

NPTEL MOOC, JAN-FEB 2015  
Week 4, Module 3

# DESIGN AND ANALYSIS OF ALGORITHMS

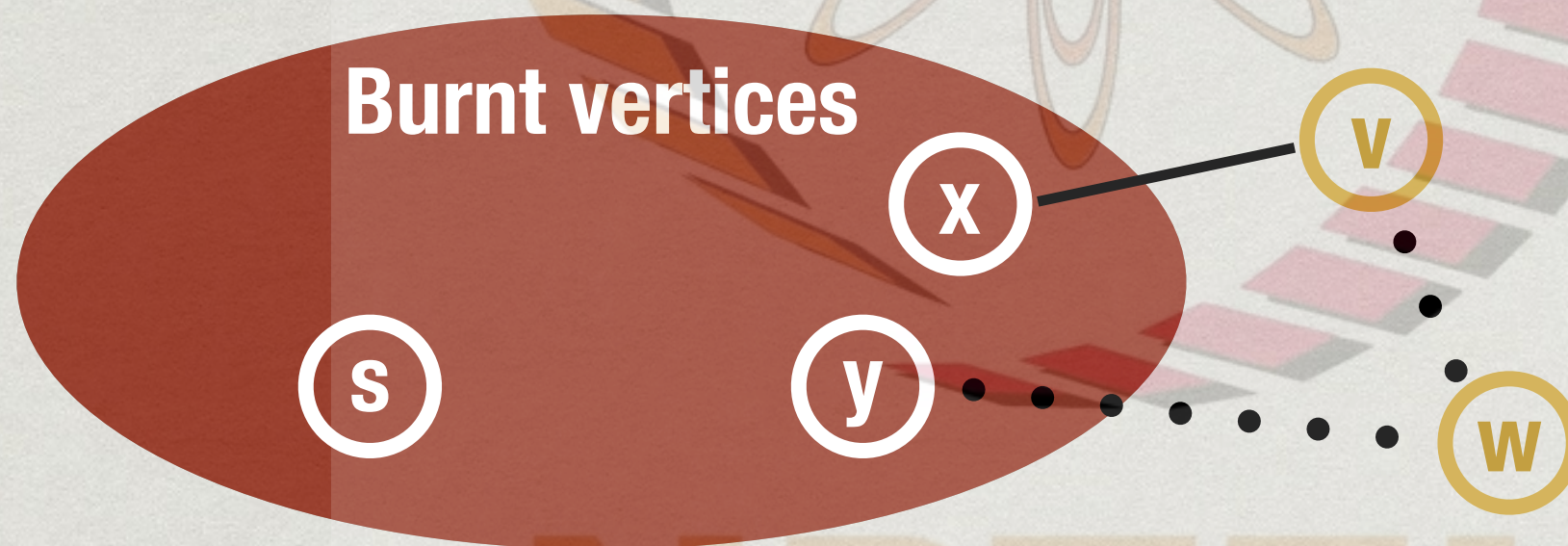
Negative edges: Bellman-Ford algorithm

MADHAVAN MUKUND, CHENNAI MATHEMATICAL INSTITUTE  
<http://www.cmi.ac.in/~madhavan>



# Correctness for Dijkstra's algorithm

- \* By induction, assume we have identified shortest paths to all vertices already burnt

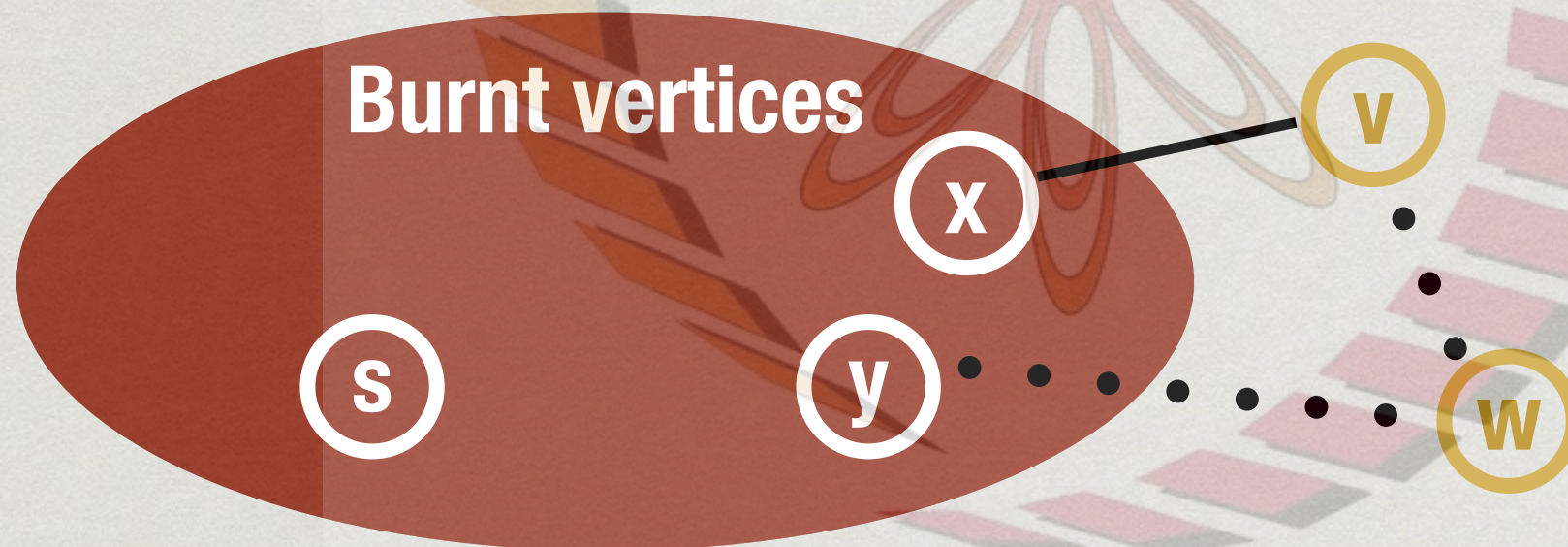


- \* Next vertex to burn is  $v$ , via  $x$
- \* Cannot later find a shorter path from  $y$  to  $w$  to  $v$



# Negative weights

- \* Our correctness argument is no longer valid



- \* Next vertex to burn is v, via x
- \* Might find a shorter path later with negative weights from y to w to v



# Negative weights ...

- \* **Negative cycle:** loop with a negative total weight
  - \* Problem is not well defined with negative cycles
  - \* Repeatedly traversing cycle pushes down cost without a bound
- \* With negative edges, but no negative cycles, shortest paths do exist



# About shortest paths

- \* Shortest paths will never loop
- \* Never visit the same vertex twice
- \* At most length  $n-1$
- \* Every prefix of a shortest path is itself a shortest path
- \* Suppose the shortest path from  $s$  to  $t$  is

$$s \rightarrow v_1 \rightarrow v_2 \rightarrow v_3 \dots \rightarrow v_m \rightarrow t$$

- \* Every prefix  $s \rightarrow v_1 \rightarrow \dots \rightarrow v_r$  is a shortest path to  $v_r$



# Updating Distance()

- \* When vertex  $j$  is “burnt”, for each edge  $(j,k)$  update
$$\text{Distance}(k) = \min(\text{Distance}(k), \text{Distance}(j) + \text{weight}(j,k))$$
- \* Refer to this as  $\text{update}(j,k)$
- \* Dijkstra’s algorithm
  - \* When we compute  $\text{update}(j,k)$ ,  $\text{Distance}(j)$  is always guaranteed to be correct distance to  $j$
- \* What can we say in general?



# Properties of update(j,k)

update(j,k):

$\text{Distance}(k) = \min(\text{Distance}(k), \text{Distance}(j) + \text{weight}(j,k))$

- \*  $\text{Distance}(k)$  is no more than  $\text{Distance}(j) + \text{weight}(j,k)$
- \* If  $\text{Distance}(j)$  is correct and  $j$  is the second-last node on shortest path to  $k$ ,  $\text{Distance}(k)$  is correct
- \* Update is safe
  - \*  $\text{Distance}(k)$  never becomes “too small”
  - \* Redundant updates cannot hurt



# Updating Distance() ...

update(j,k):

$\text{Distance}(k) = \min(\text{Distance}(k), \text{Distance}(j) + \text{weight}(j,k))$

- \* Dijkstra's algorithm performs a particular “greedy” sequence of updates
  - \* Computes shortest paths without negative weights
- \* With negative edges, this sequence does not work
- \* Is there some sequence that does work?



# Updating distance() ...

- \* Suppose the shortest path from  $s$  to  $t$  is

$$s \rightarrow v_1 \rightarrow v_2 \rightarrow v_3 \dots \rightarrow v_m \rightarrow t$$

- \* If our update sequence includes ...,  $\text{update}(s, v_1)$ , ...,  $\text{update}(v_1, v_2)$ , ...,  $\text{update}(v_2, v_3)$ , ...,  $\text{update}(v_m, t)$ , ..., in that order,  $\text{Distance}(t)$  will be computed correctly
- \* If  $\text{Distance}(j)$  is correct and  $j$  is the second-last node on shortest path to  $k$ ,  $\text{Distance}(k)$  is correct after  $\text{update}(j, k)$



# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

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# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

Iteration 1
...
update( $s, v_1$ )
...
update( $v_1, v_2$ )
...
update( $v_2, v_3$ )
...
update( $v_m, t$ )
...



# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

Iteration 1	Iteration 2
...	...
update(s, v <sub>1</sub> )	update(s, v <sub>1</sub> )
...	...
update(v <sub>1</sub> , v <sub>2</sub> )	update(v <sub>1</sub> , v <sub>2</sub> )
...	...
update(v <sub>2</sub> , v <sub>3</sub> )	update(v <sub>2</sub> , v <sub>3</sub> )
...	...
update(v <sub>m</sub> , t)	update(v <sub>m</sub> , t)
...	...



# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

Iteration 1	Iteration 2	...
...	...	...
update(s, v <sub>1</sub> )	update(s, v <sub>1</sub> )	...
...	...	...
update(v <sub>1</sub> , v <sub>2</sub> )	update(v <sub>1</sub> , v <sub>2</sub> )	...
...	...	...
update(v <sub>2</sub> , v <sub>3</sub> )	update(v <sub>2</sub> , v <sub>3</sub> )	...
...	...	...
update(v <sub>m</sub> , t)	update(v <sub>m</sub> , t)	...
...	...	...



# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

Iteration 1	Iteration 2	...	Iteration n-1
...	...	...	...
update(s,v <sub>1</sub> )	update(s,v <sub>1</sub> )	...	update(s,v <sub>1</sub> )
...	...	...	...
update(v <sub>1</sub> ,v <sub>2</sub> )	update(v <sub>1</sub> ,v <sub>2</sub> )	...	update(v <sub>1</sub> ,v <sub>2</sub> )
...	...	...	...
update(v <sub>2</sub> ,v <sub>3</sub> )	update(v <sub>2</sub> ,v <sub>3</sub> )	...	update(v <sub>2</sub> ,v <sub>3</sub> )
...	...	...	...
update(v <sub>m</sub> ,t)	update(v <sub>m</sub> ,t)	...	update(v <sub>m</sub> ,t)
...	...	...	...



# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

Iteration 1	Iteration 2	...	Iteration n-1
...	...	...	...
update(s,v <sub>1</sub> )	update(s,v <sub>1</sub> )	...	update(s,v <sub>1</sub> )
...	...	...	...
update(v <sub>1</sub> ,v <sub>2</sub> )	update(v <sub>1</sub> ,v <sub>2</sub> )	...	update(v <sub>1</sub> ,v <sub>2</sub> )
...	...	...	...
update(v <sub>2</sub> ,v <sub>3</sub> )	update(v <sub>2</sub> ,v <sub>3</sub> )	...	update(v <sub>2</sub> ,v <sub>3</sub> )
...	...	...	...
update(v <sub>m</sub> ,t)	update(v <sub>m</sub> ,t)	...	update(v <sub>m</sub> ,t)
...	...	...	...



# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

Iteration 1	Iteration 2	...	Iteration n-1
...	...	...	...
<b>update(s,v<sub>1</sub>)</b>	update(s,v <sub>1</sub> )	...	update(s,v <sub>1</sub> )
...	...	...	...
update(v <sub>1</sub> ,v <sub>2</sub> )	<b>update(v<sub>1</sub>,v<sub>2</sub>)</b>	...	update(v <sub>1</sub> ,v <sub>2</sub> )
...	...	...	...
update(v <sub>2</sub> ,v <sub>3</sub> )	update(v <sub>2</sub> ,v <sub>3</sub> )	...	update(v <sub>2</sub> ,v <sub>3</sub> )
...	...	...	...
update(v <sub>m</sub> ,t)	update(v <sub>m</sub> ,t)	...	update(v <sub>m</sub> ,t)
...	...	...	...



# Bellman-Ford algorithm

- \* Initialize  $\text{Distance}(s) = 0$ ,  $\text{Distance}(u) = \infty$  for all other vertices
- \* Update all edges  $n-1$  times!

Iteration 1	Iteration 2	...	Iteration $n-1$
...	...	...	...
<b>update(s, v<sub>1</sub>)</b>	update(s, v <sub>1</sub> )	...	update(s, v <sub>1</sub> )
...	...	...	...
update(v <sub>1</sub> , v <sub>2</sub> )	<b>update(v<sub>1</sub>, v<sub>2</sub>)</b>	...	update(v <sub>1</sub> , v <sub>2</sub> )
...	...	...	...
update(v <sub>2</sub> , v <sub>3</sub> )	update(v <sub>2</sub> , v <sub>3</sub> )	...	update(v <sub>2</sub> , v <sub>3</sub> )
...	...	...	...
update(v <sub>m</sub> , t)	update(v <sub>m</sub> , t)	...	<b>update(v<sub>m</sub>, t)</b>
...	...	...	...

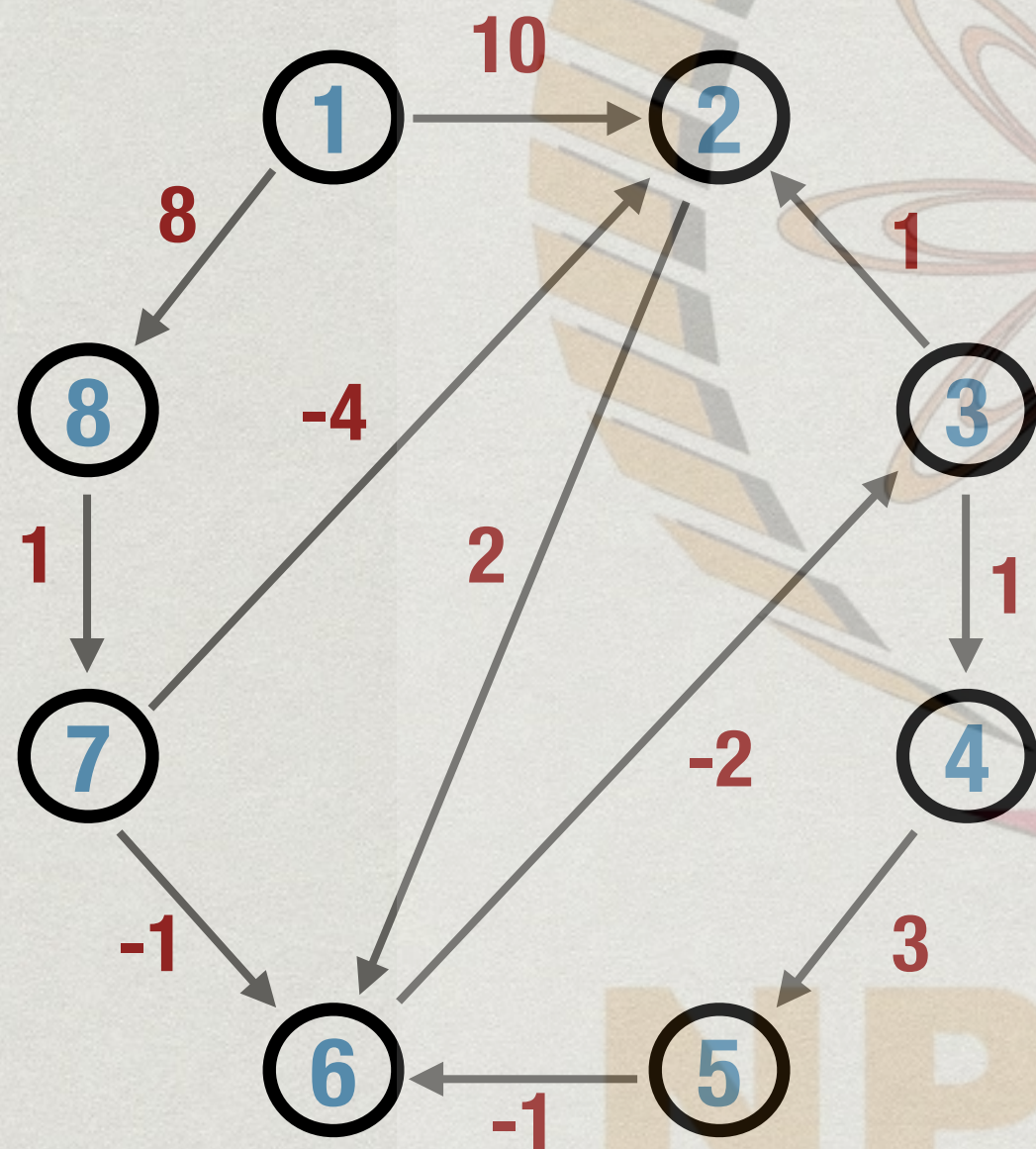


# Bellman-Ford algorithm

```
function BellmanFord(s) //source s, with -ve weights
  for i = 1 to n
    Distance[i] = infinity
  Distance[s] = 0
  for i = 1 to n-1 //repeat n-1 times
    for each edge(j,k) in E
      Distance(k) = min(Distance(k),
                        Distance(j) + weight(j,k))
```

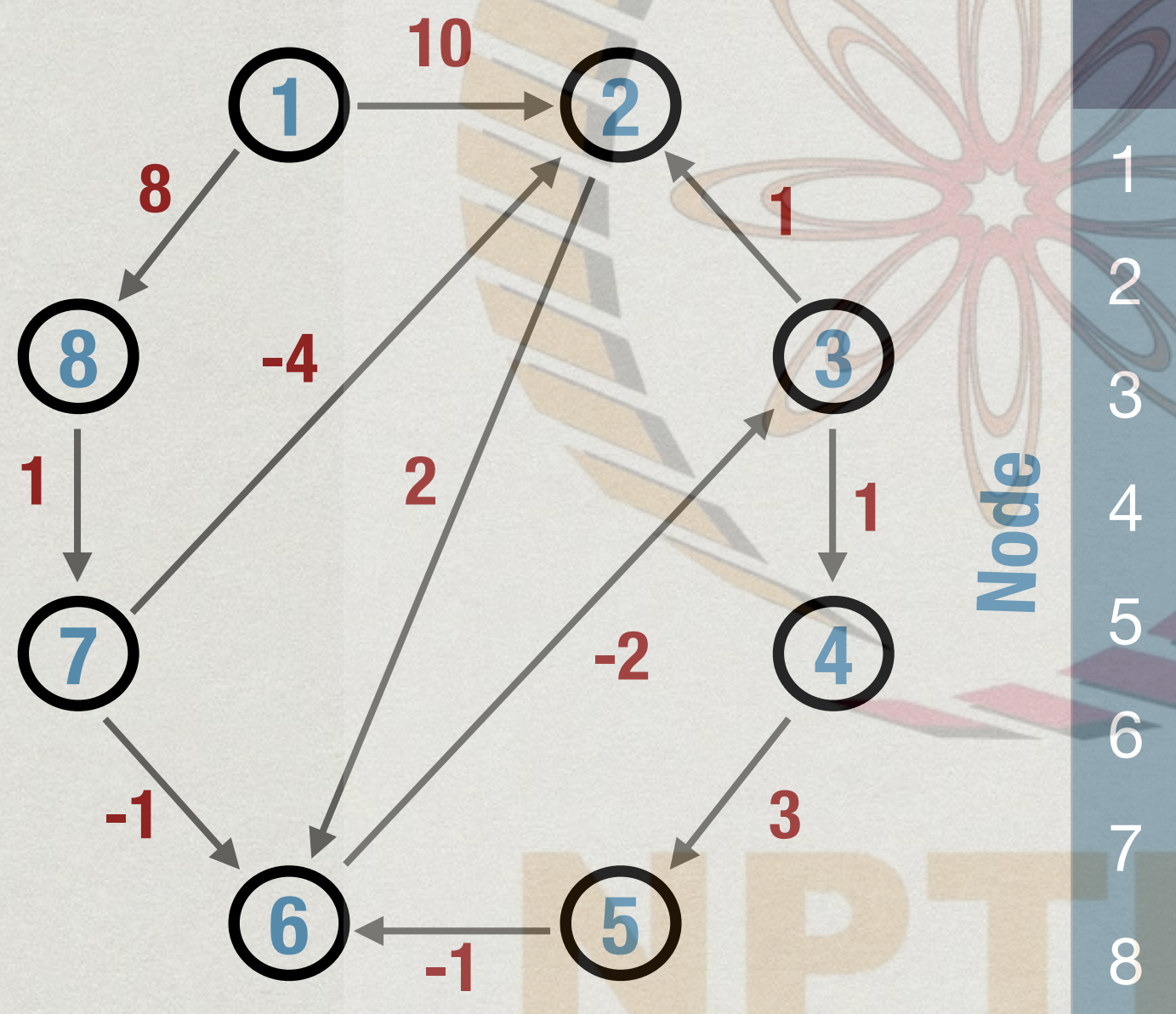


# Example





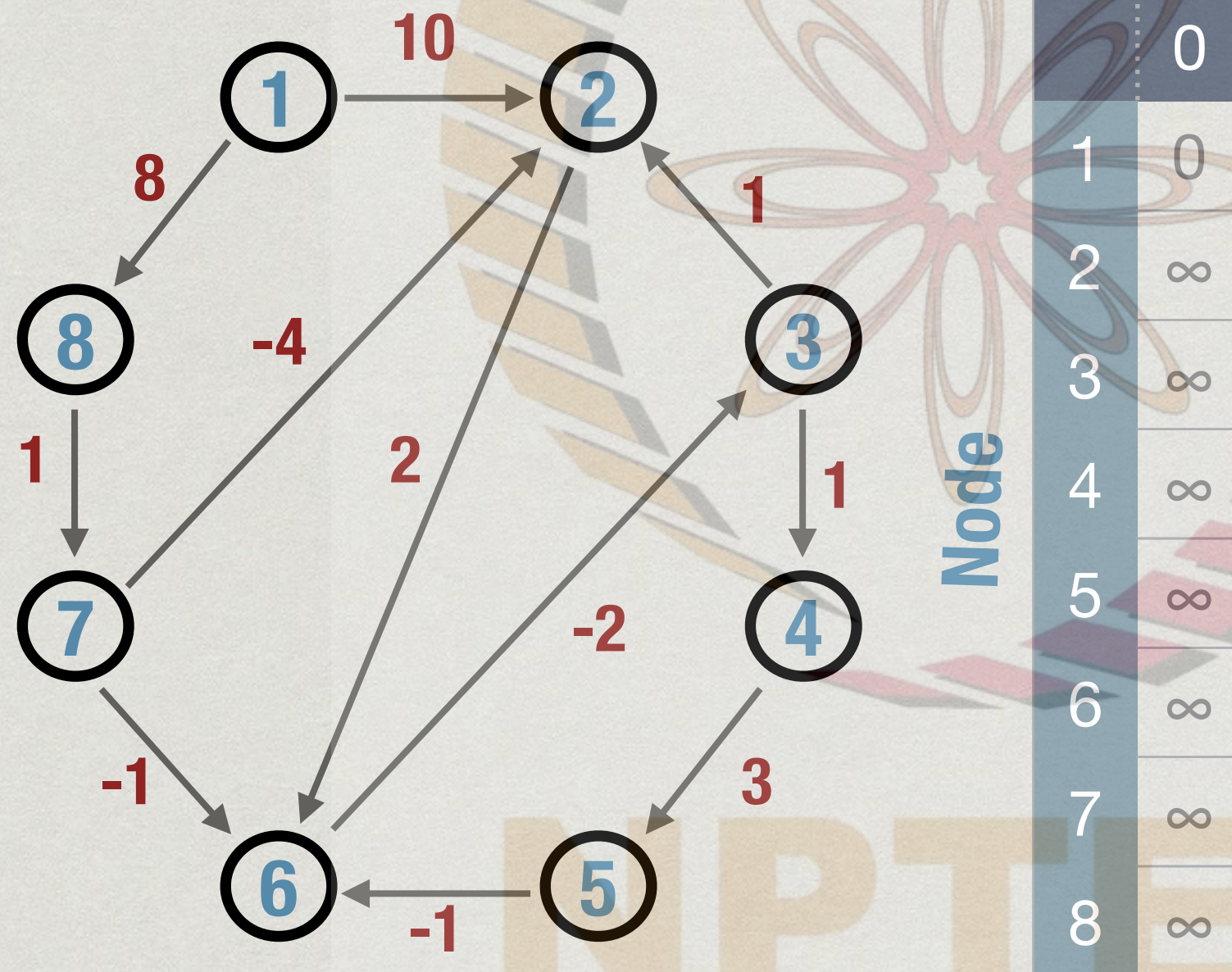
# Example





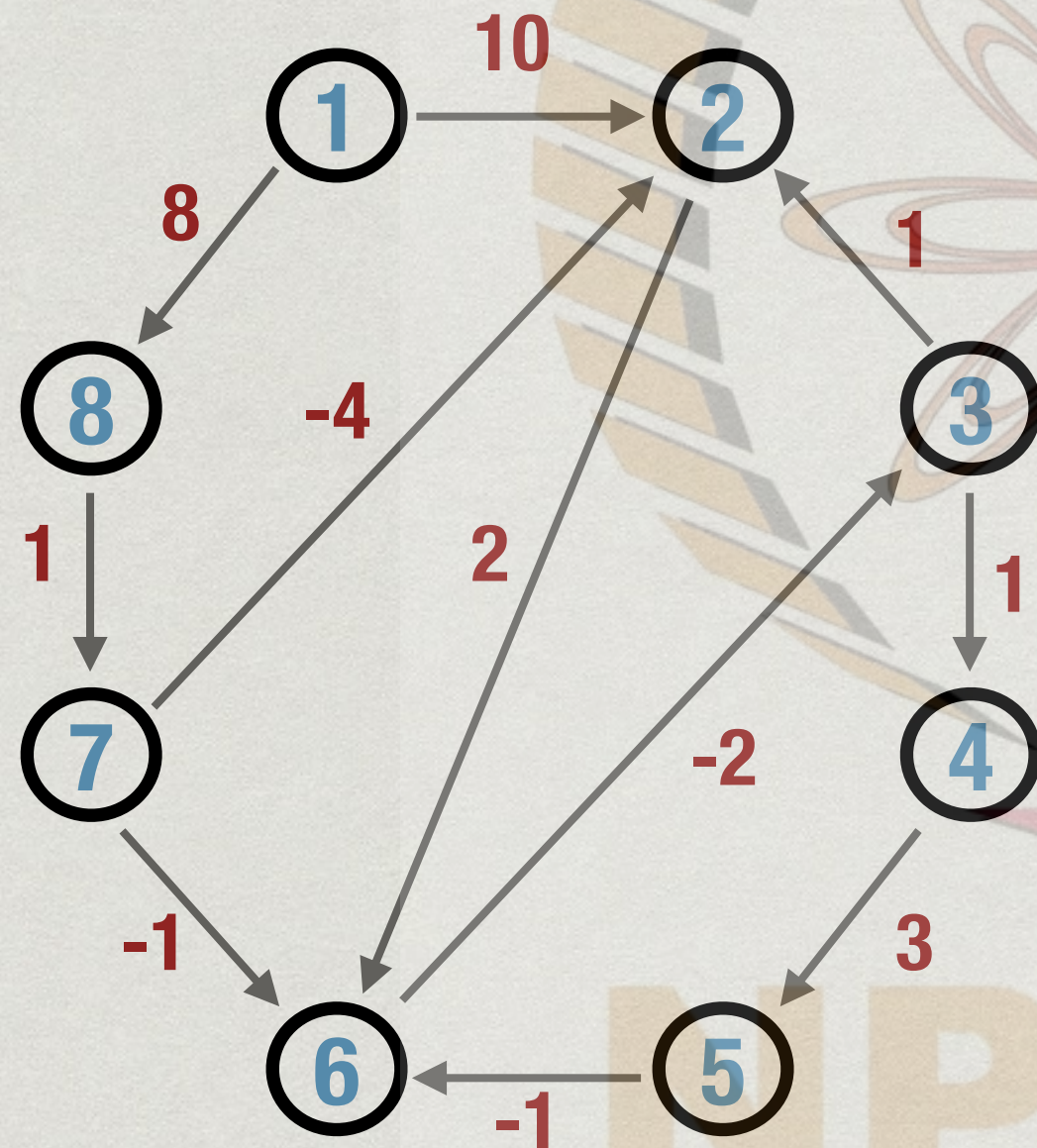
# Example

Iteration





# Example

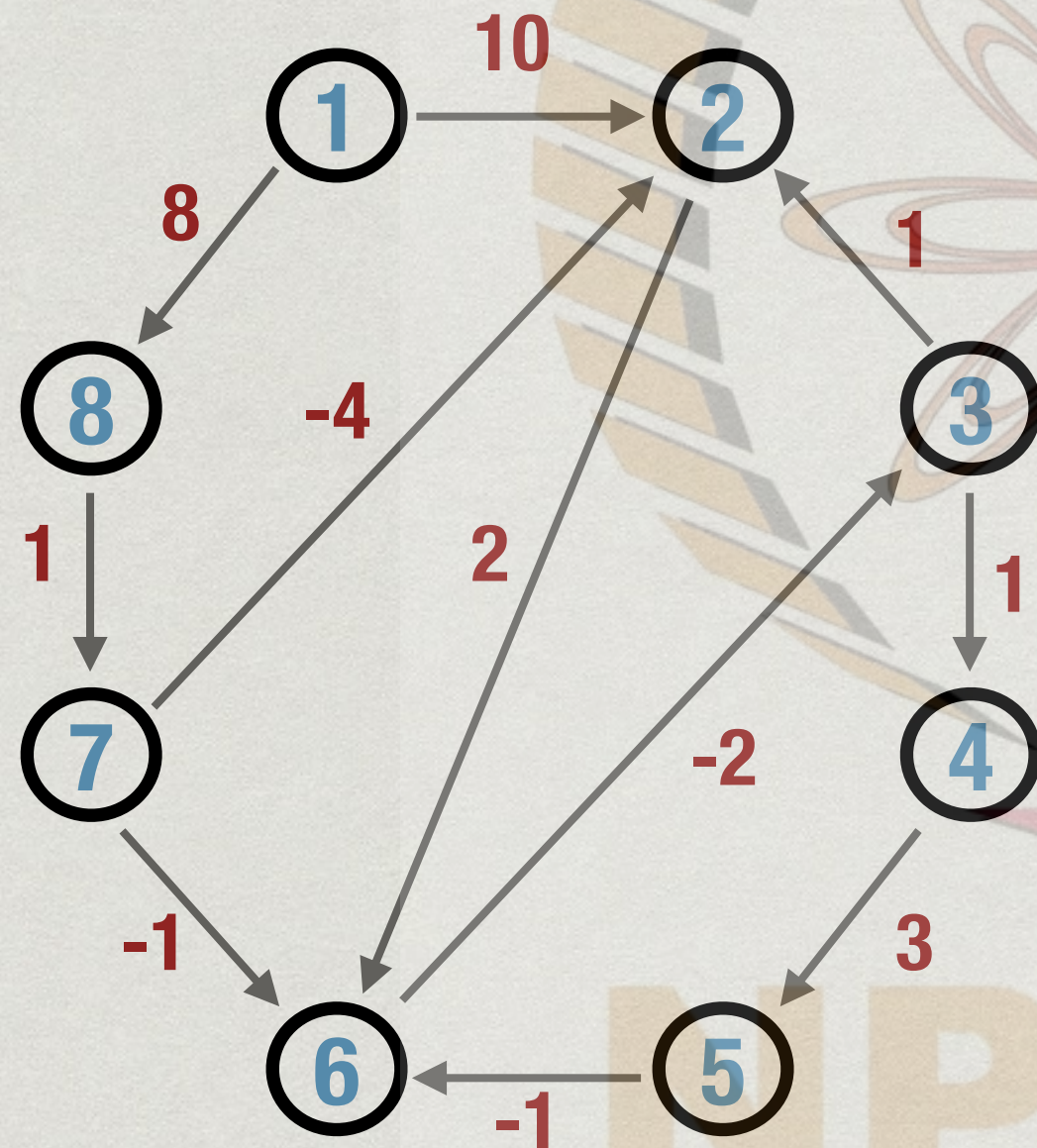


Iteration

	0	1
1	0	0
2	$\infty$	10
3	$\infty$	$\infty$
4	$\infty$	$\infty$
5	$\infty$	$\infty$
6	$\infty$	$\infty$
7	$\infty$	$\infty$
8	$\infty$	8



# Example

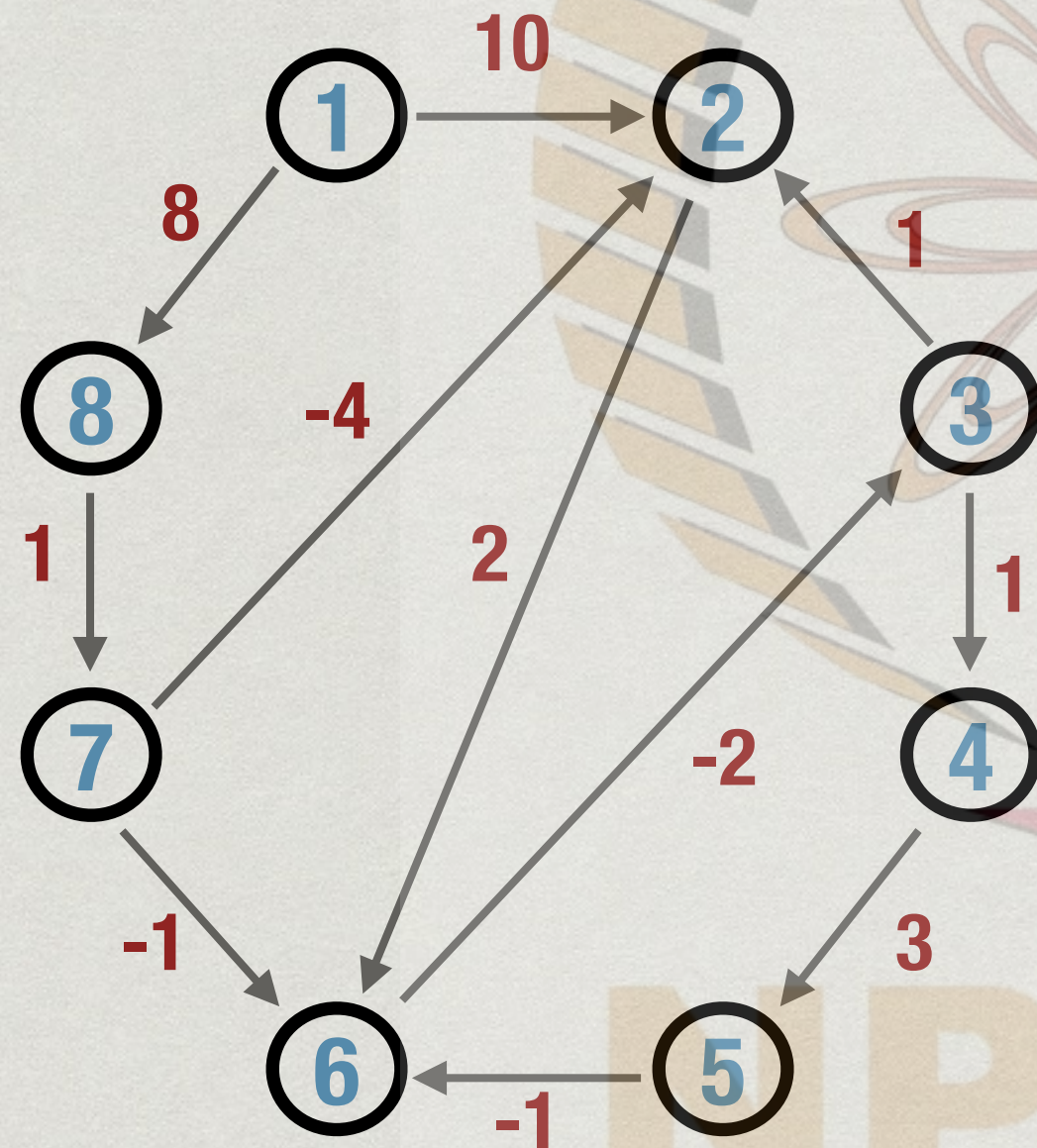


Iteration

	0	1	2
1	0	0	0
2	$\infty$	10	10
3	$\infty$	$\infty$	$\infty$
4	$\infty$	$\infty$	$\infty$
5	$\infty$	$\infty$	$\infty$
6	$\infty$	$\infty$	12
7	$\infty$	$\infty$	9
8	$\infty$	8	8



# Example

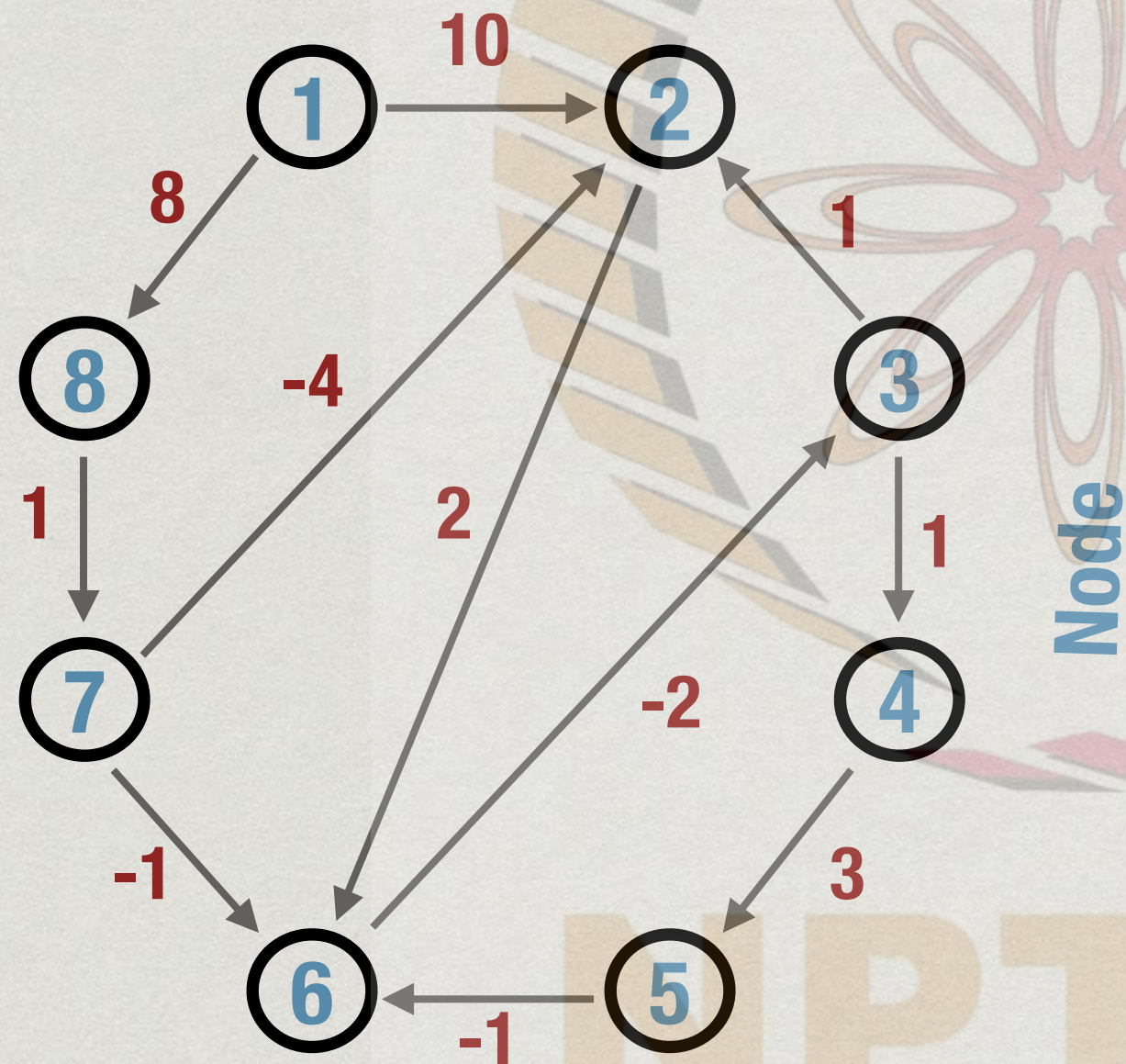


Iteration

	0	1	2	3
1	0	0	0	0
2	$\infty$	10	10	5
3	$\infty$	$\infty$	$\infty$	10
4	$\infty$	$\infty$	$\infty$	$\infty$
5	$\infty$	$\infty$	$\infty$	$\infty$
6	$\infty$	$\infty$	12	8
7	$\infty$	$\infty$	9	9
8	$\infty$	8	8	8



# Example

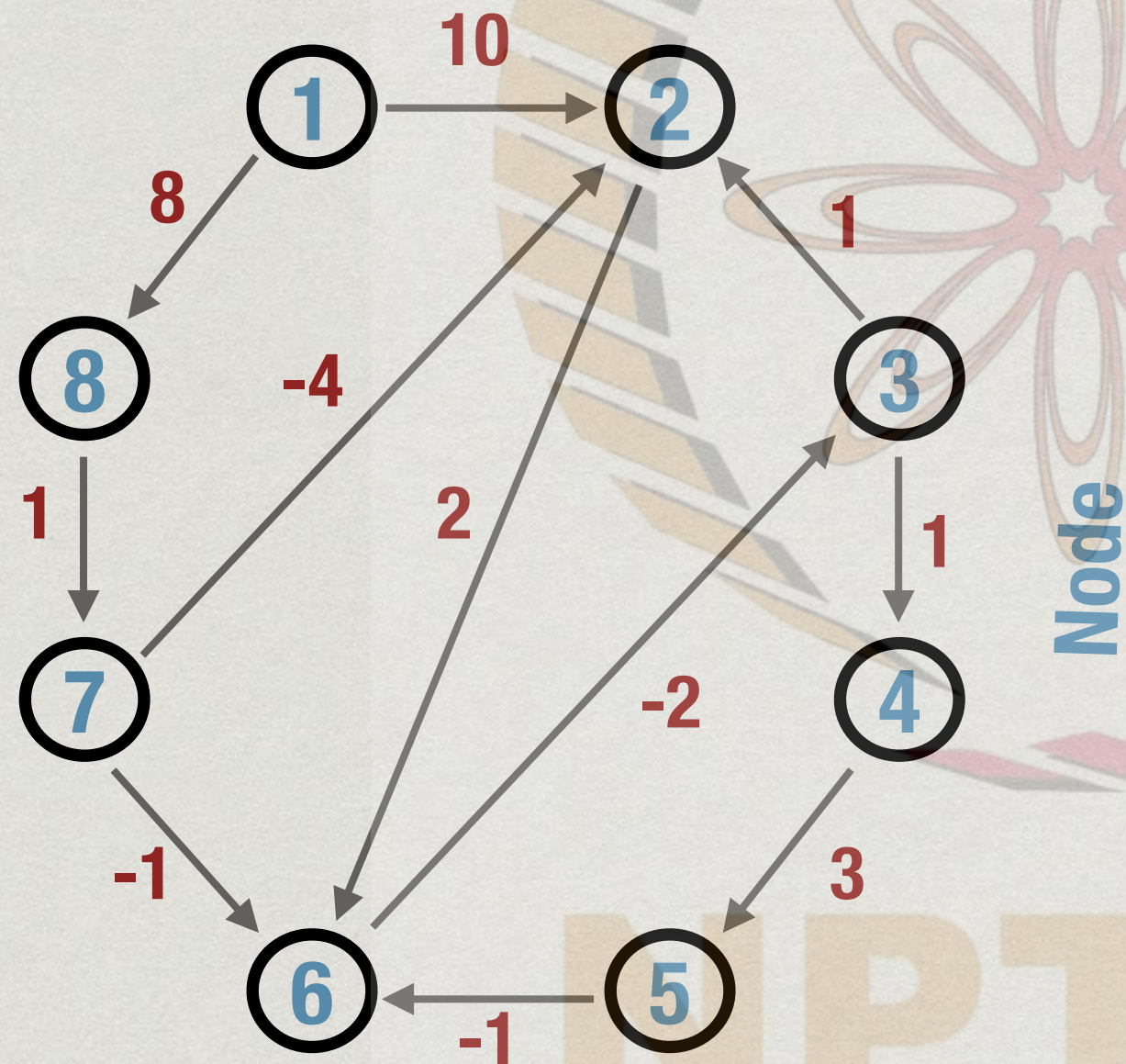


Iteration

	0	1	2	3	4
1	0	0	0	0	0
2	$\infty$	10	10	5	5
3	$\infty$	$\infty$	$\infty$	10	6
4	$\infty$	$\infty$	$\infty$	$\infty$	11
5	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
6	$\infty$	$\infty$	12	8	7
7	$\infty$	$\infty$	9	9	9
8	$\infty$	8	8	8	8



# Example

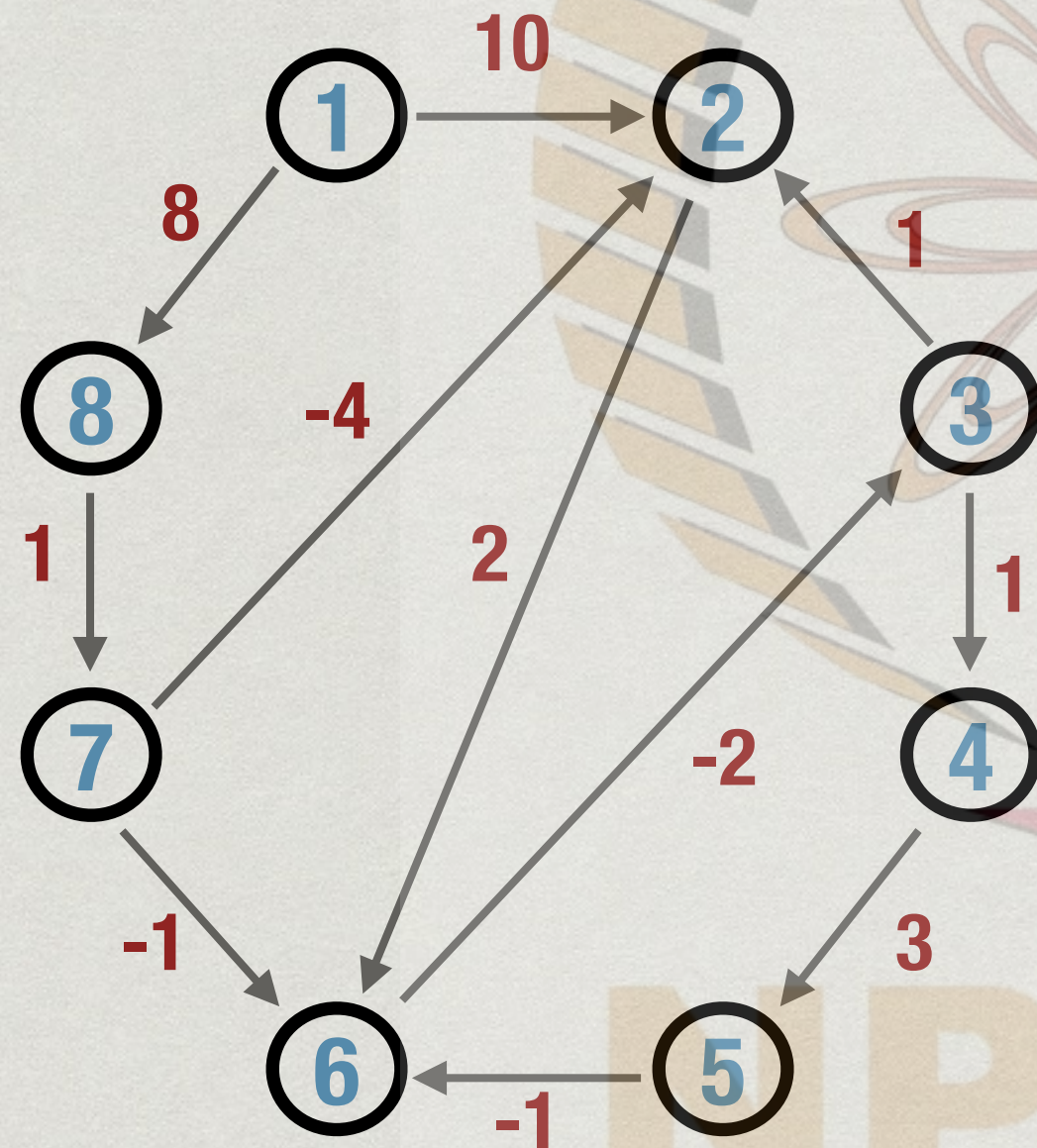


Iteration

	0	1	2	3	4	5
1	0	0	0	0	0	0
2	$\infty$	10	10	5	5	5
3	$\infty$	$\infty$	$\infty$	10	6	5
4	$\infty$	$\infty$	$\infty$	$\infty$	11	7
5	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	14
6	$\infty$	$\infty$	12	8	7	7
7	$\infty$	$\infty$	9	9	9	9
8	$\infty$	8	8	8	8	8



# Example

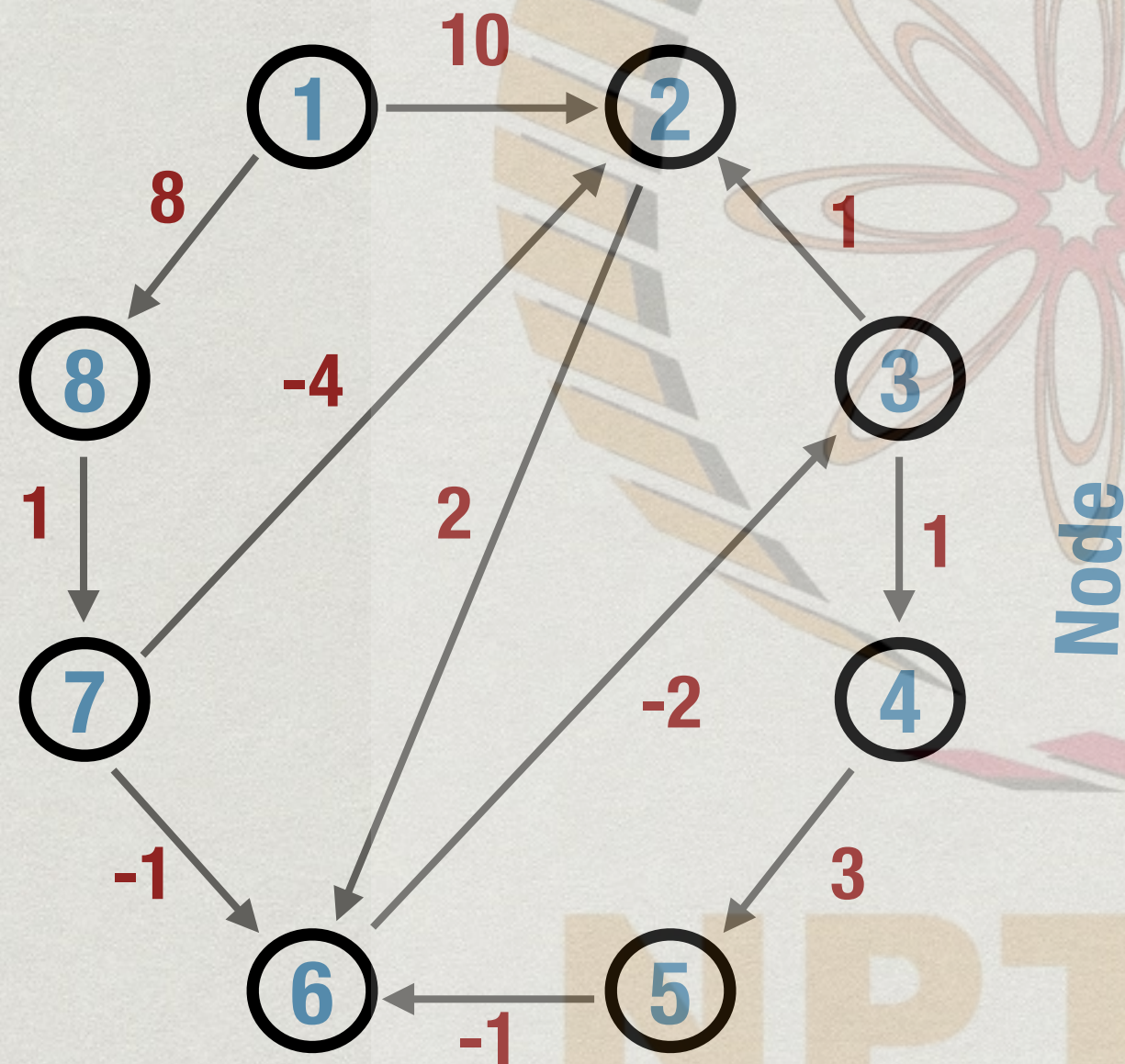


Iteration

	0	1	2	3	4	5	6
1	0	0	0	0	0	0	0
2	$\infty$	10	10	5	5	5	5
3	$\infty$	$\infty$	$\infty$	10	6	5	5
4	$\infty$	$\infty$	$\infty$	$\infty$	11	7	6
5	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	14	10
6	$\infty$	$\infty$	12	8	7	7	7
7	$\infty$	$\infty$	9	9	9	9	9
8	$\infty$	8	8	8	8	8	8



# Example



Iteration

	0	1	2	3	4	5	6	7
1	0	0	0	0	0	0	0	0
2	$\infty$	10	10	5	5	5	5	5
3	$\infty$	$\infty$	$\infty$	10	6	5	5	5
4	$\infty$	$\infty$	$\infty$	$\infty$	11	7	6	6
5	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	14	10	9
6	$\infty$	$\infty$	12	8	7	7	7	7
7	$\infty$	$\infty$	9	9	9	9	9	9
8	$\infty$	8	8	8	8	8	8	8



# Complexity

- \* Outer loop runs  $n$  times
- \* In each loop, for each edge  $(j,k)$ , we run  $\text{update}(j,k)$ 
  - \* Adjacency matrix —  $O(n^2)$  to identify all edges
  - \* Adjacency list —  $O(m)$
- \* Overall
  - \* Adjacency matrix —  $O(n^3)$
  - \* Adjacency list —  $O(mn)$