

Probability Recap: CRV

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LN12: Continuous Random Variables (CRV)

- Definition: A random variable X is continuous if its distribution function $F(x) = \int_{-\infty}^x f(u)du$.
- PDF: Every function f that satisfies $\int_{-\infty}^{\infty} f(u)du = 1$ and $f(x) \geq 0 \forall x$ is called a probability density function.
- Basic properties: Let X be a CRV with PDF $f(x)$. Then:
 - $\int_{-\infty}^{\infty} f(u)du = \lim_{x \rightarrow \infty} F(x) = 1$
 - $P(X = x) = 0 = F(x) - F(x^-)$ (left limit)
 - $P(a \leq X \leq b) = \int_a^b f(u)du = F(b) - F(a)$
- Analysis 1: $\frac{d}{dx}F(x) = f(x)$ if F differentiable at x . if f continuous in $[a, b]$ then F is differentiable in (a, b) .

Independence of CRV

- Definition: $X \perp Y$ if $\forall x, y \quad P((X \leq x) \cap (Y \leq y)) = P(X \leq x)P(Y \leq y)$.
- Borel sets: If $X \perp Y$ and A, B are two borel sets: $P(X \in A, Y \in B) = P(X \in A)P(Y \in B)$.
- Transformations: if $X \perp Y$ then $h(X) \perp g(Y)$.
- Several variables: $X_1 \perp X_2 \dots \perp X_n$ if $\forall x_1, \dots, x_n \quad P(X_1 \leq x_1, X_2 \leq x_2, \dots, X_n \leq x_n) = \prod_i P(X_i \leq x_i)$.
The same would hold for Borel sets.

Transformations of CRV

Distribution Functions

- Base case: X is a CRV, $g: \mathbb{R} \rightarrow \mathbb{R}$, and $Y = g(X)$ (Y is not necessarily continuous). Then:

$$F_y(y) = P(g(X) \leq y) = \int_{\{x: g(x) \leq y\}} f_x(u)du$$

- g strictly increasing and continuous:

$$F_y(y) = P(g(X) \leq y) = P(x \leq g^{-1}(y)) = F_x(g^{-1}(y))$$

- g strictly increasing and continuous:

$$F_y(y) = P(g(X) \leq y) = P(x \geq g^{-1}(y)) = 1 - F_x(g^{-1}(y))$$

- g strictly monotonic but not continuous: The same equations above would still hold if we substitute g^{-1} with the generalized inverse functions:

- g increasing: $g^{-1}(y) = \inf\{x : g(x) \geq y\}$
- g decreasing: $g^{-1}(y) = \inf\{x : g(x) \leq y\}$

PDF

- Base case: X is a CRV with PDF f_x , $g : \mathbb{R} \rightarrow \mathbb{R}$ is a continuously differentiable function with $g'(x) > 0 \forall x$ or $g'(x) < 0 \forall x$. Then $Y = g(X)$ is a CRV with pdf:

$$f_y(y) = f_x(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right|$$

- Restriction: If X takes values in an open interval U g is continuously differentiable with $g'(x) > 0$ or $g'(x) < 0 \forall x \in U$, $V = g(U)$, then:

$$f_y(y) = f_x(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right| I_v(y)$$

LN13: Expectation and Variance

Expectation

- Definition: $E(X) = \int_{-\infty}^{\infty} xf(x)dx$, provided $\int_{-\infty}^{\infty} |x|f(x)dx < \infty$ (converges).
- Behaviour of PDF and CDF at the tails: The existence of the Expectation puts the following constraints on the behaviour of $f(x)$ and $F(x)$:

$$\int_{-\infty}^{\infty} |x|f(x)dx < \infty \implies \lim_{x \rightarrow \infty} \int_x^{\infty} |u|f(u)du = 0, \lim_{x \rightarrow -\infty} \int_{-\infty}^x |u|f(u)du = 0$$

$$\int_{-\infty}^{\infty} |x|f(x)dx < \infty \implies F(x) = o\left(\frac{1}{|x|}\right) x \rightarrow -\infty, 1 - F(x) = o\left(\frac{1}{|x|}\right) x \rightarrow \infty$$

- The converse implication: If $\int_0^{\infty} 1 - F(x) < \infty$ and $\int_{-\infty}^0 F(x) < \infty$ then $\int_{-\infty}^{\infty} |x|f(x) < \infty$.
- Expectation in terms of distribution: $E(X) = -\int_{-\infty}^0 F(x) + \int_0^{\infty} 1 - F(x)$.
- Transformations: if $Y = g(X)$, then $E(Y) = \int_{-\infty}^{\infty} g(x)f_x(x)dx$.
 $E(aX + b) = aE(X) + b$ (follows from above).

Moments and Variance

- The k^{th} moment of X : $m_k = E(X^k) = \int_{-\infty}^{\infty} x^k f_x(x)dx$, provided $\int_{-\infty}^{\infty} |x|^k f_x(x)dx < \infty$
- Lower moments: if m_k exists finite, then $\forall j : 1 \leq j \leq k$, m_j exists finite.
- k^{th} **centred** moment: $\sigma_k = E((X - u)^k)$.
- **Variance**: $Var(X) = \sigma_2 = E((X - u)^2) = \int_{-\infty}^{\infty} (x - u)^2 f_x(x)dx$, provided $\int_{-\infty}^{\infty} (x - u)^2 f_x(x)dx < \infty$
- Properties of Variance:
 - $V(X) = E(X^2) - E(X)^2$
 - $V(aX + b) = a^2 V(X)$
- The standard deviation: $\sigma = \sqrt{\sigma^2} = \sqrt{Var(X)}$
- Non-Zero Variance: $Var(X) \neq 0$ if X is a CRV.

LN14: Noteworthy Distributions

Uniform Distribution

$$f(x) = \frac{1}{b-a} I_{[a,b]}(x), \quad F(x) = \frac{x-a}{b-a} \quad \forall x : a \leq x \leq b$$
$$E(X) = \frac{b+a}{2}, \quad V(X) = \frac{(b-a)^2}{12}$$

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Exponential Distribution

$$f(x) = \lambda e^{-\lambda x} I_{(0,\infty)}(x), \quad F(x) = (1 - e^{-\lambda x}) I_{(0,\infty)}(x)$$

$$E(X) = \frac{1}{\lambda}, \quad Var(X) = \frac{1}{\lambda^2}$$

- Lack of memory property: $P(X > x + z \mid X > z) = P(X > x)$
- Usage: The Exponential Distribution is generally used for waiting times, when time is measured continuously. The Exponential is the limit of a geometric distribution.
- Connection to Poisson: If the number of events in an interval of length t has $Poisson(\lambda t)$. The probability that no events occur in this interval is $P(N = 0) = e^{-\lambda t}$, which is exponential.

Normal Distribution

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}\right), \quad E(X) = \mu, \quad V(X) = \sigma^2$$

- Symmetry of PDF (φ): $\varphi(\mu + x) = \varphi(\mu - x)$.
- Symmetry of CDF (Φ): $\Phi(x, 0, 1) = 1 - \Phi(-x, 0, 1)$, $\Phi(\mu + x, \mu, \sigma^2) = 1 - \Phi(\mu - x, \mu, \sigma^2)$.
- Standard Normal Distribution: It is the normal distribution with parameters $\mu = 0$, $\sigma^2 = 1$
- Stable under Linear Transformations: $X \sim N(\mu, \sigma^2)$, then $Y = aX + b \sim N(a\mu + b, a^2\sigma^2)$
- Standardization: if $X \sim N(\mu, \sigma^2)$, then $Z = \frac{X-\mu}{\sigma} \sim N(0, 1)$.
- Using the Normal table: Say $X \sim N(\mu, \sigma^2)$, then $P(X \leq x) = P\left(\frac{X-\mu}{\sigma} \leq \frac{x-\mu}{\sigma}\right) = \Phi\left(\frac{x-\mu}{\sigma}, 0, 1\right)$.

Gamma Distribution

$$X \sim \Gamma(k, \lambda) \implies f(x) = \frac{\lambda^k}{\Gamma(k)} e^{-\lambda x} x^{k-1} I_{(0,\infty)}(x), \quad E(X) = \frac{k}{\lambda}, \quad Var(X) = \frac{k}{\lambda^2}$$
$$\Gamma(x) = \int_0^\infty u^{x-1} e^{-u} du$$

- Properties of Gamma function:
 - $\Gamma(1) = 1$
 - $\Gamma(x) = (x-1)\Gamma(x-1)$
 - $\Gamma(n) = (n-1)!$
 - $\Gamma(\frac{1}{2}) = \sqrt{\pi}$
- λ is a scale parameter. If $X \sim \Gamma(k, \lambda)$, then $Y = \lambda X \sim \Gamma(k, 1)$.
- Sum of Exponentials: if X_1, X_2, \dots, X_k are independent identically distributed random variables with $\text{Exp}(\lambda)$ distribution, then $\sum_i X_i \sim \Gamma(k, \lambda)$.
- Relation with Normal Distribution: if $Z \sim N(0, 1)$, then $Z^2 \sim \Gamma(\frac{1}{2}, \frac{1}{2})$

Cauchy Distribution

$$f(x) = \frac{1}{\pi(1+x^2)} \quad F(x) = \frac{1}{2} + \frac{1}{\pi} \arctan(x)$$

The Cauchy Distribution has no finite moments.

Beta Distribution

$$f(x) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} x^{a-1} (1-x)^{b-1} I_{[0,1]}(x), \quad E(X) = \frac{a}{a+b}, \quad Var(X) = \frac{ab}{(a+b)^2(a+b+1)}$$

$$\text{Beta}(1, 1) = \text{Uniform}([0, 1])$$

LN15: Dependence of CRV

- Joint Distribution of X, Y : $F(x, y) = P(X \leq x, Y \leq y)$.
- Jointly Continuous: X, Y are jointly continuous if $\exists f(x, y) : P((X, Y) \in A) = \iint_A f(x, y)$. f is called the joint density function.
- Marginal Density functions: If X, Y are jointly continuous, then X, Y are continuous and:

$$f_x(x) = \int_{-\infty}^{\infty} f_{x,y}(x, y) dy, \quad f_y(y) = \int_{-\infty}^{\infty} f_{x,y}(x, y) dx$$

Note: X, Y continuous $\not\Rightarrow X, Y$ jointly continuous.

- Density from Distribution: In the points where $f(x, y)$ is continuous we can find $f(x, y) = \frac{\partial^2}{\partial x \partial y} F(x, y)$.
- Expectation: if X, Y jointly continuous, then for any measurable function $g : \mathbb{R}^2 \rightarrow \mathbb{R}$

$$E(g(X, Y)) = \iint_{-\infty}^{\infty} g(x, y) f(x, y) dx dy$$

- Properties of the Expectation:
 - Linearity: $E(aX + bY) = aE(X) + bE(Y)$.
 - Product: $E(XY) = E(X)E(Y)$ if $X \perp\!\!\!\perp Y$.
- Independence and Density: $X \perp\!\!\!\perp Y$ if and only if $f_{x,y}(x, y) = f_x(x)f_y(y)$.
Note: if $f(x, y) = g(x)h(y)$ then $\exists c : f_x(x) = cg(x), f_y(y) = \frac{1}{c}h(y)$.
- Covariance: $Cov(X, Y) = E((X - \mu_x)(Y - \mu_y)) = E(XY) - E(X)E(Y)$.
- Covariance is a Multilinear form: $Cov(aX + bY, Z) = a Cov(X, Z) + b Cov(Y, Z)$.
- Correlation: $\rho(X, Y) = \frac{Cov(X, Y)}{\sqrt{Var(X)Var(Y)}}$
- Cauchy Schwarz: if X, Y jointly continuous $E(XY)^2 < E(X^2)E(Y^2)$ (strict inequality).
This means that $|Cov(X, Y)| < \sqrt{Var(X)Var(Y)}$ and $-1 < \rho(X, Y) < 1$.
- Bivariate Normal Distribution: If X, Y are jointly continuous with Bivariate Normal Distribution then:
 - $X \sim N(\mu_1, \sigma_1^2)$
 - $Y \sim N(\mu_2, \sigma_2^2)$
 - $\rho = \rho(X, Y)$

LN16: Conditioning

- Conditional density function: Let X, Y be jointly continuous with joint density function $f_{x,y}(x, y)$ and marginals f_x, f_y . Then the conditional density of Y given $X = x$ is **the function of y** :

$$f_{(y|x)}(y | x) = \frac{f_{x,y}(x, y)}{f_x(x)}$$

- $f_{(t|x)}$ is a density function:
 - $f_{(y|x)}(y | x) \geq 0 \forall y$.
 - $\int_{-\infty}^{\infty} f_{(y|x)} dy = 1$
- Conditional Distribution of Y given $X = x$: $F_{Y|X}(y | x) = \int_{-\infty}^y f_{(y|x)} dy$
Note: $P(Y \in A | X = x) = \int_A f_{(y|x)} dy$
- Product Rule: $f_{x,y}(x, y) = f_x(x) f_{(y|x)}(y | x)$
- Conditional Expectation: $\psi(X) = E(Y | X = x) = \int_{-\infty}^{\infty} y f_{(y|x)} dy$
- Expectation of Expectation: $E(E(Y | X)) = E(Y)$
Note: This follows from $E(g(X)E(Y | X)) = E(g(X)Y)$
- Conditional Variance: $Var(Y | X) = \int_{-\infty}^{\infty} (Y - \psi(X))^2 f_{(y|x)} dy$
- Variance Decomposition:
 - $Var(Y | X) = E(Y^2 | X) - E(Y | X)^2$
 - $Var(Y | X) = V(E(Y | X)) + E(V(Y | X))$
- Conditioning the Bivariate: Let X, Y have Bivariate joint density function. Then:

$$Y | X \sim N\left(\mu_y + \rho \frac{\sigma_y}{\sigma_x} (x - \mu_x), \sigma_y^2 (1 - \rho^2)\right)$$

LN17: Transformations

- Main Theorem: Let X, Y be CRVs with joint density function $f_{(x,y)}(x, y)$. Let $U \subset \mathbb{R}^2$ be an open set s.t $P((X, Y) \in U) = 1$. Let $T : U \rightarrow V$ be one-to-one and let T^{-1} be its inverse. If all the partial derivatives of T^{-1} exist and are continuous with $\det J_{T^{-1}}(z, w) \neq 0 \forall (z, w) \in V$, then Z and W are jointly continuous with density:

$$f_{z,w}(z, w) = f_{x,y}(T^{-1}(z, w)) | \det J_{T^{-1}}(z, w) | I_v(z, w)$$

- Sums of Random Variables: Let X and Y be continuous random variables with joint density function $f_{(x,y)}$. Let $Z = X + Y$. Z is continuous with density function:

$$f_z(z) = \int_{-\infty}^{\infty} f_{x,y}(x, z - x) dx$$

If $X \perp Y$, then $f_z = \int_{-\infty}^{\infty} f_x(x) f_y(z - x) dx$

LN18: Random Vectors and the Multivariate Distribution

- Random Vectors: Let X_1, \dots, X_k be CRVs on the same Probability Space. Then $\bar{X} = \begin{bmatrix} X_1 \\ \vdots \\ X_k \end{bmatrix}$ is a random vector.
- Continuity: \bar{X} is said to be continuous with density function $f(x_1, \dots, x_k)$ if $P(X \in A) = \int_A f(x_1, \dots, x_k)$.
If \bar{X} is continuous, then every subvector is continuous.
- Subvectors: The density function of a subvector can be obtained by integrating out the other variables.
- Independence: Let X_1, \dots, X_k be jointly continuous random variables. Then they are independent iff $f(x_1, \dots, x_k) = \prod_i f_{x_i}(x_i)$
- Expectation: $E(\bar{X}) = \bar{u} = \begin{bmatrix} E(X_1) \\ \vdots \\ E(X_k) \end{bmatrix}$, $Var(X) = \Sigma = [Cov(X_i, X_j)]_{i,j=1,2,\dots,k}$
- Non-Singularity of Σ : If X_1, \dots, X_k are jointly continuous, then Σ is non-singular and there exists the inverse Σ^{-1} . It is possible to find $\Sigma^{\frac{1}{2}}$ and $\Sigma^{-\frac{1}{2}}$ such that $\Sigma^{\frac{1}{2}} \Sigma^{\frac{1}{2}} = \Sigma$, $\Sigma^{-\frac{1}{2}} \Sigma^{-\frac{1}{2}} = \Sigma^{-1}$ and $(\Sigma^{1/2})^{-1} = \Sigma^{-\frac{1}{2}}$.
- Variance in term of Expectation: $\Sigma = E \left((\bar{X} - \bar{u}) (\bar{X}^T - \bar{u}^T) \right)$.
- Linearity of the Expectation: $E(A\bar{X} + b) = AE(\bar{X}) + b$
In particular if A is a row vector, $E(a_i X_i + \dots a_n X_n) = \sum_i a_i E(X_i)$
- Properties of the Variance:
 - $V(\bar{X}) = E(X X^T) - E(X)E(X)^T$
 - $V(AX + b) = AV(X)A^T$
 - $V(a_i X_i + \dots a_n X_n) = \sum_i a_i^2 V(X_i) + \sum_{i \neq j} a_i a_j Cov(X_i, X_j)$.
- Conditioning: The conditional density of X_1 given that $X_2 = x_2, \dots, X_k = x_k$ is defined as:

$$f_{x_1|x_2, \dots, x_k}(x_1 | x_2, \dots, x_k) = \frac{f_{x_1, \dots, x_k}(x_1, \dots, x_k)}{f_{x_2, \dots, x_k}(x_2, \dots, x_k)}$$

Transformations of Random Vectors

- Main Theorem: Let X be a continuous random vector with density function $f(x_1, \dots, x_k)$. Let $U \subset \mathbb{R}^k$ be a one-to-one function and let T^{-1} be its inverse. If all the partial derivatives of T^{-1} exist and are continuous with $\det J_{T^{-1}}(\bar{y}) \neq 0$, then \bar{Y} is a continuous random variable with density function:

$$f_Y(y) = f_x(T^{-1}(y)) | \det J_{T^{-1}}(y) | I_v(y)$$

- Linear Transformations: $Y = AX + b$ where A is a $k \times k$ non-singular matrix, then Y is also continuous with

$$f_y(y) = f_x(A^{-1}(y - b)) | \det A^{-1} |$$

Since every subvector of a continuous vector is continuous, for every $h \times k$ matrix A of rank h and for every vector b of dimension h , $Y = AX + b$ is continuous.

Multivariate Distribution

- Let μ be a vector of dimension k and let Σ be a $k \times k$ symmetric matrix with positive determinant of all positive leading principal minors. \bar{X} as multivariate normal distribution with parameters μ and Σ ($X \sim N(\mu, \Sigma)$) if \bar{X} has density:

$$f_x(x) = \frac{1}{(\sqrt{2\pi})^k} \frac{1}{\sqrt{\det(\Sigma)}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right)$$

- Independence and Uncorrelation: $\bar{X} \sim N(\bar{0}, I)$ (where $\bar{0}$ is the zero vector and I is the identity matrix) if and only if X_1, \dots, X_k are independent and identically distributed CRVs with univariate standard normal distribution.

Analogously it can be proved that if $X \sim N(\mu, \Sigma)$ then X_1, \dots, X_k are mutually independent iff Σ is a diagonal matrix. That is all covariances are 0. In this case Independence \iff Uncorrelation.

- Linear Transformations: Let $X \sim N(\mu, \Sigma)$, A a $k \times k$, non-singular matrix and b a vector of dimension k . Then $Y = AX + b \sim N(A\mu + b, A\Sigma A^T)$.

Note: This also works if A is a $h \times k$ matrix of rank h .

- Standardization: if $X \sim N(\mu, \Sigma)$, then $Z = \Sigma^{-1/2}(X - \mu) \sim N(\bar{0}, I)$.

LN19: MGF

- Definition: $M_x(t) = E(e^{tx}) = E(\sum_{k=0}^{\infty} (tx)^k / k!) = \sum_k t^k m_k / k!$
- MGFs and Distributions: If two random variables have the same MGF, then they have the same distribution.
- Convergence: If X, X_1, X_2, \dots, X_n is a sequence of random variables such that the MGFs are defined, then $M_{X_n} \rightarrow M_X$ implies $F_{X_n} \rightarrow F_X$ at least in the points where F_X is continuous.
- Maclaurin Expansion: If $t \rightarrow 0$, then $M_x(t) = 1 + M'_x(0)t + M''_x(0)t^2/2 + o(t^2) = 1 + m_1t + m_2t^2/2 + o(t^2)$.
Remark: $M_x^{(k)}(0) = E(X^k)$. (the k^{th} derivative).
- Linear Transformations: $M_{aX+b} = e^{tb} M_x(at)$.
- Independence: $M_{X+Y}(t) = M_X(t) M_Y(t)$.
- Central limit theorem: If $X_1, X_2 \dots X_n$ are independent and identically distributed such that $E(X_i^2)$ exists finite, then:

$$\frac{\sum_i X_i - nu}{\sqrt{n}\sigma} \xrightarrow{d} Z \sim N(0, 1)$$

LN20: Convergence and the Laws of Large Numbers

Inequalities

- Markov's inequality: $P(|X| \geq k)k^r \leq E(|X|^r)$
- Chebyshev's inequality: $P(|X - \mu| \geq k)k^2 \leq \sigma^2$, where $\sigma^2 = \text{Var}(X)$.
- Jensen's inequality: if $g : \mathbb{R} \rightarrow \mathbb{R}$ is a convex function: $E(g(X)) \geq g(E(X))$.

Types of Convergence

- Probability: $X_n \rightarrow X$ in probability if $P(|X_n - X| \geq \epsilon) \rightarrow 0$ as $n \rightarrow \infty$.
- Almost surely (a.s): $X_n \rightarrow X$ a.s if $P(\{\omega \in \Omega : X_n(\omega) \rightarrow X(\omega)\}) = 1$
- r^{th} Mean: $X_n \rightarrow X$ in r^{th} mean if $E(|X_n - X|^r) \rightarrow 0$ as $n \rightarrow \infty$
- Implications:
 - r^{th} mean convergence implies probability convergence.
 - a.s convergence implies probability convergence.
 - probability convergence implies distribution convergence.
 - if X_n converges to a constant in distribution, then X_n converges to the same constant in probability.
- Sufficient Condition for a.s convergence: $\sum_{n=1}^{\infty} P(|X_n - X| \geq \epsilon) < \infty$.

Laws of Large Numbers

- Sample Mean: $\overline{X_n} = \frac{1}{n} \sum_{k=1}^n X_k$.
- Weak Law of Large Numbers: if X_1, X_2, \dots, X_n are uncorrelated with finite second moment then $\overline{X} \rightarrow \mu = E(X_i)$ in probability.
- Strong Law of Large Numbers: If X_1, X_2, \dots, X_n are i.i.d with finite expectation, then $\overline{X_n} \rightarrow \mu$ almost surely.

Transformations and Convergence

- Continuous mappings: Let $g : \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function. Then:
 - $X_n \rightarrow X$ a.s $\implies g(X_n) \rightarrow g(X)$ a.s.
 - $X_n \rightarrow X$ in probability $\implies g(X_n) \rightarrow g(X)$ in probability.
 - $X_n \rightarrow X$ in distribution $\implies g(X_n) \rightarrow g(X)$ in distribution.
- Continuous mappings \mathbb{R}^2 case: Let $g : \mathbb{R} \rightarrow \mathbb{R}$ be a continuous function. Then:
 - $X_n \rightarrow X$ and $Y_n \rightarrow Y$ a.s $\implies g(X_n, Y_n) \rightarrow g(X, Y)$ a.s.
 - $X_n \rightarrow X$ and $Y_n \rightarrow Y$ in probability $\implies g(X_n, Y_n) \rightarrow g(X, Y)$ in probability.
 - The property does not hold for convergence in distribution !
- Slutski's Theorem: $X_n \rightarrow X$ in distribution and $Y_n \rightarrow c$ in probability, then:
 - $X_n + Y_n \rightarrow X + c$ in distribution.
 - $X_n Y_n \rightarrow Xc$ in distribution.

Useful facts

- $\int_0^\infty e^{-x^2} dx = \frac{\sqrt{\pi}}{2}$
- $\sum_{x=0}^\infty \frac{a^x}{x!} = e^a$
- $\lim_{n \rightarrow \infty} (1 + \frac{a}{n})^n = e^a$
- Geometric Sum = $\frac{u_1(r^n - 1)}{r - 1}$