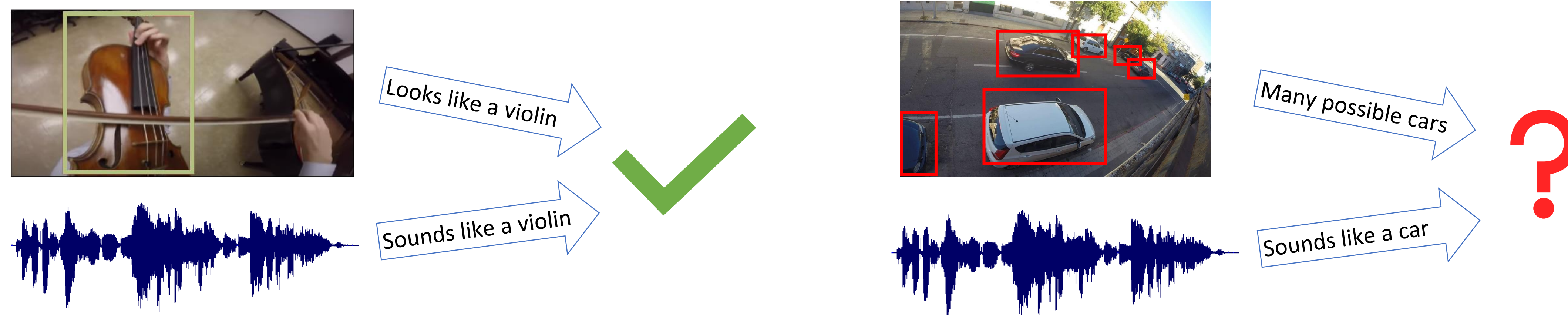




State-of-the-art methods are inadequate for urban scenes

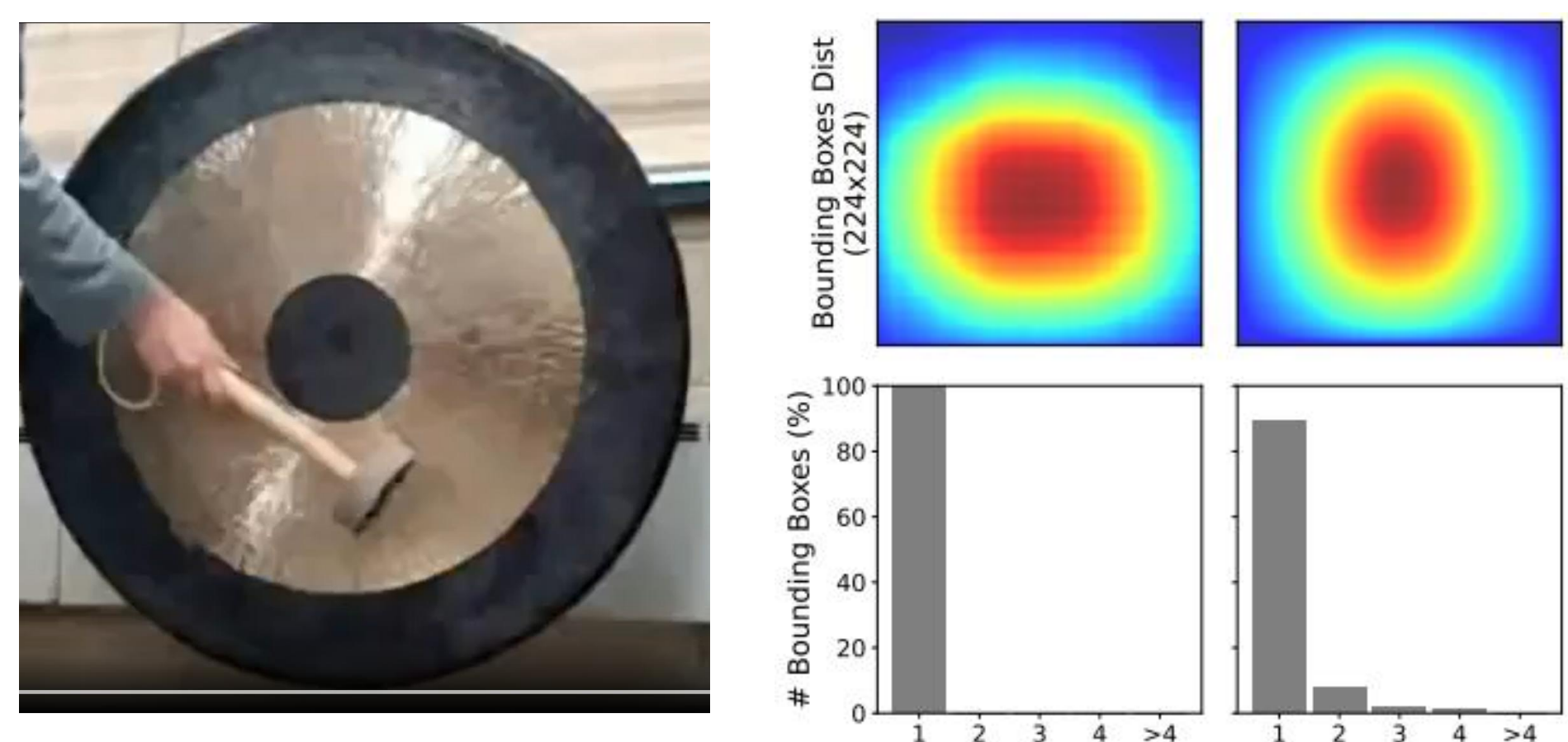
Purely semantic representations

Impossible to disambiguate between multiple potential sound sources

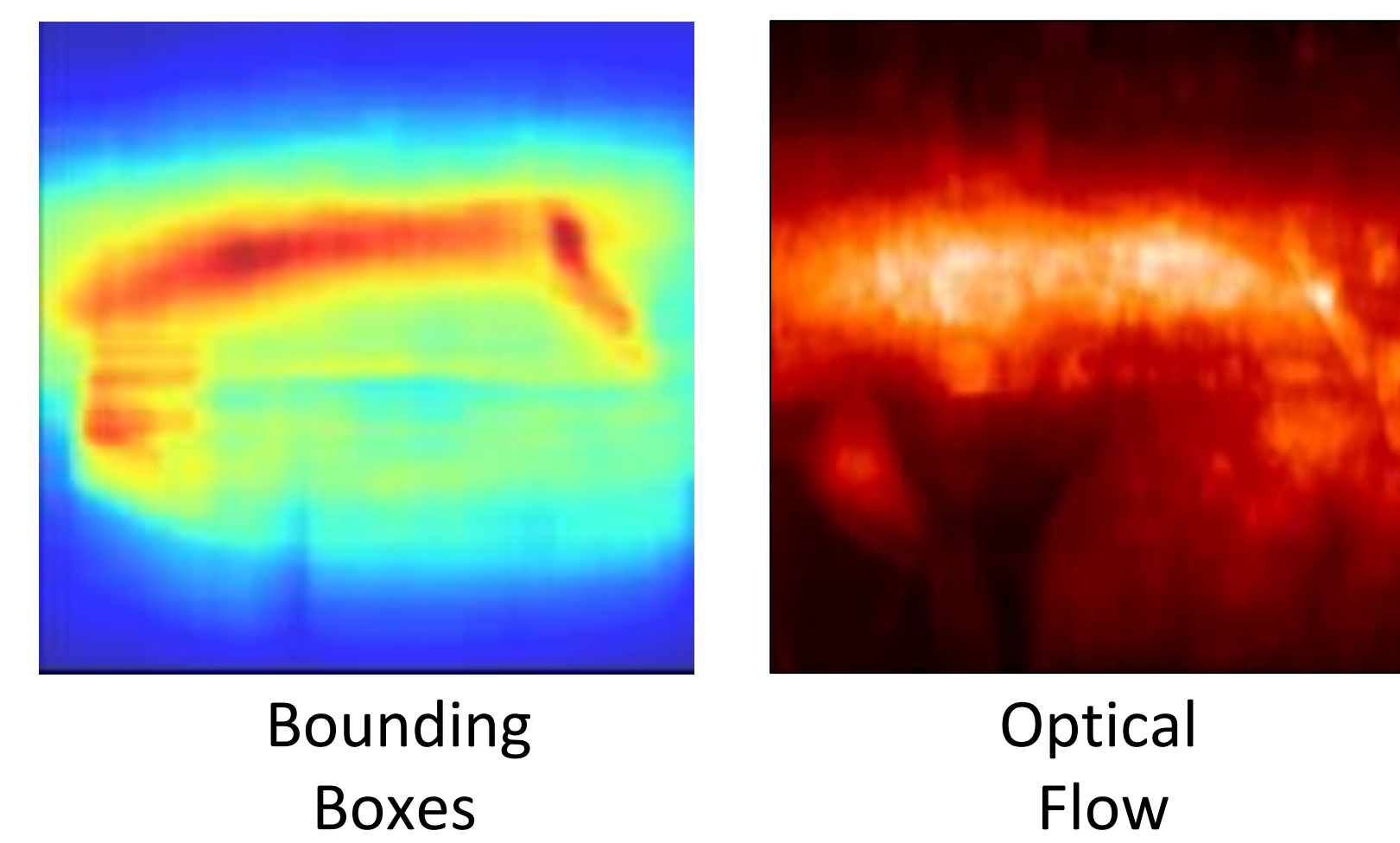


All datasets are biased, urban scenes uniquely so

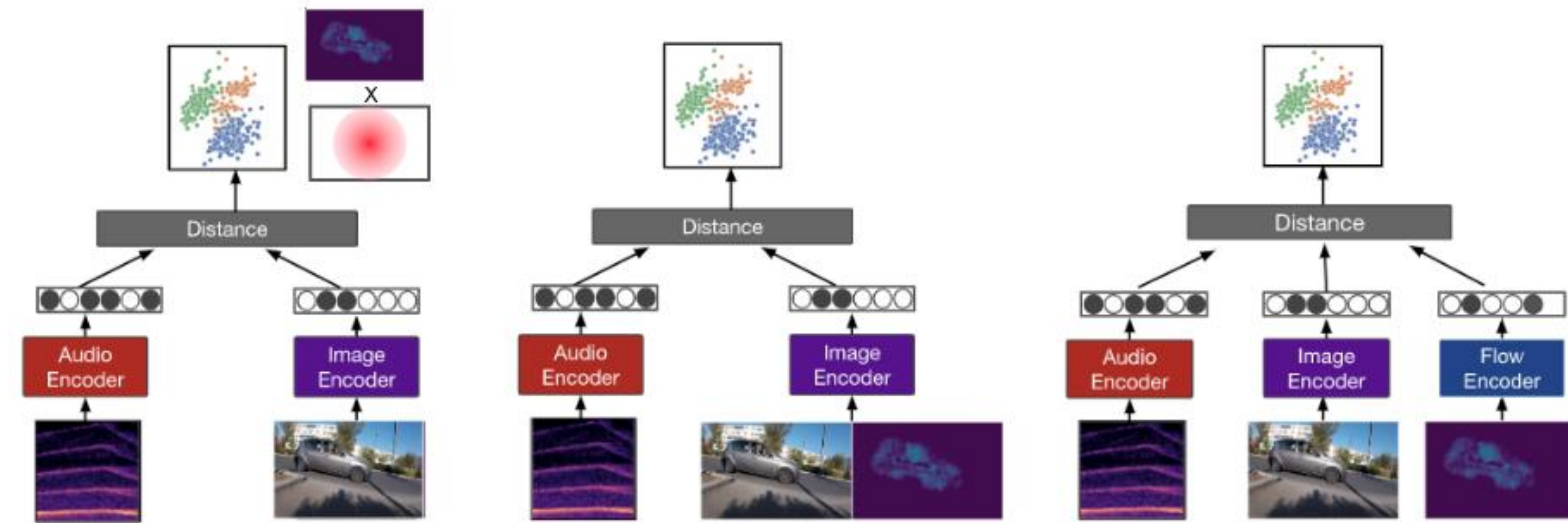
Single-centered-object bias in benchmarks



Motion bias in Urbansas



Training



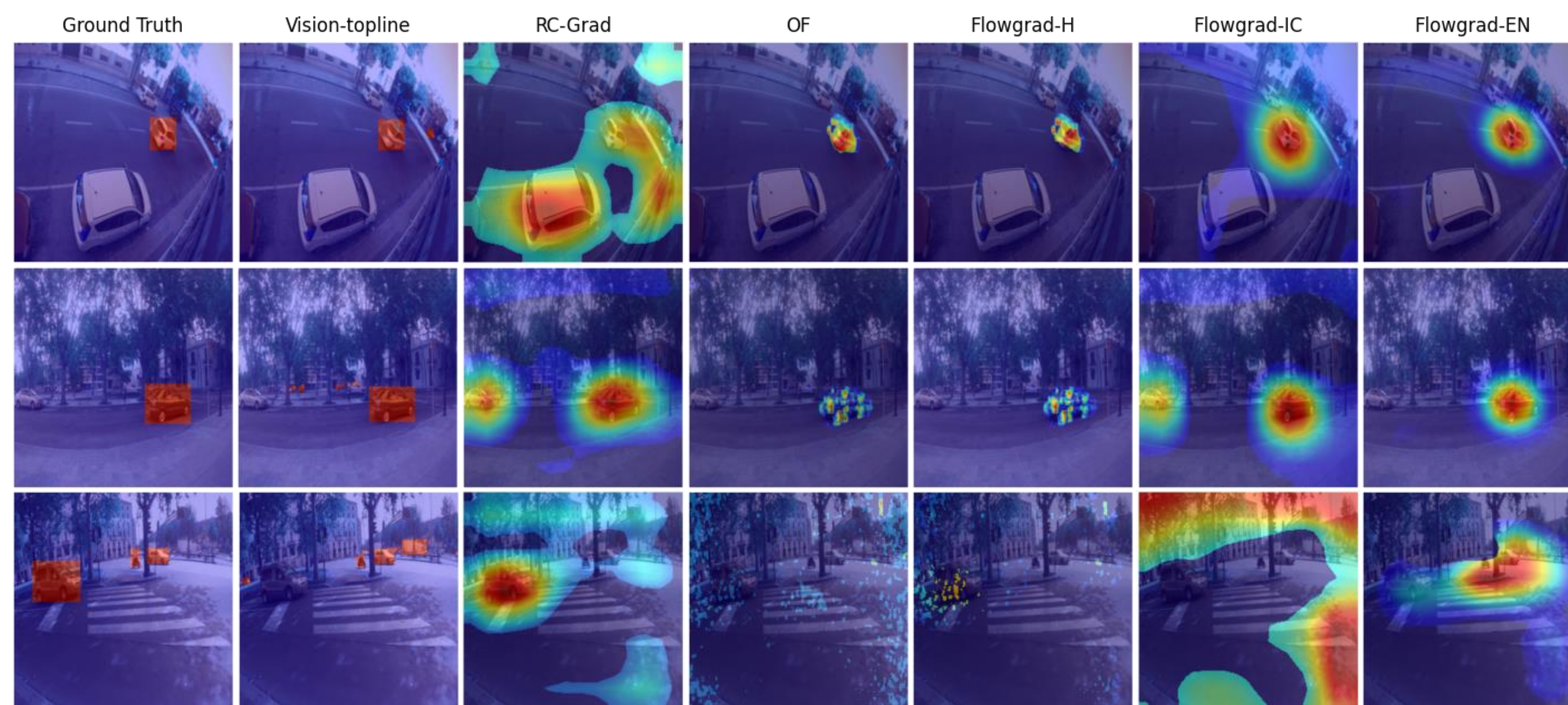
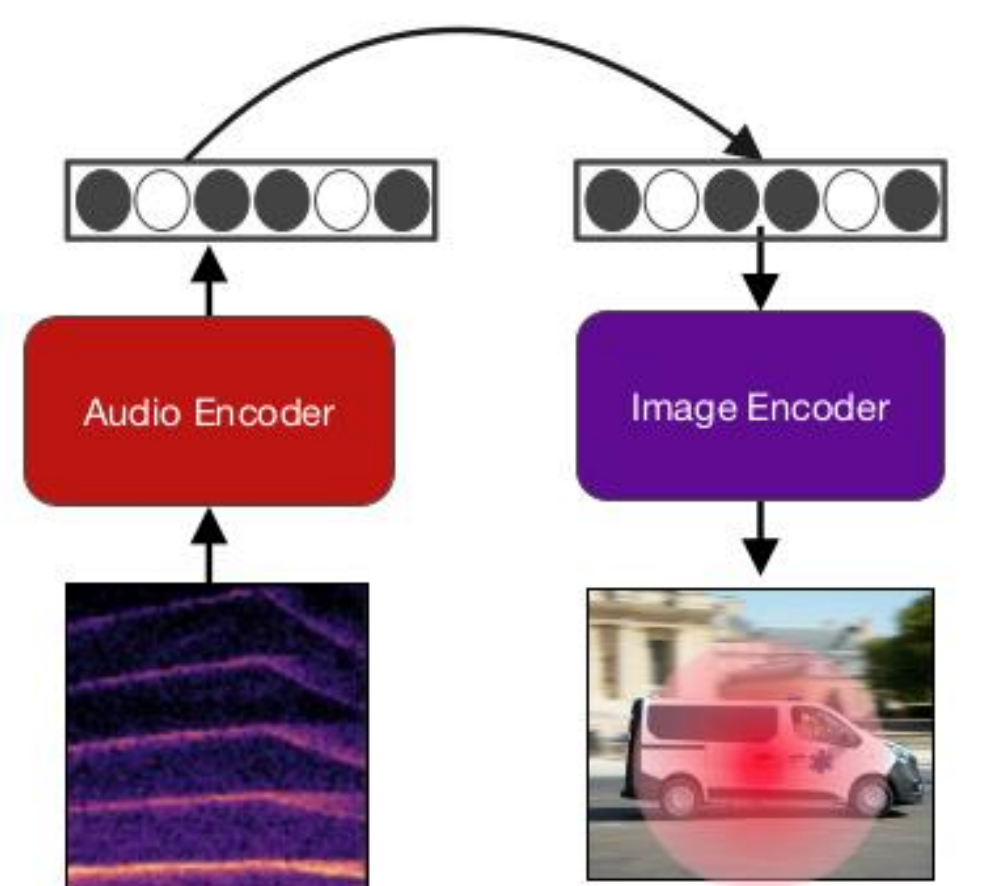
a) FlowGrad-H

b) FlowGrad-IC

FlowGrad-EN

Localization

Grad-CAM - Backpropagate through the vision subnetwork wrt the audio embedding



Results

Heuristics can outperform learning based methods

<i>model</i>	IoU	AUC
Vision-topline	0.68	0.51
Optical Flow	0.33	0.23
RCGrad	0.16	0.13
FlowGrad-H	0.50	0.30
FlowGrad-IC	0.26	0.18
FlowGrad-EN	0.37	0.23