

NPTEL MOOC, JAN-FEB 2015
Week 5, Module 7

DESIGN AND ANALYSIS OF ALGORITHMS

Divide and conquer: Closest pair of points

MADHAVAN MUKUND, CHENNAI MATHEMATICAL INSTITUTE
<http://www.cmi.ac.in/~madhavan>

Example: Video game

- * Several objects on screen
- * Basic step: find closest pair of objects
- * Given n objects, naïve algorithm is $O(n^2)$
 - * For each pair of objects, compute their distance
 - * Report minimum distance over all such pairs
- * There is a clever algorithm based on divide and conquer that takes time $O(n \log n)$

Formally

- * A point p is given by xy coordinates (x_p, y_p)
- * Distance between $p_1 = (x_1, y_1)$ and $p_2 = (x_2, y_2)$ is the usual
 - * $d(p_1, p_2) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$
- * Given n points (p_1, p_2, \dots, p_n) , find the closest pair
 - * Assume that no two points have same x or y coordinate
- * Brute force
 - * Try every pair (p_i, p_j) and report minimum
 - * $O(n^2)$

In 1 dimension

- * A point p is given by x coordinate x_p
 - * $d(p_i, p_j) = |p_j - p_i|$
- * Given n points (p_1, p_2, \dots, p_n)
 - * Sort the points — $O(n \log n)$
 - * Compute minimum separation between adjacent points after sorting — $O(n)$

2 dimensions, divide and conquer

- * Split set of points into two halves by vertical line
- * Recursively compute closest pair in left and right half
- * Need to then compute closest pairs across separating line
- * How can we do this efficiently?

Sorting points by x and y

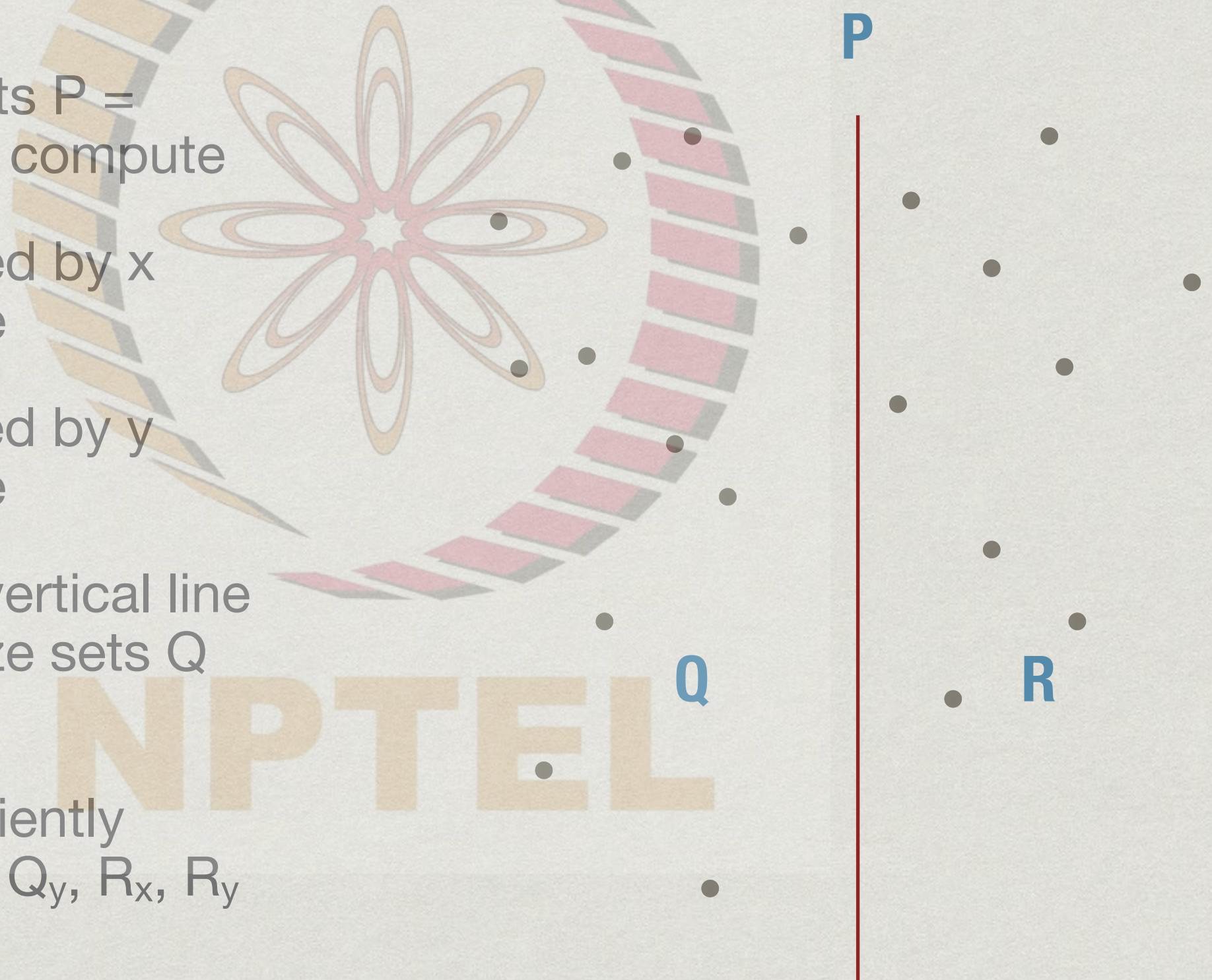
- * Given n points $P = \{p_1, p_2, \dots, p_n\}$, compute
 - * P_x , P sorted by x coordinate
 - * P_y , P sorted by y coordinate
- * Divide P by vertical line into equal size sets Q and R
- * Need to efficiently compute Q_x , Q_y , R_x , R_y

P

NPTTEL

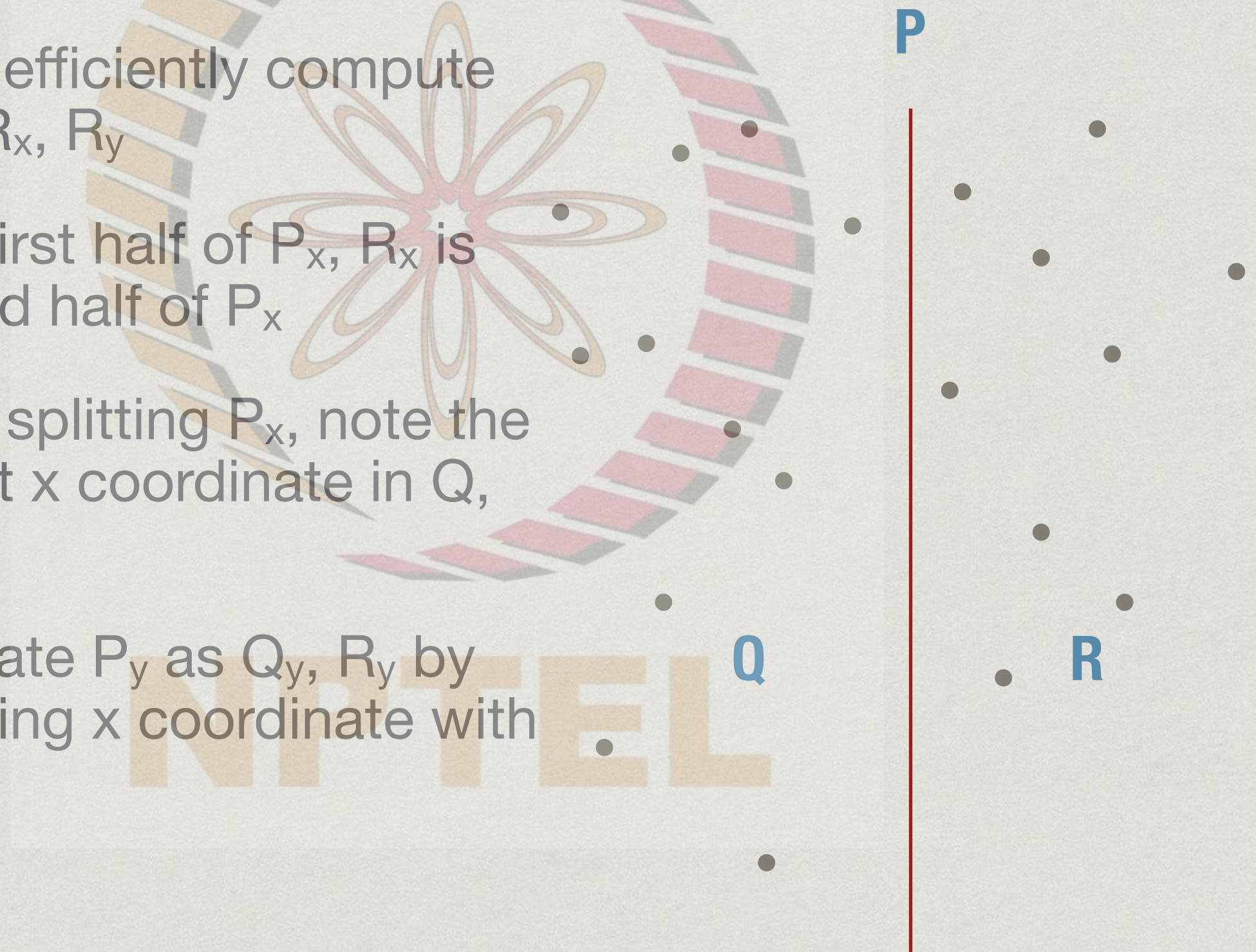
Sorting points by x and y

- * Given n points $P = \{p_1, p_2, \dots, p_n\}$, compute
 - * P_x , P sorted by x coordinate
 - * P_y , P sorted by y coordinate
- * Divide P by vertical line into equal size sets Q and R
- * Need to efficiently compute Q_x , Q_y , R_x , R_y



Sorting points by x and y

- * Need to efficiently compute Q_x, Q_y, R_x, R_y
- * Q_x is first half of P_x , R_x is second half of P_x
- * When splitting P_x , note the largest x coordinate in Q , x_Q
- * Separate P_y as Q_y, R_y by checking x coordinate with x_Q
- * All $O(n)$

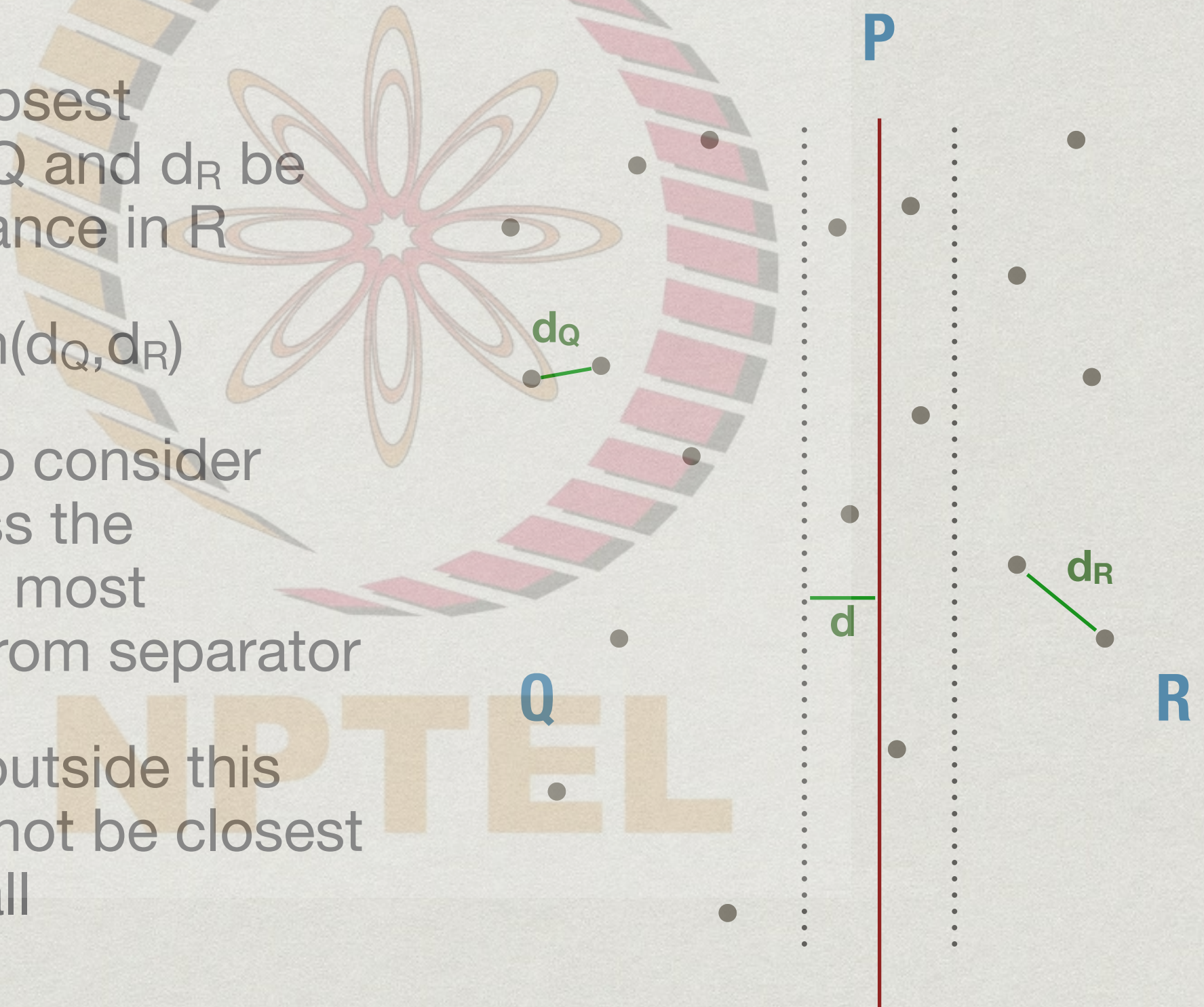


2 dimensions, divide and conquer

- * Basic recursive call is $\text{ClosestPair}(P_x, P_y)$
- * Set up recursive calls $\text{ClosestPair}(Q_x, Q_y)$ and $\text{ClosestPair}(R_x, R_y)$ for left and right half of P in time $O(n)$
- * How to combine these recursive solutions?

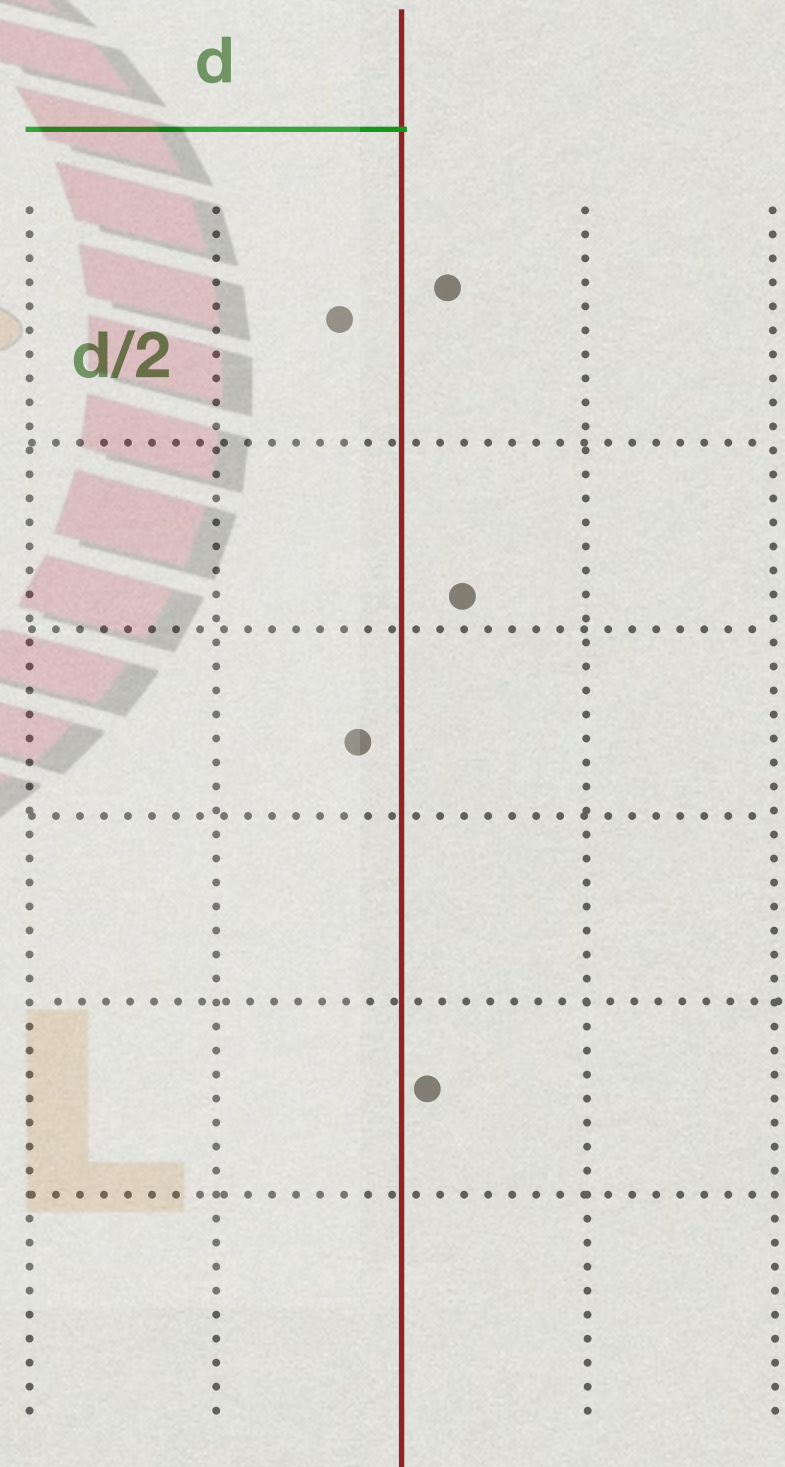
Combining solutions

- * Let d_Q be closest distance in Q and d_R be closest distance in R
- * Let d be $\min(d_Q, d_R)$
- * Only need to consider points across the separator at most distance d from separator
- * Any pair outside this band cannot be closest pair overall



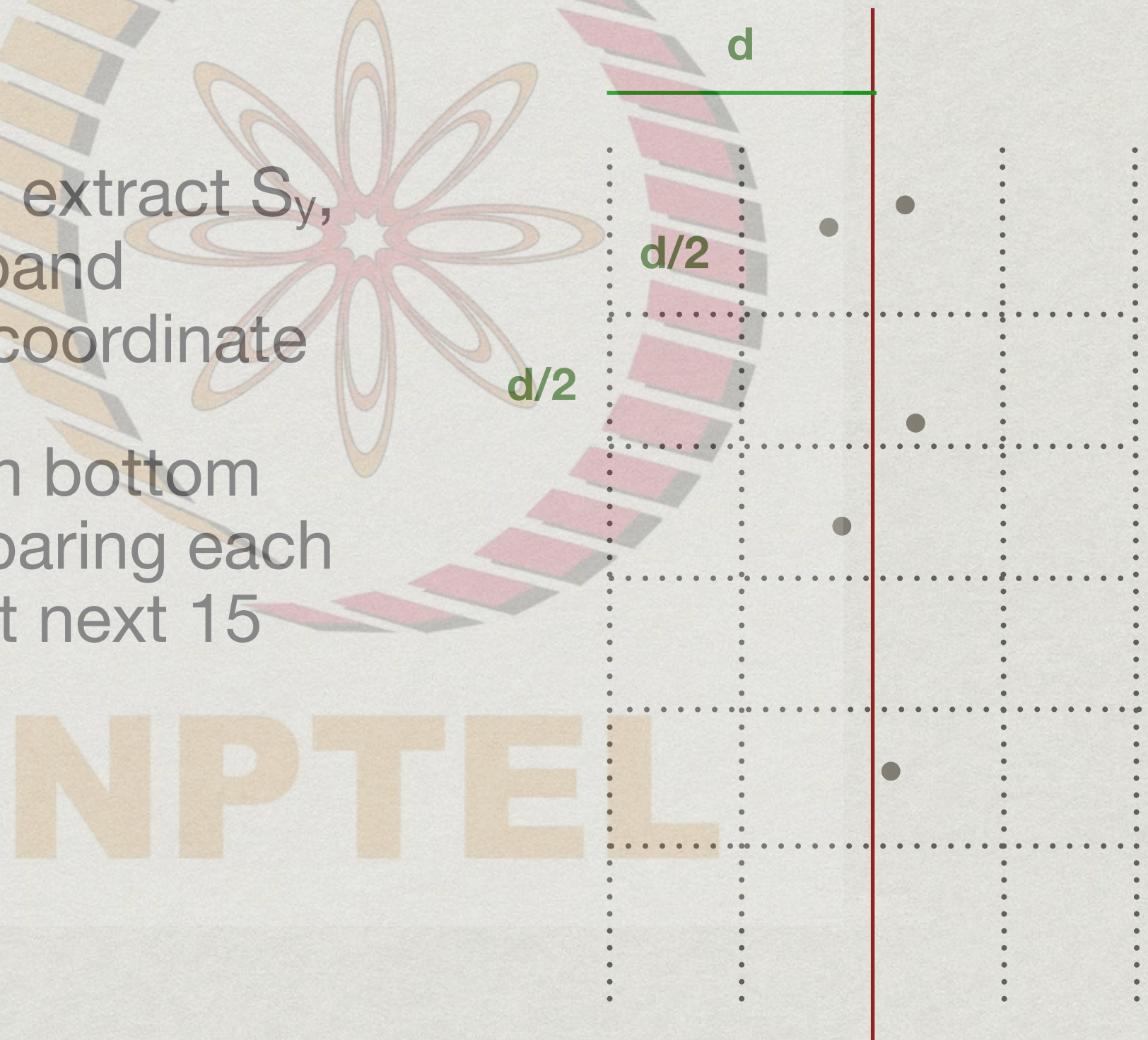
Combining solutions

- * Divide the distance d zone into boxes of side $d/2$
- * Cannot have two points in same box
- * Diagonal is $\sqrt{2}d/2$
- * Any point within distance d must lie in a neighbourhood of 4×4 boxes
- * Need to check each point against 15 others



Combining solutions

- * From Q_y , R_y , extract S_y , points in d-band sorted by y coordinate
- * Scan S_y from bottom to top, comparing each point against next 15 points in S_y
- * Linear scan



Algorithm

```
function ClosestPair(Px,Py)
```

```
if ( $|Px| \leq 3$ )
```

```
    compute pairwise distances and  
    return closest pair and distance
```

```
Construct (Qx,Qy,Rx,Ry)
```

```
(dQ,q1,q2) = ClosestPair(Qx,Qy)
```

```
(dR,r1,r2) = ClosestPair(Rx,Ry)
```

```
Construct Sy and scan to find (dS,s1,s2)
```

```
Return (dQ,q1,q2), (dR,r1,r2), (dS,s1,s2) depending  
on which among (dQ,dR,dS) is minimum
```


Analysis

- * Computing (P_x, P_y) from P takes $O(n \log n)$
- * Recursive algorithm
 - * Setting up (Q_x, Q_y, R_x, R_y) from (P_x, P_y) is $O(n)$
 - * Setting up S_y from Q_y, R_y is $O(n)$
 - * Scanning S_y is $O(n)$
 - * Recurrence is same as merge sort
- * Overall $T(n) = O(n \log n)$