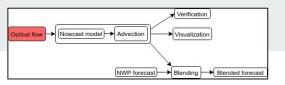
Hands-on session "users"

Introduction

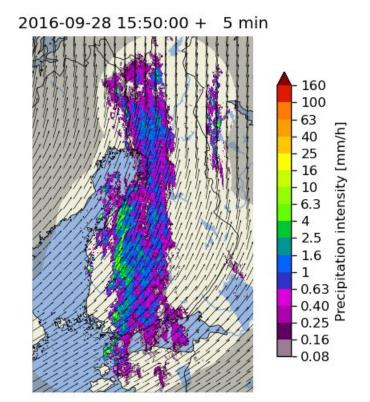
Outline

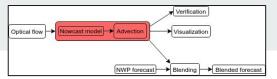
- The purpose of this session is to give a "hands-on" experience of using pysteps.
- The session is divided into 5 exercise blocks + bonus exercises.
- In the following slides, we give an introduction to the basic pysteps workflow.



Optical Flow and Extrapolation

- Advection (optical flow & extrapolation) is the key component of all pysteps nowcasting methods.
- All methods are based on the "Lagrangian persistence" nowcast shown on the right.
- Three different types of optical flow methods have been implemented in the **motion** module:
 - Feature tracking: Lucas-Kanade
 - Variational: VET and Proesmans
 - Spectral: DARTS
- For advection, pysteps implements the backward semi-Lagrangian scheme in the extrapolation module.

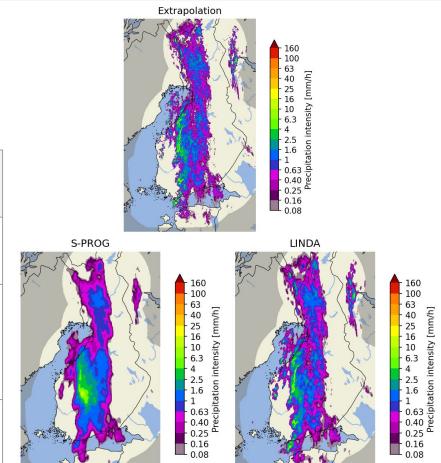




Deterministic Nowcasts

The main methods implemented in the **nowcasts** module:

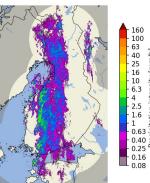
i ne main methods implemented in the nowcasts module:			
Method	Pros	Cons	Typical computation time
Extrapola tion	very fast	no prediction of growth or decay of precipitation	< 10 seconds
S-PROG	 for low-intensity precipitation (< 1-2 mm/h) has generally the best skill choose for stratiform events 	inability to preserve the spatial structure of rainfall fields, and particularly convective cells	< 20 seconds
LINDA-D	 the most accurate method for intense precipitation (> 1-2 mm/h) choose for convective events 	slow to compute	might take several minutes



Ensemble Nowcasts

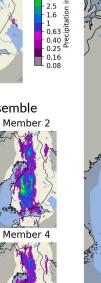
- The main ensemble methods implemented in the **nowcasts** module are STEPS and LINDA-P.
- They model two sources of uncertainty: advection field estimation and Lagrangian growth and decay.
- The basic rule for choosing the method:
 - stratiform events: STEPS
 - convective events: LINDA-P
- LINDA-P generally produces more realistic ensemble members.
- Computation times for the 4-member ensembles shown on the right:
 - STEPS: ~20 seconds
 - LINDA-P: ~5 minutes

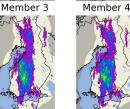
Observations at 2016-09-28 15:50 UTC



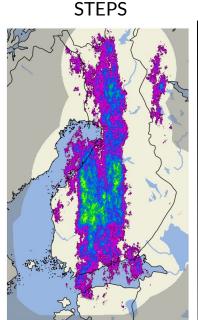
Nowcast ensemble

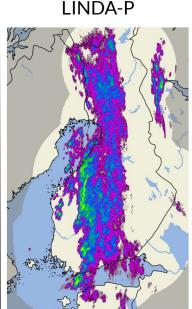
Member 1

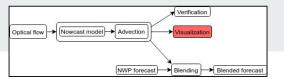




First ensemble members





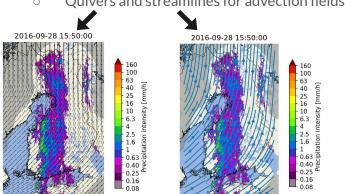


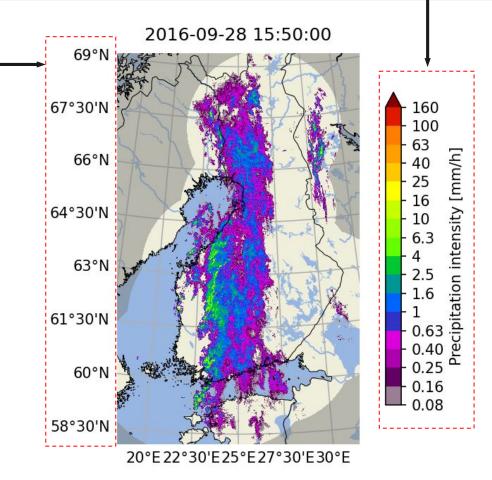
Colorbars with several pre-configured scales and for different data units

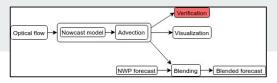
Longitude-latitude lines with labels

Visualization tools

- Extensive set of visualization tools has been implemented in the visualization module
- Support for multiple layers: basemap, precipitation and motion field
 - Plotting of basemaps by using cartopy
 - Quivers and streamlines for advection fields







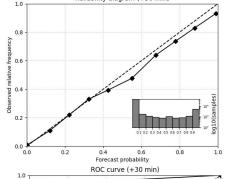
Verification tools / metrics

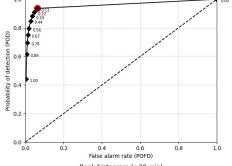
- A large number of verification utilities and metrics have been implemented in the verification module
- Functionality
 - Creation of verification objects and aggregation from multiple nowcasts
 - Plotting of verification results

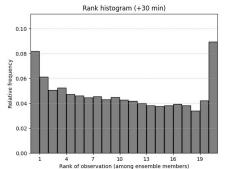
Metrics

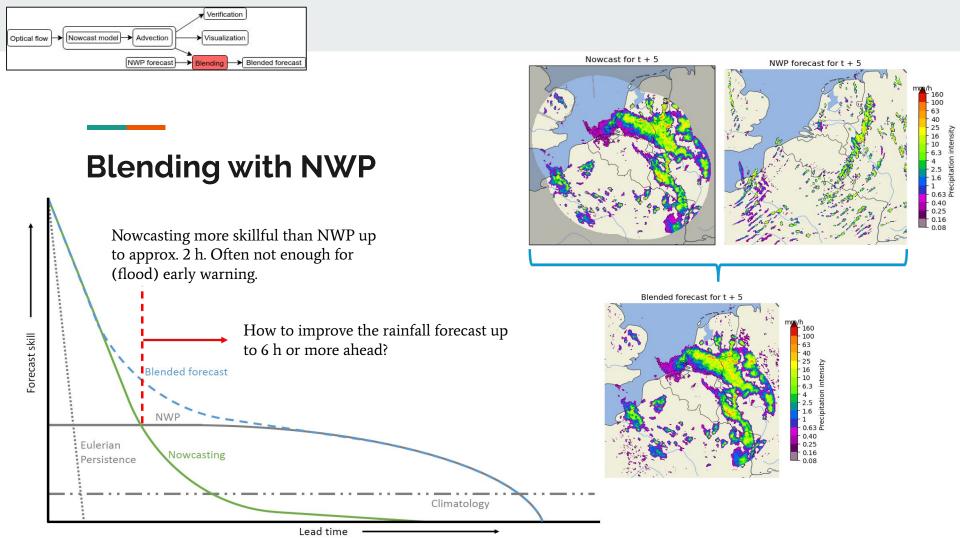
- Deterministic
 - o Categorical: CSI, ETS, POD, FAR
 - Continuous: MAE, ME
 - Scale/intensity-based metrics:
 FSS, intensity-scale
 - Radially averaged power spectral density (RAPSD)
- Probabilistic
 - o CRPS
 - Reliability diagram
- Ensemble
 - Spread
 - Rank histogram

Examples of verification plots for 30-minute STEPS nowcasts Reliability diagram (+30 min)







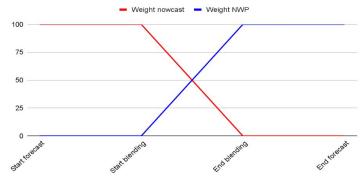


Blending with NWP: methods in pysteps

1. Linear blending

- Fixed start and end point of blending procedure
- Weights go linearly from 1 to 0 and 0 to 1.

Linear blending weights

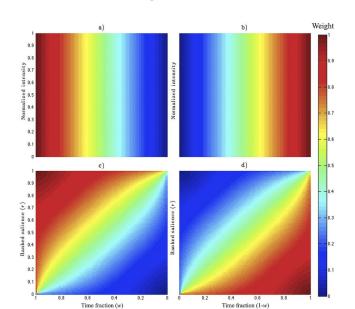


2. Saliency-based blending

- Similar to linear blending, but:
- Preserves pixel intensities over time if they are strong enough according to their ranked salience.

Hwang et al., 2015, Weather and Forecasting

3. STEPS blending (see next slide)



See the QPN session on Monday (16:30 - 18:00) for more information about this method and its' implementation in pysteps!

Per ensemble member:

