(f) = \det(f)$$

$$A = \Phi_B^B(f)$$

a_{ij} = i -th coordinate of $f(b_j)$ and $s_j(A) = \Phi_B(f(b_j))$.

Theorem 13. Let $f : V \rightarrow V$ be an isomorphism $\Leftrightarrow \det(f) \neq 0$.

Proof. Let f be an isomorphism.

$$\begin{aligned} &\Leftrightarrow (f(b_1), \dots, f(b_n)) \text{ is basis} \\ &\Leftrightarrow \Delta(f(b_1), \dots, f(b_n)) \neq 0 \\ &\Leftrightarrow \det(f) \cdot \Delta(b_1, \dots, b_n) \\ &\Leftrightarrow \det(f) \neq 0 \end{aligned}$$

□

Theorem 14. Let $f, g : V \rightarrow V$ be linear.

$$\Rightarrow \det(f \circ g) = \det(f) \cdot \det(g)$$

Remark 6. We show: $f \circ g$ is isomorphism $\Leftrightarrow f$ and g are isomorphisms.

If f, g are invertible, then $f \circ g$ are invertible.

1.

$$(f \circ g)^{-1} = g^{-1} \circ f^{-1}$$

2. Attention! This is wrong, if $\dim = \infty$! For example: $\delta : (x_1, x_2, \dots) \mapsto (0, x_1, x_2, \dots)$ over \mathbb{K}^∞ is injective, but not surjective!

$$S_L : (x_1, x_2, \dots) = (x_2, x_3, \dots)$$

is not injective, but surjective.

$$S_L \circ S_R = I$$

$$S_R \circ S_L = I - P_1$$

If $f \circ g$ is bijective, then g is injective and f surjective.

$$\xLeftrightarrow{\dim < \infty} g \text{ bijective, } f \text{ bijective}$$

Proof. Case distinction:

$$\det(f \circ g) = 0$$

$$\xLeftrightarrow{\text{Theorem 13}} f \circ g \text{ is not bijective}$$

$$\Leftrightarrow f \text{ is not bijective or } g \text{ not bijective}$$

$$\Leftrightarrow \det(f) = 0 \vee \det(g) = 0$$

$$\Leftrightarrow \det(f) \cdot \det(g) = 0$$

$$\det(f \circ g) \neq 0$$

$$\Leftrightarrow f \circ g \text{ is bijective}$$

$$\Rightarrow g \text{ bijective}$$

$$\Rightarrow \Delta^g \text{ non-trivial}$$

Let (b_1, \dots, b_n) be a basis of V , then Δ is non-trivial determinant.

$$\begin{aligned} \det(f \circ g) &= \frac{\Delta(f \circ g(b_1), \dots, f \circ g(b_n))}{\Delta(b_1, \dots, b_n)} \\ &= \frac{\Delta(f(g(b_1)), \dots, f(g(b_n)))}{\Delta(g(b_1), \dots, g(b_n))} \cdot \frac{\Delta(g(b_1), \dots, g(b_n))}{\Delta(b_1, \dots, b_n)} \\ &= \frac{\Delta(f(b'_1), \dots, f(b'_n))}{\Delta(b'_1, \dots, b'_n)} \cdot \frac{\Delta(g(b_1), \dots, g(b_n))}{\Delta(b_1, \dots, b_n)} \\ &= \det(f) \cdot \det(g) \end{aligned}$$

$b'_i = g(b_i)$ are also a basis, because g is bijective.

□

Corollary 6. Let $A, B \in \mathbb{K}^{n \times n}$.

$$1. \det(A \cdot B) = \det(A) \cdot \det(B)$$

$$2. A \text{ is regular} \Rightarrow \det(A^{-1}) = \frac{1}{\det(A)}$$

$$3. \det(A) = 0 \Leftrightarrow \text{rank}(A) < n$$

$$4. \det(A^t) = \det(A)$$

Proof. 1. A first proof follows from Theorem 14.

A second proof approach is:

$$A = [s_1, \dots, s_n] \quad \text{column vectors}$$

$$A \cdot B = \left[\sum_{i_1=1}^n s_{i_1} \cdot b_{i_1,1}, \sum_{i_2=1}^n s_{i_2} b_{i_2,2}, \dots, \sum_{i_n=1}^n s_{i_n} b_{i_n,n} \right]$$

Select determinant form such that $\Delta(e_1, \dots, e_n) = 1$.

$$\det(A \cdot B) = \Delta \left(\sum_{i_1=1}^n s_{i_1} b_{i_1}, \dots, \sum_{i_n=1}^n s_{i_n} b_{i_n,n} \right)$$

From multilinearity it follows that

$$\sum_{i_1=1}^n \sum_{i_2=1}^n \cdots \sum_{i_n=1}^n b_{i_1,1} b_{i_2,2} \cdots b_{i_n,n} \Delta(s_{i_1}, \dots, s_{i_n})$$

If two indices satisfy $i_k = i_l \Rightarrow \Delta = 0$.

$$\begin{aligned} &\Rightarrow \sum_{\text{different indices}} = \sum_{\text{permutations}} \\ &= \sum_{\pi \in \sigma_n} \underbrace{b_{\pi(1),1} b_{\pi(2),2} \cdots b_{\pi(n),n}}_{\det(B)} \underbrace{\Delta(s_{\pi(1)}, \dots, s_{\pi(n)})}_{\text{sign}(\pi) \Delta(s_1, \dots, s_n)} \\ &= \det A \cdot \det B \end{aligned}$$

Be aware that $\det(B)$ also includes $\text{sign}(\pi)$ from the right-hand side.

2.

$$\begin{aligned} A \cdot A^{-1} = I &\Leftrightarrow \det(A \cdot A^{-1}) = \det I = 1 \\ \det(A \cdot A^{-1}) &\stackrel{!}{=} \det(A) \cdot \det(A^{-1}) \end{aligned}$$

3. $\det(A) = 0$ and $\det(A) = \det(f_A)$.

$$\Leftrightarrow f_A \text{ is not bijective} \Leftrightarrow \text{rank}(A) < n$$

4.

$$\begin{aligned} \det(A^T) &= \sum_{\pi \in \sigma_n} \text{sign}(\pi) a_{\pi(1),1}^T \cdots a_{\pi(n),n}^T \\ &= \sum_{\pi \in \sigma_n} \text{sign}(\pi) a_{1,\pi(1)} \cdots a_{n,\pi(n)} \\ &= \sum_{\pi \in \sigma_n} \text{sign} \pi a_{\pi^{-1}(1),1} \cdots a_{\pi^{-1}(n),1} \\ &= \sum_{\rho} \text{sign} \rho^{-1} a \end{aligned} \quad \rho = \pi^{-1}$$

For fixed π :

$$\begin{aligned} \prod_{j=1}^n a_{j,\pi(j)} &= \prod_{k=1}^n a_{\pi^{-1}(k),k} \\ \pi(j) = 1 &\Leftrightarrow j = \pi'(1) \\ \pi(j) = k &\Leftrightarrow j = \pi'(k) \end{aligned}$$

$$\begin{aligned} &\sum_{\pi} \text{sign} \pi a_{\pi^{-1}(1),1} \cdots a_{\pi^{-1}(n),n} \\ &= \sum_{\rho} \text{sign}(\rho^{-1}) a_{\rho(1),1} \cdots a_{\rho(n),n} = \sum_{\rho} \text{sign}(\rho) a_{\rho(1),1} \cdots a_{\rho(n),n} = \det A \end{aligned}$$

Remark:

$\sigma_n \rightarrow \sigma_n$ is bijective

$$\pi \mapsto \pi^{-1}$$

$\text{sign}(\rho) = (-1)^k$ where $\rho = \tau_1, \dots, \tau_k$

$$\Rightarrow \rho^{-1} = \tau_k \circ \dots \circ \tau_1$$

$$\text{sign} \rho^{-1} = (-1)^k$$

□

Remark 7 (Determination of determinants). $\dim \leq 3$

For $n = 2$:

$$\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

For $n = 3$:

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = \sum_{\pi \in \sigma_3} \text{sign}(\pi) a_{\pi(1),1} a_{\pi(2),2} a_{\pi(3),3}$$

General linear group:

$$\begin{aligned} \text{GL}(n, \mathbb{K}) &= \text{group of invertible matrices} \\ &= \{A \in \mathbb{K}^{n \times n} \mid \det(A) \neq 0\} \\ \text{SL}(n, \mathbb{K}) &= \text{special linear group} \\ &= \{A \in \mathbb{K}^{n \times n} \mid \det(A) = 1\} \end{aligned}$$

σ_3 is a coxeter group.

$$\sigma_3 = \langle \tau_{12}, \tau_{23} \rangle$$

Is created by two transpositions.

$$\begin{aligned} \begin{vmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{vmatrix} &= \begin{vmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{vmatrix} \rightarrow \begin{vmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{vmatrix} \\ \begin{vmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{vmatrix} &\rightarrow \begin{vmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{vmatrix} \end{aligned}$$

$$= a_{11}a_{22}a_{33} + a_{21}a_{32}a_{13} + a_{31}a_{12}a_{23} - a_{21}a_{12}a_{33} - a_{11}a_{32}a_{23} - a_{31}a_{22}a_{13}$$

Remark 8 (Rule of Sarrus). Compare with Figure 3.

You write the first two columns next to right side of the matrix. You add up all 3 diagonals (the product of their values) from top left diagonally to the right bottom and subtract all 3 diagonals from left bottom to the top right.

The rule of Sarrus does not hold for $n = 4$!

Example 6.

$$\begin{aligned} \det \begin{vmatrix} 1 & 2 & 5 \\ 2 & 5 & 14 \\ 5 & 14 & 42 \end{vmatrix} &= 1 \cdot 5 \cdot 42 + 2 \cdot 14 \cdot 5 + 5 \cdot 2 \cdot 14 - 5 \cdot 5 \cdot 5 - 14 \cdot 14 \cdot 1 - 2 \cdot 2 \cdot 42 \\ &= 14(1 \cdot 5 \cdot 3 + 2 \cdot 5 + 5 \cdot 2 - 14 - 2 \cdot 2 \cdot 3) - 125 = 14 \cdot 9 - 125 = 1 \end{aligned}$$

It turns out, if we use Catalan numbers, we always end up with determinant 1.

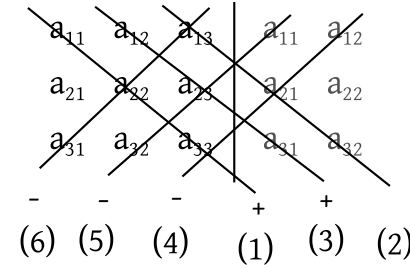


Figure 3: Rule of Sarrus visualized

Lemma 4. Let A be an upper triangular matrix, hence $a_{ij} = 0 \forall i > j$. Then it holds that $\det A = a_{11}a_{22} \dots a_{nn}$.

Proof.

$$\det A = \sum_{\pi \in \sigma_n} \text{sign } \pi a_{\pi(1),1} \dots a_{\pi(n),n}$$

it must hold that

$$\pi(j) \leq j \quad \forall j$$

$$\Rightarrow \pi(1) = 1, \pi(2) = 2, \dots, \pi(n) = n$$

The only permutation which contributes something is the identity. And $\text{sign id} = 1$, hence

$$= 1 \cdot a_{11}a_{22} \dots a_{nn}$$

□

German keywords

Bidualraum, 7
Bilineare Abbildung, 5
Charakter, 19
Coxetergruppe, 31
Determinantenform, 13
Determinante, 9
Dualbasis eines Vektorraums, 3
Dualraum des Vektorraums, 3
Fehlstand (Permutation), 17
Lineare Funktionale, 3
Linearformen, 3
Multilineare Abbildung, 5
Multilinearität, 13
Transponierte Abbildung, 7
Vertauschung, 17

English keywords

Bidual space, 7

Bilinear map, 5

Character, 19

Coxeter group, 31

Determinant, 9

determinant form, 13

Dual basis of a vector space, 3

Dual space of a vector space, 3

Linear forms, 3

Linear functionals, 3

Malposition, 17

Multilinear map, 5

Multilinearity, 13

Transposed map, 7

transposition, 17