PROGRAMMING FOR ROBOTS AND MANIPULATORS (VRM)

Faculty of Mechanical Engineering, Brno University of Technology Institute of Automation and Computer Science Technicka 2896/2, Brno 616 69, Czech Republic Roman.Parak@vutbr.cz

Project no. 1

Title:

ABB RobotStudio with a name that describes a robotic solution (e.g., ABB Robotstudio - Sorting Machine).

Detailed description:

The project focuses on controlling multiple robots using the simulation tool RobotStudio ABB. The robot on Table No.1 will communicate with another robot on Table No.2 using a conveyor belt. The main goal of the project will be to create a sorting production line. A more detailed description of the project will be discussed with the lecturer.

Note 1: It will be possible to create your own production line design, but in accordance with certain principles!

Note 2: It will be possible to create a team (max. 3 members), but with a reduction of the maximum score!

Language:

Comments: Czech, Slovak, English (recommended) Variables, functions, and other.: English

Form:

RobotStudio Pack & Go file (.rspag)

<u>Location:</u>

GitHub

Important Dates:

Assignment: 22.2.2021 Deadline: 22.3.2021

Maximum Score:

30 points

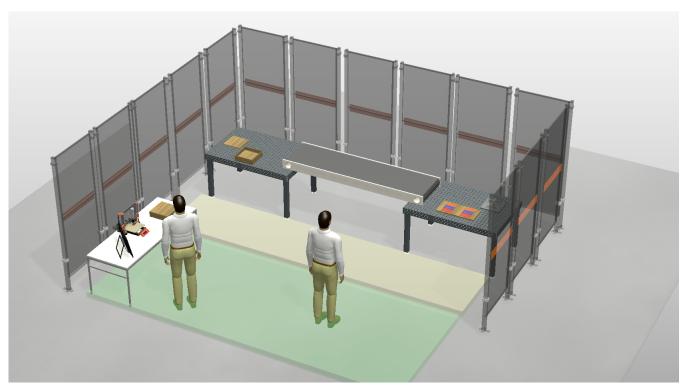


Figure 1: Project no. 1



Figure 2: Project no. 1