			M. III D. I		5.1	9	0	in But it						
			Multi-Rob	oot Movers	Robot L	ibrarian	Cone La	ying Robot						
		System Attributes (Relevant Feature)												
Evaluation Critoria	Driority (1.5)	(Relevant	Metric Score (1-	Moightod Coore	Metric Score (1-	Waighted Coors	Metric Score (1-	Weighted Score						
Evaluation Criteria	Priority (1-5)	reature)	5)	vveignted Score	3)	weighted Score	5)	vveignted Score						
		# of mechanically significant parts												
Mechanical Complexity	-5	significant parts	2	-10	4	-20	3	-15						
Algorithmic Interest		# of interesting problems	,	40	_	6	,	9						
Algorithmic interest		Problems	4	12	2	ь	3	9						
Time to build		Schedule predictability	3	-12	3	-12	4	-16						
		,												
Usability	1	Startup potential	3	3	2	2	5	5						
		# of fragile												
Durability	-2	# of fragile mechanical components	1	-2	3	-6	2	-4						
				-9		-30		-21						
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