

So what did happen on Tristan da Cunha?

Anton Camacho

Thesis: Stochastic modelling in epidemiology
with applications to human influenza



Under the supervision of
Bernard Cazelles and Amaury Lambert

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Methods

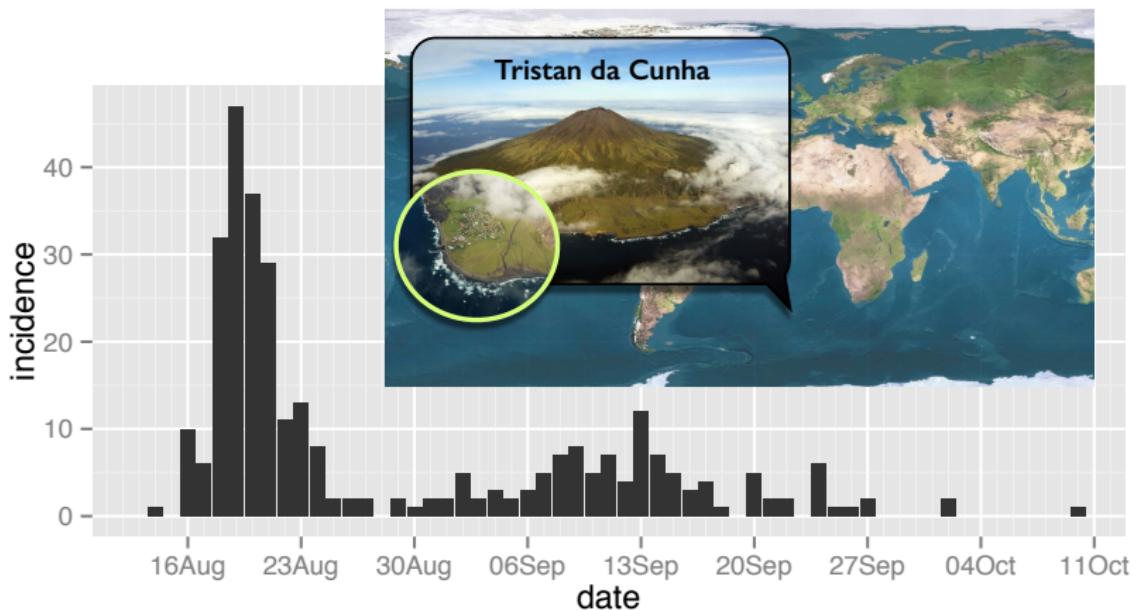
Modelling

Inference

Results

Model inference & selection

1971 influenza epidemic on Tristan da Cunha



Two waves, 96% infected, 32% reinjected

Broader context

- Influenza usually spreads through the human population in multiple-wave outbreaks.
- Successive reinfection of individuals over a short time interval has been explicitly reported during past pandemics.

Cross-Protection between Successive Waves of the 1918–1919 Influenza Pandemic: Epidemiological Evidence from US Army Camps and from Britain

John M. Barry,¹ Cécile Viboud,² and Lone Simonsen³

2008 *J Infect Dis*

**Pandemic (H1N1)
2009 Reinfection,
Chile**

Carlos M. Perez,
Marcela Ferres,
and Jaime A. Labarca

2010 *Emerg Infect Dis*

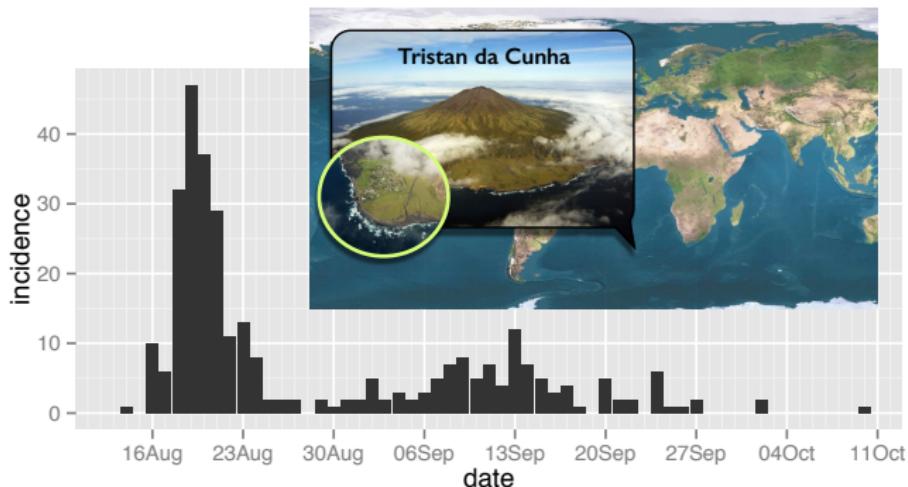
Broader context

- Influenza usually spreads through the human population in multiple-wave outbreaks.
- Successive reinfection of individuals over a short time interval has been explicitly reported during past pandemics.

Problematic

The causes of rapid reinfection and the *role* of reinfection in driving multiple-wave outbreaks remain poorly understood.

Case study



Objectives

- Disentangling between 5 biological mechanisms that could explain rapid reinfection of the islanders
- Assess how well the most likely mechanism can reproduce the data

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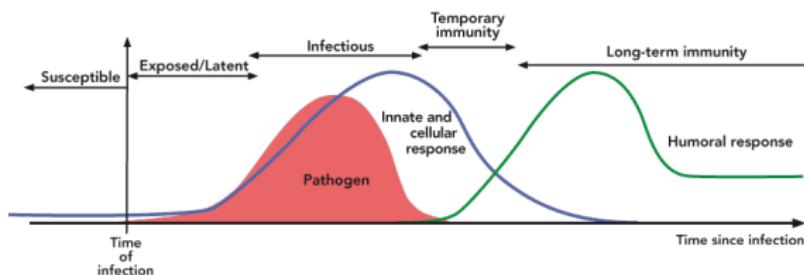
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Mechanistic modelling of reinfection hypotheses



Primary immune response to influenza

Mut the virus Mutated during the first wave

2Vi 2 Viruses since the beginning of the epidemic

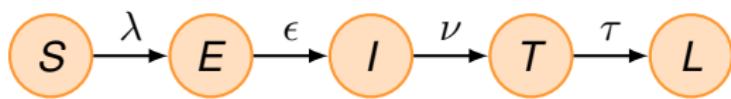
InH Intra-Host reinfection

PPI Partially Protective Immunity

AoN All or Nothing (the SEITL model in the practical)

Win Window of reinfection

Mechanistic modelling of reinfection hypotheses



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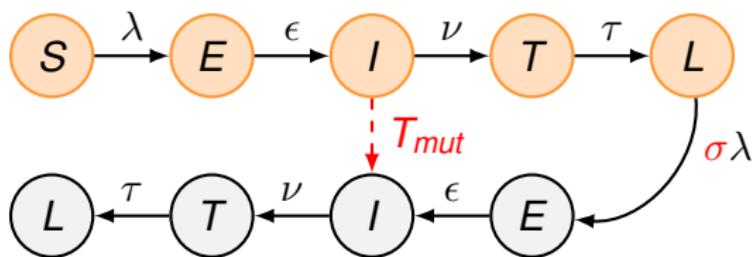
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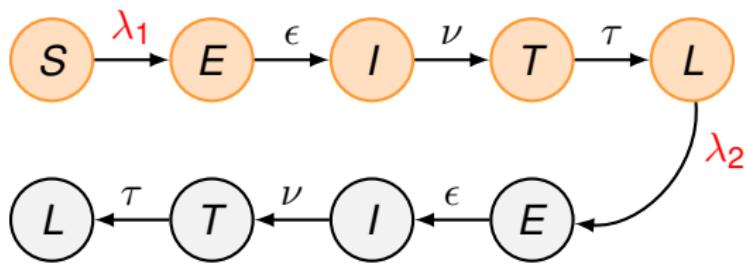
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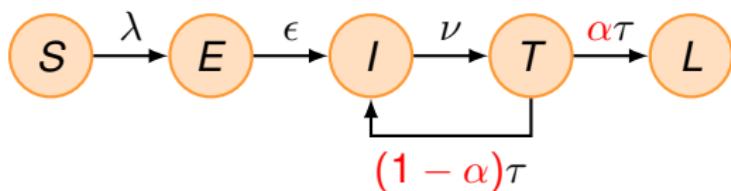
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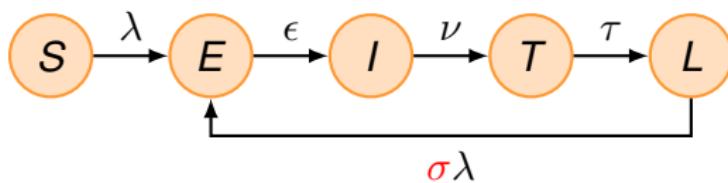
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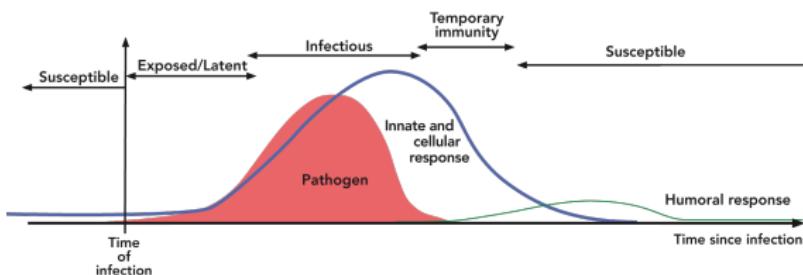
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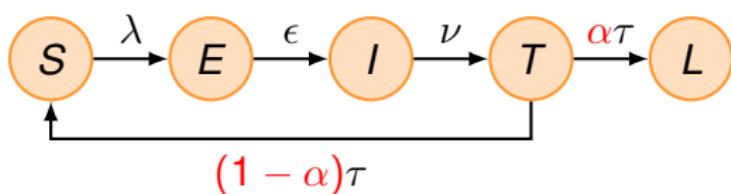
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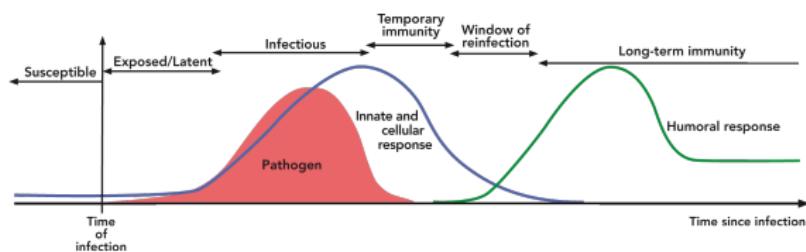
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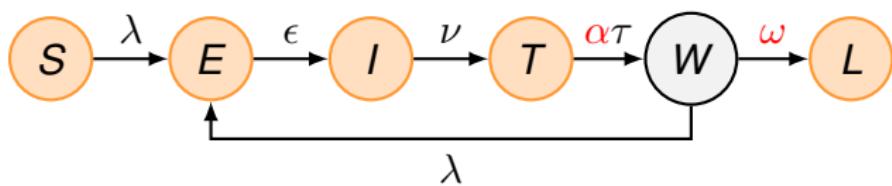
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Win Window of reinfection

Likelihood approach

For a given **time series**: $y_{1:T} = (y_1, y_2, \dots, y_T)$ and a **state space model** completely specified by:

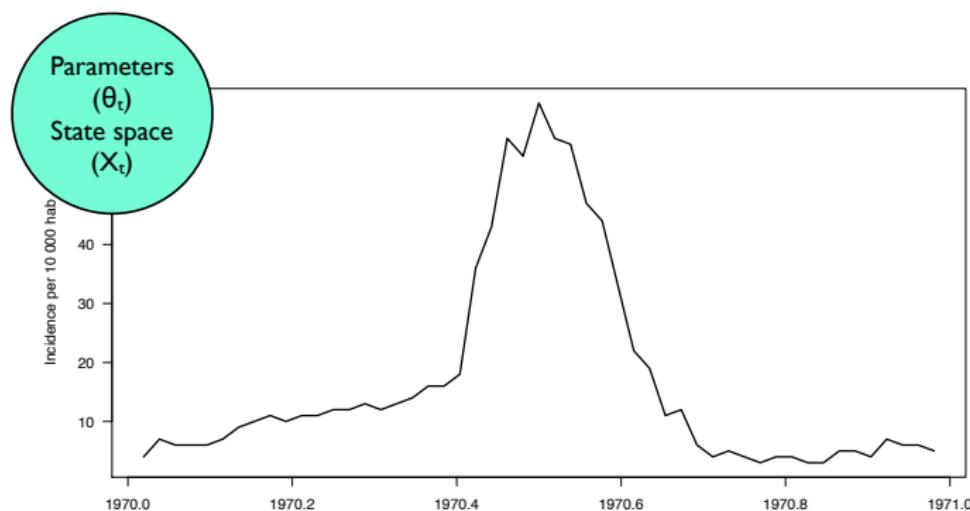
$$M : \begin{cases} p(x_t|x_{t-1}, \theta) & \text{fitmodel\$simulate} \\ p(y_t|x_t, \theta) & \text{fitmodel\$pointLogLike} \\ p(x_0|\theta) & \text{init.state now depends on } \theta \end{cases}$$

the **likelihood** is given by the identity:

$$p(y_{1:T}|\theta) = \prod_{t=1}^T p(y_t|y_{1:t-1}, \theta)$$

How can we find θ_{MLE} that maximises the likelihood?

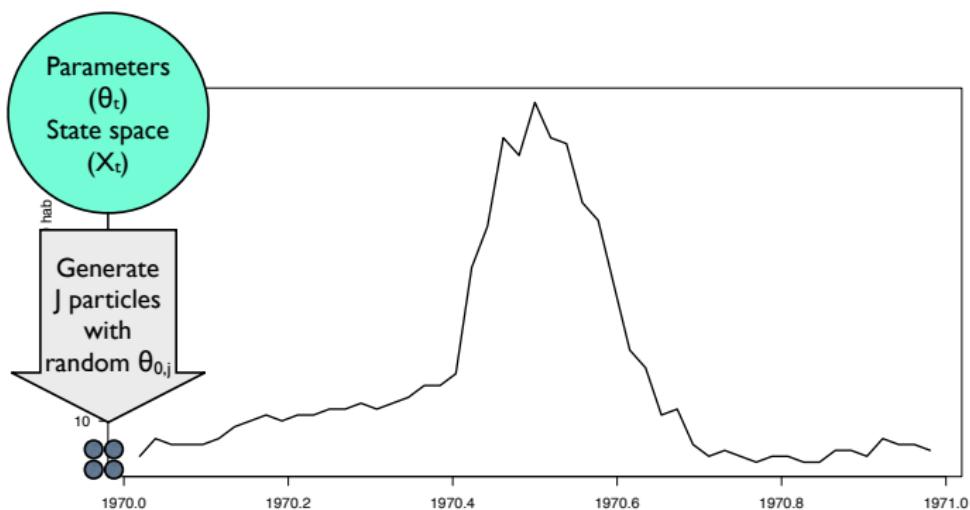
Iterated Filtering (Ionides et al., 2006)



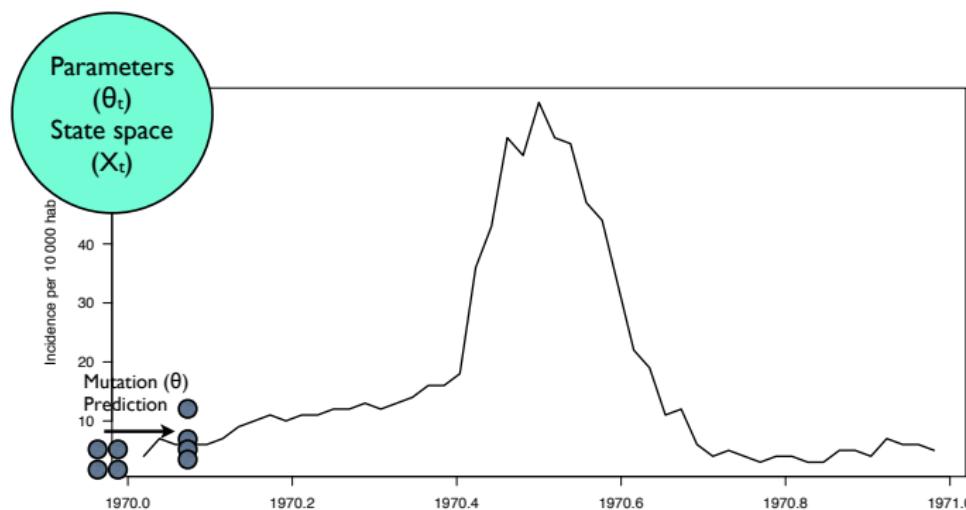
Parameters
(θ_t)
State space
(X_t)

$$M \left\{ \begin{array}{l} f(x_t|x_{t-1}, \theta) \\ f(y_t|x_t, \theta) \\ f(x_0|\theta) \end{array} \right. \rightarrow M' \left\{ \begin{array}{l} f(x_t|x_{t-1}, \theta_t) \\ f(y_t|x_t, \theta_t) \\ f(x_0|\theta_t) \end{array} \right.$$

Iterated Filtering (Ionides et al., 2006)

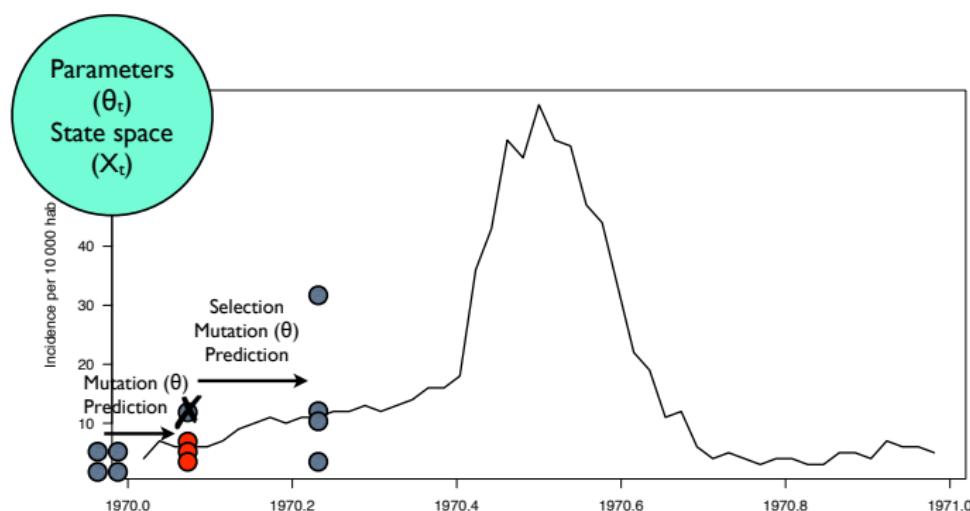


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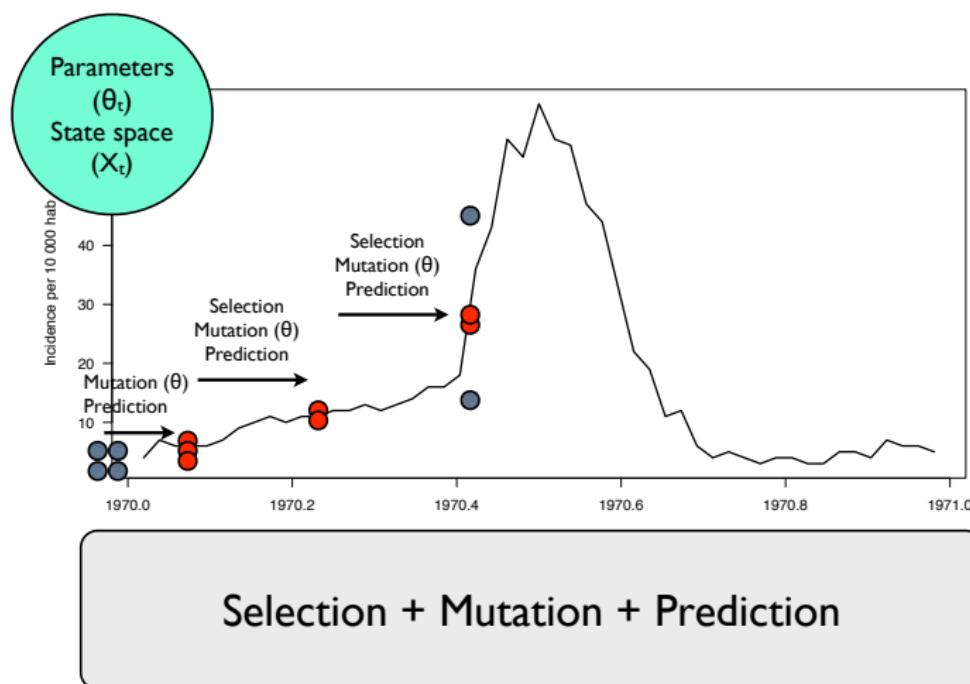
For each particle j :
$$\begin{cases} X_{1,j} & \text{is drawn from } f(x_1|x_0 = X_{0,j}, \theta_{0,j}) \\ \theta_{1,j} & \text{is drawn from } \mathcal{N}(\theta_{0,j}, \sigma) \\ w_{1,j} & \text{is equal to } f(y_1|x_1 = X_{1,j}, \theta_{1,j}) \end{cases}$$

Iterated Filtering (Ionides et al., 2006)

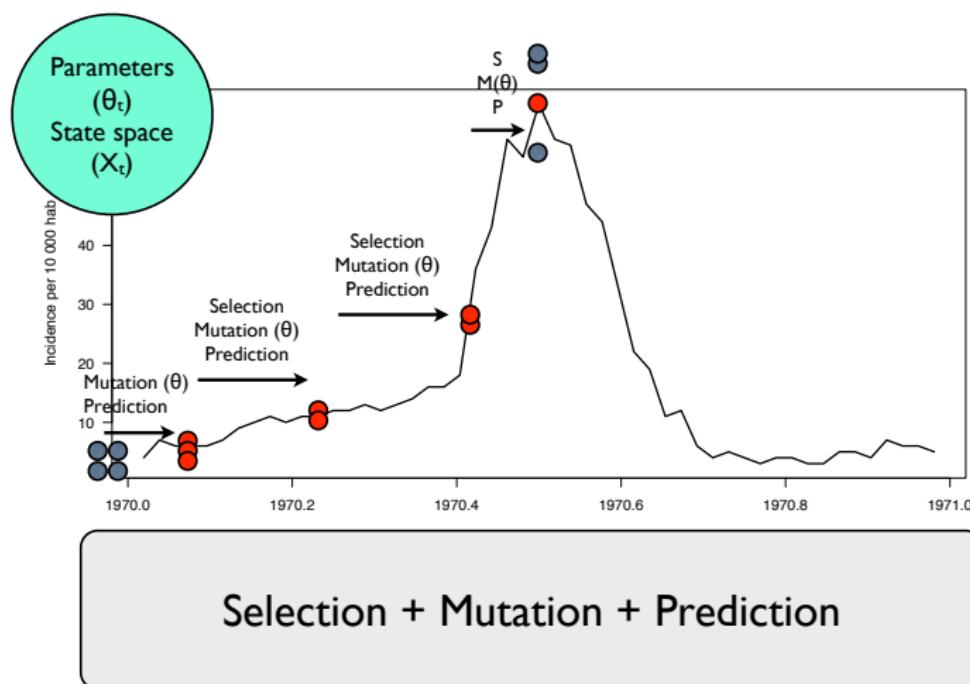


Darwinian selection: particles reproduce proportionally to their weight w_j

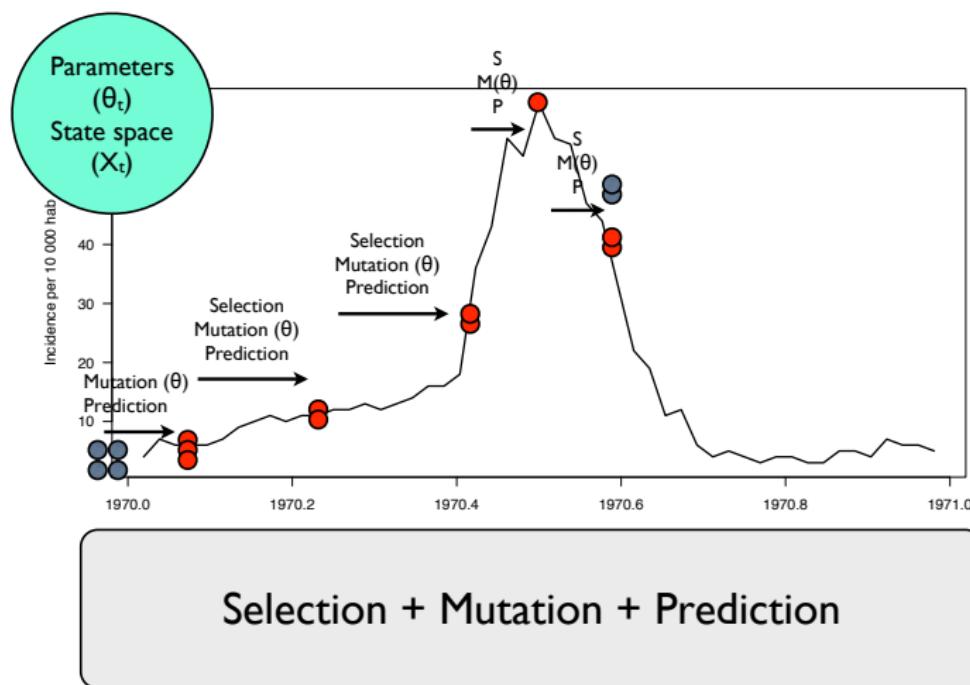
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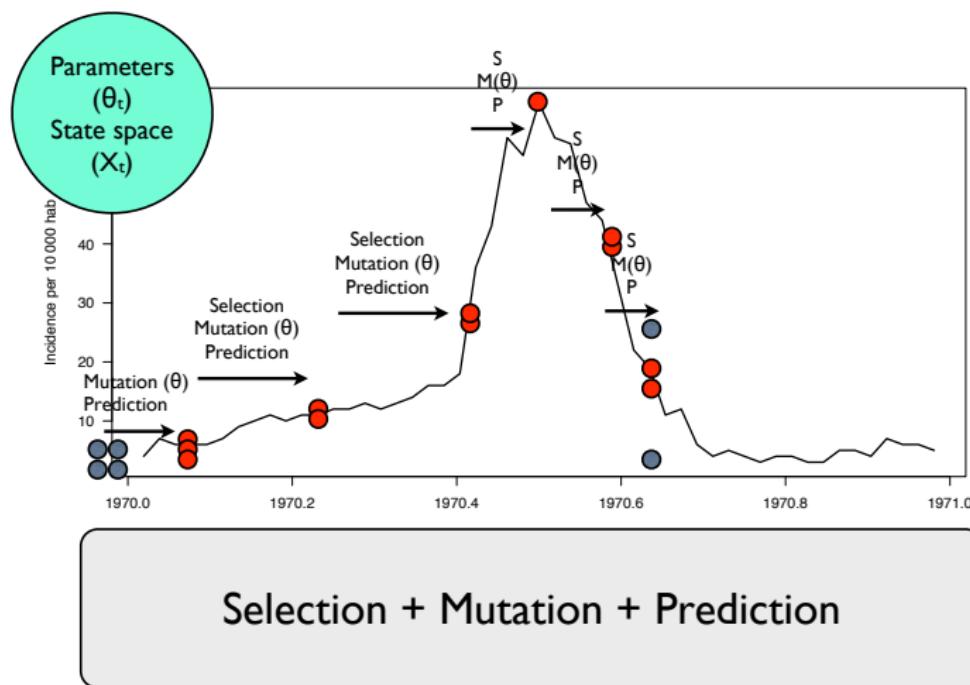
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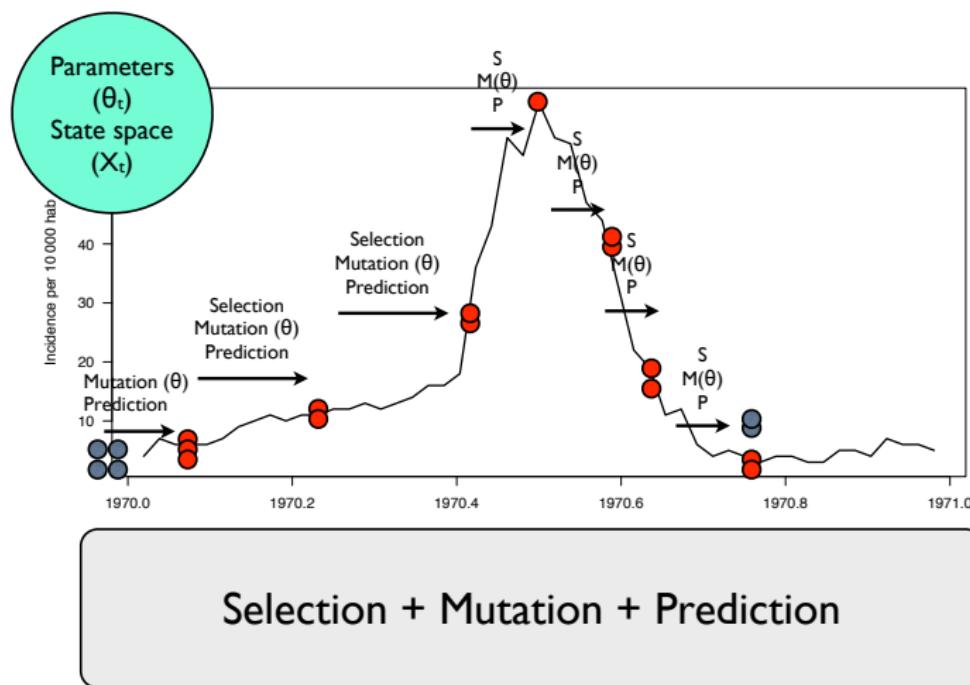
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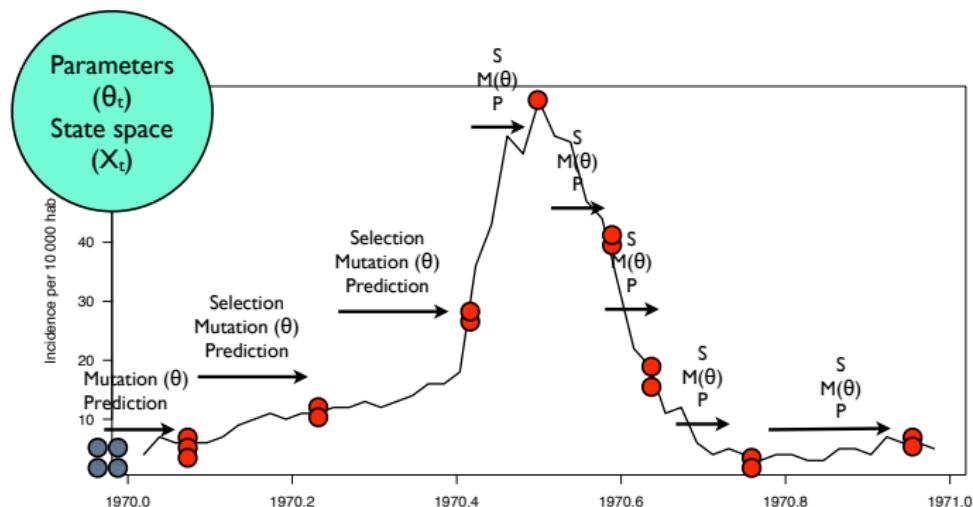
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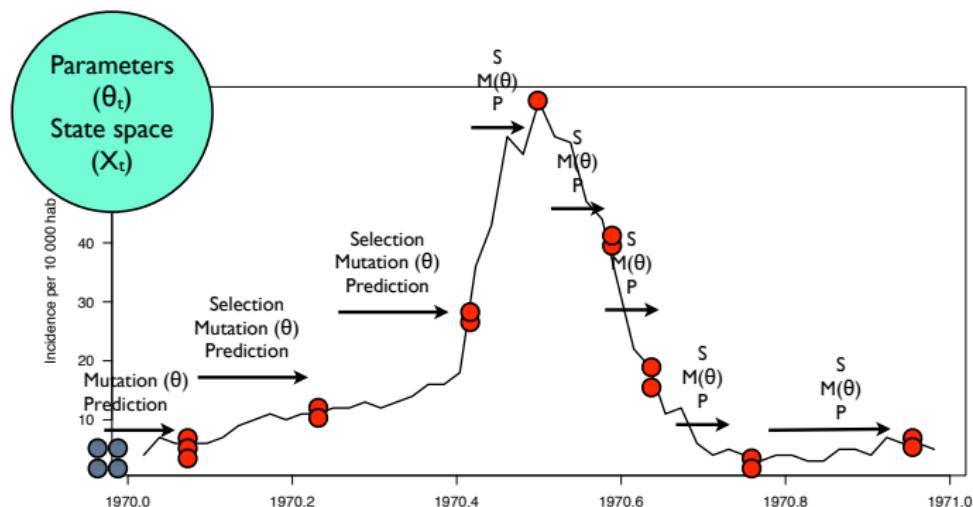
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Punctual estimates
for each time t
from $\{(\theta_{t,j}, w_{t,j})\}_J$

$$\left\{ \begin{array}{ll} E[\theta_t | y_{1:t}] & \text{by } \hat{\theta}_t \\ Var(\theta_t | y_{1:t-1}) & \text{by } V_t \\ f(y_t | y_{1:t-1}, \theta) & \text{by } l_t(\theta) = \frac{1}{J} \sum_J w_{t,j} \end{array} \right.$$

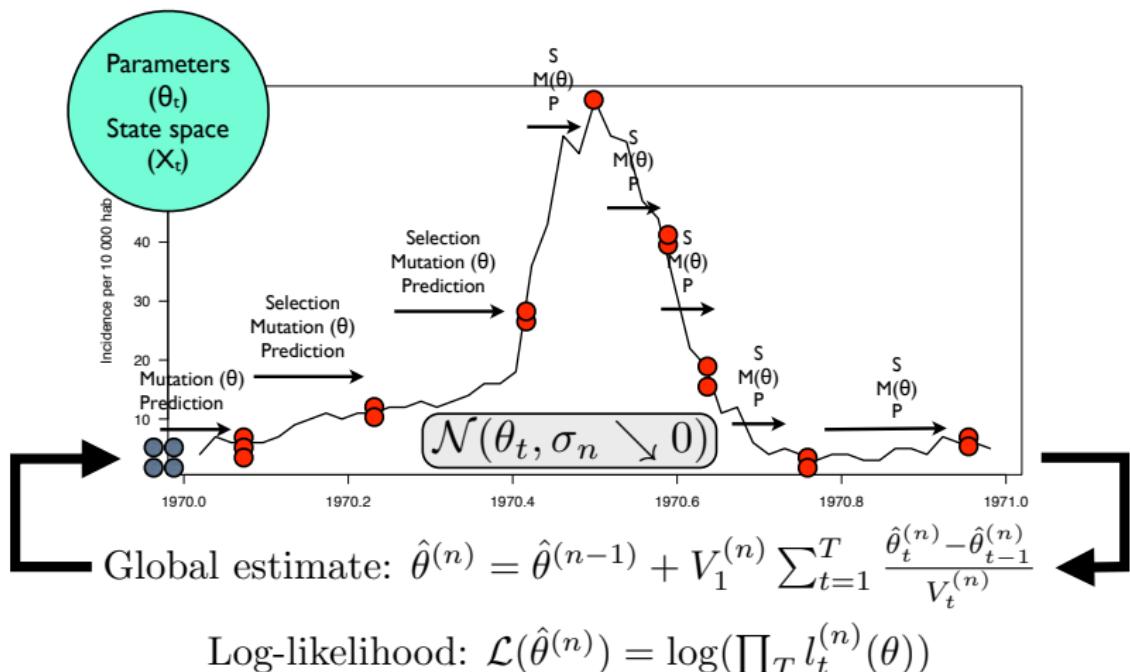
Iterated Filtering (Ionides et al., 2006)



$$\text{Global estimate: } \hat{\theta} = \hat{\theta}_0 + V_1 \sum_{t=1}^T \frac{\hat{\theta}_t - \hat{\theta}_{t-1}}{V_t}$$

$$\text{Log-likelihood: } \mathcal{L}(\hat{\theta}) = \log(\prod_T l_t(\theta))$$

Iterated Filtering (Ionides et al., 2006)



Convergence of global estimator

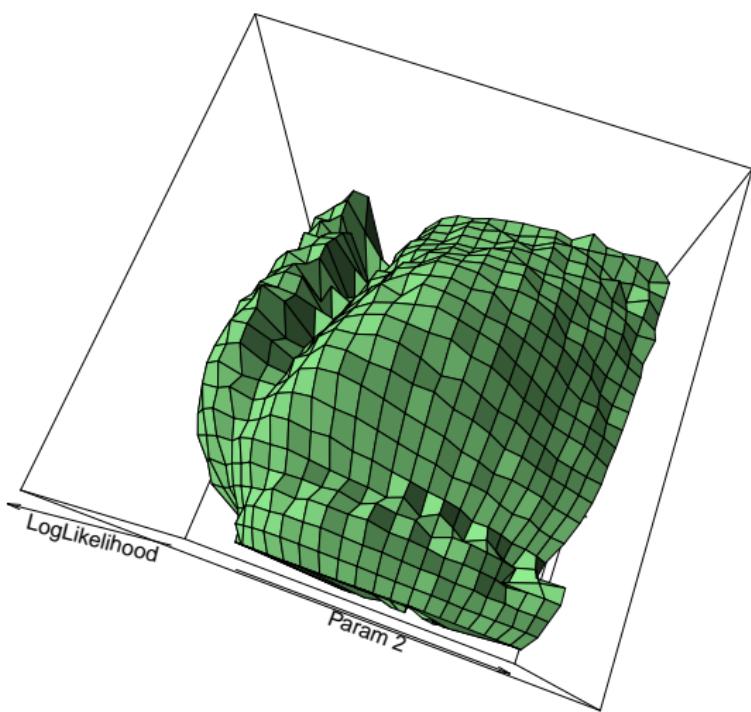
$$\hat{\theta}^{(n)} = \hat{\theta}^{(n-1)} + V_1^{(n)} \sum_{t=1}^T \frac{\hat{\theta}_t^{(n)} - \hat{\theta}_{t-1}^{(n)}}{V_t^{(n)}}$$

As shown by Ionides *et al.* (2006), under rather mild assumptions,

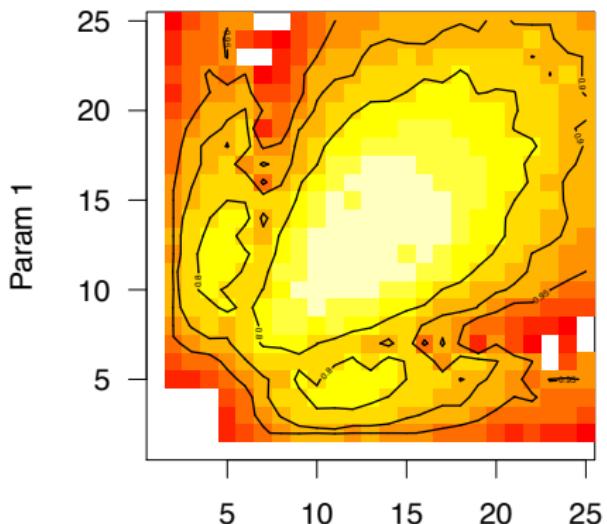
$$\lim_{\sigma \rightarrow 0} \sum_{t=1}^T \frac{\hat{\theta}_t - \hat{\theta}_{t-1}}{V_t} = \nabla \log f(y_{1:T} | \theta, \sigma = 0)$$

so that, for a sufficiently small σ_n , the algorithm iteratively updates $\hat{\theta}^{(n)}$ in the direction of increasing likelihood, with a fixed point at a **local maximum of the likelihood surface**.

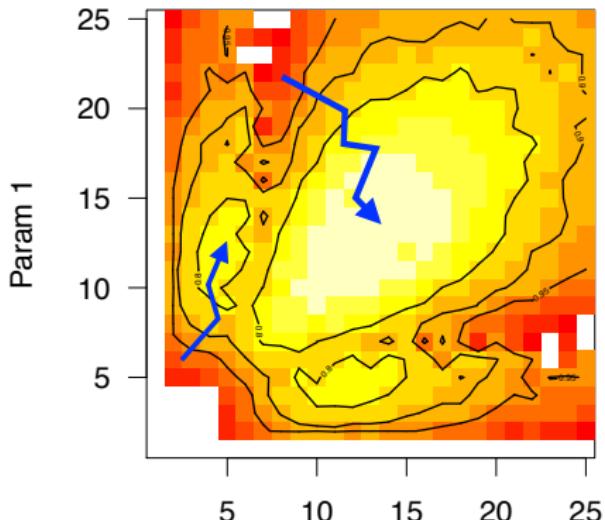
Exploring the likelihood surface



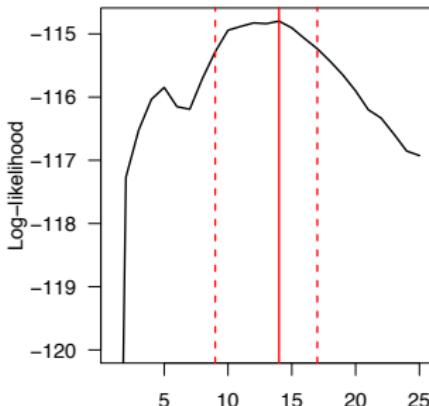
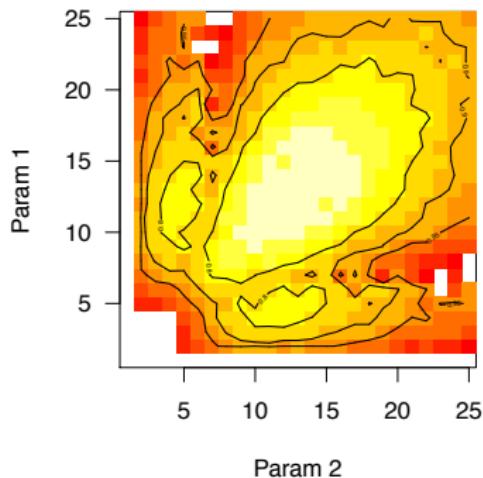
Exploring the likelihood surface



Exploring the likelihood surface

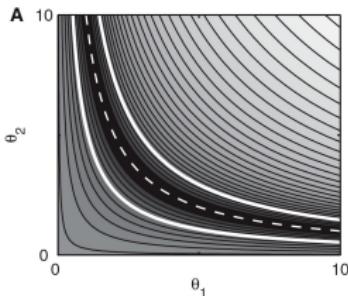


Exploring the likelihood surface

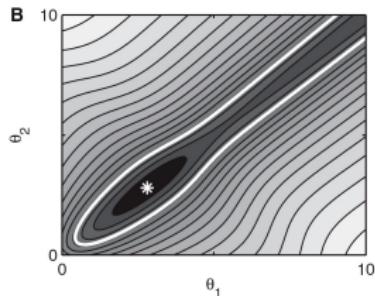


Log-likelihood profiles allows us to compute 95% *confidence* intervals.

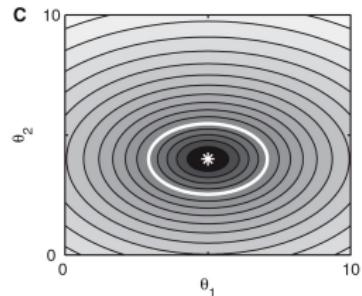
Identifiability issues



Structural
non-identifiability

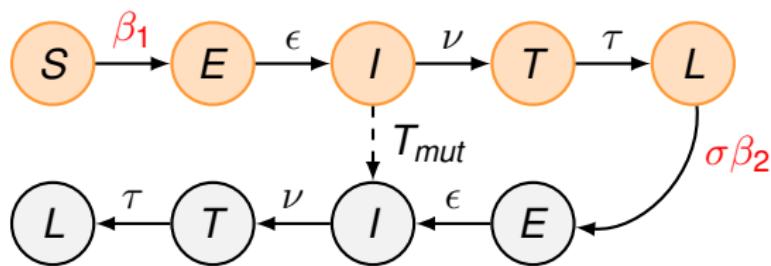


Practical
non-identifiability

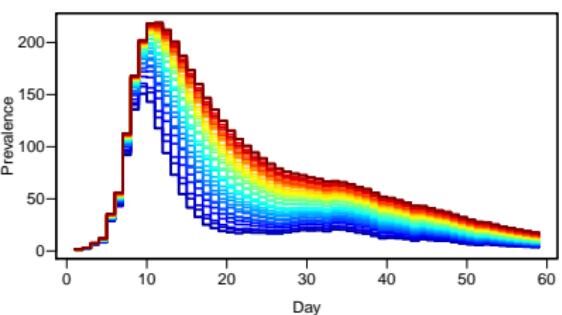
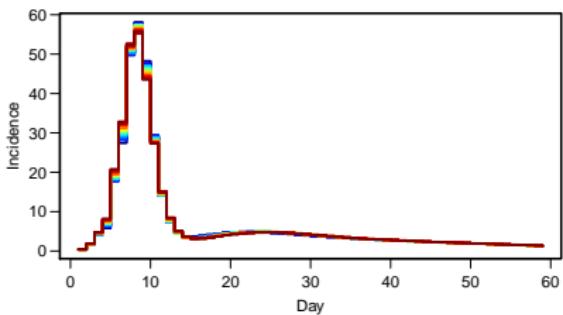
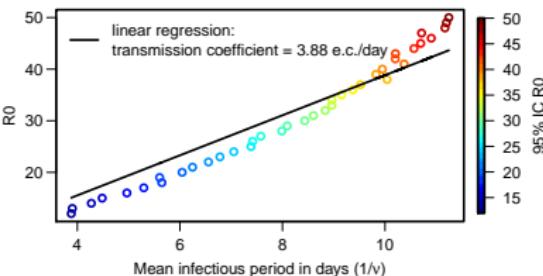
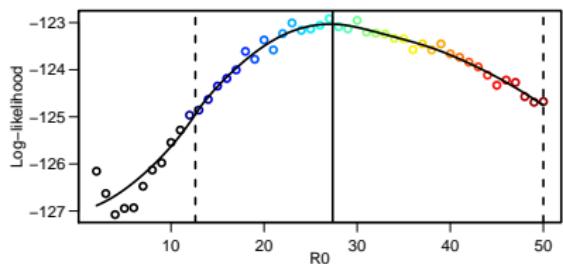


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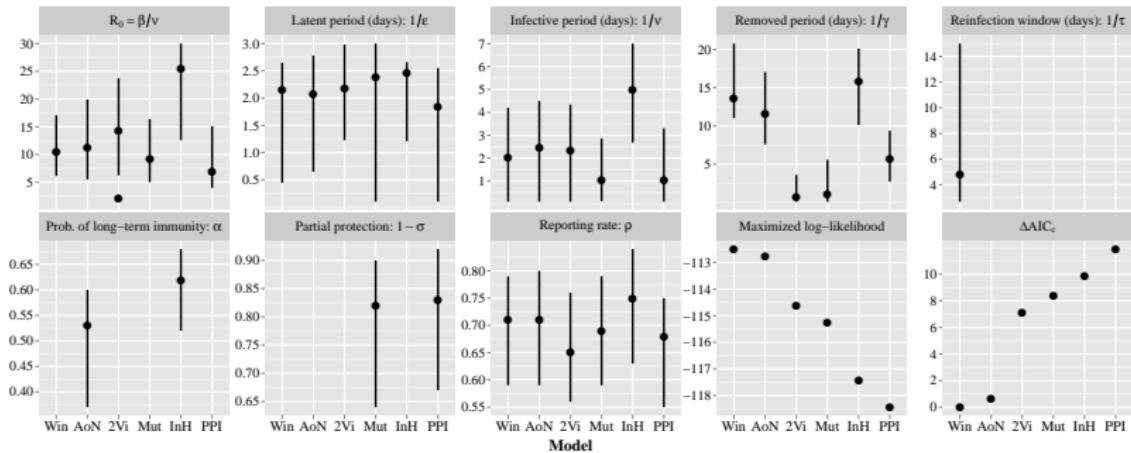
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Parameter inference



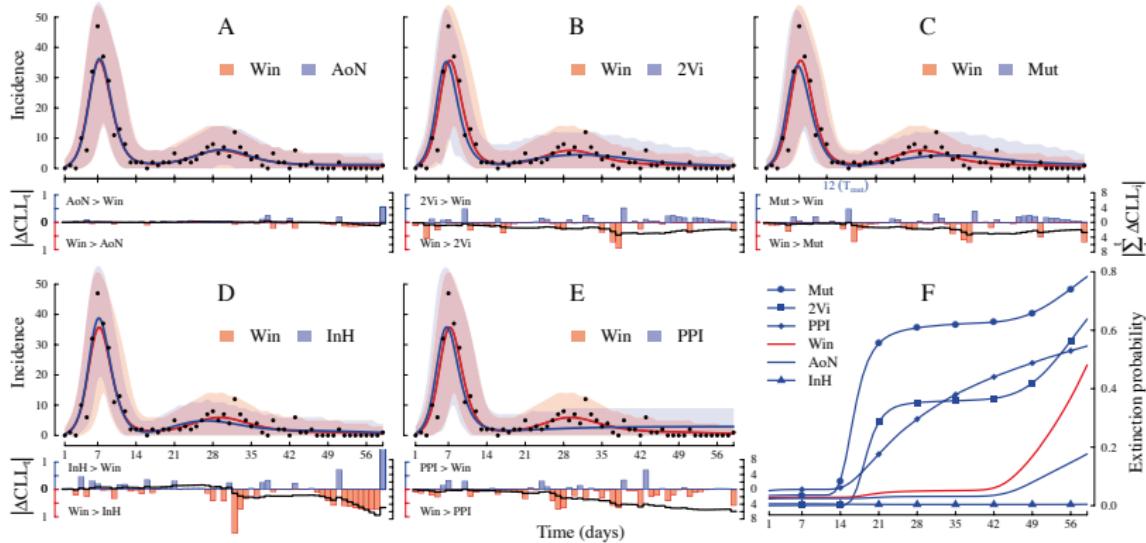
Model selection

- We used the corrected Akaike Information Criterion (AIC_c) to select the best model

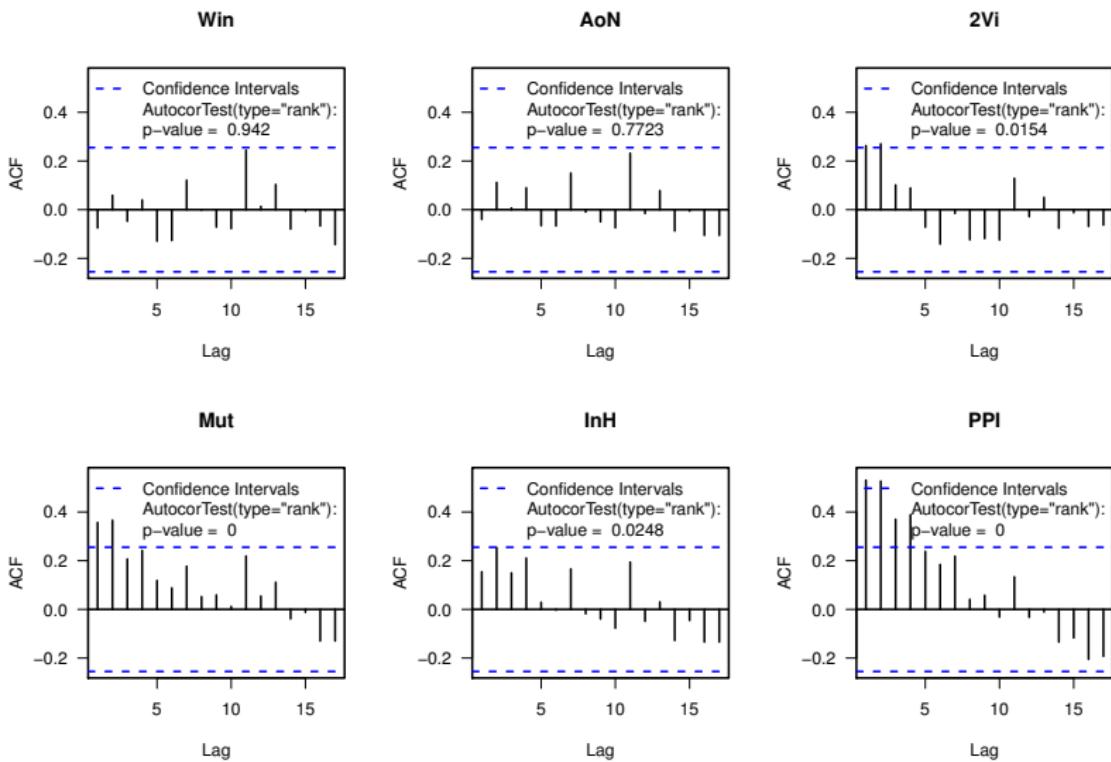
$$AIC_c = -2\mathcal{L}(\theta_{MLE}) + 2k + \frac{2k(k+1)}{T-k-1} \text{ with } k = ||\theta||$$

- The best model corresponds to the Windows of reinfection hypothesis.
- The AoN (SEITL in the practical) model has substantial support ($\Delta AIC_c < 2$).
- The other models have considerably less support ($\Delta AIC_c > 7$)

Assess the fit



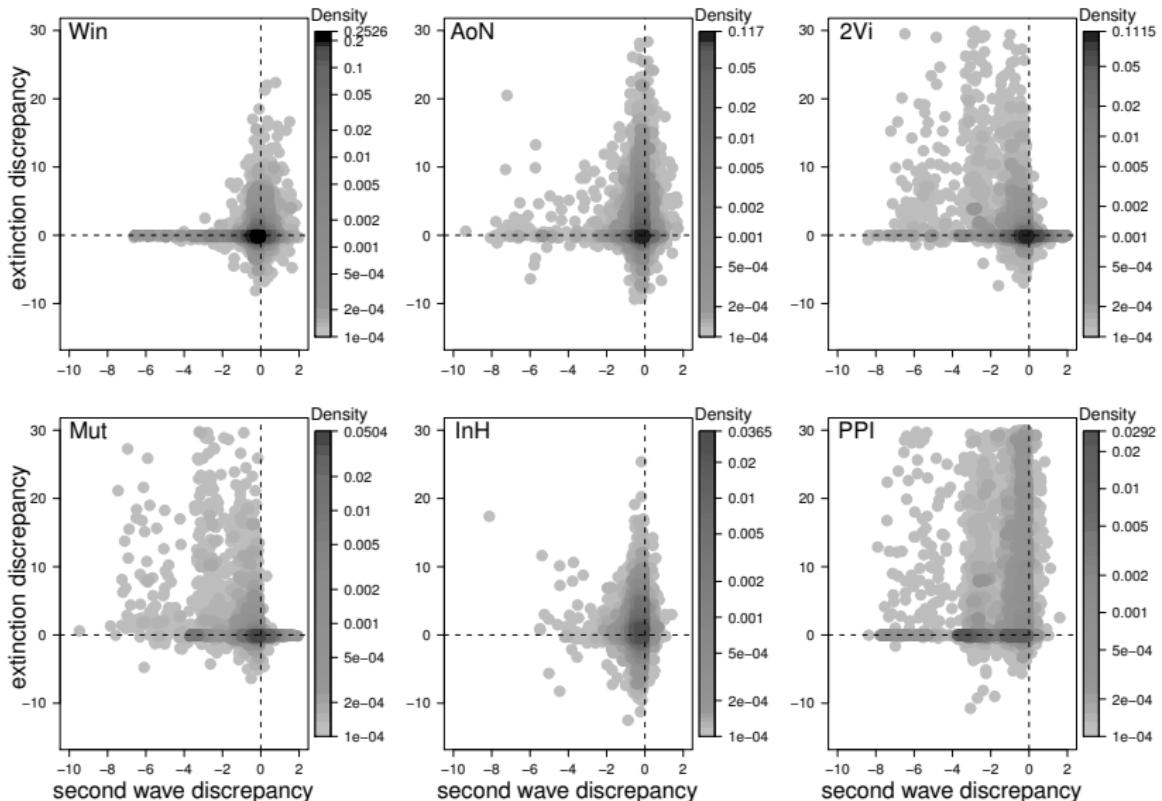
Autocorrelation of the residuals



Posterior predictive checks

- Pick one or more summary-statistics of the time-series
- Compute their distances between model and data
- Do it for 10000 replicates of the model under $\theta_M LE$

Posterior predictive checks



Posterior predictive checks

Proportion of points within a radius R from $(0, 0)$:

Model	$R = 0.25$	$R = 0.5$	$R = 1$	$R = 2$
<i>Win</i>	0.26	0.5	0.7	0.81
<i>AoN</i>	0.12	0.26	0.43	0.60
<i>2Vi</i>	0.14	0.31	0.42	0.50
<i>Mut</i>	0.06	0.14	0.20	0.24
<i>InH</i>	0.02	0.14	0.40	0.65
<i>PPI</i>	0.01	0.05	0.11	0.18

Conclusion; fitting stochastic models

- Bayesian (pMCMC) or Frequentist (MIF)?
- Sampling from the posterior vs Exploring the likelihood surface?
- For both methods, a particle filter is required to evaluate the likelihood of stochastic models.

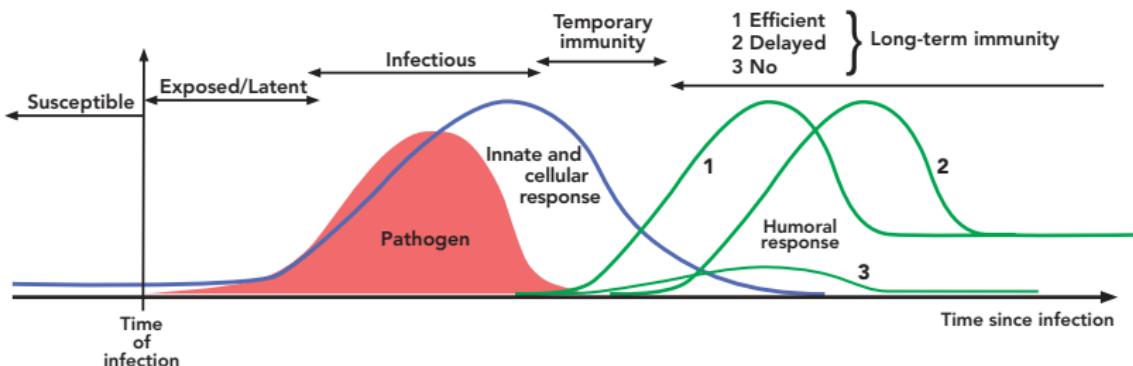
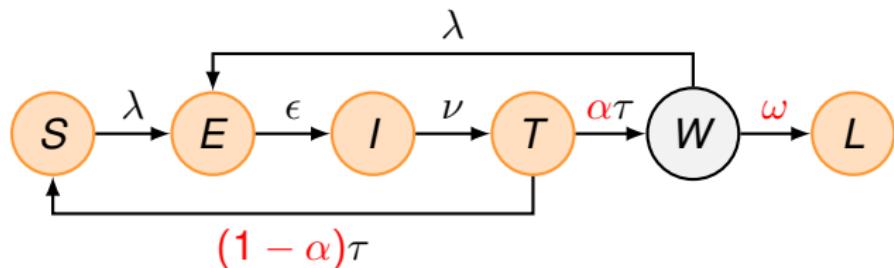
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Win + AoN = WoN



Thanks! Merci! Danke!

