

PROGRAMMING FOR ROBOTS AND MANIPULATORS (VRM)

Faculty of Mechanical Engineering, Brno University of Technology
Institute of Automation and Computer Science
Technická 2896/2, Brno 616 69, Czech Republic
Roman.Parak@vutbr.cz

Seminar Paper

Title:

The title of the seminar paper will correspond to the chosen topic (e.g., The main pillars of Industry 4.0).

Detailed description:

The seminar paper focuses mainly on the topic of robotics, motion planning, artificial intelligence, Industry 4.0, smart grippers/sensors, and more. Seminar papers can have a maximum of 10 pages and the recommended range is 4 to 6 pages. Please use the relevant literature and resources for your work, such as books on robotics, scientific journals, etc. (at least 10 sources).

Text language:

Czech, Slovak, English (recommended)

Form:

LaTeX (e.g. Overleaf - Online LaTeX Editor) → PDF

Location:

GitHub

Important Dates:

Assignment: 15.2.2021

Deadline: 29.3.2021

Maximum Score:

20 points



Figure 1: Seminar paper