

INSTITUTE OF AUTOMATION AND COMPUTER SCIENCE



Programming for robots and manipulators Lecture 2.2

Roman Parak







Content



1. Introduction

2. Robot Control

3. Type of Simulation Tools

3.1 Standard: B&R, ABB, UR, etc.

3.2 Modern: ROS, NVIDIA Omniverse, etc.

3.3 Unity3D





Introduction

Simulation Software



Simulation tools are built to replicate real-world robotic applications as closely as possible, taking every environmental and physical factor into account and testing for all possible variables.

Why use simulation tools?

- 1. Proof of Concept and Proof of Design.
 - 2. Reduced Integration Costs.
 - 3. Shorter System Delivery Times.
 - 4. Something else?







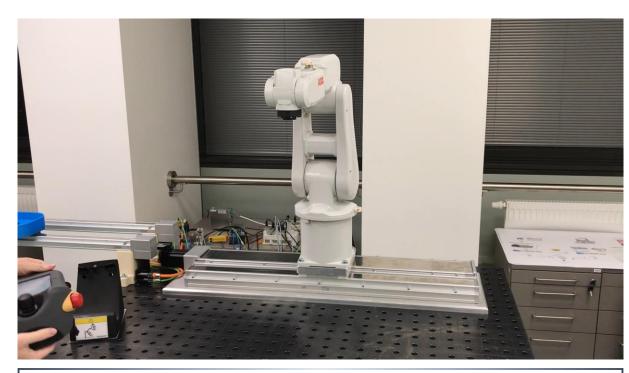


Robot Control



Robot Control: Teach Pendant





Industrial Robot ABB IRB 120



Collaborative Robot Universal Robots UR3

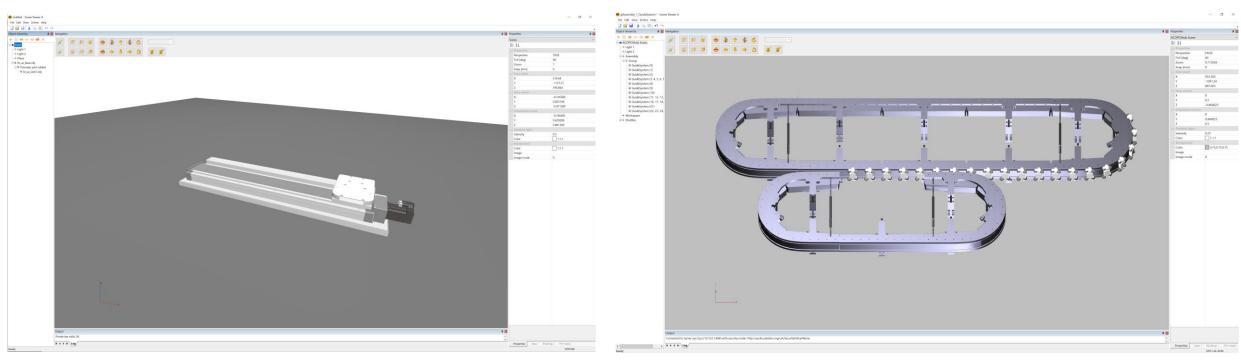


Type of Simulation Tools



B&R Automation





B&R Automation - SceneViewer





ABB Robotics



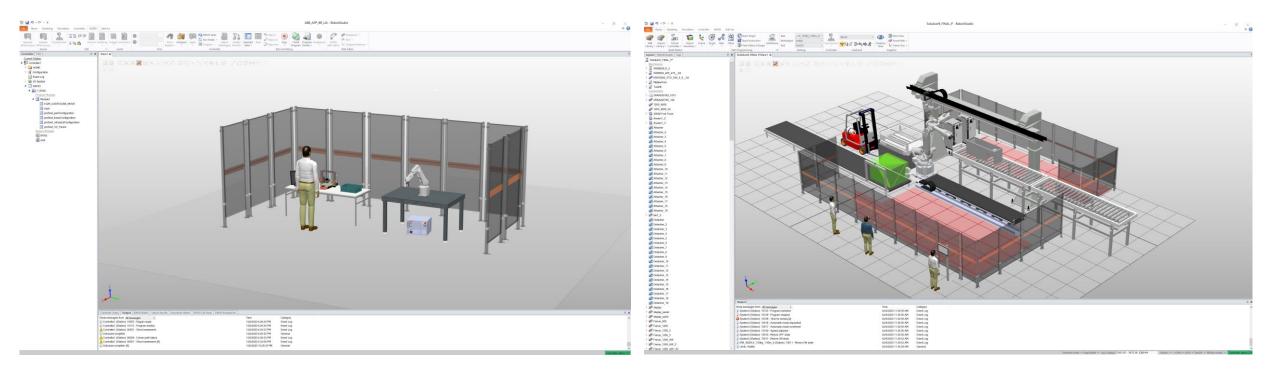


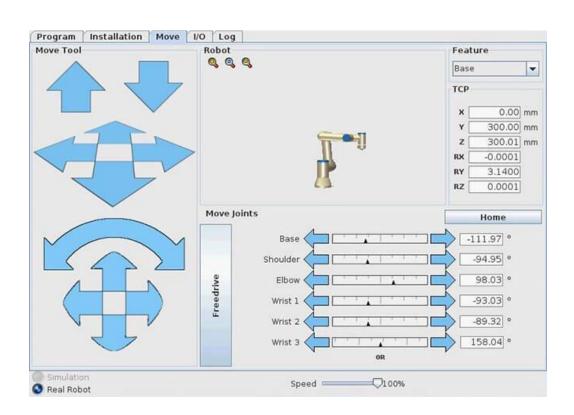
ABB RobotStudio

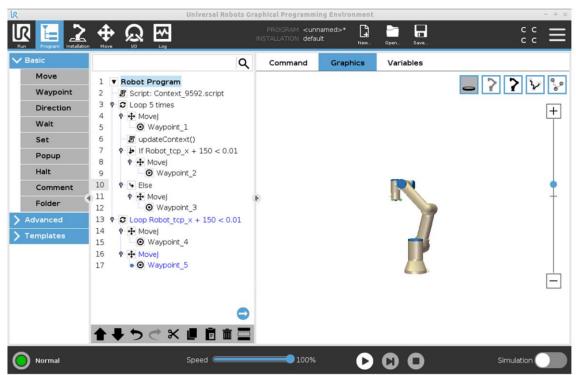




Universal Robots





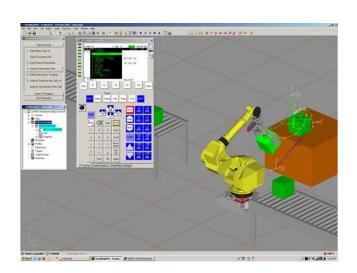


<u>UR – Polyscope</u>

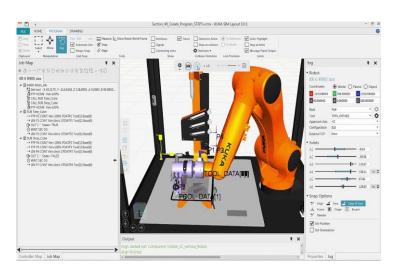




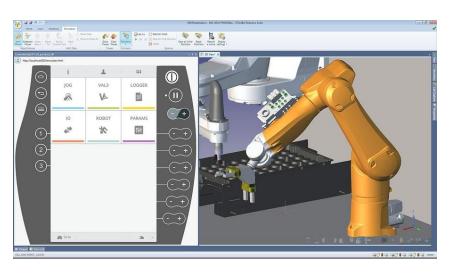
Another Official Robotics Simulator



Fanuc Roboguide



Kuka Sim Pro



Staubli Robotics Suite





Robot Operating System (ROS)



ROS, an open-source project, provides a common framework for robotics applications. ROS is heavily utilized by the research community for service robotics applications, but its technology can be applied to other application areas, including industrial robotics.

ROS-Industrial:

ROS-Industrial is an open-source project that extends the advanced capabilities of ROS to manufacturing automation and robotics. The ROS-Industrial repository includes interfaces for common industrial manipulators, grippers, sensors, and device networks.









Robot Operating System (ROS)



ROS

/rosnode

/rosservice

/rostopic

/rosparam

...







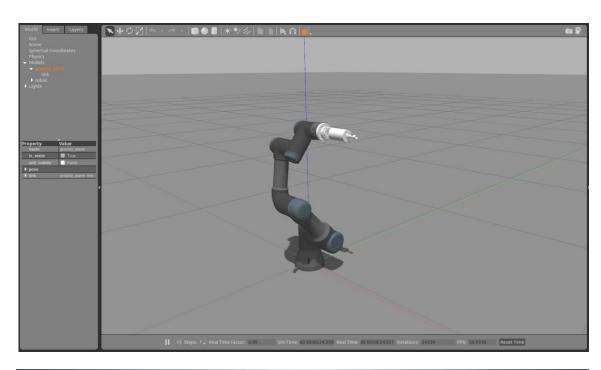






ROS: Simulation Tools





The final control of the control of

Gazebo

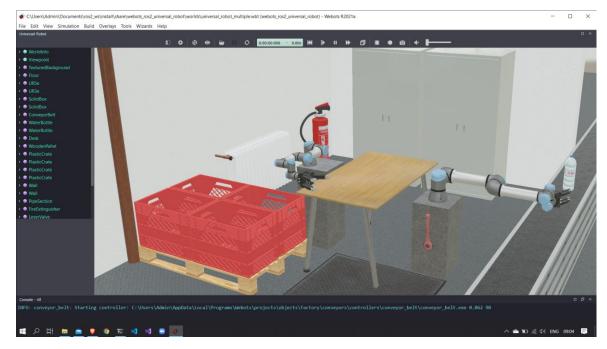
RVIZ

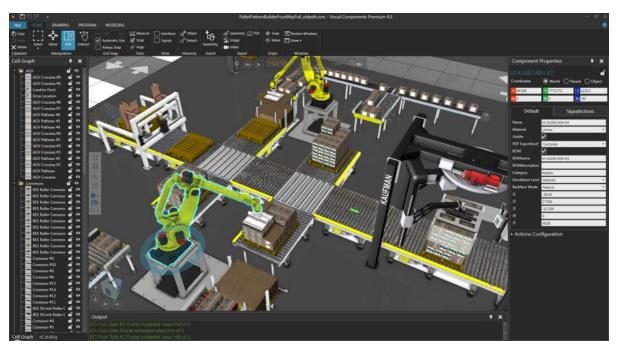




Another Useful Robot Simulators







WEBOTS

<u>Visual Components</u>

Another Useful Robot Simulators





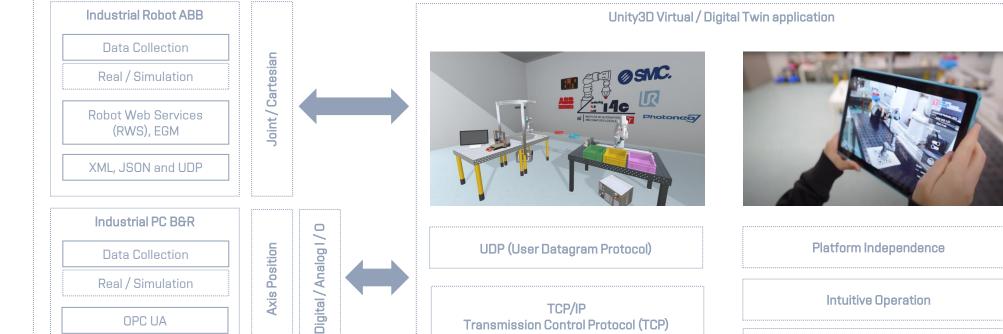
NVIDIA Omniverse





Individual Approach: Virtual / Digital Twin





Collaborative Robot UR

Real / Simulation

OPC UA

Data Collection

Real / Simulation

TCP/IP



TCP/IP Transmission Control Protocol (TCP) Internet Protocol (IP)

OPC Unified Architecture (UA)

Intuitive Operation

Multi-Threading

NVIDIA PhysX

Easy compilation into Augmented reality (AR)





7

Unity3D Application Portfolio





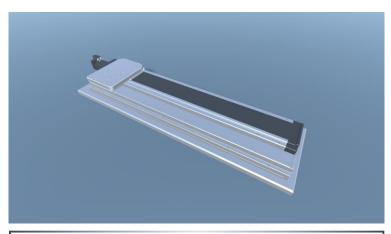
Industry 4.0 Cell: Sorting Line



B&R Automation ACOPOStrak



Industrial Robot ABB IRB 120



Simple Linear Axis (B&R Automation, SMC)



Sorting Machine (B&R Automation, SMC)



Collaborative Robot Universal Robots UR3



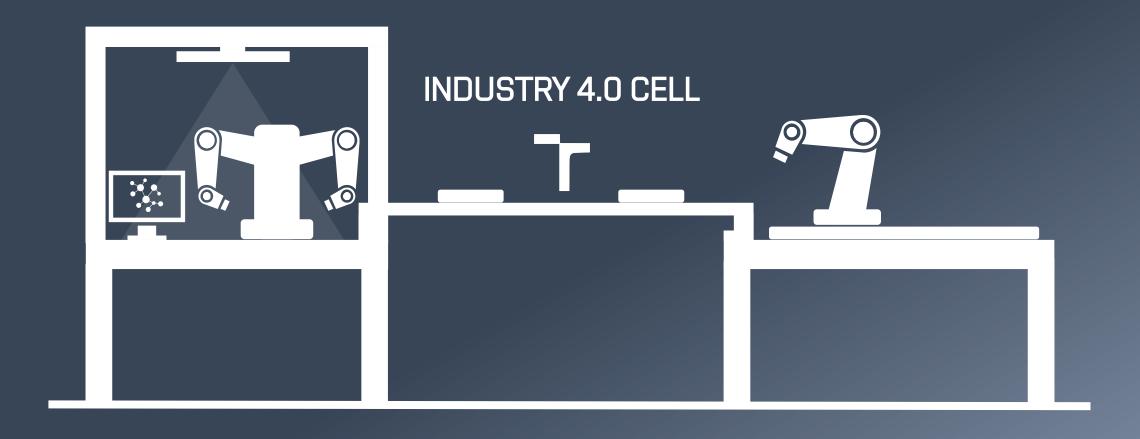


Thank You!



Questions?





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