

## gcc-4\_8\_2 (/gcc-4\_8\_2)

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## How To Build GCC 4.8.2 ARM Cross-Compiler

### Intro

In this How To we are going to build an ARM cross-compiler based upon GCC 4.8.2. Before you begin you might want to take a look at my build [machine specs](#) to get an idea of what I'm running on compared to your machine. In the least please make sure you have enough memory. Do not expect a flawless build, especially if you are only running with 1 to 2 GB of memory 8P If you run into issues try to figure them out. Just for some perspective, the ~/workbench/gcc-4.8.2 directory on my machine is approx. 4 GB when all is done.

### Tar Balls

Here is a list of source packages that we'll need for the build. You can either download them now or wait 'til later in the How To.

- binutils-2.23.2.tar.bz2
- glibc-2.18.tar.gz
- gcc-4.8.2.tar.bz2
- gmp-4.3.2.tar.bz2
- mpfr-2.4.2.tar.bz2
- mpc-0.8.1.tar.gz
- linux-2.6.38.tar.bz2

### Create a Workspace

I recommend creating a workspace under your /home/<your user>/ directory that is dedicated to this build. So let's fire up your terminal and run the following:

```
$ export SRCDIR=~/.workbench/gcc-4.8.2/xtools/src
$ mkdir -pv ~/.workbench/gcc-4.8.2/xtools
$ mkdir $SRCDIR
$ cd $SRCDIR
```

### Gather the Sources

Now that we have a workspace created and we are currently in the `src` directory we can begin bringing down the sources and extracting them.

### binutils

```
$ wget http://ftp.gnu.org/gnu/binutils/binutils-2.23.2.tar.bz2
$ tar -pxjf binutils-2.23.2.tar.bz2
```

### glibc

```
$ wget http://ftp.gnu.org/gnu/glibc/glibc-2.18.tar.gz
$ tar -pxzf glibc-2.18.tar.gz
```

### gcc

**Refer to [gcc-4.8.2/contrib/download\\_prerequisites](#) for recommended gmp, mpfr, and mpc**

```
$ wget http://ftp.gnu.org/gnu/gcc/gcc-4.8.2/gcc-4.8.2.tar.bz2
$ wget http://ftp.gnu.org/gnu/gmp/gmp-4.3.2.tar.bz2
$ wget http://ftp.gnu.org/gnu/mpfr/mpfr-2.4.2.tar.bz2
$ wget ftp://gcc.gnu.org/pub/gcc/infrastructure/mpc-0.8.1.tar.gz
$ tar -pxjf gcc-4.8.2.tar.bz2
$ cd gcc-4.8.2/
$ tar -pxjf ../gmp-4.3.2.tar.bz2
$ tar -pxjf ../mpfr-2.4.2.tar.bz2
$ tar -pxzf ../mpc-0.8.1.tar.gz
$ mv gmp-4.3.2/ gmp
$ mv mpfr-2.4.2/ mpfr
$ mv mpc-0.8.1/ mpc
$ cd $SRCDIR
```

### kernel

```
$ wget http://www.kernel.org/pub/linux/kernel/v2.6/linux-2.6.38.tar.bz2
$ tar -pxjf linux-2.6.38.tar.bz2
```

## Build Environment

To make things a little smoother let's setup some environment variables:

```
$ export BINUTILS_SRC=$SRCDIR/binutils-2.23.2
$ export KERNEL_SRC=$SRCDIR/linux-2.6.38
```

```
$ export GCC_SRC=$SRCDIR/gcc-4.8.2
$ export GLIBC_SRC=$SRCDIR/glibc-2.18
$ export BUILDDIR=~/.workbench/gcc-4.8.2/xtools/build
$ export TARGETMACH=arm-none-linux-gnueabi
$ export BUILDMACH=i686-pc-linux-gnu
$ export INSTALLDIR=~/.workbench/gcc-4.8.2/arm
$ export SYSROOTDIR=$INSTALLDIR/sysroot
```

Next up is to begin building.

## Build binutils

```
$ mkdir $BUILDDIR
$ mkdir $BUILDDIR/binutils
$ cd $BUILDDIR/binutils
$ $BINUTILS_SRC/configure --disable-werror --build=$BUILDMACH --target=$
$ make
$ make install
```

Hopefully that went without any errors ;-). If not, try to figure them out. When you are ready to go and/or fixed any errors move to the next step.

## Kernel Headers

I'm building this cross-compiler for the [PandaBoard](#) thus for ARCH I'm using `arm` `omap2plus_defconfig`. Substitute your own board here. In any case, make sure you're specifying the correct architecture, i.e. `arm`.

```
$ cd $KERNEL_SRC
$ make mrproper
$ make ARCH=arm omap2plus_defconfig
$ mkdir -pv $INSTALLDIR/sysroot/usr
$ make ARCH=arm headers_check
$ make ARCH=arm INSTALL_HDR_PATH=$INSTALLDIR/sysroot/usr headers_install
$ cd $SRCDIR
```

Easy peasy. Next is our first go around with `gcc`.

## Bootstrap gcc

```
$ mkdir $BUILDDIR/bootstrap-gcc
$ cd $BUILDDIR/bootstrap-gcc
```

```
$ $GCC_SRC/configure --build=$BUILDMACH --host=$BUILDMACH --target=$TARG
$ make all-gcc install-gcc
$ make all-target-libgcc install-target-libgcc
$ ln -s $INSTALLDIR/lib/gcc/arm-none-linux-gnueabi/4.8.2/libgcc.a $INSTA
```

Not too bad I hope :o)

## **glibc Headers - If binutils is not compatible with glibc this is where it will fail**

**NOTE:** Make sure you have gawk installed (else you get an error similar to [this](#) ).

```
$ mkdir -pv $BUILDDIR/libc
$ cd $BUILDDIR/libc
$ echo "libc_cv_forced_unwind=yes" > config.cache
$ echo "libc_cv_c_cleanup=yes" >> config.cache
$ export PATH=$INSTALLDIR/bin:$PATH
$ export CROSS=arm-none-linux-gnueabi
$ export CC=${CROSS}-gcc
$ export LD=${CROSS}-ld
$ export AS=${CROSS}-as
$ $GLIBC_SRC/configure --build=$BUILDMACH --host=$TARGETMACH --prefix=$S
$ make -k install-headers cross_compiling=yes install_root=$SYSROOTDIR

*** We need to move some files ***
$ pushd $SYSROOTDIR/$INSTALLDIR/sysroot/usr/include
$ cp -rv * $SYSROOTDIR/usr/include/
$ popd

$ ln -s $INSTALLDIR/lib/gcc/arm-none-linux-gnueabi/4.8.2/libgcc.a $INSTA
$ cd $SRCDIR
```

## **Building glibc**

```
$ rm -rf $BUILDDIR/libc
$ mkdir -pv $BUILDDIR/libc
$ cd $BUILDDIR/libc
$ echo "libc_cv_forced_unwind=yes" > config.cache
$ echo "libc_cv_c_cleanup=yes" >> config.cache

*** check to make sure these are still set, they should be ***
$ echo $PATH
$ echo $CROSS
```

```
$ echo $CC

$ $GLIBC_SRC/configure --build=$BUILDMACH --host=$TARGETMACH --prefix=/u
$ make -k install-headers cross_compiling=yes install_root=$SYSROOTDIR
$ ln -s $INSTALLDIR/lib/gcc/arm-none-linux-gnueabi/4.8.2/libgcc.a $INSTA
$ make
$ make install_root=$SYSROOTDIR install
```

## Building The Next gcc

**NOTE:** Here is where we would enable more languages, i.e. c++

```
*** unset CC, LD, and AS. We do not want to xcompile the xcompiler :-) *
$ unset CC
$ unset LD
$ unset AS

*** delete gcc-x.x.x and re-install it ***
$ cd $SRCDIR
$ rm -rf gcc-4.8.2
$ tar -pxjf gcc-4.8.2.tar.bz2
$ cd gcc-4.8.2/
$ tar -pxjf ../gmp-4.3.2.tar.bz2
$ tar -pxjf ../mpfr-2.4.2.tar.bz2
$ tar -pxzf ../mpc-0.8.1.tar.gz
$ mv gmp-4.3.2/ gmp
$ mv mpfr-2.4.2/ mpfr
$ mv mpc-0.8.1/ mpc
$ mkdir -pv $BUILDDIR/final-gcc
$ cd $BUILDDIR/final-gcc
$ echo "libc_cv_forced_unwind=yes" > config.cache
$ echo "libc_cv_c_cleanup=yes" >> config.cache
$ BUILD_CC=gcc
$ $GCC_SRC/configure --build=$BUILDMACH --target=$TARGETMACH --prefix=$I
$ make all-gcc
$ make install-gcc
```

If you made it this far, take a break and give yourself an attaboy :-D

## Building The Final gcc

```
*** make sure these are still unset ***
$ echo $CC
```

```

$ echo $LD
$ echo $AS

*** delete gcc-x.x.x and re-install it ***
$ cd $SRCDIR
$ rm -rf gcc-4.8.2
$ tar -pxjf gcc-4.8.2.tar.bz2
$ cd gcc-4.8.2/
$ tar -pxjf ../gmp-4.3.2.tar.bz2
$ tar -pxjf ../mpfr-2.4.2.tar.bz2
$ tar -pxzf ../mpc-0.8.1.tar.gz
$ mv gmp-4.3.2/ gmp
$ mv mpfr-2.4.2/ mpfr
$ mv mpc-0.8.1/ mpc
$ mkdir -pv $BUILDDIR/final-gcc-2
$ cd $BUILDDIR/final-gcc-2
$ echo "libc_cv_forced_unwind=yes" > config.cache
$ echo "libc_cv_c_cleanup=yes" >> config.cache
$ $GCC_SRC/configure --build=$BUILDMACH --target=$TARGETMACH --prefix=$I
$ make
$ make install

```

You're done! :) Now go compile a test program with your new toy and see if it works. In a *\*new\** terminal run:

```

$ export INSTALLEDIR=~/.workbench/gcc-4.8.2/arm
$ export PATH=$INSTALLEDIR/bin:$PATH
$ export TARGETMACH=arm-none-linux-gnueabi
$ export BUILDMACH=i686-pc-linux-gnu
$ export CROSS=arm-none-linux-gnueabi
$ export CC=${CROSS}-gcc
$ export LD=${CROSS}-ld
$ export AS=${CROSS}-as

```

Now compile your test program:

```

$ $CC -Wall -Wextra <your test>.c -o <your test>

```

Check to see if your test program was successfully cross-compiled for ARM:

```

$ file <your test>
bash: ELF 32-bit LSB executable, ARM, version 1 (SYSV), dynamically link

```

If you see something similar to the output above, then you have successfully cross-compiled your test program.

## Usage

To use the cross-compiler all you need to do is set the following in a new terminal/tab:

```
$ export INSTALLDIR=~/.workbench/gcc-4.8.2/arm
$ export PATH=$INSTALLDIR/bin:$PATH
$ export TARGETMACH=arm-none-linux-gnueabi
$ export BUILDARCH=i686-pc-linux-gnu
$ export CROSS=arm-none-linux-gnueabi
$ export CC=${CROSS}-gcc
$ export LD=${CROSS}-ld
$ export AS=${CROSS}-as
```

It may be cumbersome but I highly recommend doing the above for *every* build. That is to say, each time you cross-compile software for ARM do it in a new terminal/tab and begin by setting the environment variables above. In doing so you ensure that your build starts clean. I have had many occasions where my build would fail at odd times and some of the times I was able to fix it by closing the terminal/tab and starting fresh.

To run the programs that have been compiled with this cross-compiler you'll need to move some of the libraries and binaries to the file system on your dev board or your custom Linux file system. These are located in sysroot: `~/.workbench/gcc-4.8.2/arm/sysroot`.