Séverin Lemaignan

Post-doctoral Researcher, Cognition for Human-Robot Interaction



Scientific Interests

Scientific Focus Robot cognition and decision making, which includes human-robot multi-modal interaction; theory of mind for robots; formal knowledge representation.

PhD Title Grounding the Interaction: Knowledge Representation for Interactive Robots

Keywords Robotic Cognition, Human-Robot Interaction, Grounding, Ontologies

Education and Research Activities

2013– **Post-doctoral fellow**, *CHILI, EPFL, Lausanne, Switzerland*. Interaction with Robots in Educational Environments – Supervision of the robotic group.

2012–2013 **Post-doctoral fellow**, *LAAS-CNRS*, *Toulouse*, *France*. Spatial and Temporal Reasoning for Cognitive Robotic Architectures.

2008–2012 **German-French PhD in Cognitive Robotics**, *LAAS-CNRS*, *Toulouse*, *France / IAS-TUM*, *Munich*, *Germany*.

with High Distinction "Summa Cum Laude" – awarded CNRS' Best PhD in Robotics 2012 Supervisors: Pr. Rachid Alami, CNRS Senior Researcher, Pr. Michael Beetz, TUM Senior Researcher.

2006–2007 Research Engineer, INRIA, Paris, France.

Development of semantic-aware control architectures for autonomous vehicles.

2002–2006 **German-French MSc of Engineering**, *Karlsruhe Institute of Technology / ENSAM ParisTech*, **Gold Medal** (top ten students).

Final project: Ontologies and distributed systems for industrial processes.

2004–2005 **MSc Artificial Intelligence for Learning Technologies**, *University Paris V, College of Mathematics and Computer Sciences*, With Honours.

Selected Publications

See my website for the complete list of publications, workshops and seminars.

International peer-reviewed journals

- Lemaignan, S. and Warnier, M. and Sisbot, E. A. Alami, R., **Human-Robot Interaction: Tackling the AI Challenges**, *Artificial Intelligence*, 2014.
- Lemaignan, S. and Ros, R. and Sisbot, E. A. Alami, R. and Beetz M., Grounding the Interaction: Anchoring Situated Discourse in Everyday Human-Robot Interaction, International Journal of Social Robotics, 2011.

International peer-reviewed conference articles (6-8 pages)

- Lemaignan, S. and Ros, R. and Alami, R. and Beetz, M., What are you talking about?
 Grounding dialogue in a perspective-aware robotic architecture, ROMAN, 2011.
- Lemaignan, S. and Ros, R. and Mösenlechner, L. and Alami, R. and Beetz, M., ORO, a knowledge management module for cognitive architectures in robotics, IROS 2010.

o Ros, R. and Lemaignan, S. and Sisbot, E. A. and Alami, R. and Steinwender, J. and Hamann, K. and Warneken, F., Which One? Grounding the Referent Based on Efficient Human-Robot Interaction, ROMAN. 2010. Best paper award.

Supervision & Teaching Experience

2010- Students supervision.

- o A. Jacq (PhD, 2014-): Mutual modeling and repair strategies in HRI
- o A. Özgür (PhD, 2014-): Cellulo: paper robots for large-scale robotic deployments in schools
- o D. Hood (Master, 2014): CoWriter project: Getting Nao to write on a tactile tablet
- o S. Chandra (PhD, 2013-2014): CoWriter project: learning by teaching handwriting to a robot
- J. Fink (PhD, 2013-2014): Long-term acceptance of robots in daily life, Anthropomorphism
- o P. Tsemengue, M. Chouayakh (Master, 2010): The Dialogs natural language processor
- 2008–2013 Support lectures in robotics, EPFL, LAAS-CNRS, Université de Toulouse. ROS, robotic simulation, ontologies, Python, software development.
- 2008-2011 Teaching assistant, INSA Toulouse.

Prolog, Ontology Modeling, Java, ADA, SQL.

2006–2007 **Teaching assistant**, École des Mines de Paris. Mechatronics.

Technical Skills and Spoken Languages

- Robotics o Expert in cognitive robotics and human-robot interaction
 - Expert in symbolic knowledge representation
 - o Expert PR2, Nao developer
 - Contributor to ROS, OpenCV
 - Lead dev. MORSE simulator

Languages

French Native

English **Expert**

German Advanced

- Programming Python, C++, Haskell, Prolog, SmallTalk
 - GitHub:

github.com/severin-lemaignan

TOEIC score 925/990

DSH

Dissemination Activities

Workshops

- 2013 Steering Committee, Intl. Workshop on MORSE for Human-Robot Interaction, HRI 2014.
- 2013 Program Committee, Workshop on Developmental Social Robotics, IROS 2013, http://devsor2013.sciencesconf.org.
- 2012 Steering Committee, Intl. Workshop on MORSE and its Applications.
- 2008-2009 Steering Committee, Cognitive Sciences' Young Researchers Conference 2009, http://fresco.risc.cnrs.fr/cjcsc2009/.

Outreach

- 2008–2012 Robotics Science Day Coordinator, LAAS-CNRS.
- 2008-2011 Vice President of Toulouse's Cognitive Science Student Association . www.incognu.fr
- 2008–2009 Science Communicator at South African SciFest festival.
 - 1997 Involvement at Planète Sciences, Head of the Robotics Department in 2006-2007 -Executive Committee member since 2008 – Science Camps leader (with BAFA certification) - Coordinator on the EUROBOT Robotic Competition .

http://www.planete-sciences.org/